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2.830J / 6.780J / ESD.63J Control of Manufacturing Processes (SMA 6303)  
Spring 2008

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# Control of Manufacturing Processes

**Subject 2.830/6.780/ESD.63**

**Spring 2008**

**Lecture #1**

**Introduction**

**February 5, 2008**

# Background

- Pre-requisites
- Your Background and Interests
- Relevant Experience
- Course Schedule

# Expectations

- Assignments ~ Weekly
- 2 Quizzes in Class
- Group Project
  - End of term presentation
  - Report

# Syllabus Details

- **Lecturers**
  - **Duane Boning**
  - **David Hardt**
- **Course Secretary: Sharlene Blake**

# Syllabus Details

- **Prerequisites:** One of the following :
  - 2.008 or 2.810 Manufacturing
  - 2.751J or 6.152J or 6.041 or 15.064J
- **Required Texts:**
  - Montgomery, D.C., *Introduction to Statistical Quality Control*, 5<sup>th</sup> Ed. Wiley, 2005
  - May and Spanos, *Fundamentals of Semiconductor Manufacturing and Process Control*, John Wiley, 2006.
- **Grading:**
  - Problem sets 40%
  - Quizzes 40%
  - Team Projects 20%
- **Assignments:** All except project are to be individual efforts
- **Final exam:** No final exam
- **Course URL:** (Registration and Certificate Required)

# Team Projects

- Topics:
  - Process Diagnosis
  - Process Improvement
  - Process Optimization / Robustness
  - Advanced Applications
- Expectations
  - Background research on process and problem
  - Use of existing data or generation of new data
  - Oral presentation of results
  - Project report from group

# Main Topics

- Physical Origins of Variation
  - Process Sensitivities
- Statistical Models and Interpretation
  - Process as a Random Variable(s)
  - Diagnosis of Problems
- Effects Models and Designed Experiments
  - Input - Output Empirical Models
- Process Optimization (Robustness)
  - Ideal Operating Points

# Manufacturing Process Control

- Process Goals
  - Cost
  - Quality
  - Rate
  - Flexibility

# Focus

- Unit Operations
- **(1) Maximizing Quality**
  - Conformance to Specifications
- (2) Improving Throughput
- (3) Improving Flexibility
- (4) Reducing Cost

# Typical Process Control Problems

- Minimum feature size on a semiconductor chip has too much variability
- DNA diagnostic chip has uneven flow channels
- Toys never fit when assembled at home!
- Next generation high density electrical connector cannot be made reliably

# Typical Process Control Problems

- Airframe skin needs trimming and bending to fit frame
- Web thickness of a machined panel is non-uniform
- Plastic throttle bodies for fuel injection are out of round
- Submarine hull welds need constant rework in production

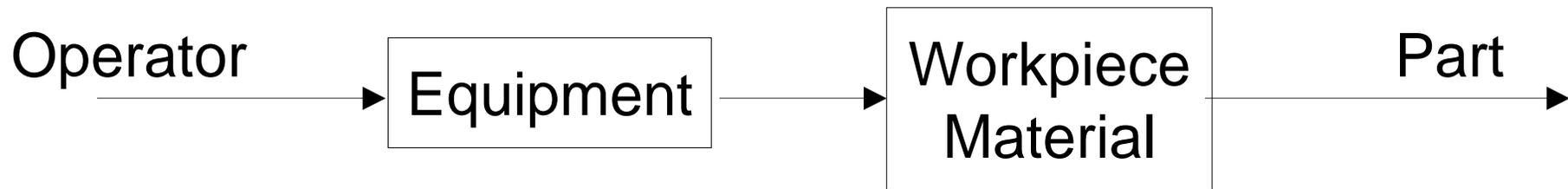
# Other Related Problems – Cost, Rate and Flexibility:

- 100% inspection with high scrap rates
  - low throughput
  - high costs
- 100% inspection with frequent rework
  - low throughput
  - high costs
- High variability at changeover
  - Reluctance to changeover
  - low flexibility

# Manufacturing Processes

- How are they defined?
- How do they do their thing?
- How can they be categorized?
  
- **Why don't they always get it right?**

# The Process Components



- |                    |   |                   |   |                  |
|--------------------|---|-------------------|---|------------------|
| • Etch bath        | ➡ | • Coated Silicon  | ➡ | • IC chip        |
| • Injection Molder |   | • Plastic Pellets |   | • Connector Body |
| • Lathe            |   | • Bar stock       |   | • Shaft          |
| • Draw Press       |   | • Sheet Metal     |   | • Hood           |
| • ...              |   | • ...             |   | • ...            |

# Process Definition

A Manufacturing Process is a Change in the Workpiece *Material*

- A change in geometry
- A change in constitutive properties

# Conceptual Semiconductor Process Model

Image removed due to copyright restrictions. Please see Fig. 1 in Boning, D. S., et al. "A General Semiconductor Process Modeling Framework." *IEEE Transactions on Semiconductor Manufacturing* 5 (November 1992): 266-280.

Boning et al., c. 1990

# Simplified Conceptual Semiconductor Process Model

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# Example: Oxidation

## Wafer states

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# Example: Oxidation

## Treatment (wafer environment)

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# Oxidation Models

$$x_{ox} = \frac{A}{2} \left\{ \left[ 1 + \frac{(t + \tau)4B}{A^2} \right]^{1/2} - 1 \right\}$$

$$\tau = \frac{x_i^2 + Ax_i}{B}$$

## Analytic: Deal-Grove

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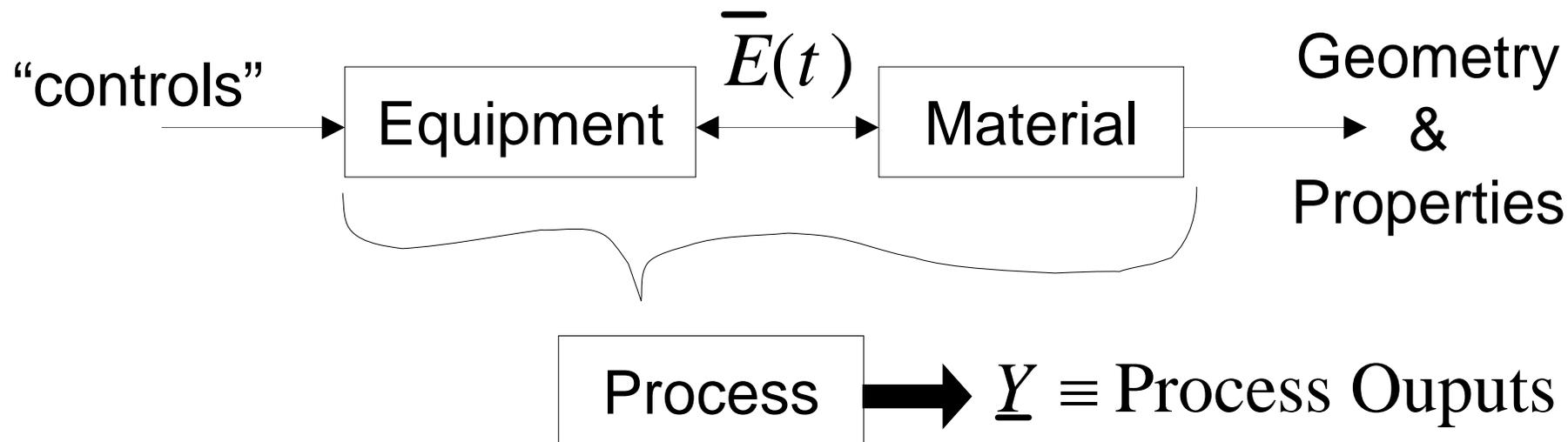
**Empirical: Change in wafer state**

**Empirical: Equipment model for mean and std. dev. of oxide thickness**

# (Semiconductor) Manufacturing Process Control

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# Process Model for Control



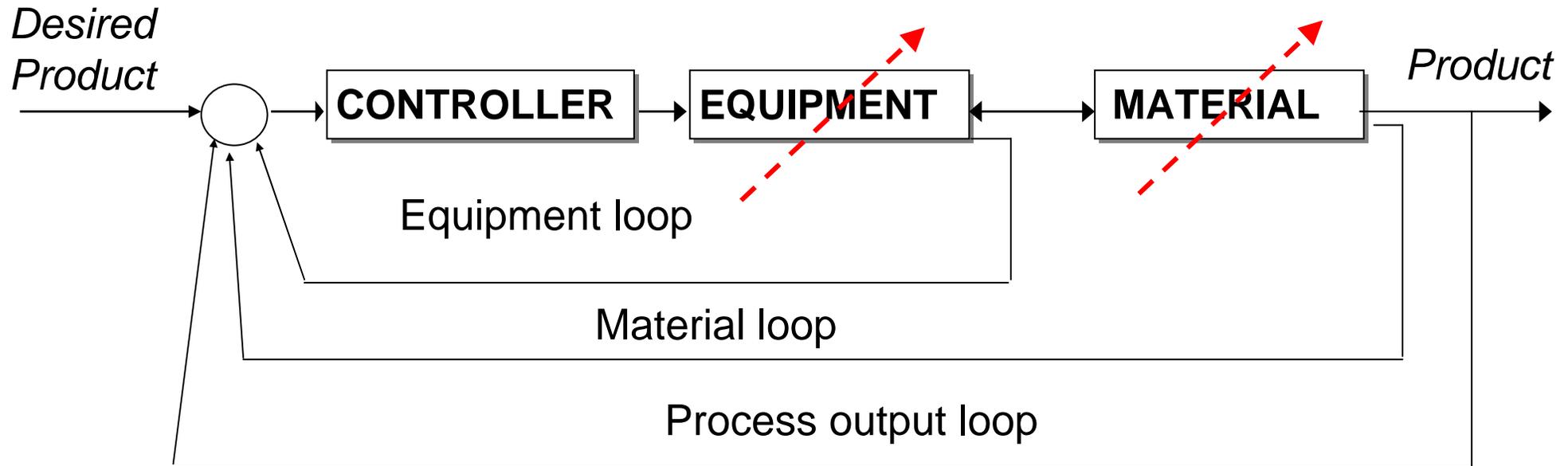
$$\underline{Y} = \Phi(\underline{\alpha})$$

$\underline{\alpha} \equiv$  process *parameters*

What are the  $\alpha$ 's?

Hardt, c. 1995

# The General Process Control Problem



## Control of **Equipment**:

Forces,  
Velocities  
Temperatures, , ..

## Control of **Material**:

Strains  
Stresses  
Temperatures,  
Pressures, ..

## Control of **Product**:

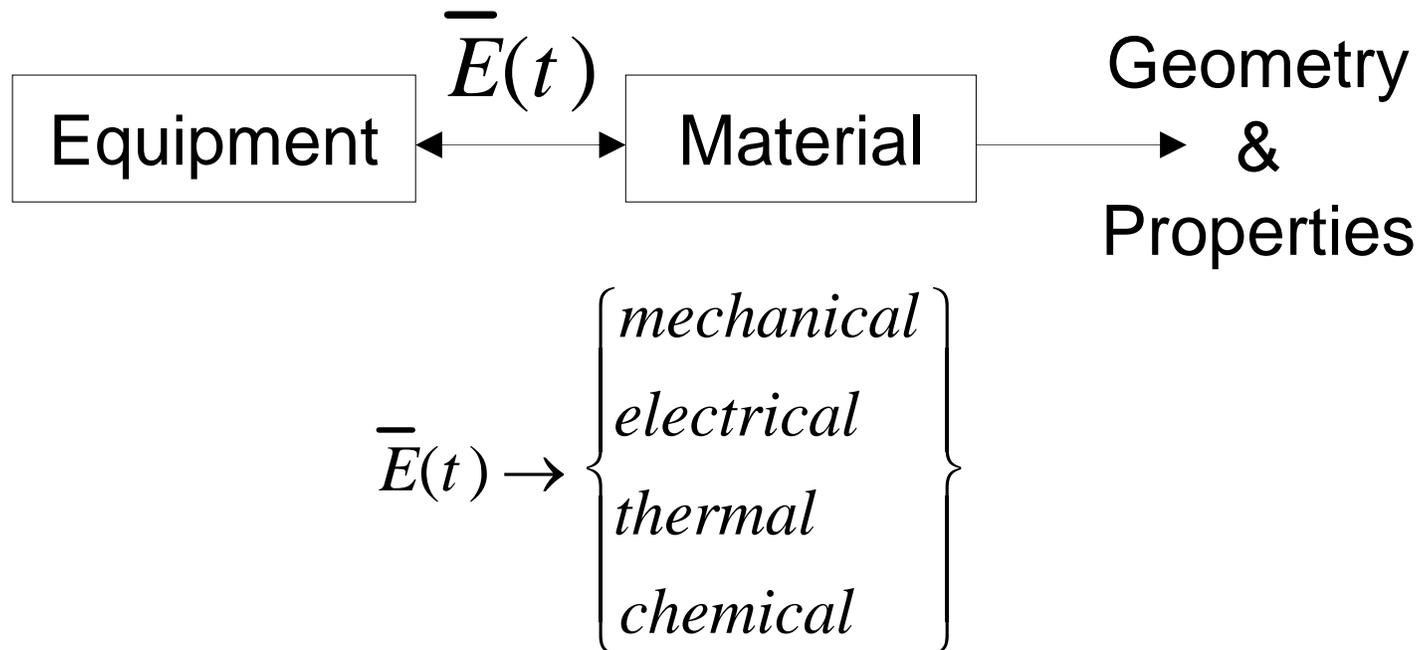
Geometry  
and  
Properties

# Process Control Hierarchy

- **Reduce Disturbances**
  - Good Housekeeping (Ops Management)
  - Standard Operations (SOP's)
  - **Statistical Analysis and Identification of Sources (SPC; 2.830J)**
  - **Feedback Control of Machines (Automation and Control; 2.168)**
- **Reduce Sensitivity (Process Optimization or Robustness)**
  - **Measure Sensitivities via Designed Experiments (2.830J)**
  - Adjust “free” parameters to minimize
- **Measure output and manipulate inputs**
  - **Feedback control of Output(s) (2.830J)**

# Back to the Process: What Causes the Output Change?

- A Directed Energy Exchange with the Equipment



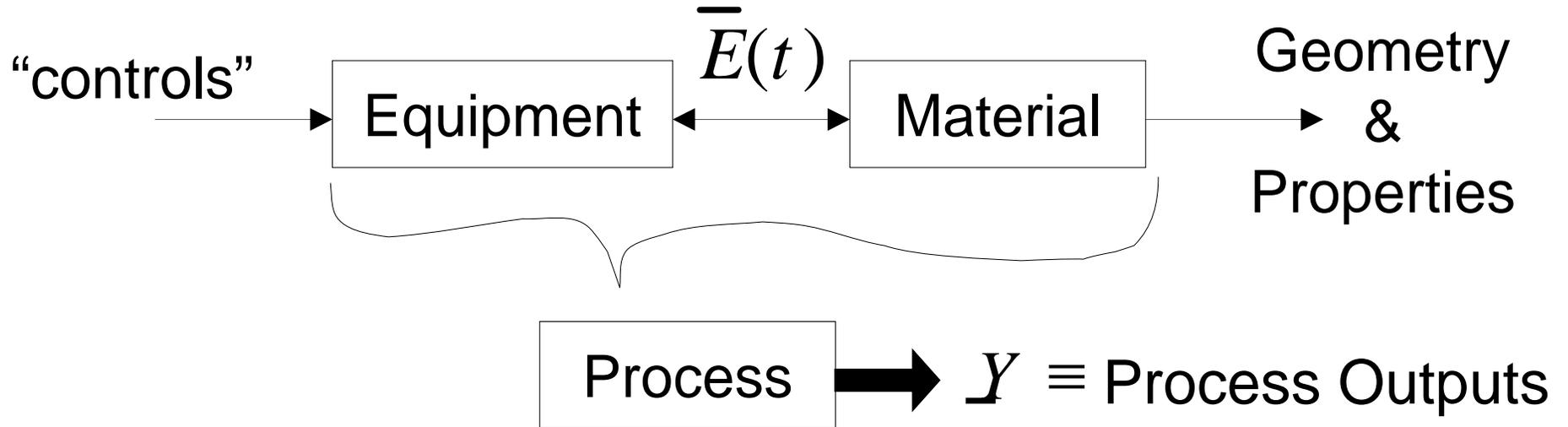
# Modes of Geometry Change?

- **Removal** of Material
- Plastic **Deformation** of Material
- **Addition** of Material
- **Formation** of Material from a Gas or Liquid
  
- Any others???

# What Causes *Variation* in the Process Output?

- Material Variations
  - Properties, Initial Geometry
- Equipment Variations
  - Non-repeatable, long term wear, deflections
- Operator Variations
  - Inconsistent control, excessive “tweaking”
- “Environment” Variations
  - Temperature and Handling inconsistencies

# Process Model for Control



$$\underline{Y} = \Phi(\underline{\alpha})$$

$\underline{\alpha} \equiv$  process *parameters*

What are the  $\alpha$ 's?

# What *are* the Process Parameters?

- Equipment Energy “States”
- Equipment Constitutive “Properties”
  
- Material Energy “States”
- Material Constitutive “Properties”

# Energy States

## Energy Domain

## Energy or Power Variables

Mechanical

$F, v ; P, Q$  or  $F, d ; \sigma, \varepsilon$

Electrical

$V, I$

Thermal

$T, ds/dt$  (or  $dq/dt$ )

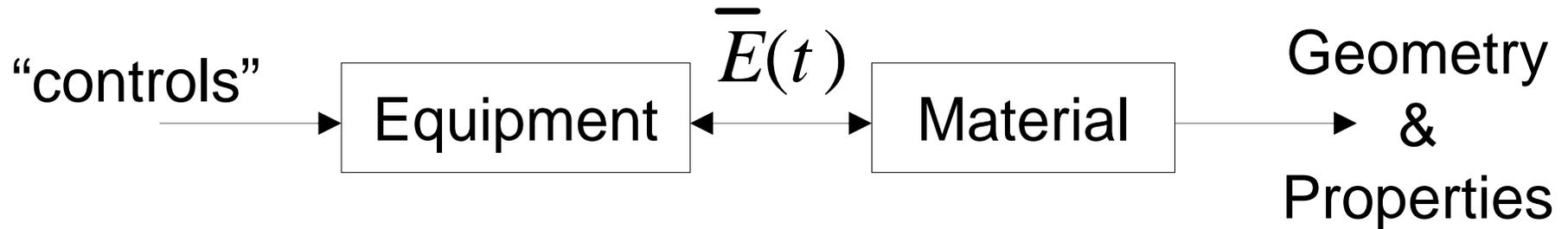
Chemical

chemical potential, rate

# Properties

- *Extensive*: GEOMETRY
- *Intensive*: Constitutive Properties
  - Modulus of Elasticity, damping, mass
  - Plastic Flow Properties
  - Viscosity
  - Resistance, Inductance, Capacitance
  - Chemical Reactivity
  - Heat Transfer Coefficient
- Which has the highest precision?

# A Model for Process Variations



- Recall:  $\underline{Y} = \Phi(\underline{\alpha})$

- One or more  $\alpha$ 's “qualify” as inputs :  $\underline{u}$

$$\underline{Y} = \Phi(\underline{\alpha}, \underline{u}); \quad \underline{u} = \text{vector of inputs}$$

- The first order variation  $\Delta Y$  gives the “Variation Equation”

# The Variation Equation

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u$$

Disturbance Sensitivity

Disturbances

Control Sensitivity or "Gain"

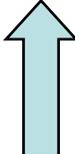
Control Inputs

# Primary Process Control Goal: Minimize $\Delta Y$

How do we make  $\Delta Y \rightarrow 0$  ?

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u$$

- hold  $u$  fixed ( $\Delta u = 0$ )
  - operator training (SOP's)
  - good steady-state machine physics
- minimize disturbances

$$\Delta \alpha \rightarrow \Delta \alpha_{\min}$$


This is the goal of Statistical Process Control (SPC)

# OR

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u \quad \Delta Y \rightarrow 0$$

- hold  $u$  fixed ( $\Delta \underline{u} = 0$ )
- minimize the term:  $\frac{\partial Y}{\partial \alpha}$  the disturbance sensitivity

This is the goal of Process Optimization

- Assuming  $\frac{\partial Y}{\partial \alpha} = \Phi(\underline{\alpha})$   $\underline{\alpha} =$  operating point

# OR

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u \quad \Delta Y \rightarrow 0$$

- manipulate  $\Delta \underline{u}$  by measuring  $\Delta Y$  such that

$$\Delta u \frac{\partial Y}{\partial u} = - \frac{\partial Y}{\partial \alpha} \Delta \alpha$$

This is the goal of Process Feedback Control

- Compensating for (not eliminating) disturbances

# Statistical Process Control

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u$$

Detect  
and  
Minimize

# Process Optimization

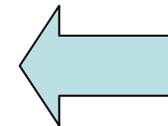
$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u$$

Empirically  
Minimize

# Output Feedback Control

$$\Delta Y = \frac{\partial Y}{\partial \alpha} \Delta \alpha + \frac{\partial Y}{\partial u} \Delta u$$

$$\frac{\partial Y}{\partial u} \Delta u = -\frac{\partial Y}{\partial \alpha} \Delta \alpha$$



Manipulate  
Actively  
Such That

*Compensate for Disturbances*

# Process Control Hierarchy

- **Reduce Disturbances**
  - Good Housekeeping
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