

**15.082J & 6.855J & ESD.78J**  
**October 7, 2010**

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**Introduction to Maximum Flows**

# The Max Flow Problem

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$G$  =  $(N,A)$

$x_{ij}$  = flow on arc  $(i,j)$

$u_{ij}$  = capacity of flow in arc  $(i,j)$

$s$  = source node

$t$  = sink node

Maximize  $v$

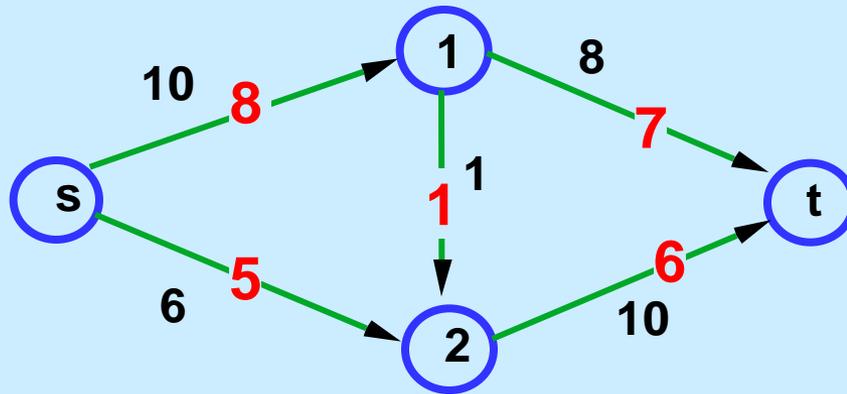
Subject to  $\sum_j x_{ij} - \sum_k x_{ki} = 0$  for each  $i \neq s,t$

$$\sum_j x_{sj} = v$$

$$0 \leq x_{ij} \leq u_{ij} \text{ for all } (i,j) \in A.$$

# Maximum Flows

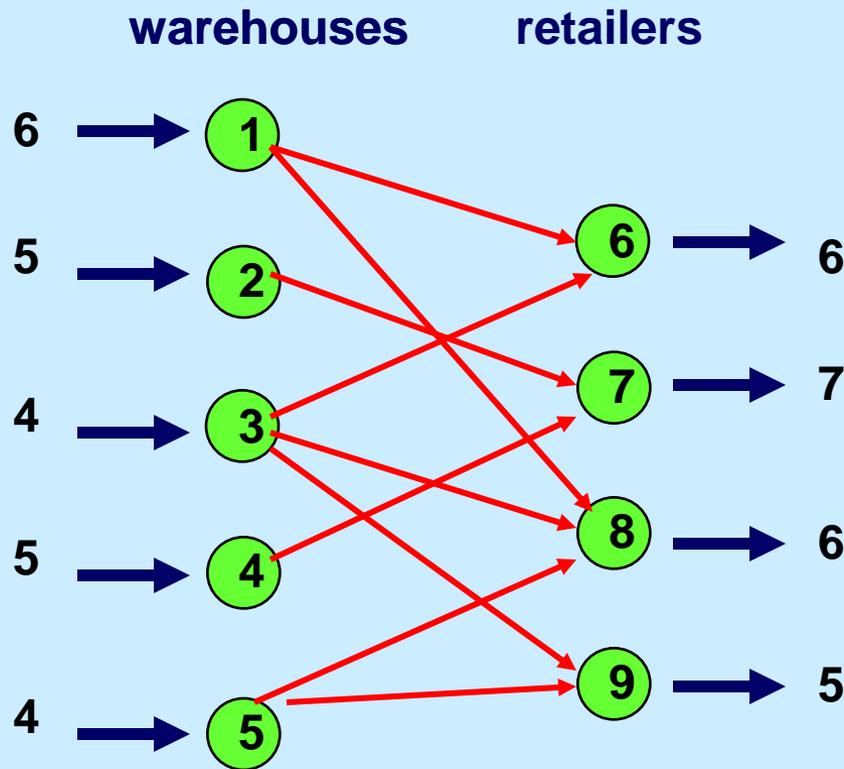
We refer to a flow  $x$  as **maximum** if it is feasible and maximizes  $v$ . Our objective in the max flow problem is to find a maximum flow.



A max flow problem. Capacities and a non-optimum flow.

# The feasibility problem: find a feasible flow

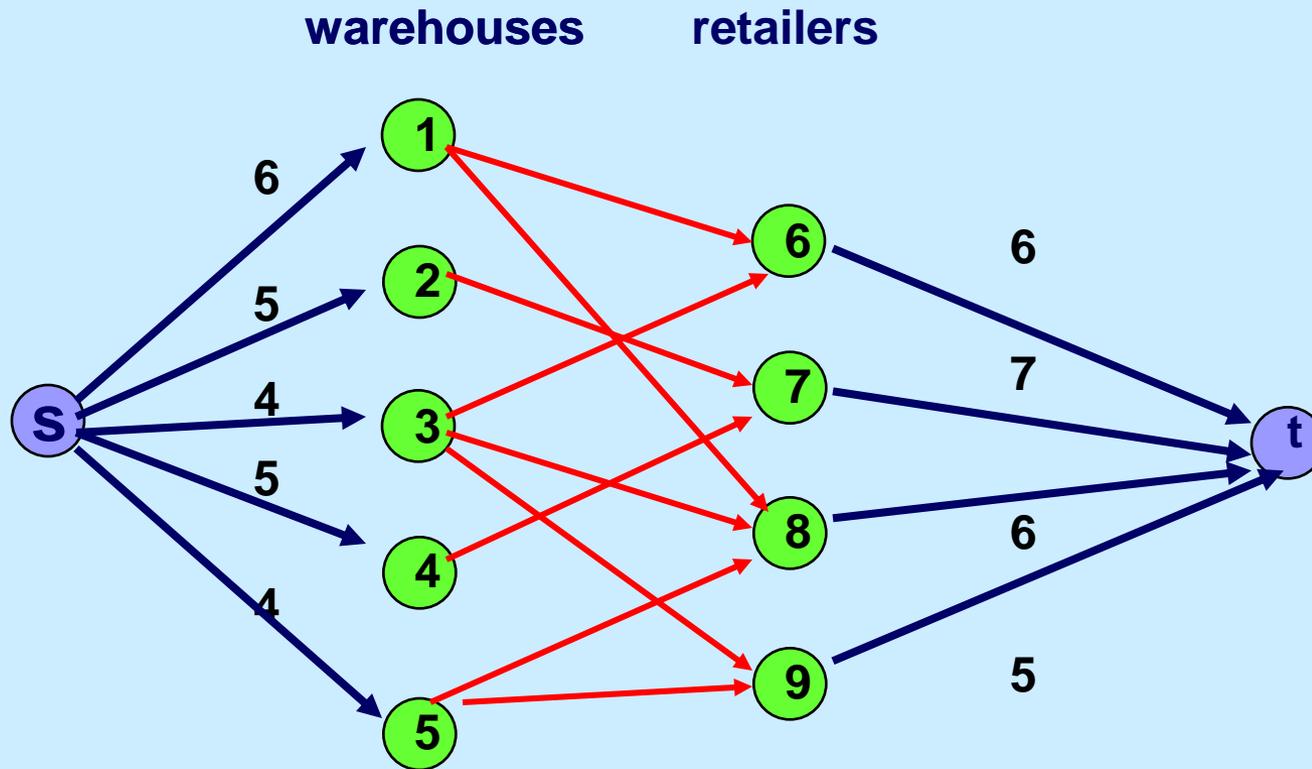
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Is there a way of shipping from the warehouses to the retailers to satisfy demand?

# Transformation to a max flow problem

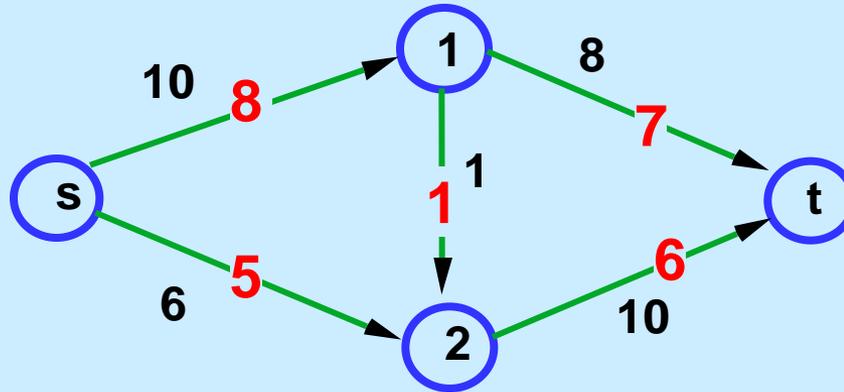
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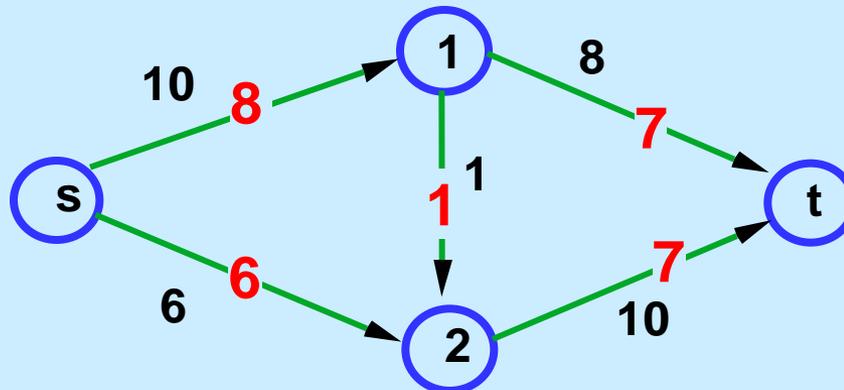
There is a 1-1 correspondence with flows from  $s$  to  $t$  with 24 units (why 24?) and feasible flows for the transportation problem.

# sending flows along s-t paths

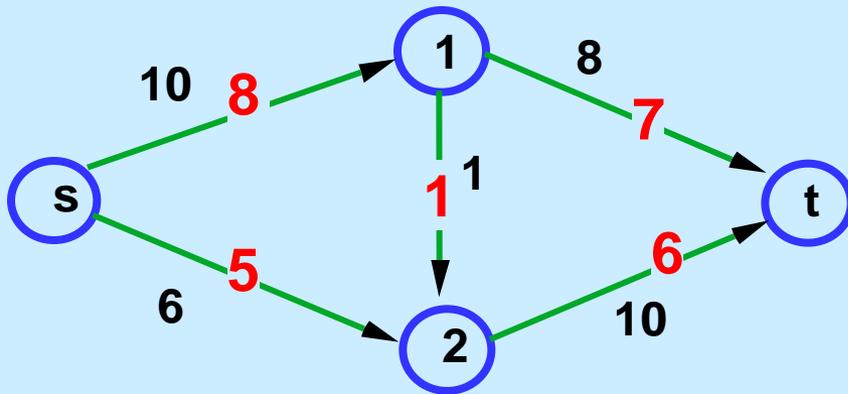
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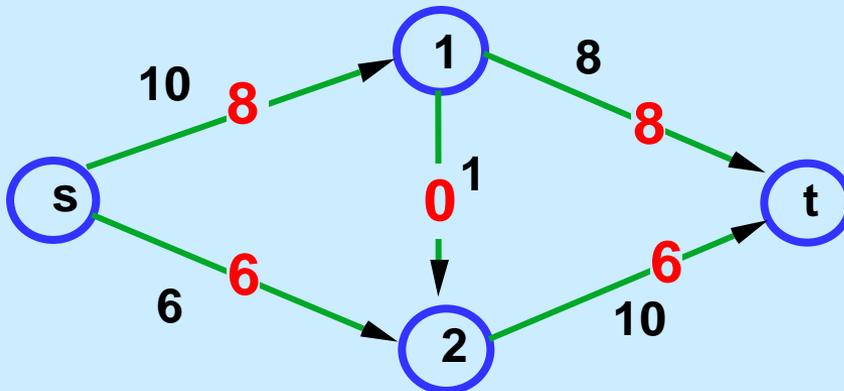
One can find a larger flow from s to t by sending 1 unit of flow along the path s-2-t



# A different kind of path

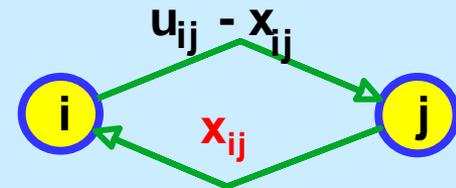
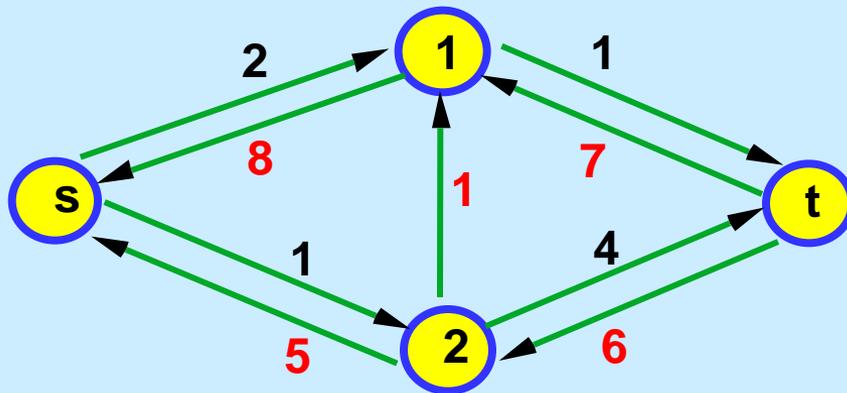
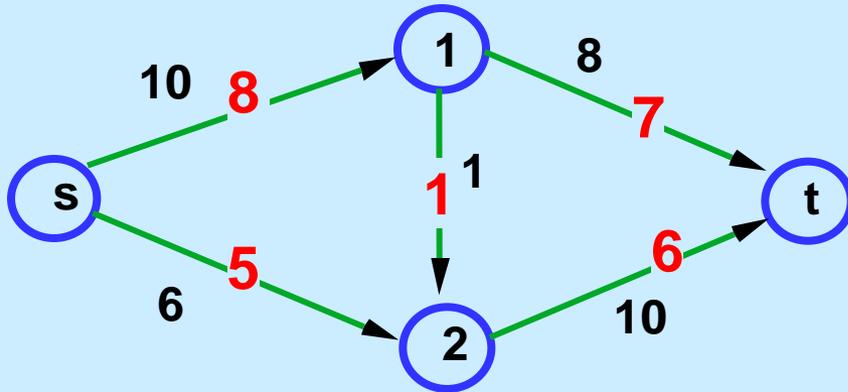


One could also find a larger flow from s to t by sending 1 unit of flow along the path s-2-1-t. (Backward arcs have their flow decreased.)



Decreasing flow in (1, 2) is mathematically equivalent to sending flow in (2, 1) w.r.t. node balance constraints.

# The Residual Network



The *Residual Network*  $G(x)$

We let  $r_{ij}$  denote the *residual capacity* of arc  $(i,j)$

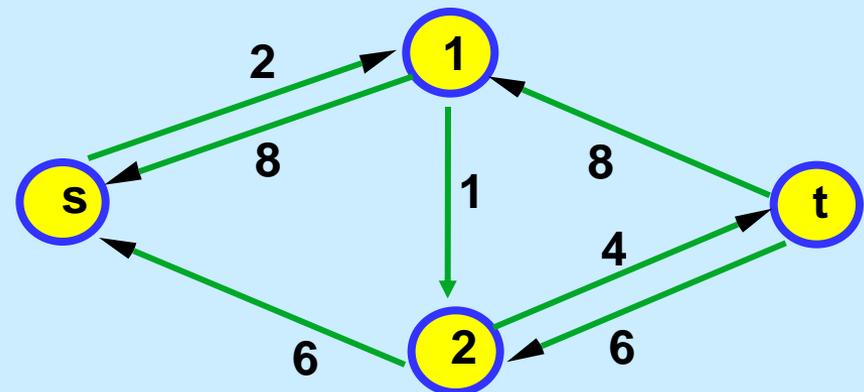
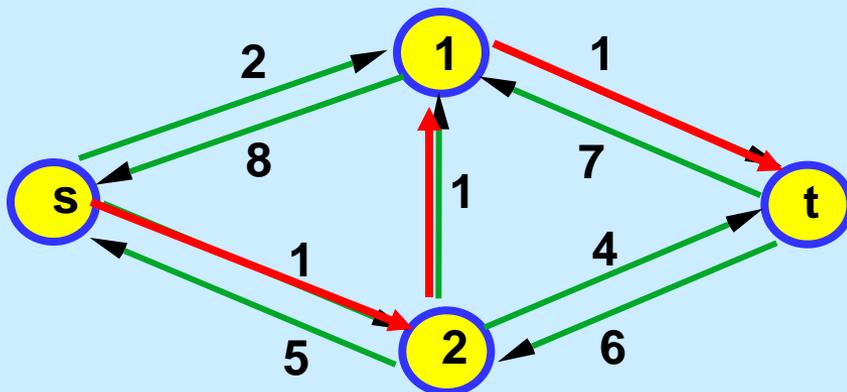
# A Useful Idea: Augmenting Paths

An **augmenting path** is a path from  $s$  to  $t$  in the residual network.

The **residual capacity** of the augmenting path  $P$  is  
 $\tau^M(P) = \min\{r_{ij} : (i,j) \in P\}$ .

To **augment along  $P$**  is to send  $\tau^M(P)$  units of flow along each arc of the path. We modify  $x$  and the residual capacities appropriately.

$r_{ij} := r_{ij} - \tau^M(P)$  and  $r_{ji} := r_{ji} + \tau^M(P)$  for  $(i,j) \in P$ .



# The Ford Fulkerson Maximum Flow Algorithm

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$x := 0;$

create the residual network  $G(x);$

while there is some directed path from  
 $s$  to  $t$  in  $G(x)$  do

    let  $P$  be a path from  $s$  to  $t$  in  $G(x);$

$\tau := \tau(P);$

    send  $\tau$  units of flow along  $P;$

    update the  $r$ 's;

**Ford-  
Fulkerson  
Algorithm  
Animation**

# To prove correctness of the algorithm

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**Invariant:** at each iteration, there is a feasible flow from  $s$  to  $t$ .

**Finiteness** (assuming capacities are integral and finite):

- The residual capacities are always integer valued
- The residual capacities out of node  $s$  decrease by at least one after each update.

**Correctness**

- If there is no augmenting path, then the flow must be maximum.
- max-flow min-cut theorem.

# Integrality

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Assume that all data are integral.

***Lemma:*** *At each iteration all residual capacities are integral.*

**Proof.** It is true at the beginning. Assume it is true after the first  $k-1$  augmentations, and consider augmentation  $k$  along path  $P$ .

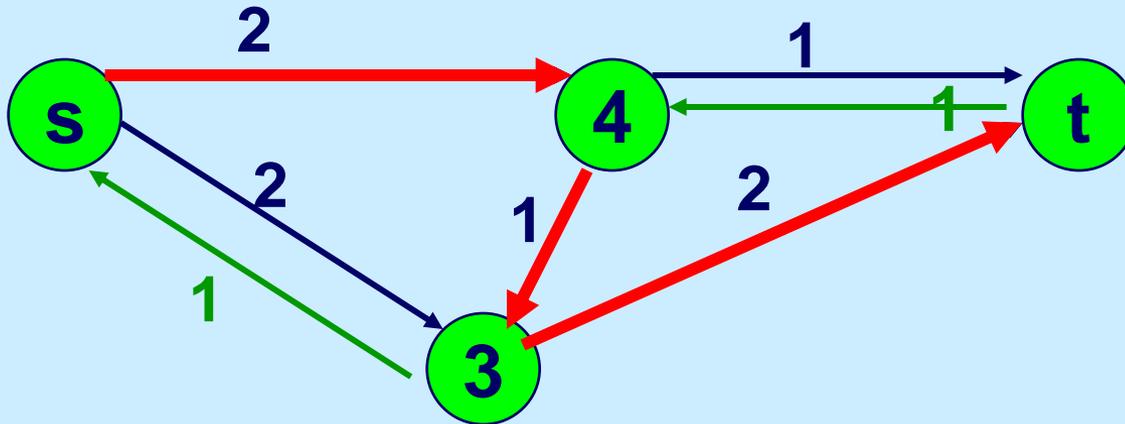
The residual capacity  $^{\text{TM}}$  of  $P$  is the smallest residual capacity on  $P$ , which is integral.

After updating, we modify residual capacities by 0, or  $^{\text{TM}}$ , and thus residual capacities stay integral.

# Theorem. The Ford-Fulkerson Algorithm is finite

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**Proof.** The capacity of each augmenting path is at least 1.



$r_{sj}$  decreases for some  $j$ .

So, the sum of the residual capacities of arcs out of  $s$  decreases at least 1 per iteration.

Number of augmentations is  $O(nU)$ , where  $U$  is the largest capacity in the network.

# Mental Break

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**What are aglets?**

**The plastic things on the ends of shoelaces.**

**How fast does the quartz crystal in a watch vibrate?**

**About 32,000 times per second.**

**If Barbie (the doll) were life size and 5' 9" tall, how big would her waist be?**

**18 inches. Incidentally, Barbie's full name is Barbara Millicent Roberts**

# Mental Break

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True or false. In Alaska it is illegal to shoot a moose from a helicopter or any other flying vehicle.

**True.**

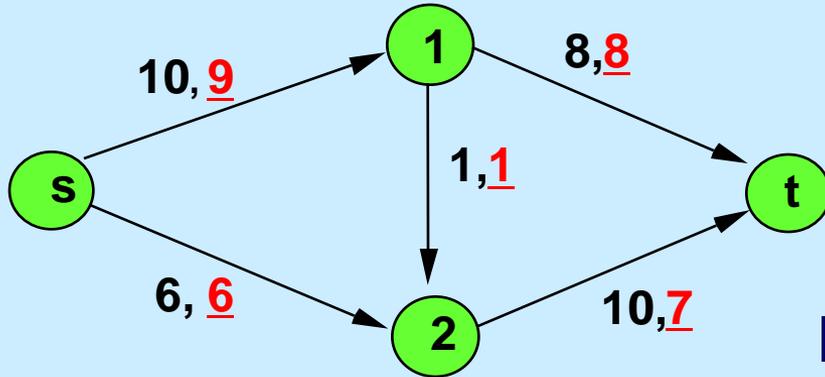
True or false. In Athens, Georgia, a driver's license can be taken away by law if the driver is deemed either "unbathed" or "poorly dressed."

**False. However, it is true for Athens, Greece.**

In Helsinki, Finland that don't give parking tickets to illegally parked cars. What do they do instead?

**They deflate the tires of the car.**

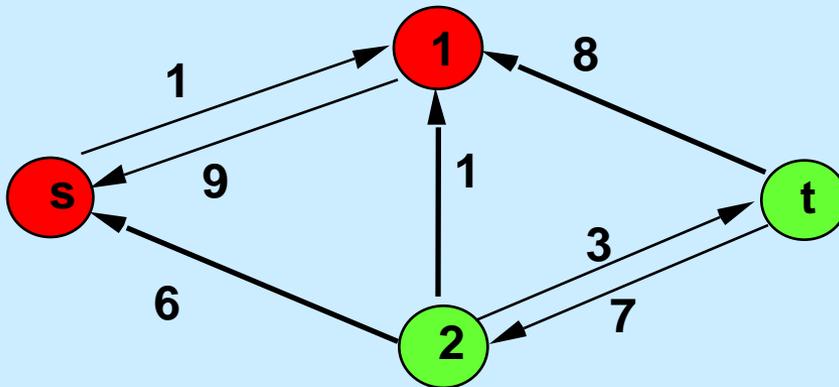
# To be proved: If there is no augmenting path, then the flow is maximum



$G(x)$  = residual network for flow  $x$ .

$x^*$  = final flow

If there is a directed path from  $i$  to  $j$  in  $G$ , we write  $i \rightarrow j$ .

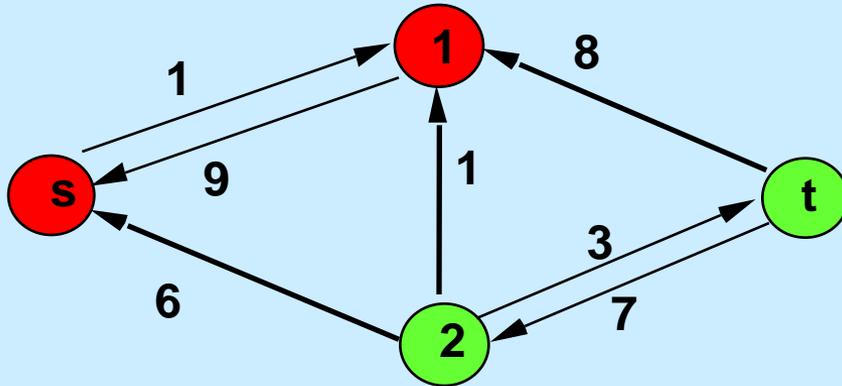


●  $S^* = \{j : s \rightarrow j \text{ in } G(x^*)\}$

●  $T^* = N \setminus S^*$

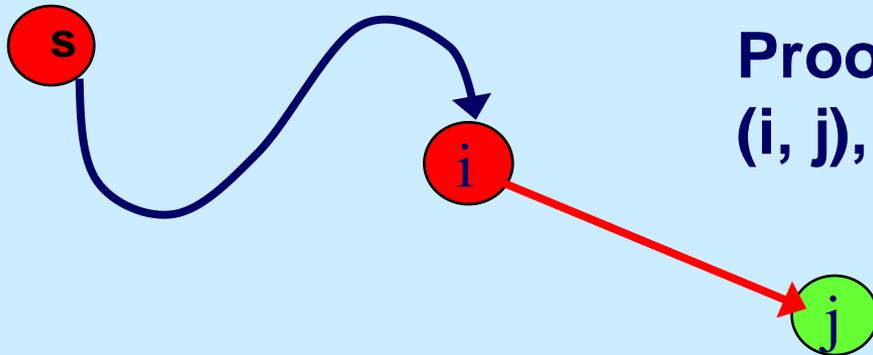
# Lemma: there is no arc in $G(x^*)$ from $S^*$ to $T^*$

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  $S^* = \{j : s \rightarrow j \text{ in } G(x^*)\}$

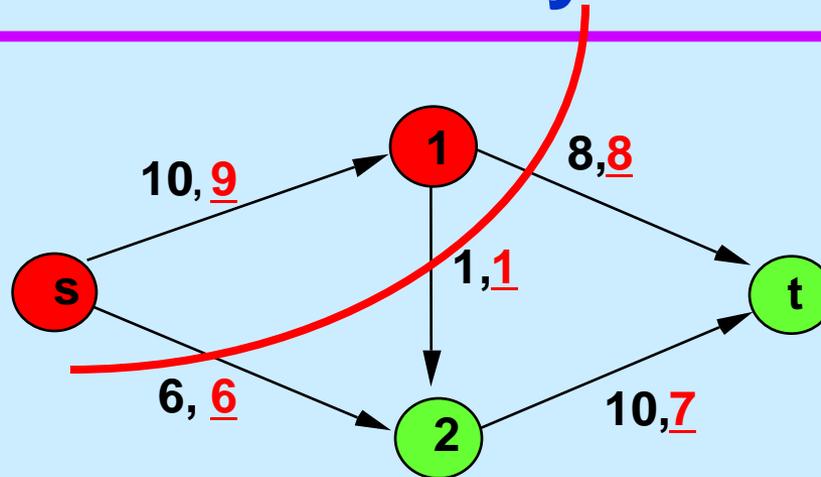
  $T^* = N \setminus S^*$



**Proof.** If there were such an arc  $(i, j)$ , then  $j$  would be in  $S^*$ .

**We will use this Lemma in 6 slides.**

# Cut Duality Theory



An  $(s,t)$ -cut in a network  $G = (N,A)$  is a partition of  $N$  into two disjoint subsets  $S$  and  $T$  such that  $s \in S$  and  $t \in T$ , e.g.,  $S = \{ s, 1 \}$  and  $T = \{ 2, t \}$ .

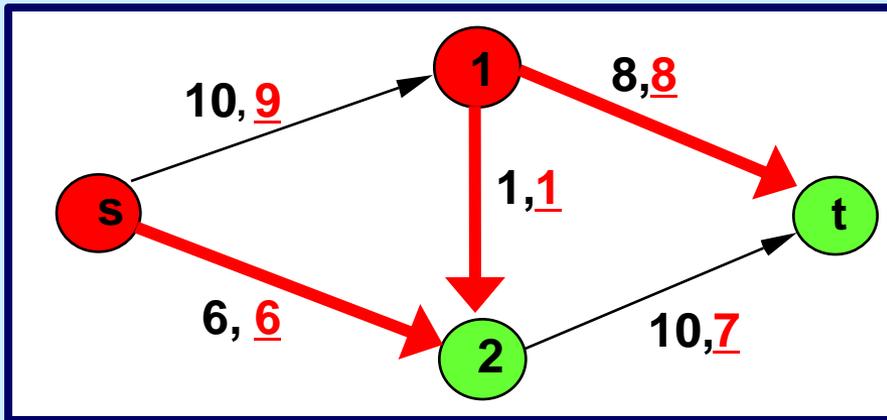
The **capacity** of a cut  $(S,T)$  is

$$\text{CAP}(S,T) = \sum_{i \in S} \sum_{j \in T} u_{ij}$$

# The flow across a cut

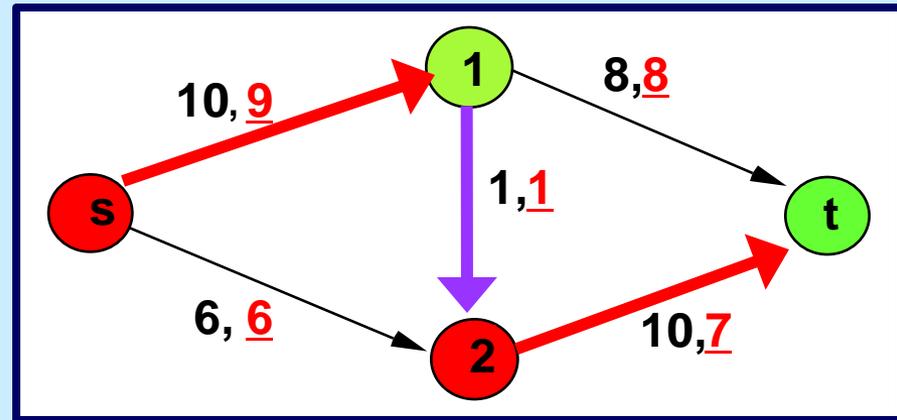
We define the *flow across the cut*  $(S,T)$  to be

$$F_x(S,T) = \sum_{i \in S} \sum_{j \in T} x_{ij} - \sum_{i \in S} \sum_{j \in T} x_{ji}$$



If  $S = \{s, 1\}$ , then

$$F_x(S,T) = 6 + 1 + 8 = 15$$



If  $S = \{s, 2\}$ , then

$$F_x(S,T) = 9 - 1 + 7 = 15$$

# Max Flow Min Cut

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**Theorem.** (Max-flow Min-Cut). *The maximum flow value is the minimum value of a cut.*

**Proof.** The proof will rely on the following three lemmas:

**Lemma 1.** For any flow  $x$ , and for any  $s$ - $t$  cut  $(S, T)$ , the flow out of  $s$  equals  $F_x(S, T)$ .

**Lemma 2.** For any flow  $x$ , and for any  $s$ - $t$  cut  $(S, T)$ ,  $F_x(S, T) \leq \text{CAP}(S, T)$ .

**Lemma 3.** Suppose that  $x^*$  is a feasible  $s$ - $t$  flow with no augmenting path. Let  $S^* = \{j : s \rightarrow j \text{ in } G(x^*)\}$  and let  $T^* = N \setminus S^*$ . Then  $F_{x^*}(S^*, T^*) = \text{CAP}(S^*, T^*)$ .

# Proof of Theorem (using the 3 lemmas)

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Let  $x'$  be a maximum flow

Let  $v'$  be the maximum flow value

Let  $x^*$  be the final flow.

Let  $v^*$  be the flow out of node  $s$  (for  $x^*$ )

Let  $S^*$  be nodes reachable in  $G(x^*)$  from  $s$ .

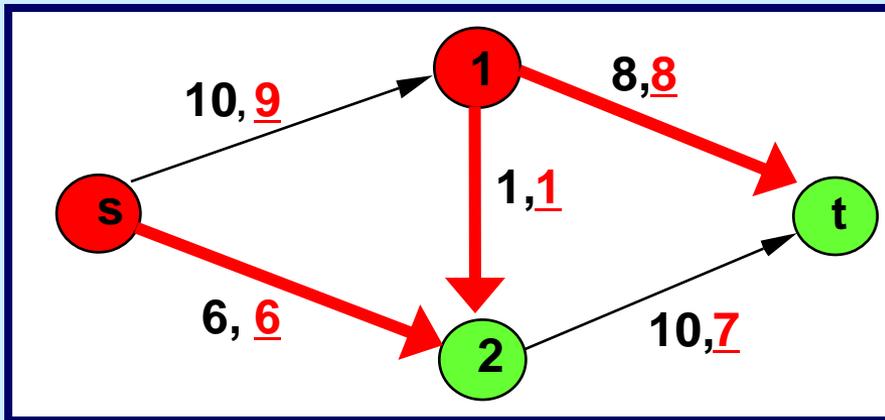
Let  $T^* = N \setminus S^*$ .

1.  $v^* \leq v'$  by definition of  $v'$
2.  $v' = F_{x'}(S^*, T^*)$  by Lemma 1.
3.  $F_{x'}(S^*, T^*) \leq \text{CAP}(S^*, T^*)$  by Lemma 2.
4.  $v^* = F_{x^*}(S^*, T^*) = \text{CAP}(S^*, T^*)$  by Lemmas 1,3.

Thus all inequalities are equalities and  $v^* = v'$ .

# Proof of Lemma 1

**Proof.** Add the conservation of flow constraints for each node  $i \in S - \{s\}$  to the constraint that the flow leaving  $s$  is  $v$ . The resulting equality is  $F_x(S,T) = v$ .

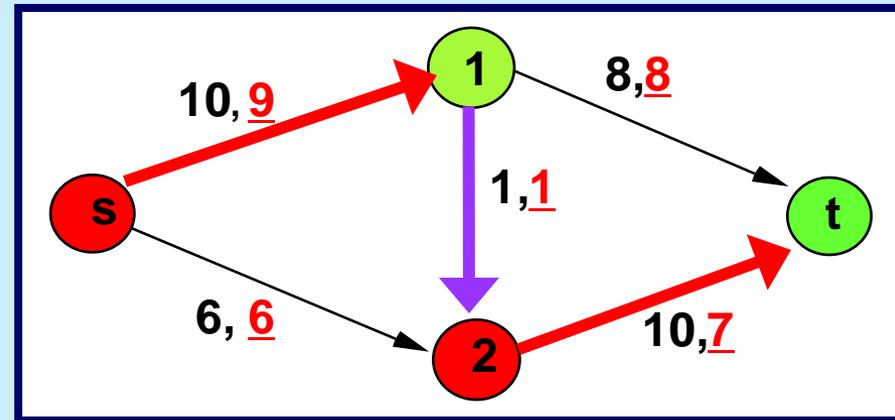


$$x_{s1} + x_{s2} = v$$

$$x_{12} + x_{1t} - x_{s1} = 0$$

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$$x_{s2} + x_{12} + x_{1t} = v$$



$$x_{s1} + x_{s2} = v$$

$$x_{2t} - x_{s2} - x_{12} = 0$$

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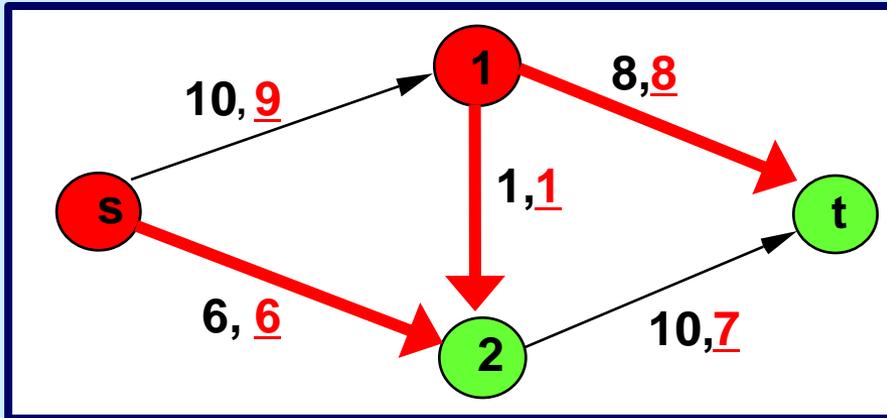

$$x_{s1} - x_{12} + x_{2t} = v$$

# Proof of Lemma 2

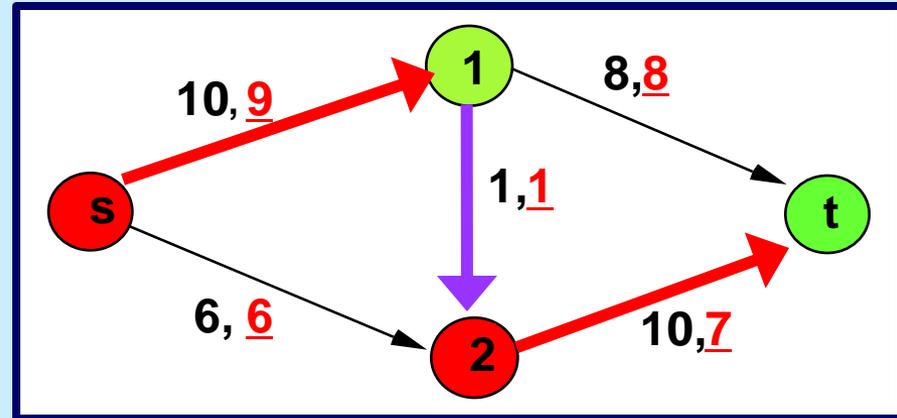
**Proof.** If  $i \in S$ , and  $j \in T$ , then  $x_{ij} \leq u_{ij}$ . If  $i \in T$ , and  $j \in S$ , then  $x_{ij} \geq 0$ .

$$F_x(S, T) = \sum_{i \in S} \sum_{j \in T} x_{ij} - \sum_{i \in S} \sum_{j \in T} x_{ji}$$

$$CAP(S, T) = \sum_{i \in S} \sum_{j \in T} u_{ij} - \sum_{i \in S} \sum_{j \in T} 0$$



$CAP(S, T) = 15$



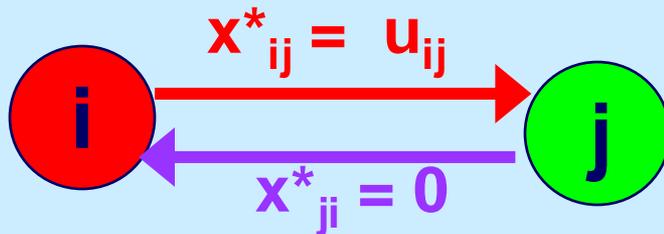
$CAP(S, T) = 16$

# Proof of Lemma 3.

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We have already seen that there is no arc from  $S^*$  to  $T^*$  in  $G(x^*)$ .

$$i \in S^* \text{ and } j \in T^* \Rightarrow x^*_{ij} = u_{ij} \text{ and } x^*_{ji} = 0$$



Otherwise, there is an arc  $(i, j)$  in  $G(x^*)$

Therefore  $F_{x^*}(S^*, T^*) = \text{CAP}(S^*, T^*)$

# Review

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**Corollary.** If the capacities are finite integers, then the Ford-Fulkerson Augmenting Path Algorithm terminates in finite time with a maximum flow from  $s$  to  $t$ .

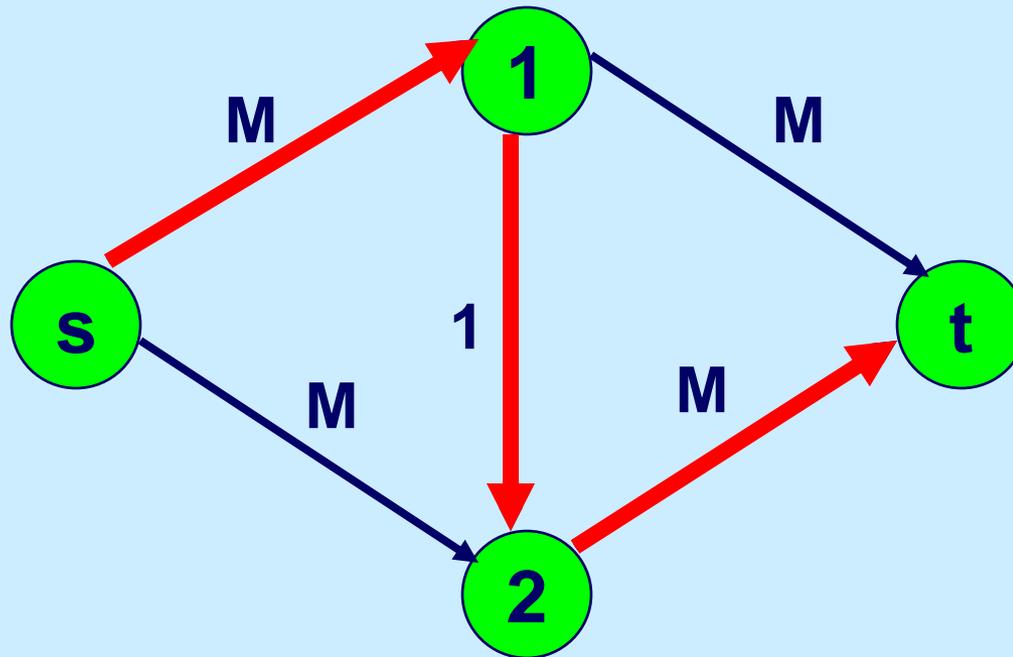
**Corollary.** If the capacities are finite rational numbers, then the Ford-Fulkerson Augmenting Path Algorithm terminates in finite time with a maximum flow from  $s$  to  $t$ .  
(why?)

**Corollary.** To obtain a minimum cut from a maximum flow  $x^*$ , let  $S^*$  denote all nodes reachable from  $s$  in  $G(x)$ , and  $T^* = N \setminus S^*$

**Remark.** This does not establish finiteness if  $u_{ij} = \infty$  or if capacities may be irrational.

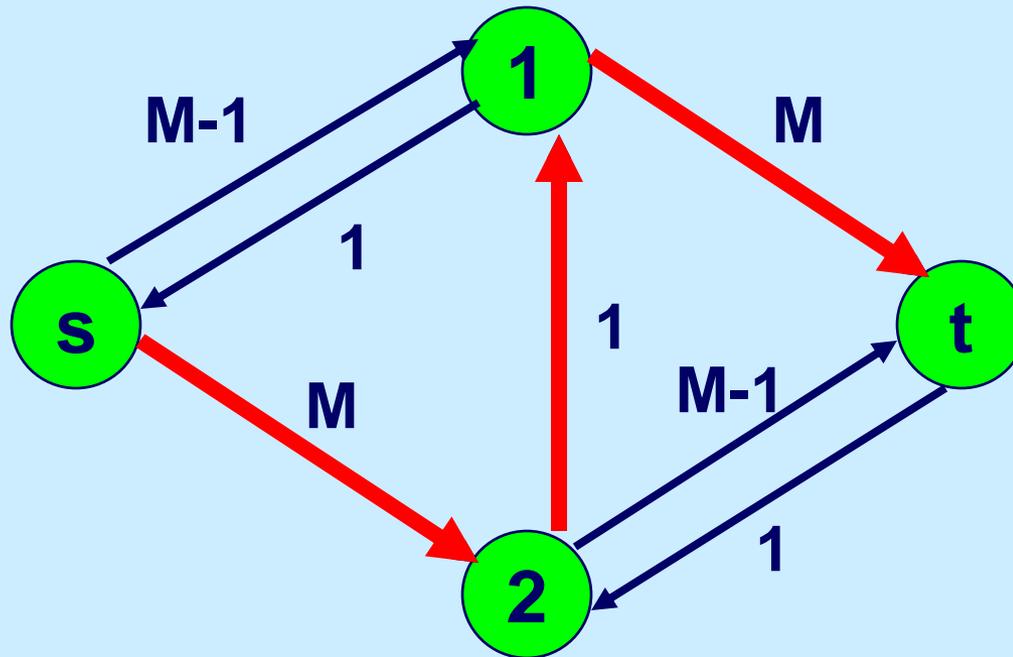
# A simple and very bad example

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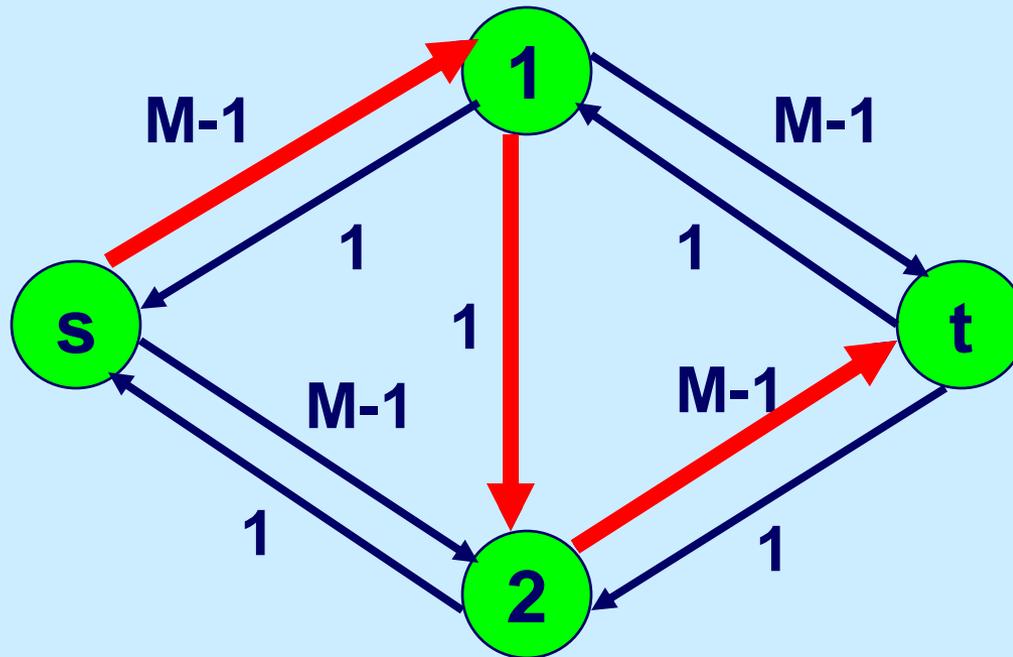
# After 1 augmentation

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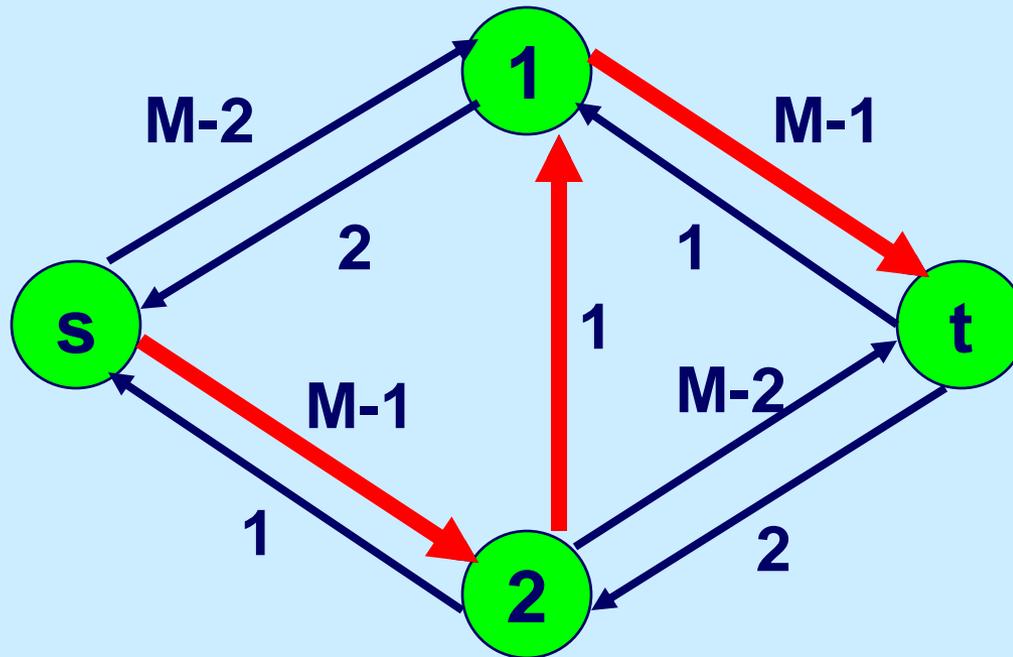
# After two augmentations

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# After 3 augmentations

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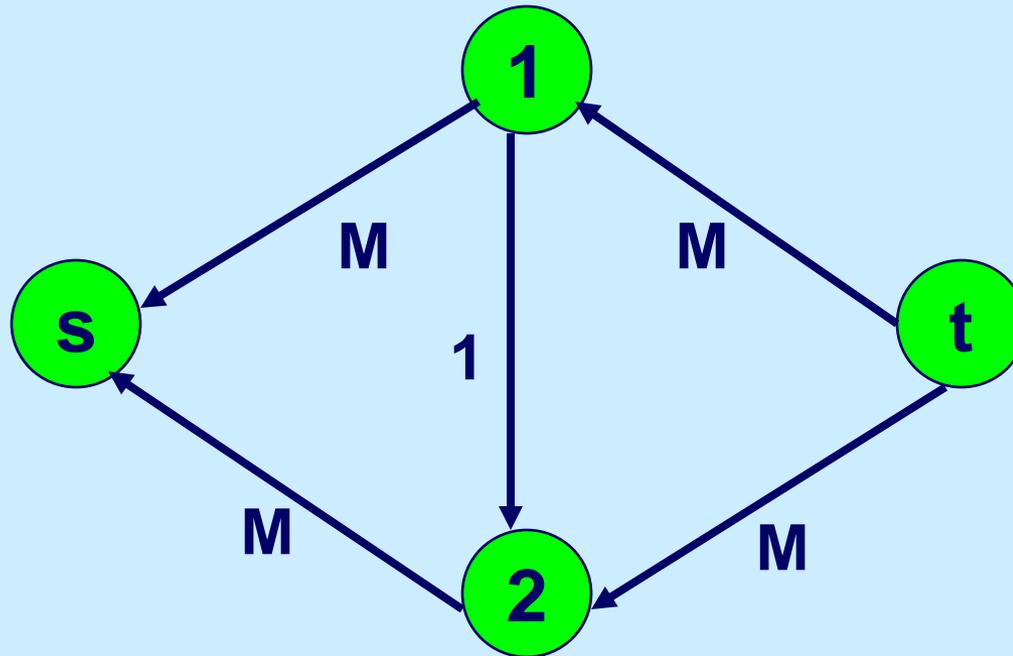
# And so on

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# After 2M augmentations

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# An even worse example

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**In Exercise 6.48, there is an example that takes an infinite number of augmentations on irrational data, and does not converge to the correct flow.**

**But we shall soon see how to solve max flows in a polynomial number of operations, even if data can be irrational.**

# Summary and Extensions

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1. Augmenting path theorem

2. Ford-Fulkerson Algorithm

3. Duality Theory.

4. Next Lecture:

- Polynomial time variants of FF algorithm
- Applications of Max-Flow Min-Cut

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