

## Summary of last lecture:

### (Assumptions leading to this?)

- We're done! The Lorentz transformation is

$$\Lambda(\mathbf{v}) = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix},$$

*i.e.,*

$$\begin{pmatrix} x' \\ y' \\ z' \\ ct' \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ ct \end{pmatrix} = \begin{pmatrix} \gamma(x - \beta ct) \\ y \\ z \\ \gamma(ct - \beta x) \end{pmatrix}.$$

- Compare to Einstein's 1905 paper

# MIT Course 8.033, Fall 2006, Lecture 5

Max Tegmark

## Today: Relativistic Kinematics

- Time dilation
- Length contraction
- Relativity of simultaneity
- Proper time, rest length
- **Key people:** Einstein

IS IT RIGHT?

# Implications: time dilation

- In the frame  $S$ , a clock is at rest at the origin ticking at time intervals that are  $\Delta t = 1$  seconds long, so the two consecutive ticks at  $t = 0$  and  $t = \Delta t$  have coordinates

$$\mathbf{x}_1 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ c\Delta t \end{pmatrix}.$$

- In the frame  $S'$ , the coordinates are

$$\mathbf{x}'_1 = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix},$$
$$\mathbf{x}'_2 = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ c\Delta t \end{pmatrix} = \begin{pmatrix} -\gamma v\Delta t \\ 0 \\ 0 \\ \gamma c\Delta t \end{pmatrix}$$

- So in  $S'$ , the clock appears to tick at intervals  $\Delta t' = \gamma\Delta t > \Delta t$ , *i.e.*, slower! (Draw Minkowski diagram.)

## Time dilation, cont'd

- The light clock movie says it all:  
*[http : //www.anu.edu.au/Physics/qt/](http://www.anu.edu.au/Physics/qt/)*

## Time dilation, cont'd

- The light clock movie says it all:  
*[http : //www.anu.edu.au/Physics/qt/](http://www.anu.edu.au/Physics/qt/)*
- Cosmic ray muon puzzle
  - Created about 10km above ground
  - Half life  $1.56 \times 10^{-6}$  second
  - In this time, light travels 0.47 km
  - So how can they reach the ground?
  - $v \approx 0.99c$  gives  $\gamma \approx 7$
  - $v \approx 0.9999c$  gives  $\gamma \approx 71$
- Leads to twin paradox

Consider two frames in relative motion. For  $t = 0$ , the Lorentz transformation gives  $x' = \gamma x$ , where  $\gamma > 1$ .

**Question:** How long does a yard stick at rest in the unprimed frame look in the primed frame?

1. Longer than one yard
2. Shorter than one yard
3. One yard

**Let's measure the  
length of our  
moving eraser!**

# Implications: relativity of simultaneity

- Consider two events simultaneous in frame  $S$ :

$$\mathbf{x}_1 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} L \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

- In the frame  $S'$ , they are

$$\begin{aligned} \mathbf{x}'_1 &= \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \\ \mathbf{x}'_2 &= \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} L \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \gamma L \\ 0 \\ 0 \\ -\gamma\beta L \end{pmatrix} \end{aligned}$$

- So in  $S'$ , the second event happened first!
- So  $S$ -clocks appear unsynchronized in  $S'$  - those with larger  $x$  run further ahead

## Transformation toolbox: the inverse Lorentz transform

- Since  $\mathbf{x}' = \Lambda(v)\mathbf{x}$  and  $\mathbf{x} = \Lambda(-v)\mathbf{x}'$ , we get the consistency requirement

$$\mathbf{x} = \Lambda(-v)\mathbf{x}' = \Lambda(-v)\Lambda(v)\mathbf{x}$$

for any event  $\mathbf{x}$ , so we must have  $\Lambda(-v) = \Lambda(v)^{-1}$ , the matrix inverse of  $\Lambda(v)$ .

- Is it?

$$\Lambda(-\mathbf{v})\Lambda(\mathbf{v}) = \begin{pmatrix} \gamma & 0 & 0 & \gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix},$$

*i.e.*, yes!

# Implications: length contraction

- Trickier than time dilation, opposite result (interval appears shorter, not longer)
- In the frame  $S$ , a yardstick of length  $L$  is at rest along the  $x$ -axis with its endpoints tracing out world lines with coordinates

$$\mathbf{x}_1 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ ct \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} L \\ 0 \\ 0 \\ ct \end{pmatrix}.$$

- In the frame  $S'$ , these world lines are

$$\begin{aligned} \mathbf{x}'_1 &= \begin{pmatrix} x'_1 \\ y'_1 \\ z'_1 \\ ct'_1 \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ ct \end{pmatrix} = \begin{pmatrix} -\gamma\beta ct \\ 0 \\ 0 \\ \gamma ct \end{pmatrix} \\ \mathbf{x}'_2 &= \begin{pmatrix} x'_2 \\ y'_2 \\ z'_2 \\ ct'_2 \end{pmatrix} = \begin{pmatrix} \gamma & 0 & 0 & -\gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma\beta & 0 & 0 & \gamma \end{pmatrix} \begin{pmatrix} L \\ 0 \\ 0 \\ ct \end{pmatrix} = \begin{pmatrix} \gamma L - \gamma\beta ct \\ 0 \\ 0 \\ \gamma ct - \gamma\beta L \end{pmatrix} \end{aligned}$$

- Let's work out the new world lines of the yard stick endpoints
- $x'_1 + \beta ct'_1 = 0$ , so left endpoint world line is

$$x'_1 = -vt'_1$$

- $x'_2 - \gamma L + \beta(ct'_2 + \gamma\beta L) = 0$ , so right endpoint world line is

$$x'_2 = \gamma L - \beta(ct'_2 + \gamma\beta L) = \frac{L}{\gamma} - vt'_2$$

- Length in  $S'$  is

$$x'_2 - x'_1 = \frac{L}{\gamma} + v(t'_1 - t'_2) = \frac{L}{\gamma}$$

since both endpoints measured at same time ( $t'_1 = t'_2$ )

- Draw Minkowski diagram of this

- An observer in  $S'$  measures length as  $x'_2 - x'_1$  at the same time  $t'$ ,  
- *not* at the same time  $t$ .
- Let's measure at  $t' = 0$ .
- $t'_1 = 0$  when  $t = 0$  — at this time,  $x'_1 = 0$
- $t'_2 = 0$  when  $ct = \beta L$  - at this time,  $x'_2 = \gamma L - \gamma\beta^2 L = L/\gamma$
- So in  $S'$ -frame, measured length is  $L' = L/\gamma$ , *i.e.*, *shorter*

# Transformation toolbox: velocity addition

SIMPLER  
WITH 2x2  
MATRICES

- If the frame  $S'$  has velocity  $v_1$  relative to  $S$  and the frame  $S''$  has velocity  $v_2$  relative to  $S'$  (both in the x-direction), then what is the speed  $v_3$  of  $S''$  relative to  $S$ ?
- $\mathbf{x}' = \Lambda(v_1)\mathbf{x}$  and  $\mathbf{x}'' = \Lambda(v_2)\mathbf{x}' = \Lambda(v_2)\Lambda(v_1)\mathbf{x}$ , so
- $\Lambda(\mathbf{v}_3) = \Lambda(v_2)\Lambda(v_1)$ , *i.e.*

$$\begin{aligned} \begin{pmatrix} \gamma_3 & 0 & 0 & -\gamma_3\beta_3 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma_3\beta_3 & 0 & 0 & \gamma_3 \end{pmatrix} &= \begin{pmatrix} \gamma_2 & 0 & 0 & -\gamma_2\beta_2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma_2\beta_2 & 0 & 0 & \gamma_2 \end{pmatrix} \begin{pmatrix} \gamma_1 & 0 & 0 & -\gamma_1\beta_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma_1\beta_1 & 0 & 0 & \gamma_1 \end{pmatrix} \\ &= \gamma_1\gamma_2 \begin{pmatrix} 1 + \beta_1\beta_2 & 0 & 0 & -[\beta_1 + \beta_2] \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -[\beta_1 + \beta_2] & 0 & 0 & 1 + \beta_1\beta_2 \end{pmatrix} \end{aligned}$$

- Take ratio between (1, 4) and (1, 1) elements:

$$\beta_3 = -\frac{\Lambda(v_3)_{41}}{\Lambda(v_3)_{11}} = \frac{\beta_1 + \beta_2}{1 + \beta_1\beta_2}.$$

- In other words,

$$v_3 = \frac{v_1 + v_2}{1 + \frac{v_1 v_2}{c^2}}.$$

# Transformation toolbox: perpendicular velocity addition

- Here's an alternative derivation of velocity addition that easily gives the non-parallel components too
- If the frame  $S'$  has velocity  $v$  in the  $x$ -direction relative to  $S$  and a particle has velocity  $\mathbf{u}' = (u'_x, u'_y, u'_z)$  in  $S'$ , then what is its velocity  $\mathbf{u}$  in  $S$ ?
- Applying the inverse Lorentz transformation

$$\begin{aligned}x &= \gamma(x' + vt') \\y &= y' \\z &= z' \\t &= \gamma(t' + vx'/c^2)\end{aligned}$$

to two nearby points on the particle's world line and subtracting gives

$$\begin{aligned}dx &= \gamma(dx' + vdt') \\dy &= dy' \\dz &= dz' \\dt &= \gamma(dt' + vdx'/c^2).\end{aligned}$$

$$\begin{aligned}
 dx &= \gamma(dx' + vdt') \\
 dy &= dy' \\
 dz &= dz' \\
 dt &= \gamma(dt' + vdx'/c^2).
 \end{aligned}$$

• Answer:

$$\begin{aligned}
 u_x &= \frac{dx}{dt} = \frac{\gamma(dx' + vdt')}{\gamma(dt' + \frac{vdx'}{c^2})} = \frac{\frac{dx'}{dt'} + v}{1 + \frac{v}{c^2} \frac{dx'}{dt'}} = \frac{u'_x + v}{1 + \frac{u'_x v}{c^2}} \\
 u_y &= \frac{dy}{dt} = \frac{dy'}{\gamma(dt' + \frac{vdx'}{c^2})} = \frac{\gamma^{-1} \frac{dy'}{dt'}}{1 + \frac{v}{c^2} \frac{dx'}{dt'}} = \frac{u'_y \sqrt{1 - \frac{v^2}{c^2}}}{1 + \frac{u'_x v}{c^2}} \\
 u_z &= \frac{dz}{dt} = \frac{dz'}{\gamma(dt' + \frac{vdx'}{c^2})} = \frac{\gamma^{-1} \frac{dz'}{dt'}}{1 + \frac{v}{c^2} \frac{dx'}{dt'}} = \frac{u'_z \sqrt{1 - \frac{v^2}{c^2}}}{1 + \frac{u'_x v}{c^2}}
 \end{aligned}$$

# Transformation toolbox: boosts as generalized rotations

- A “boost” is a Lorentz transformation with no rotation
- A rotation around the  $z$ -axis by angle  $\theta$  is given by the transformation

$$\begin{pmatrix} \cos \theta & \sin \theta & 0 & 0 \\ -\sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

- We can think of a boost in the  $x$ -direction as a rotation by an imaginary angle in the  $(x, ct)$ -plane:

$$\Lambda(-v) = \begin{pmatrix} \gamma & 0 & 0 & \gamma\beta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \gamma\beta & 0 & 0 & \gamma \end{pmatrix} = \begin{pmatrix} \cosh \eta & 0 & 0 & \sinh \eta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sinh \eta & 0 & 0 & \cosh \eta \end{pmatrix},$$

where  $\eta \equiv \tanh^{-1} \beta$  is called the *rapidity*.

- Proof: use hyperbolic trig identities on next page
- Implication: for multiple boosts in same direction, rapidities add and hence the order doesn't matter

# Hyperbolic trig reminders

$$\cosh x = \frac{e^x + e^{-x}}{2}$$

$$\sinh x = \frac{e^x - e^{-x}}{2}$$

$$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

$$\cosh^{-1} x = \ln(x + \sqrt{x^2 - 1})$$

$$\sinh^{-1} x = \ln(x + \sqrt{x^2 + 1})$$

$$\tanh^{-1} x = \frac{1}{2} \ln \left( \frac{1+x}{1-x} \right)$$

$$\cosh \tanh^{-1} x = \frac{1}{\sqrt{1-x^2}}$$

$$\sinh \tanh^{-1} x = \frac{x}{\sqrt{1-x^2}}$$

$$\cosh^2 x - \sinh^2 x = 1$$

# The Lorentz invariant

- The Minkowski metric

$$\eta = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

is left invariant by all Lorentz matrices  $\Lambda$ :

$$\Lambda^t \eta \Lambda = \eta$$

(indeed, this equation is often used to define the set of Lorentz matrices — for comparison,  $\Lambda^t \mathbf{I} \Lambda = \mathbf{I}$  would define rotation matrices)

- Proof: Show that works for boost along  $x$ -axis. Show that works for rotation along  $y$ -axis or  $z$ -axis. General case is equivalent to applying such transformations in succession.

- All Lorentz transforms leave the quantity

$$\mathbf{x}^t \boldsymbol{\eta} \mathbf{x} = x^2 + y^2 + z^2 - (ct)^2$$

invariant

- Proof:

$$\mathbf{x}'^t \boldsymbol{\eta} \mathbf{x}' = (\boldsymbol{\Lambda} \mathbf{x})^t \boldsymbol{\eta} (\boldsymbol{\Lambda} \mathbf{x}) = \mathbf{x}^t (\boldsymbol{\Lambda}^t \boldsymbol{\eta} \boldsymbol{\Lambda}) \mathbf{x} = \mathbf{x}^t \boldsymbol{\eta} \mathbf{x}$$

- (More generally, the same calculation shows that  $\mathbf{x}^t \boldsymbol{\eta} \mathbf{y}$  is invariant)
- So just as the usual Euclidean squared length  $|\mathbf{r}|^2 = \mathbf{r} \cdot \mathbf{r} = \mathbf{r}^t \mathbf{r} = \mathbf{r}^t \mathbf{I} \mathbf{r}$  of a 3-vector is rotationally invariant, the generalized “length”  $\mathbf{x}^t \boldsymbol{\eta} \mathbf{x}$  of a 4-vector is Lorentz-invariant.
- It can be positive or negative

- For events  $\mathbf{x}_1$  and  $\mathbf{x}_2$ , their Lorentz-invariant separation is defined as

$$\Delta s^2 \equiv \Delta \mathbf{x}^t \boldsymbol{\eta} \Delta \mathbf{x} = \Delta x^2 + \Delta y^2 + \Delta z^2 - (c\Delta t)^2$$

- A separation  $\Delta s^2 = 0$  is called *null*
- A separation  $\Delta s^2 > 0$  is called *spacelike*, and

$$\Delta \sigma \equiv \sqrt{\Delta s^2}$$

is called the *proper distance* (the distance measured in a frame where the events are simultaneous)

- A separation  $\Delta s^2 < 0$  is called *timelike*, and

$$\Delta \tau \equiv \sqrt{-\Delta s^2}$$

is called the *proper time interval* (the time interval measured in a frame where the events are at the same place)

## “Everything is relative” — or is it?

- All observers agree on rest length
- All observers agree on proper time
- All observers (as we’ll see later) agree on rest mass

## **Summary lecture:**

- Time dilation
- Length contraction
- Relativity of simultaneity
- Problem solving tips