

## MITOCW | MIT8\_01SCF10mod15\_07\_300k

A given spring with a given value of  $k$ , and a given value for the mass that hangs on this spring, has one and only one period. If I change the amplitude of the screen, that period is not going to change. If I changed my definition of  $t$  equals 0, which would introduce a value for  $\alpha$ , that period is not going to change.  $\omega$  and  $p$  are completely independent of  $a$  and  $\alpha$ .

What is the meaning of  $a$  and  $\alpha$ ? Well,  $a$  and  $\alpha$  are what we call the initial conditions. I discussed one initial condition: if you define that  $t$  equals 0, that the object is at  $x$  plus  $a$ , and you release it with 0 speed, then out comes  $\alpha$ . You could also have released it at  $t$  equals 0, you could release it at  $x$  equals 0, and you could release it with a certain speed  $v$ -- just give it a kick. Out of this information will follow both  $\alpha$  and  $a$ -- that's why we call them initial conditions.

Now, in our simple harmonic oscillation, which has the form of  $x$  in its most general form, times a cosine  $\omega t$  plus  $\alpha$ -- notice that this oscillation will go on forever and ever and ever. Here's  $x$  equals 0-- it will reach plus  $a$ , and we'll go back and reach minus  $a$ , and there never comes an end to this. This is, of course, not very realistic.

In practice, there will be damping-- that means there will be some form of air friction-- and then, the oscillation will gradually die out, but we have not taken that into account. It will oscillate maybe many times, and ultimately, it will come to a halt.

In the problems that I will be doing in this section, I will always ignore friction and air drag of any kind.