

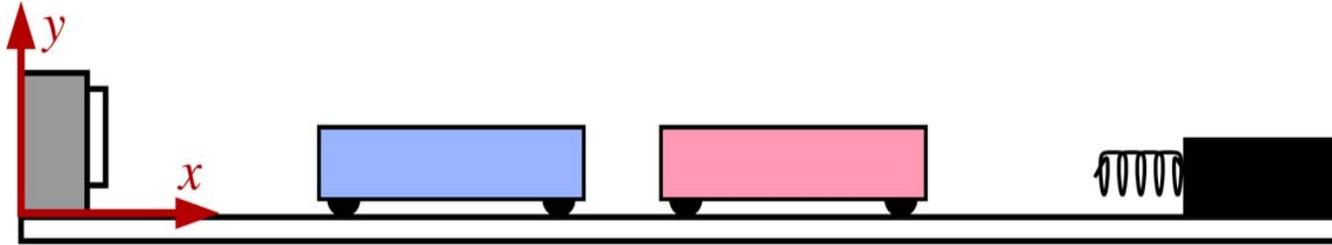
# Experiment 07: Momentum and Collisions



# Goals

- Investigate the **conservation of momentum** in **elastic and inelastic collisions**
- Investigate the **conservation of energy** in an **elastic collision**
- Investigate the amount of kinetic energy available for **non-conservative work** in an **inelastic collision**

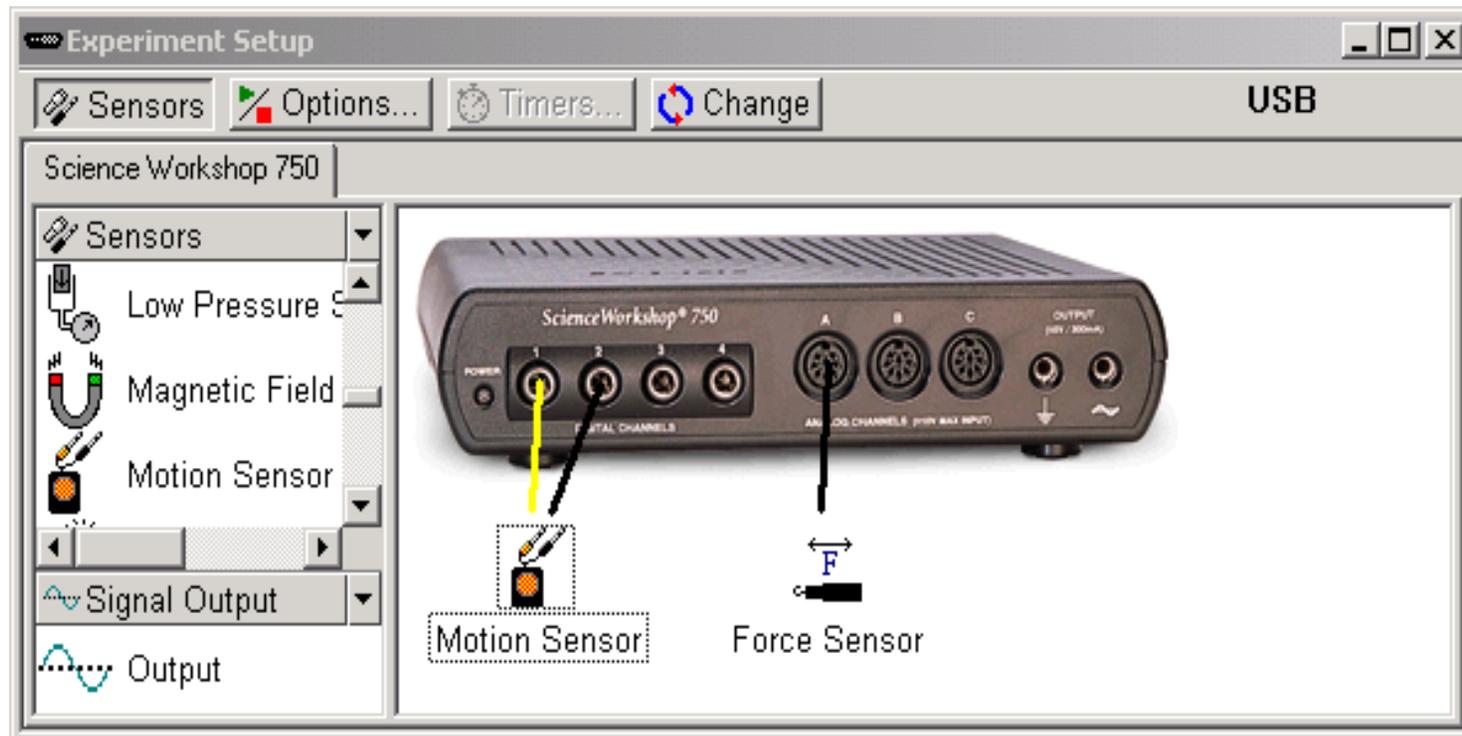
# Equipment setup



- Use the lighter spring on the force sensor.
- Clip the motion sensor to the end of the track.
- Level the track.
  
- Place **Target cart** at rest about **10cm from the spring**.
- Place **Incident cart** about **16-20cm from motion sensor**.
- Note: **Velcro facing = inelastic** and **magnets facing = elastic**.
- Roll incident cart just hard enough to come back to its starting point.  
**Practice this first before you take your data!**
- Make measurements with different weights of incident and target cart.

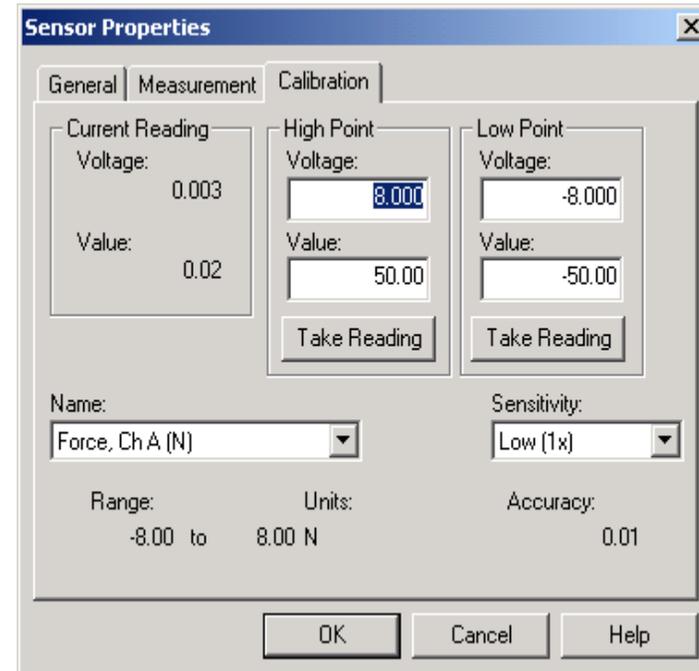
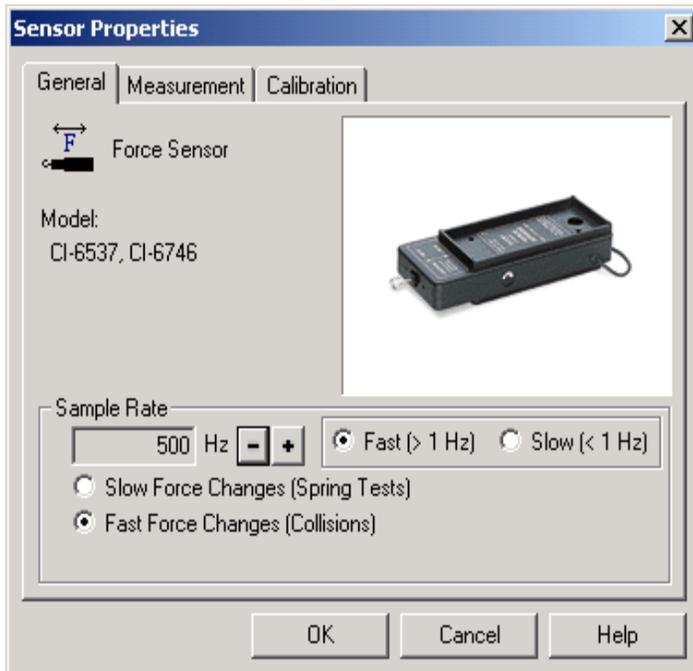
# Starting DataStudio

- ❑ Create a new experiment.
- ❑ Plug force and motion sensors into the 750 and
- ❑ drag their icons to inputs in the Setup window.



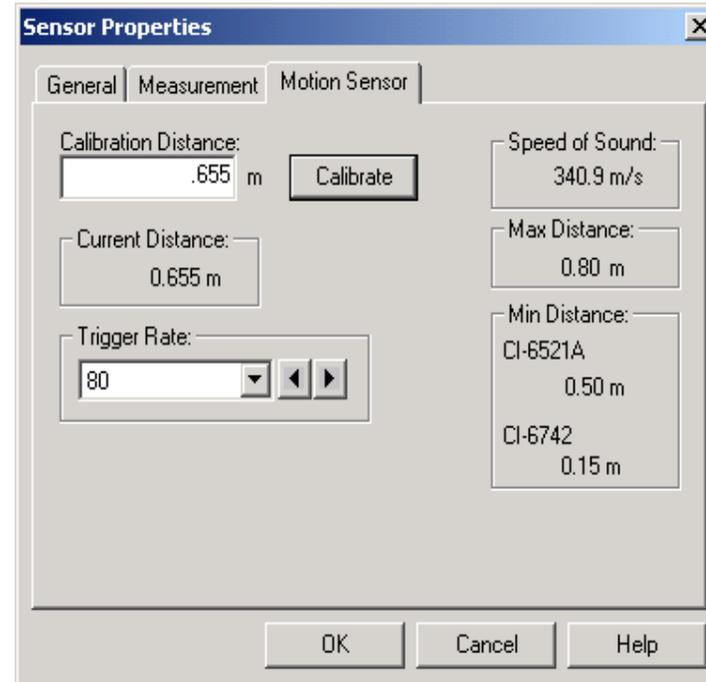
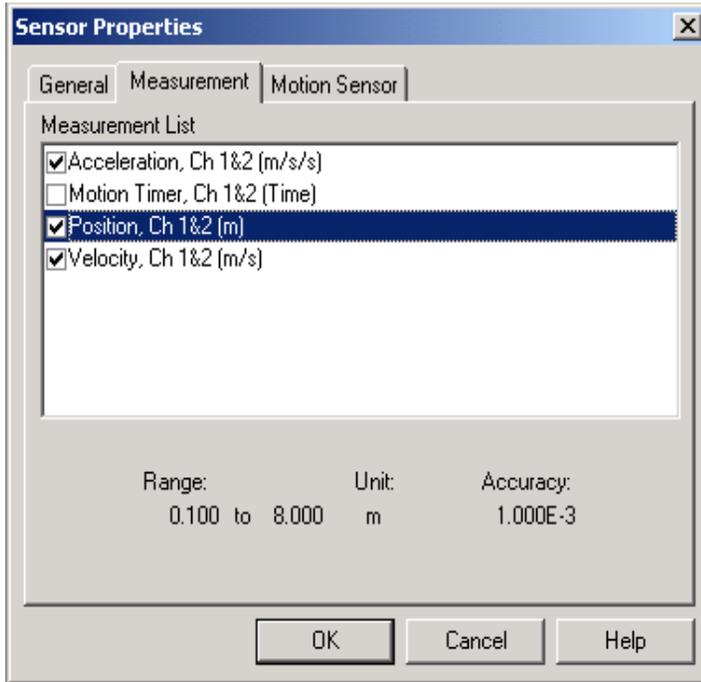
- ❑ Double-click the Force Sensor icon.

# Force Sensor



- ❑ Set Sample Rate to 500Hz and Sensitivity to Low.
- ❑ Double-click the Motion Sensor Icon.

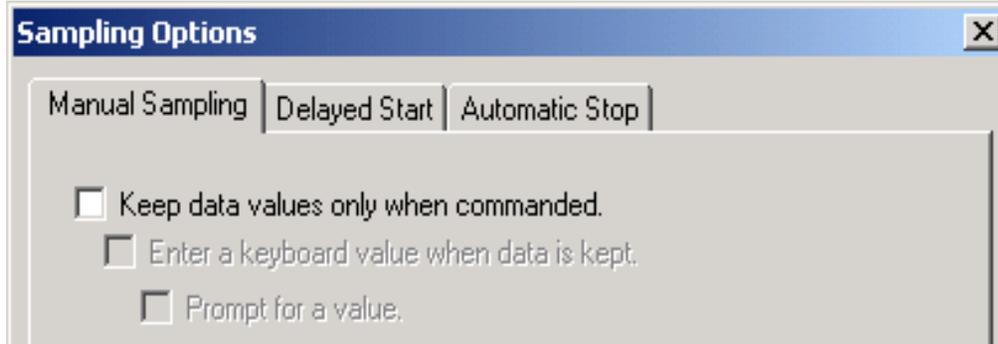
# Motion Sensor



- ❑ Ensure to have Acceleration, Position and Velocity checked
- ❑ Set Trigger Rate to 80Hz

Click  Options...

# Sampling Options



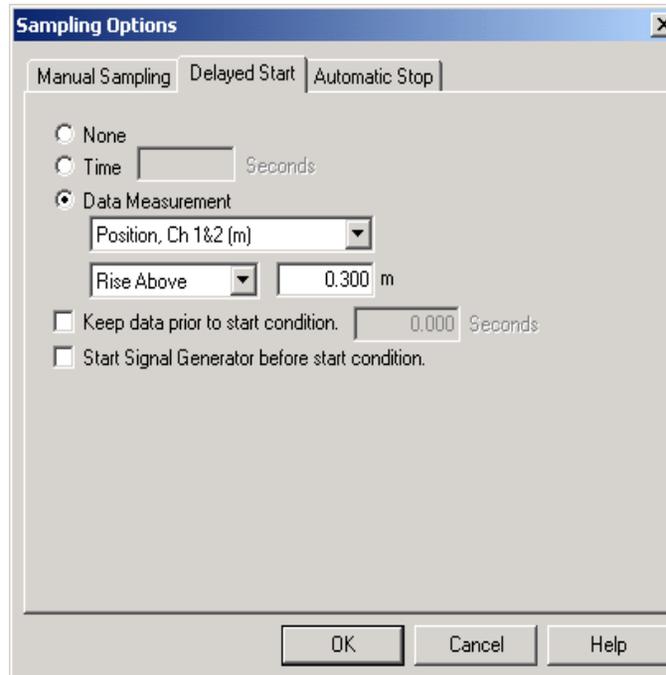
Sampling Options

Manual Sampling | Delayed Start | Automatic Stop

Keep data values only when commanded.  
 Enter a keyboard value when data is kept.  
 Prompt for a value.

No boxes checked!

Delayed  
Start and  
Automatic  
Stop!



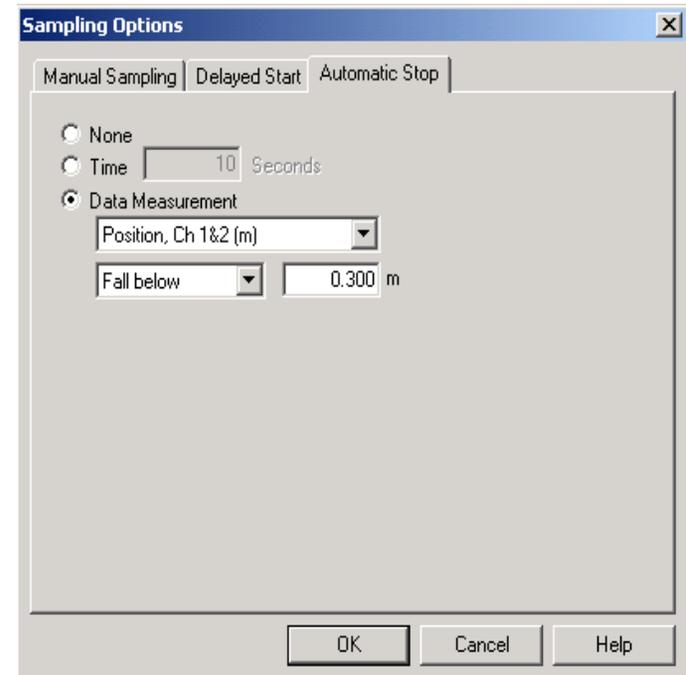
Sampling Options

Manual Sampling | Delayed Start | Automatic Stop

None  
 Time  Seconds  
 Data Measurement  
Position, Ch 1&2 (m)  
Rise Above  0.300 m  
 Keep data prior to start condition.  0.000 Seconds  
 Start Signal Generator before start condition.

OK Cancel Help

Position rises above  
0.3m.



Sampling Options

Manual Sampling | Delayed Start | Automatic Stop

None  
 Time  10 Seconds  
 Data Measurement  
Position, Ch 1&2 (m)  
Fall below  0.300 m

OK Cancel Help

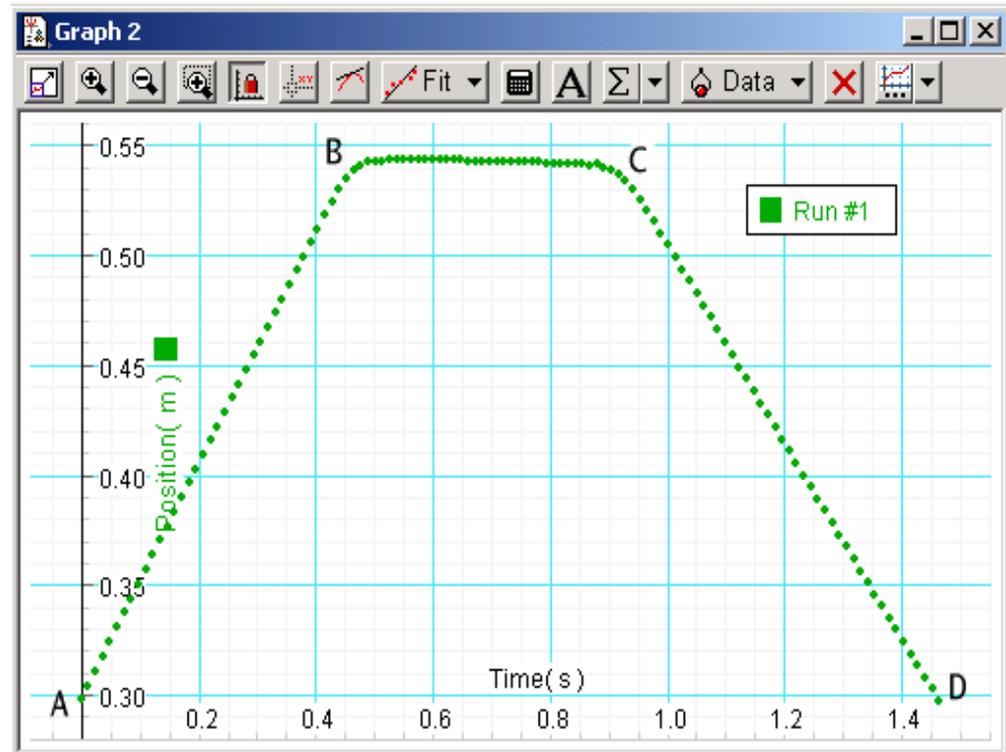
Position falls below  
0.3m.

# Graph 1

Two equal mass carts A and B collide.  
This is  $X_A$  vs. time.

What happens...:

1. Along line AB?
2. At point B?
3. Along line BC?
4. At point C?
5. Along line CD?



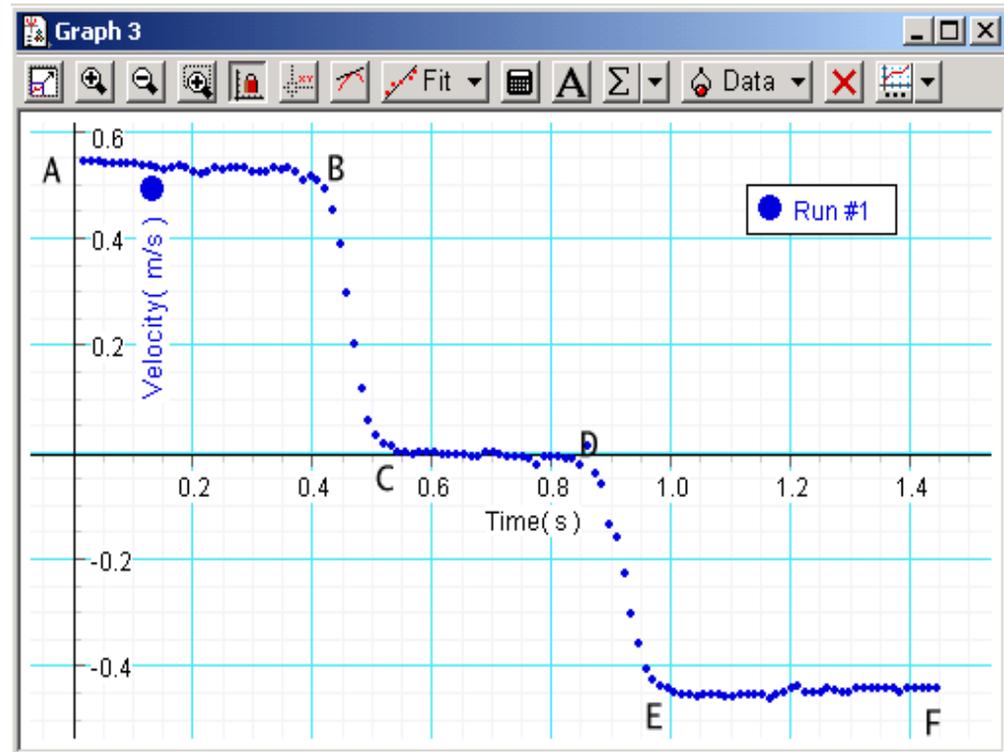
At approximately what time does cart B hit the spring?

# Graph 2

Two equal mass carts A and B collide.  
This is  $V_A$  vs. time.

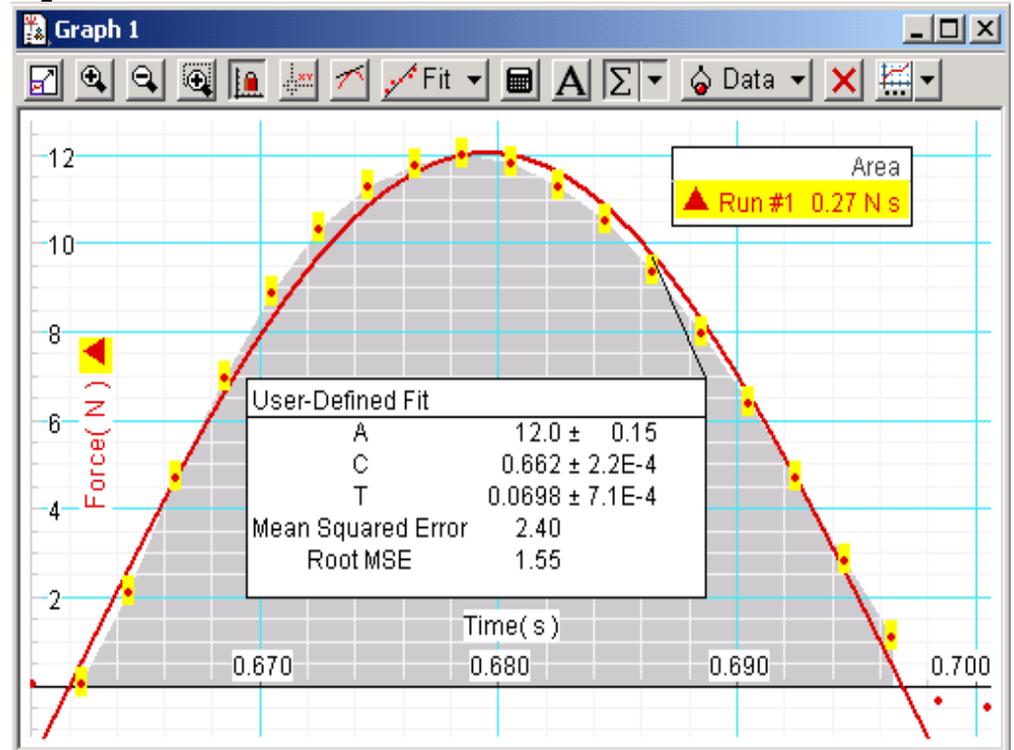
What happens...:

1. Along line AB?
2. Along line BC?
3. Along line CD?
4. Along line DE?
5. Along line EF?



# Graph 3

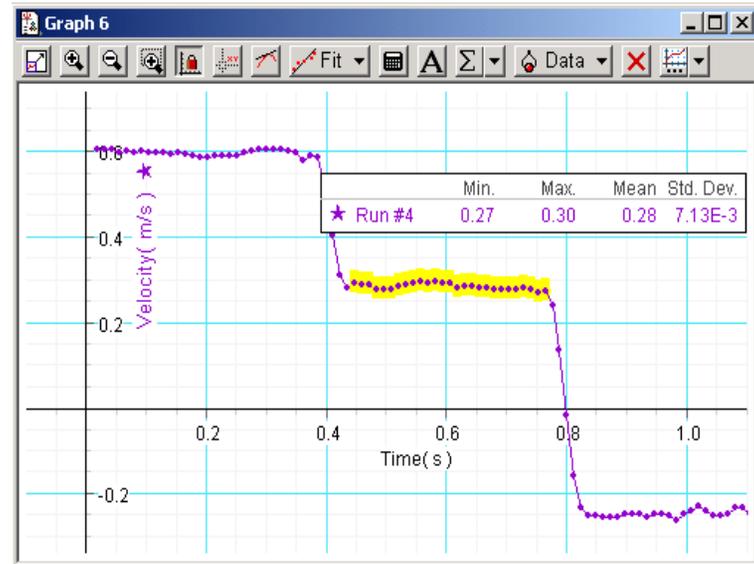
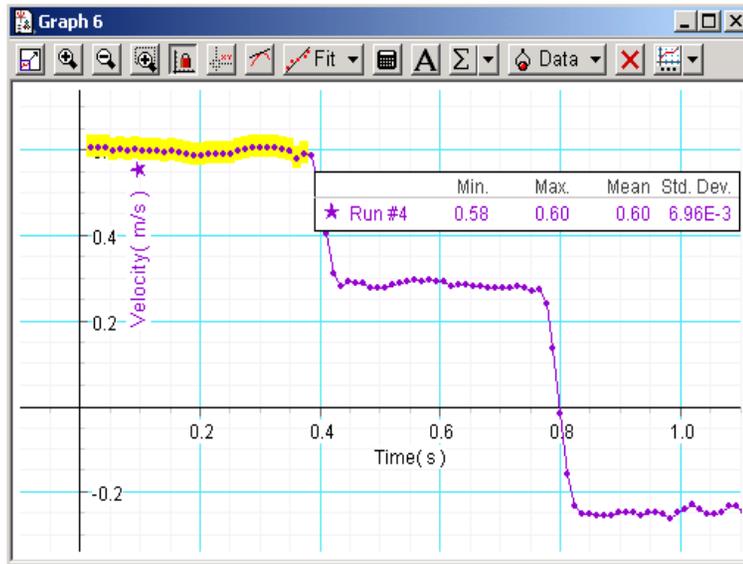
A cart of mass 0.25kg collides with a spring on the force sensor. Here is the force during the collision. The fit is to:  
 $A \cdot \sin(2\pi(x-C)/T)$



What does the area under the curve tell you?

What can you learn from the parameter T?

# Inelastic collisions

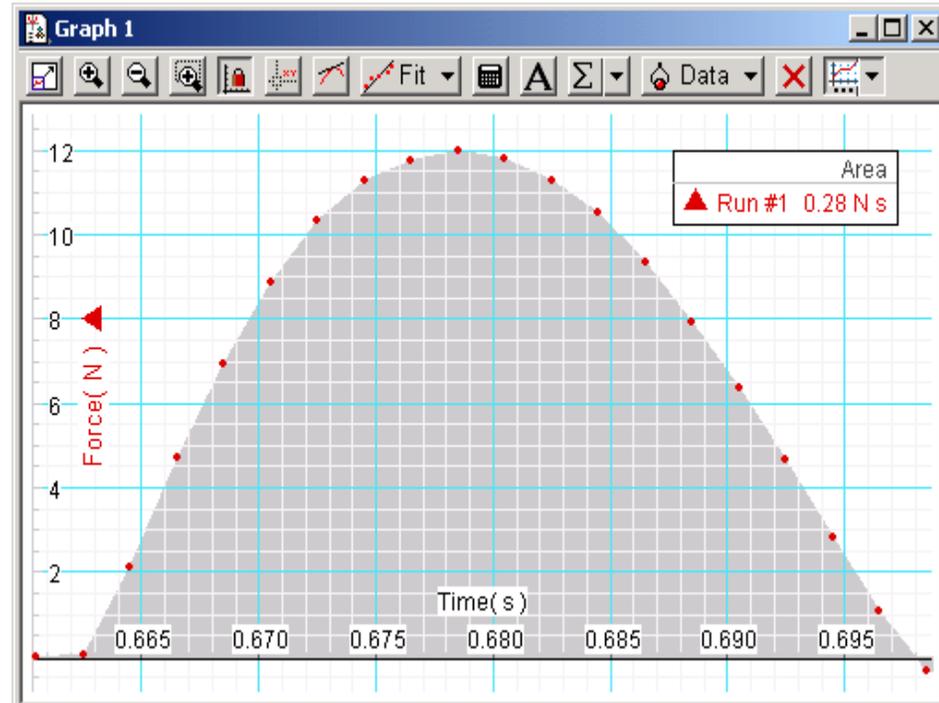


□ Use Statistics Tool ( $\Sigma$ ) to measure velocities  $v_{A,1}$  and  $v_2$ , before and after the collision. Complete the table.

$m_A$	$m_B$	$v_{A,1}$	$v_2$
0.25 kg	0.25kg		
0.25 kg	0.50 kg		
0.50 kg	0.25 kg		

# Elastic collisions

- Measure  $v_{A,1}$  and  $v_{A,2}$  as before.
- Determine the spring impulse  $J$ . ( $\Sigma$  tool)
- Find  $v_{B,2}$  from  $J$ .



$m_A$	$m_B$	$v_{A,1}$	$v_{A,2}$	$J$
0.25 kg	0.25kg			
0.25 kg	0.75 kg			
0.75 kg	0.25 kg			

# Inelastic analysis (Homework)

$m_A$	$m_B$	$v_{A,1}$	$v_{CM}$	$K_1$	$K_{CMCS}$	$v_2$	$K_2$	$W_{NC}$
0.25 kg	0.25 kg							
0.25 kg	0.50 kg							
0.50 kg	0.25 kg							

Fill in the table!

$$v_{CM} = \frac{m_A v_{A,1}}{m_A + m_B} \quad K_{CMCS} = \frac{1}{2} m_A (v_{A,1}^2 - v_{CM}^2) + \frac{1}{2} m_B v_{CM}^2$$

$$K_1 = \frac{1}{2} m_A v_{A,1}^2 \quad K_2 = \frac{1}{2} (m_A + m_B) v_2^2 = K_1 - W_{NC}$$

# Elastic analysis (Homework)

$m_A$	$m_B$	$v_{A,1}$	$v_{CM}$	$K_1$	$v_{A,2}$	$J$	$v_{B,2}$	$K_2$
0.25 kg	0.25 kg							
0.25 kg	0.75 kg							
0.75 kg	0.25 kg							

Fill in the table. Part of Problem Set  
9.

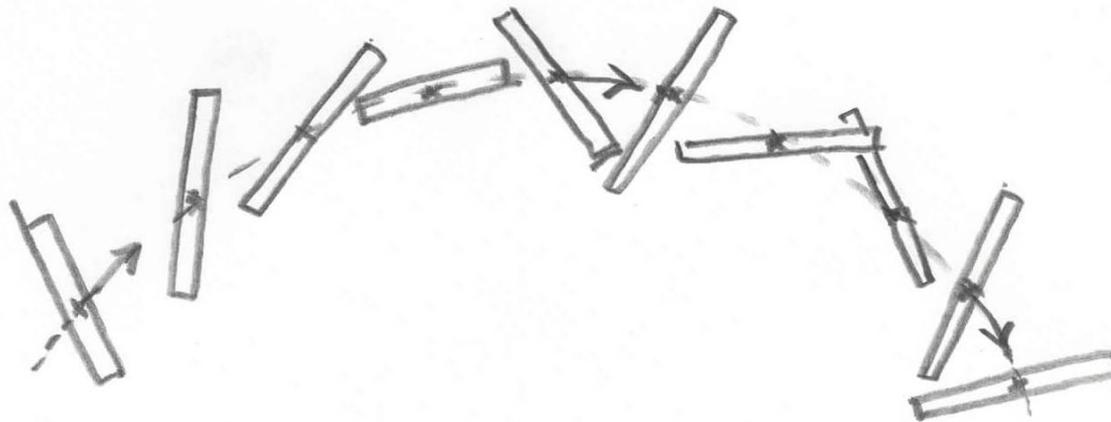
# **Rotational Motion, Torque, Angular Acceleration, and Moment of Inertia**

**8.01t**

**Nov 3, 2004**

# Rotation and Translation of Rigid Body

Motion of a thrown object



# Translational Motion of the Center of Mass

- Total momentum  $\vec{\mathbf{p}}^{\text{total}} = m^{\text{total}} \vec{\mathbf{V}}_{cm}$
- External force and acceleration of center of mass

$$\vec{\mathbf{F}}_{ext}^{\text{total}} = \frac{d\vec{\mathbf{p}}^{\text{total}}}{dt} = m^{\text{total}} \frac{d\vec{\mathbf{V}}_{cm}}{dt} = m^{\text{total}} \vec{\mathbf{A}}_{cm}$$

# Rotation and Translation of Rigid Body

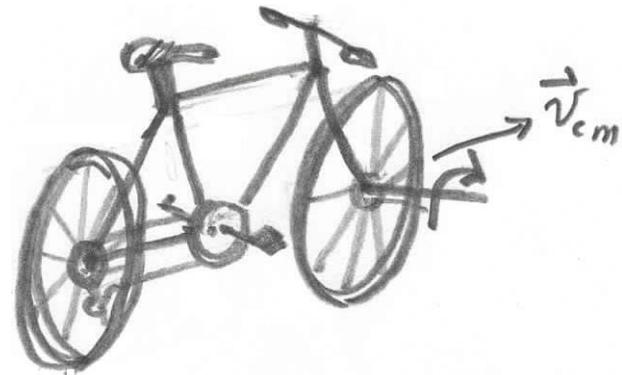
- Torque produces angular acceleration about center of mass

$$\tau_{cm}^{total} = I_{cm} \alpha_{cm}$$

- $I_{cm}$  is the moment of inertial about the center of mass
- $\alpha_{cm}$  is the angular acceleration about center of mass

# Fixed Axis Rotation

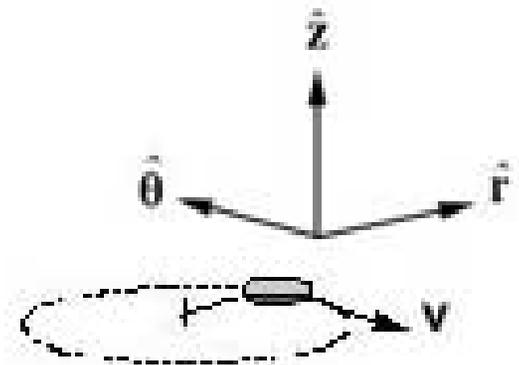
- CD is rotating about axis passing through the center of the disc and is perpendicular to the plane of the disc.
- For straight line motion, bicycle wheel rotates about fixed direction and center of mass is translating



# PRS Question

Consider the uniformly rotating object shown below. If the object's angular velocity is a vector (in other words, it points in a certain direction in space) is there a particular direction we should associate with the angular velocity?

1. yes,  $\pm \hat{\theta}$  direction (tangential)
2. yes,  $\pm \hat{r}$  direction (radial)
3. yes,  $\pm \hat{z}$  direction (perpendicular to plane)
4. yes, some other direction
5. no, the choice is really arbitrary



# Fixed Axis Rotation: Angular Velocity and Angular Acceleration

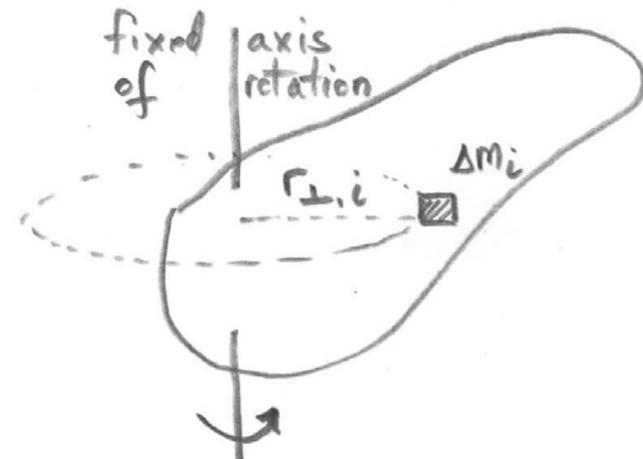
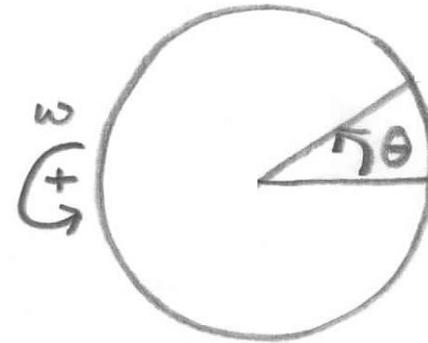
Angle variable  $\theta$

Angular velocity  $\omega \equiv \frac{d\theta}{dt}$

Angular acceleration  $\alpha \equiv \frac{d^2\theta}{dt^2}$

Mass element  $\Delta m_i$

Radius of orbit  $r_{\perp,i}$



# PRS Question

A ladybug sits at the outer edge of a merry-go-round, and a gentleman bug sits halfway between her and the axis of rotation. The merry-go-round makes a complete revolution once each second. The gentleman bug's angular speed is

1. half the ladybug's.
2. the same as the ladybug's.
3. twice the ladybug's.
4. impossible to determine

# PRS Question

A ladybug sits at the outer edge of a merry-go-round that is turning and slowing down. The tangential component of the ladybug's (Cartesian) acceleration is

1. in the direction of the velocity.
2. is opposite the direction of the velocity.
3. is perpendicular to the plane of the merry-go round.
4. is towards the center of the merry-go round.
5. zero

# Fixed Axis Rotation: Tangential Velocity and Tangential Acceleration

- Individual mass elements  $\Delta m_i$
- Tangential velocity  $v_{\text{tan},i} = r_{\perp,i} \omega$
- Tangential acceleration  $a_{\text{tan},i} = r_{\perp,i} \alpha$
- Radial Acceleration  $a_{\text{rad},i} = \frac{v_{\text{tan},i}^2}{r_{\perp,i}} = r_{\perp,i} \omega^2$

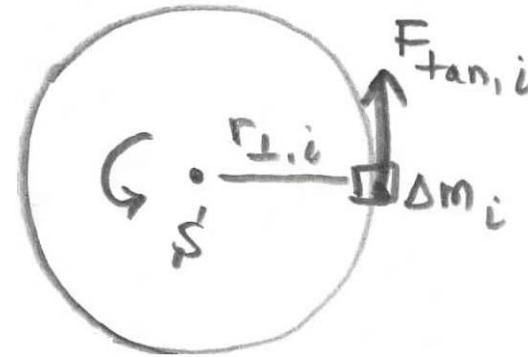
# Class Problem

A turntable is a uniform disc of mass  $1.2 \text{ kg}$  and a radius  $1.3 \times 10^{-1} \text{ m}$ . The turntable is spinning initially at a constant rate of  $(33 \text{ rpm})$ . The motor is turned off and the turntable slows to a stop in  $8.0 \text{ s}$ . Assume that the angular acceleration is constant.

- a) What is the initial angular velocity of the turntable?
- b) What is the angular acceleration of the turntable?

# Newton's Second Law

- Tangential force on mass element produces torque



- Newton's Second Law

$$F_{\text{tan},i} = \Delta m_i a_{\text{tan},i}$$

$$F_{\text{tan},i} = \Delta m_i r_{\perp,i} \alpha$$

- Torque

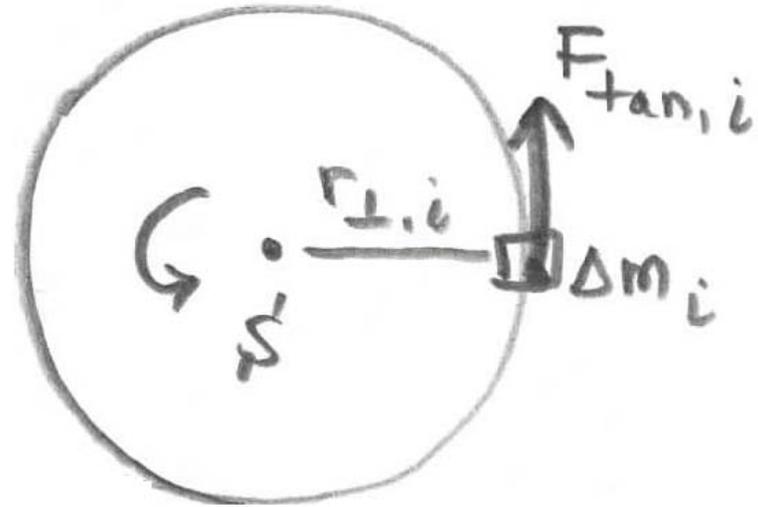
$$\vec{\tau}_{S,i} = \vec{r}_{S,i} \times \vec{F}_i$$

# Torque

Torque about  $S$  is:

$$\vec{\tau}_{S,i} = \vec{r}_{S,i} \times \vec{F}_i$$

- Counterclockwise
- perpendicular to the plane



$$\tau_{S,i} = r_{\perp,i} F_{\text{tan},i} = \Delta m_i (r_{\perp,i})^2 \alpha$$

# Moment of Inertia

- Total torque is the sum over all mass elements

$$\tau_S^{total} = \tau_{S,1} + \tau_{S,2} + \dots = \sum_{i=1}^{i=N} \tau_{S,i} = \sum_{i=1}^{i=N} r_{\perp,i} F_{\tan,i} = \sum_{i=1}^{i=N} \Delta m_i (r_{\perp,i})^2 \alpha$$

- Moment of Inertia about S:

$$I_S = \sum_{i=1}^{i=N} \Delta m_i (r_{\perp,i})^2$$

- Continuous Body

$$I_S = \int_{body} dm (r_{\perp})^2$$

- Mass Element:

$$dm = \lambda dl$$

one dim'l:

two dim'l:

$$dm = \sigma dA$$

- Unit:

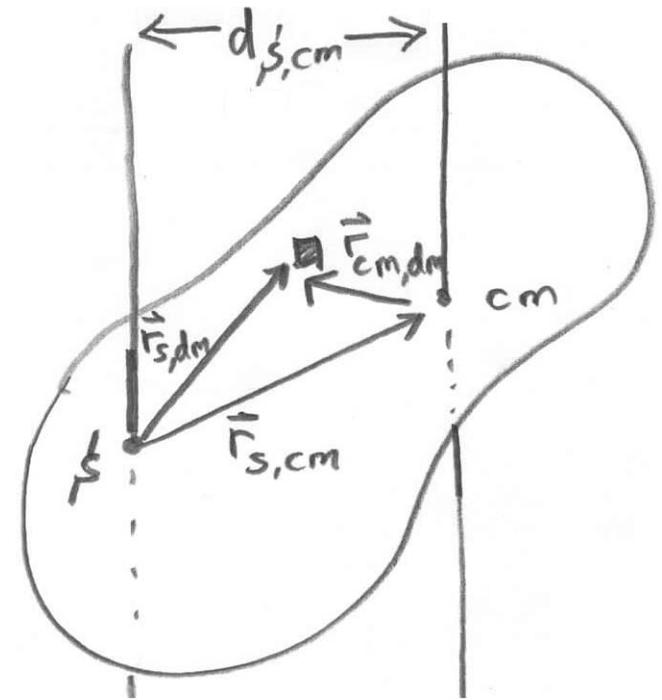
$$[kg - m^2]$$

- Summary:

$$\tau_S^{total} = I_S \alpha$$

# Parallel Axis Theorem

- rigid body of mass  $m$ .
- axis one through center of mass of the body.
- parallel axis through point  $S$  in body.
- $d_{S,cm}$  perpendicular distance between two parallel axes.



$$I_S = I_{cm} + md_{S,cm}^2$$

# **Class Problem: Moment of Inertia of a Rod**

Consider a thin uniform rod of length  $L$  and mass  $m$ . In this problem, you will calculate the moment of inertia about two different axes that pass perpendicular to the rod. One passes through the center of mass of the rod and the second passes through an endpoint of the rod.

# Strategy: Moment of Inertia

**Step 1: Identify the axis of rotation**

**Step 2: Choose a coordinate system**

**Step 3: Identify the infinitesimal mass element  $dm$ .**

**Step 4: Identify the radius,  $r_{\perp}$ , of the circular orbit of the infinitesimal mass element  $dm$ .**

**Step 5: Set up the limits for the integral over the body in terms of the physical dimensions of the rigid body.**

**Step 6: Explicitly calculate the integrals.**

# Class Problem

A turntable is a uniform disc of mass  $1.2 \text{ kg}$  and a radius  $1.3 \times 10^{-1} \text{ m}$ . The moment of inertia of the disc is  $1.0 \times 10^{-1} \text{ kg} \cdot \text{m}^2$ . The turntable is spinning at an initial constant frequency of  $f_0 = 33 \text{ cycles/min}$ . The motor is turned off and the turntable slows to a stop in  $8.0 \text{ s}$  due to frictional torque. Assume that the angular acceleration is constant. What is the magnitude of the frictional torque acting on the disc?