

## Alternative views on gradient sensing:

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- Postma and van Haastert. 'A diffusion-translocation model for gradient sensing by chemotactic cells.' *Biophys. J.* **81**, 1314 (2001).
- Levchenko and Iglesias. 'Models of eukaryotic gradient sensing: applications to chemotaxis of amoeba and neutrophils' *Biophys. J.* **82**, 50 (2002).

Main point: - how to prevent cells to polarize 'inreversibly'?

$$\frac{dm}{dt} = D_m \frac{\partial^2 m}{\partial x^2} - k_{-1}m + P$$

$D_m \sim 1 \mu\text{m}^2\text{s}^{-1}$   
 (membrane protein, lipid)  
 $D_m \sim 100 \mu\text{m}^2\text{s}^{-1}$   
 (cytosolic small molecule)

Images removed due to copyright considerations.  
 See Postma, M., and P. J. Van Haastert.  
 "A diffusion-translocation model for gradient sensing  
 by chemotactic cells." *Biophys J.* 81, no. 3 (Sep, 2001): 1314-23.

For a second messenger to establish and maintain a gradient the dispersion range  $\lambda$  should be smaller than cell size

$$\lambda = \sqrt{\frac{D_m}{k_{-1}}}$$

$$k_{-1} = 1\text{s}^{-1}$$

$$L = 10 \mu\text{m}$$

## Second messenger production in a gradient

$D_m \sim 1 \mu\text{m}^2\text{s}^{-1}$  (membrane protein, lipid)  
 $D_m \sim 100 \mu\text{m}^2\text{s}^{-1}$   
(cytosolic small molecule)

$$\frac{dm}{dt} = D_m \frac{\partial^2 m}{\partial x^2} - k_{-1} m + P(x)$$

$$P(x) = k_R \left( \bar{R}^* - \Delta R^* \frac{x}{r} \right)$$

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Diffusion flattens internal  
gradient

Gain is  $< 1$  (the larger  
 $D_m$  the smaller the gain)

How to amplify ?

# Amplification by positive feedback

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- A.** Before receptor stimulation only a small number of effectors (inactive) bound to membrane
- B.** After receptor stimulation, membrane bound effectors will be stimulated to produce more phospholipid second messengers
- C.** Local phospholipid increase leads to increased translocation of effector molecules
- D.** receptor can signal to more effectors leading to even more phospholipid production and further depletion of cytosolic effector molecules.

$$\frac{dm}{dt} = D_m \frac{\partial^2 m}{\partial x^2} - k_{-1}m + P(x)$$

$$P(x) = k_o + k_E R^*(x) E_m(x)$$

$E_m$ : effector concentration in membrane

$E_c$ : effector concentration in cytosol.

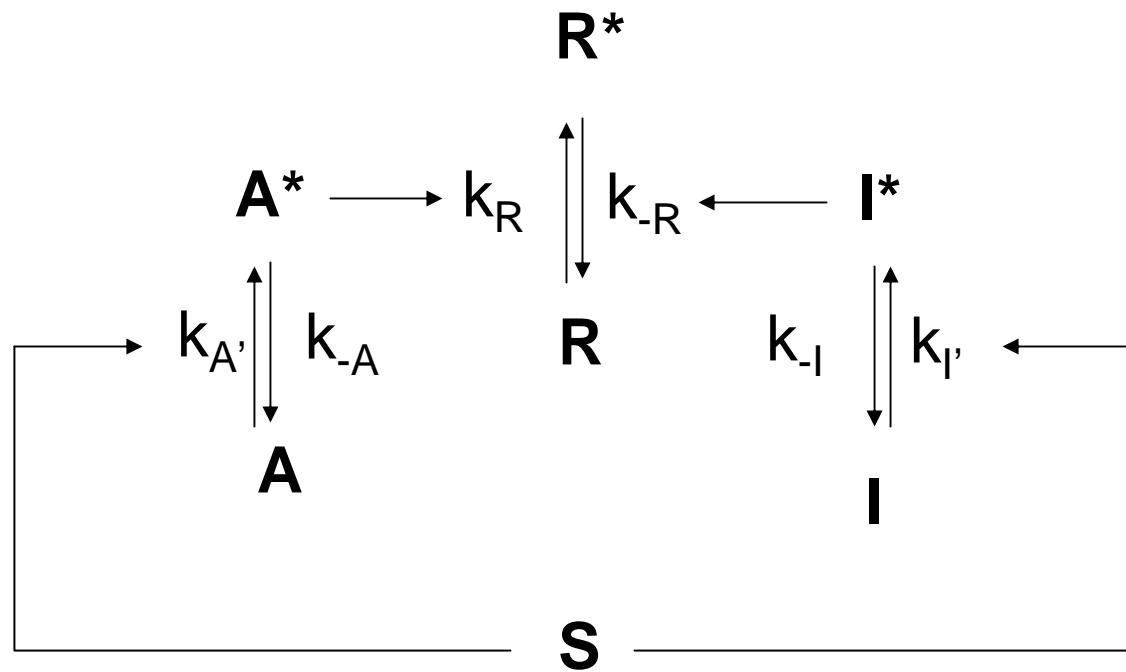
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81, no. 3 (Sep, 2001): 1314-23.

# Molecules ??

Image removed due to copyright considerations. See Levchenko, A., and P. A. Iglesias.  
"Models of eukaryotic gradient sensing: application to chemotaxis of amoebae and neutrophils."  
*Biophys J.* 82 (1 Pt 1)(Jan 2002): 50-63.

receptor binding →  
G-protein activation →  
activation of PI3K (activator) →  
activation of PTEN (inhibitor) →  
P3 ~ R\* (binding PH domains)

# Perfect adaptation module:



$$\frac{dR^*}{dt} = -k_{-R} I^* R^* + k_R A^* R$$

$$\frac{dA^*}{dt} = -k_{-A} A^* + \dot{k}_A S A = -k_{-A} A^* + \dot{k}_A S (A_{tot} - A^*)$$

$$\frac{dI^*}{dt} = -k_{-I} I^* + \dot{k}_I S I = -k_{-I} I^* + \dot{k}_I S (I_{tot} - I^*)$$

Main assumption:  $k_{-A} & k_{-I} \gg \dot{k}_A & \dot{k}_I$  ( $A_{tot} \gg A^*$ ,  $I_{tot} \gg I^*$ )

$$\frac{dR^*}{dt} = -k_{-R} I^* R^* + k_R A^* R$$

$$\frac{dA^*}{dt} = -k_{-A} A + \dot{k}_A S$$

$$\dot{k}_A = k_A A_{tot}$$

$$\frac{dI^*}{dt} = -k_{-I} I + \dot{k}_I S$$

$$\dot{k}_I = k_I I_{tot}$$

## Steady state:

$$A_{ss}^* = \frac{k_A}{k_{-A}} S$$

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$$I_{ss}^* = \frac{k_I}{k_{-I}} S$$

$$R_{ss}^* = \frac{k_R A_{ss}^* / I_{ss}^*}{k_R A_{ss}^* / I_{ss}^* + k_{-R}}$$

for the rest of the calculations

ignore '\*' for I and A !

Now introduce diffusion:

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- only I diffuses, other components are local

$$\frac{\partial I(x,t)}{\partial t} = -k_{-I} I(x,t) + k_I S(x,t) + D \frac{\partial^2 I(x,t)}{\partial x^2}$$

- assume signal S varies linearly with S

$$S(x) = s_o + s_1 x$$

- no flux boundary conditions for I

$$\frac{\partial I(0,t)}{\partial x} = \frac{\partial I(1,t)}{\partial x} = 0$$

in steady state, this system can be solved analytically !

$$\frac{\partial I(x,t)}{\partial t} = -k_{-I} I(x,t) + k_I S(x,t) + D \frac{\partial^2 I(x,t)}{\partial x^2}$$

$$\frac{\partial^2 I(x)}{\partial x^2} = \frac{k_{-I}}{D} I(x) - \frac{k_I}{D} [s_o + s_1 x]$$

steady-state:

$$\frac{\partial^2 I(x)}{\partial x^2} = aI(x) - b - cx$$

MATLAB can solve this for you:

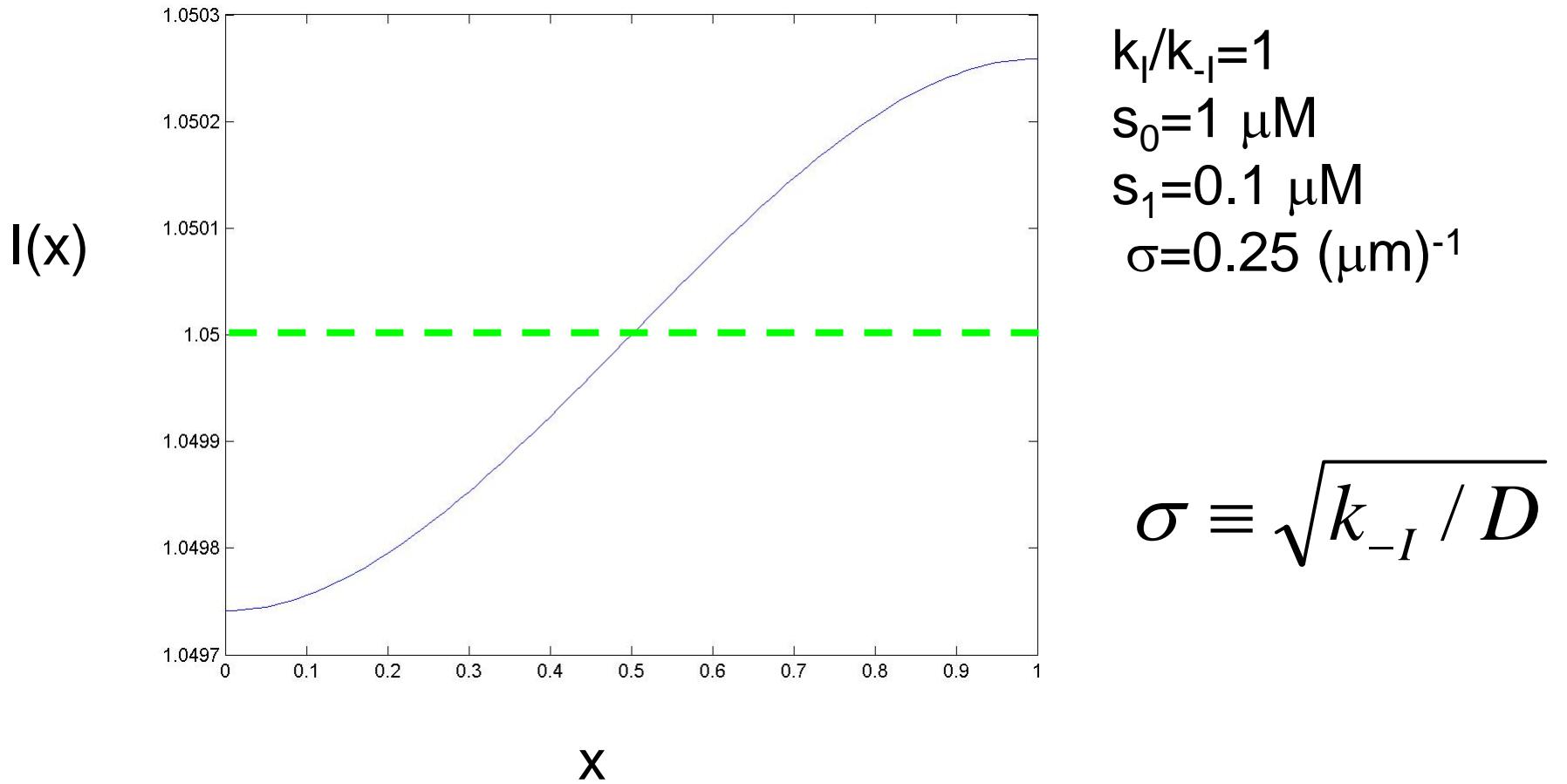
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```
>> dsolve('D2x=a*x-b-c*t', 'Dx(0)=0, Dx(1)=0')
```

ans =

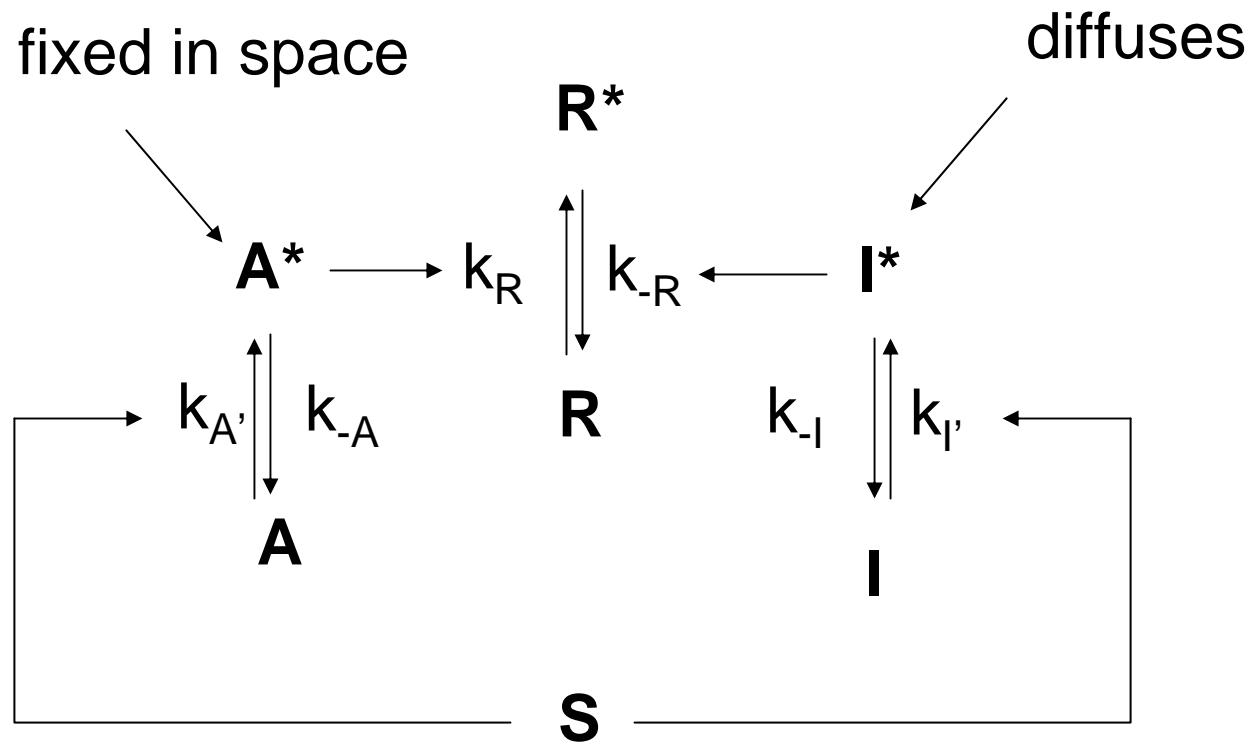
```
(b+c*t)/a+c*(-1+cosh(a^(1/2)))/a^(3/2)/sinh(a^(1/2))*cosh(a^(1/2)*t)
-c/a^(3/2)*sinh(a^(1/2)*t)
```

$$I(x) = \frac{k_I}{k_{-I}} \left( s_o + s_1 \left( x - \frac{\sinh \sigma x}{\sigma} + \frac{\cosh \sigma x}{\sigma} \frac{\cosh \sigma - 1}{\sinh \sigma} \right) \right)$$



Remember: Perfect adaptation module:

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Steady state:

$$A_{ss}^* = \frac{k_A}{k_{-A}} S$$

$$I_{ss}^* = \frac{k_I}{k_{-I}} S$$

$$R_{ss}^* = \frac{k_R A_{ss}^* / I_{ss}^*}{k_R A_{ss}^* / I_{ss}^* + k_{-R}}$$

independent of  $S$ ,  
perfect adaptation

$A$  does not diffuse, so

$A(x)$  directly reflects  $S(x)$

For finding  $R^*$  only the ratio  $A/I$  is important

$$A(x) = \frac{k_A}{k_{-A}} (s_o + s_1 x)$$

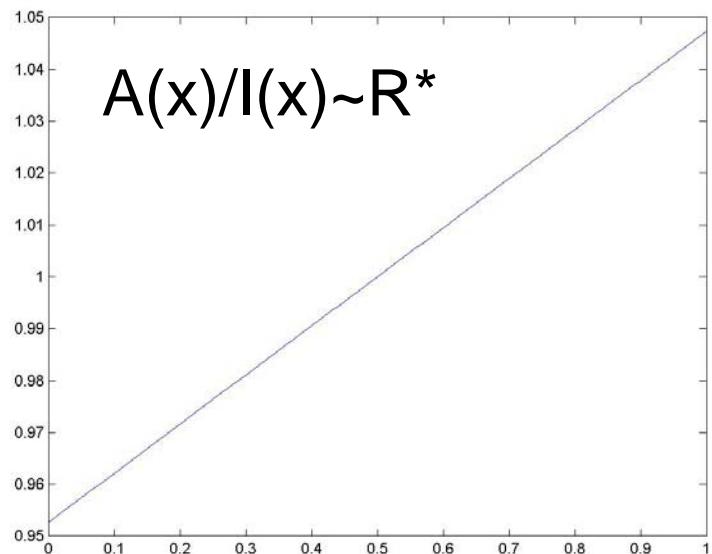
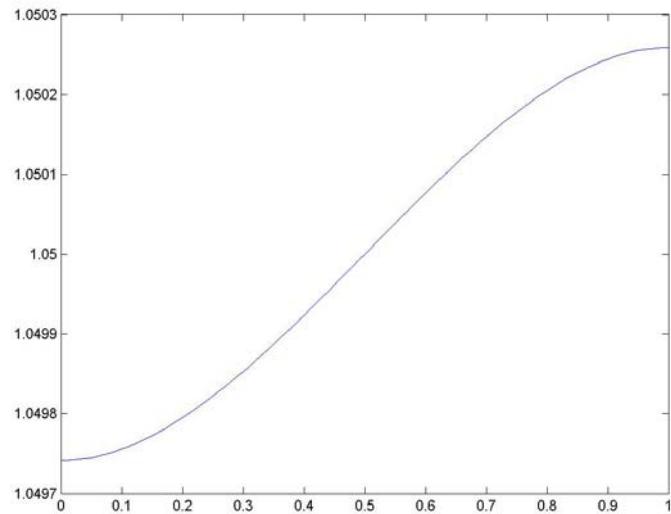
$$I(x) = \frac{k_I}{k_{-I}} \left( s_o + s_1 \left( x - \frac{\sinh \sigma x}{\sigma} + \frac{\cosh \sigma x}{\sigma} \frac{\cosh \sigma - 1}{\sinh \sigma} \right) \right)$$

$$\frac{A(x)}{I(x)} = \frac{k_A k_{-I}}{k_{-A} k_I} \left( 1 + \frac{s_1}{s_o + s_1 x} \left( \frac{\cosh \sigma x}{\sigma} \frac{\cosh \sigma - 1}{\sinh \sigma} - \frac{\sinh \sigma x}{\sigma} \right) \right)^{-1}$$

small  $\sigma \equiv \sqrt{k_{-I} / D} \sim 0.4$

well mixed, A/I directly reflects signal

$I(x)$



$x$

$$I(x) = I(\bar{S}) = \text{const}$$

$x$

$$A(x) = A(S)$$

$$R^*(x) = A(S) / I(\bar{S})$$