

Lecture 15: Factor Models

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Outline

- 1 Factor Models
 - Linear Factor Model
 - Macroeconomic Factor Models
 - Fundamental Factor Models
 - Statistical Factor Models: Factor Analysis
 - Principal Components Analysis
 - Statistical Factor Models: Principal Factor Method

Linear Factor Model

Data:

- m assets/instruments/indexes: $i = 1, 2, \dots, m$
- n time periods: $t = 1, 2, \dots, n$
- m -variate random vector for each time period:

$$\mathbf{x}_t = (x_{1,t}, x_{2,t}, \dots, x_{m,t})'$$

E.g., returns on m stocks/futures/currencies;

interest-rate yields on m US Treasury instruments.

Factor Model

$$\begin{aligned} x_{i,t} &= \alpha_i + \beta_{1,i}f_{1,t} + \beta_{2,i}f_{2,t} + \dots + \beta_{k,i}f_{k,t} + \epsilon_{i,t} \\ &= \alpha_i + \boldsymbol{\beta}'_i \mathbf{f}_t + \epsilon_{i,t} \quad \text{where} \end{aligned}$$

- α_i : intercept of asset i
- $\mathbf{f}_t = (f_{1,t}, f_{2,t}, \dots, f_{k,t})'$: **common factor** variables at period t (constant over i)
- $\boldsymbol{\beta}_i = (\beta_{1,i}, \dots, \beta_{k,i})'$: **factor loadings of asset i** (constant over t)
- $\epsilon_{i,t}$: the **specific factor of asset i** at period t .

Linear Factor Model

Linear Factor Model: Cross-Sectional Regressions

$$\mathbf{x}_t = \boldsymbol{\alpha} + B\mathbf{f}_t + \boldsymbol{\epsilon}_t,$$

for each $t \in \{1, 2, \dots, T\}$, where

$$\boldsymbol{\alpha} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_m \end{bmatrix} \quad (m \times 1); \quad B = \begin{bmatrix} \beta_1' \\ \beta_2' \\ \vdots \\ \beta_m' \end{bmatrix} = [[\beta_{i,k}]] \quad (m \times K); \quad \boldsymbol{\epsilon}_t = \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \vdots \\ \epsilon_{m,t} \end{bmatrix} \quad (m \times 1)$$

- $\boldsymbol{\alpha}$ and B are the same for all t .
- $\{\mathbf{f}_t\}$ is (K -variate) covariance stationary $I(0)$ with

$$\begin{aligned} E[\mathbf{f}_t] &= \boldsymbol{\mu}_f \\ \text{Cov}[\mathbf{f}_t] &= E[(\mathbf{f}_t - \boldsymbol{\mu}_f)(\mathbf{f}_t - \boldsymbol{\mu}_f)'] = \boldsymbol{\Omega}_f \end{aligned}$$

- $\{\boldsymbol{\epsilon}_t\}$ is m -variate white noise with:

$$\begin{aligned} E[\boldsymbol{\epsilon}_t] &= \mathbf{0}_m \\ \text{Cov}[\boldsymbol{\epsilon}_t] &= E[\boldsymbol{\epsilon}_t \boldsymbol{\epsilon}_t'] = \boldsymbol{\Psi} \\ \text{Cov}[\boldsymbol{\epsilon}_t, \boldsymbol{\epsilon}_{t'}] &= E[\boldsymbol{\epsilon}_t \boldsymbol{\epsilon}_{t'}'] = \mathbf{0} \quad \forall t \neq t' \end{aligned}$$

$\boldsymbol{\Psi}$ is the ($m \times m$) diagonal matrix with entries $(\sigma_1^2, \sigma_2^2, \dots, \sigma_m^2)$ where $\sigma_i^2 = \text{var}(\epsilon_{i,t})$, the variance of the i th asset specific factor.

- The two processes $\{\mathbf{f}_t\}$ and $\{\boldsymbol{\epsilon}_t\}$ have null cross-covariances:

Linear Factor Model

Summary of Parameters

- α : $(m \times 1)$ intercepts for m assets
- B : $(m \times K)$ loadings on K common factors for m assets
- μ_f : $(K \times 1)$ mean vector of K common factors
- Ω_f : $(K \times K)$ covariance matrix of K common factors
- $\Psi = \text{diag}(\sigma_1^2, \dots, \sigma_m^2)$: m asset-specific variances

Features of Linear Factor Model

- The m -variate stochastic process $\{\mathbf{x}_t\}$ is a covariance-stationary multivariate time series with
 - Conditional moments:

$$E[\mathbf{x}_t | \mathbf{f}_t] = \alpha + B\mathbf{f}_t$$

$$\text{Cov}[\mathbf{x}_t | \mathbf{f}_t] = \Psi$$
 - Unconditional moments:

$$E[\mathbf{x}_t] = \mu_x = \alpha + B\mu_f$$

$$\text{Cov}[\mathbf{x}_t] = \Sigma_x = B\Omega_f B' + \Psi$$

Linear Factor Model

Linear Factor Model: Time Series Regressions

$$\mathbf{x}_i = \mathbf{1}_T \alpha_i + \mathbf{F} \beta_i + \epsilon_i,$$

for each asset $i \in \{1, 2, \dots, m\}$, where

$$\mathbf{x}_i = \begin{bmatrix} x_{i,1} \\ \vdots \\ x_{i,t} \\ \vdots \\ x_{i,T} \end{bmatrix} \quad \epsilon_i = \begin{bmatrix} \epsilon_{i,t} \\ \vdots \\ \epsilon_{i,t} \\ \vdots \\ \epsilon_{i,T} \end{bmatrix} \quad \mathbf{F} = \begin{bmatrix} \mathbf{f}'_1 \\ \vdots \\ \mathbf{f}'_t \\ \vdots \\ \mathbf{f}'_T \end{bmatrix} = \begin{bmatrix} f_{1,1} & f_{2,1} & \cdots & f_{K,1} \\ \vdots & \vdots & \vdots & \vdots \\ f_{1,t} & f_{2,t} & \cdots & f_{K,t} \\ \vdots & \vdots & \vdots & \vdots \\ f_{1,T} & f_{2,T} & \cdots & f_{K,T} \end{bmatrix}$$

- α_i and $\beta_i = (\beta_{1,i}, \dots, \beta_{K,i})$ are regression parameters.
- ϵ_i is the T -vector of regression errors with $\text{Cov}(\epsilon_i) = \sigma_i^2 \mathbf{1}_T$

Linear Factor Model: Multivariate Regression

$$\mathbf{X} = [\mathbf{x}_1 | \cdots | \mathbf{x}_m], \quad \mathbf{E} = [\epsilon_1 | \cdots | \epsilon_m], \quad \mathbf{B} = [\beta_1 | \cdots | \beta_m],$$

$$\mathbf{X} = \mathbf{1}_T \alpha' + \mathbf{F} \mathbf{B} + \mathbf{E}$$

(note that \mathbf{B} equals the transpose of cross-sectional B)

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Macroeconomic Factor Models

Single Factor Model of Sharpe (1970)

$$x_{i,t} = \alpha_i + \beta_i R_{Mt} + \epsilon_{i,t} \quad i = 1, \dots, m \quad t = 1, \dots, T$$

where

- R_{Mt} is the return of the market index in excess of the risk-free rate; the **market risk factor**.
- $x_{i,t}$ is the return of asset i in excess of the risk-free rate.
- $K = 1$ and the single factor is $f_{1,t} = R_{Mt}$.
- Unconditional cross-sectional covariance matrix of the assets:

$$\text{Cov}(\mathbf{x}_t) = \boldsymbol{\Sigma}_x = \sigma_M^2 \boldsymbol{\beta} \boldsymbol{\beta}' + \boldsymbol{\Psi} \quad \text{where}$$

- $\sigma_M^2 = \text{Var}(R_{Mt})$
- $\boldsymbol{\beta} = (\beta_1, \dots, \beta_m)'$
- $\boldsymbol{\Psi} = \text{diag}(\sigma_1^2, \dots, \sigma_m^2)$

Estimation of Sharpe's Single Index Model

- Single Index Model satisfies the Generalized Gauss-Markov assumptions so the least-squares estimates $(\hat{\alpha}_i, \hat{\beta}_i)$ from the time-series regression for each asset i are best linear unbiased estimates (BLUE) and the MLEs under Gaussian assumptions.

$$\mathbf{x}_i = \mathbf{1}_T \hat{\alpha}_i + \mathbf{R}_M \hat{\beta}_i + \hat{\epsilon}_i$$

- Unbiased estimators of remaining parameters:
 - $\hat{\sigma}_i^2 = (\hat{\epsilon}_i' \hat{\epsilon}_i) / (T - 2)$
 - $\hat{\sigma}_M^2 = [\sum_{t=1}^T (\mathbf{R}_{Mt} - \bar{\mathbf{R}}_M)^2] / (T - 1)$ with $\bar{\mathbf{R}}_M = (\sum_{t=1}^T \mathbf{R}_{Mt}) / T$
 - $\hat{\Psi} = \text{diag}(\hat{\sigma}_1^2, \dots, \hat{\sigma}_m^2)$
- Estimator of unconditional covariance matrix:

$$\widehat{\text{Cov}}(\mathbf{x}_t) = \hat{\Sigma}_x = \hat{\sigma}_M^2 \hat{\beta} \hat{\beta}' + \hat{\Psi}$$

Macroeconomic Multifactor Model

The common factor variables $\{\mathbf{f}_t\}$ are realized values of macroeconomic variables, such as

- Market risk
- Price indices (CPI, PPI, commodities) / Inflation
- Industrial production (GDP)
- Money growth
- Interest rates
- Housing starts
- Unemployment

See Chen, Ross, Roll (1986). "Economic Forces and the Stock Market"

Linear Factor Model as Time Series Regressions

$$\mathbf{x}_i = \mathbf{1}_T \alpha_i + \mathbf{F} \beta_i + \epsilon_i, \quad \text{where}$$

- $\mathbf{F} = [\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_T]'$ is the $(T \times K)$ matrix of realized values of $(K > 0)$ macroeconomic factors.
- Unconditional cross-sectional covariance matrix of the assets:

$$\text{Cov}(\mathbf{x}_t) = B \Omega_f B' + \Psi$$

where $B = (\beta_1, \dots, \beta_m)'$ is $(m \times K)$

Estimation of Multifactor Model

- Multifactor model satisfies the Generalized Gauss-Markov assumptions so the least-squares estimates $\hat{\alpha}_i$ and $\hat{\beta}_i$ ($K \times 1$) from the time-series regression for each asset i are best linear unbiased estimates (BLUE) and the MLEs under Gaussian assumptions.

$$\mathbf{x}_i = \mathbf{1}_T \hat{\alpha}_i + \mathbf{F} \hat{\beta}_i + \hat{\epsilon}_i$$

- Unbiased estimators of remaining parameters:

- $\hat{\sigma}_i^2 = (\hat{\epsilon}_i' \hat{\epsilon}_i) / [T - (k + 1)]$
- $\hat{\Psi} = \text{diag}(\hat{\sigma}_1^2, \dots, \hat{\sigma}_m^2)$
- $\hat{\Omega}_f = [\sum_{t=1}^T (\mathbf{f}_t - \bar{\mathbf{f}})(\mathbf{f}_t - \bar{\mathbf{f}})'] / (T - 1)$
with $\bar{\mathbf{f}} = (\sum_{t=1}^T \mathbf{f}_t) / T$

- Estimator of unconditional covariance matrix:

$$\widehat{\text{Cov}}(\mathbf{x}_t) = \hat{\Sigma}_x = \hat{\sigma}_M^2 \hat{B} \hat{\Omega}_f \hat{B}' + \hat{\Psi}$$

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Fundamental Factor Models

The common-factor variables $\{\mathbf{f}_t\}$ are determined using fundamental, asset-specific attributes such as

- Sector/industry membership.
- Firm size (market capitalization)
- Dividend yield
- Style (growth/value as measured by price-to-book, earnings-to-price, ...)
- Etc.

BARRA Approach (Barr Rosenberg)

- Treat observable asset-specific attributes as **factor betas**
- Factor realizations $\{\mathbf{f}_t\}$ are unobservable, but are estimated.

Fama-French Approach (Eugene Fama and Kenneth French)

- For every time period t , apply cross-sectional sorts to define factor realizations
 - For a given asset attribute, sort the assets at period t by that attribute and define quintile portfolios based on splitting the assets into 5 equal-weighted portfolios.
 - Form the hedge portfolio which is long the top quintile assets and short the bottom quintile assets.
- Define the common factor realizations for period t as the period- t returns for the K hedge portfolios corresponding to the K fundamental asset attributes.
- Estimate the factor loadings on assets using time series regressions, separately for each asset i .

Barra Industry Factor Model

- Suppose the m assets ($i = 1, 2, \dots, m$) separate into K industry groups ($k = 1, \dots, K$)
- For each asset i , define the factor loadings ($k = 1, \dots, K$)

$$\beta_{i,k} = \begin{cases} 1 & \text{if asset } i \text{ is in industry group } k \\ 0 & \text{otherwise} \end{cases}$$

These loadings are time invariant.

- For time period t , denote the realization of the K factors as

$$\mathbf{f}_t = (f_{1t}, \dots, f_{Kt})'$$

These K -vector realizations are unobserved.

The Industry Factor Model is

$$X_{i,t} = \beta_{i,1}f_{1t} + \dots + \beta_{i,K}f_{Kt} + \epsilon_{it}, \quad \forall i, t$$

where

$$\begin{aligned} \text{var}(\epsilon_{it}) &= \sigma_i^2, & \forall i \\ \text{cov}(\epsilon_{it}, f_{kt}) &= 0, & \forall i, k, t \\ \text{cov}(f_{k't}, f_{kt}) &= [\Omega_f]_{k',k}, & \forall k', k, t \end{aligned}$$

Barra Industry Factor Model

Estimation of the Factor Realizations

For each time period t consider the cross-sectional regression for the factor model:

$$\mathbf{x}_t = B\mathbf{f}_t + \boldsymbol{\epsilon}_t \quad (\boldsymbol{\alpha} = 0 \text{ so it does not appear})$$

with

$$\mathbf{x}_t = \begin{bmatrix} x_{1,t} \\ x_{2,t} \\ \vdots \\ x_{m,t} \end{bmatrix} \quad (m \times 1); \quad B = \begin{bmatrix} \beta'_1 \\ \beta'_2 \\ \vdots \\ \beta'_m \end{bmatrix} = [[\beta_{i,k}]] \quad (m \times K); \quad \boldsymbol{\epsilon}_t = \begin{bmatrix} \epsilon_{1,t} \\ \epsilon_{2,t} \\ \vdots \\ \epsilon_{m,t} \end{bmatrix} \quad (m \times 1)$$

where $E[\boldsymbol{\epsilon}_t] = \mathbf{0}_m$, $E[\boldsymbol{\epsilon}_t \boldsymbol{\epsilon}_t'] = \boldsymbol{\Psi}$, and $\text{Cov}(\mathbf{f}_t) = \boldsymbol{\Omega}_f$.

- Compute $\hat{\mathbf{f}}_t$ by least-squares regression of \mathbf{x}_t on B with regression parameter \mathbf{f}_t .
- B is $(m \times K)$ matrix of indicator variables (same for all t)
 $B'B = \text{diag}(m_1, \dots, m_K)$,
 where m_k is the count of assets i in industry k , and $\sum_{k=1}^K m_k = m$.
- $\hat{\mathbf{f}}_t = (B'B)^{-1} B' \mathbf{x}_t$ (vector of industry averages!)
- $\hat{\boldsymbol{\epsilon}}_t = \mathbf{x}_t - B\hat{\mathbf{f}}_t$

Barra Industry Factor Model

Estimation of Factor Covariance Matrix

$$\hat{\Omega}_f = \frac{1}{T-1} \sum_{t=1}^T (\hat{\mathbf{f}}_t - \bar{\hat{\mathbf{f}}})(\hat{\mathbf{f}}_t - \bar{\hat{\mathbf{f}}})'$$

$$\bar{\hat{\mathbf{f}}} = \frac{1}{T} \sum_{t=1}^T \hat{\mathbf{f}}_t$$

Estimation of Residual Covariance Matrix $\hat{\Psi}$

$$\hat{\Psi} = \text{diag}(\hat{\sigma}_1^2, \dots, \hat{\sigma}_m^2)$$

where

$$\hat{\sigma}_i^2 = \frac{1}{T-1} \sum_{t=1}^T [\hat{\epsilon}_{i,t} - \bar{\hat{\epsilon}}_i]^2$$

$$\bar{\hat{\epsilon}}_i = \frac{1}{T} \sum_{t=1}^T \hat{\epsilon}_{i,t}$$

Estimation of Industry Factor Model Covariance Matrix

$$\hat{\Sigma} = B' \hat{\Omega}_f B + \hat{\Psi}$$

Barra Industry Factor Model

Further Details

- Inefficiency of least squares estimates due to heteroscedasticity in Ψ .
Resolution: apply Generalized Least Squares (GLS) estimating Ψ in the cross-sectional regressions.
- The factor realizations can be rescaled to represent **factor mimicking portfolios**
- The Barra Industry Factor Model can be expressed as a **seemingly unrelated regression (SUR) model**

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Statistical Factor Models

The common-factor variables $\{\mathbf{f}_t\}$ are hidden (*latent*) and their structure is deduced from analysis of the observed returns/data $\{\mathbf{x}_t\}$. The primary methods for extraction of factor structure are:

- Factor Analysis
- Principal Components Analysis

Both methods model the $\boldsymbol{\Sigma}$, the covariance matrix of $\{\mathbf{x}_t, t = 1, \dots, T\}$ by focusing on the sample covariance matrix $\hat{\boldsymbol{\Sigma}}$, computed as follows:

$$\begin{aligned} \mathbf{X} &= [\mathbf{x}_1 : \cdots : \mathbf{x}_T] \quad (m \times T) \\ \mathbf{X}^* &= \mathbf{X} \cdot (\mathbf{I}_T - \frac{1}{T} \mathbf{1}_T \mathbf{1}'_T) \quad (\text{'de-meanned' by row}) \\ \hat{\boldsymbol{\Sigma}}_x &= \frac{1}{T} \mathbf{X}^* (\mathbf{X}^*)' \end{aligned}$$

Factor Analysis Model

Linear Factor Model as Cross-Sectional Regression

$$\mathbf{x}_t = \boldsymbol{\alpha} + B\mathbf{f}_t + \boldsymbol{\epsilon}_t,$$

for each $t \in \{1, 2, \dots, T\}$ (m equations expressed in vector/matrix form) where

- $\boldsymbol{\alpha}$ and B are the same for all t .
- $\{\mathbf{f}_t\}$ is (K -variate) covariance stationary $I(0)$ with $E[\mathbf{f}_t] = \boldsymbol{\mu}_f$, $Cov[\mathbf{f}_t] = \boldsymbol{\Omega}_f$
- $\{\boldsymbol{\epsilon}_t\}$ is m -variate white noise with $E[\boldsymbol{\epsilon}_t] = \mathbf{0}_m$ and $Cov[\boldsymbol{\epsilon}_t] = \boldsymbol{\Psi} = \text{diag}(\sigma_i^2)$

Invariance to Linear Transforms of \mathbf{f}_t

- For any ($K \times K$) invertible matrix H define

$$\mathbf{f}_t^* = H\mathbf{f}_t \text{ and } B^* = BH^{-1}$$

- Then the linear factor model holds replacing \mathbf{f}_t and B

$$\begin{aligned} \mathbf{x}_t &= \boldsymbol{\alpha} + B^*\mathbf{f}_t^* + \boldsymbol{\epsilon}_t = \boldsymbol{\alpha} + BH^{-1}H\mathbf{f}_t + \boldsymbol{\epsilon}_t \\ &= \boldsymbol{\alpha} + B\mathbf{f}_t + \boldsymbol{\epsilon}_t \end{aligned}$$

and replacing $\boldsymbol{\mu}_f$ and $\boldsymbol{\Omega}_f$ with

$$\boldsymbol{\Omega}_f^* = Cov(\mathbf{f}_t^*) = Cov(H\mathbf{f}_t) = HCov(\mathbf{f}_t)H' = H\boldsymbol{\Omega}_fH'$$

$$\boldsymbol{\mu}_f^* = H\boldsymbol{\mu}_f$$

Factor Analysis Model

Standard Formulation of Factor Analysis Model

- Orthonormal factors: $\Omega_f = \mathbf{I}_K$

This is achieved by choosing $H = \Gamma \Lambda^{-\frac{1}{2}}$, where

$\Omega_f = \Gamma \Lambda \Gamma'$ is the spectral/eigen decomposition with orthogonal ($K \times K$) matrix Γ and diagonal matrix $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_K)$, where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_K > 0$.

- Zero-mean factors: $\mu_f = \mathbf{0}_K$

This is achieved by adjusting α to incorporate the mean contribution from the factors:

$$\alpha^* = \alpha + B\mu_f$$

Under these assumptions the unconditional covariance matrix is

$$\text{Cov}(\mathbf{x}_t) = \Sigma_x = BB' + \Psi$$

Factor Analysis Model

Maximum Likelihood Estimation

For the model

$$\mathbf{x}_t = \boldsymbol{\alpha} + B\mathbf{f}_t + \boldsymbol{\epsilon}_t$$

- $\boldsymbol{\alpha}$ and B are vector/matrix constants.
- All random variables are Normal/Gaussian:
 - \mathbf{x}_t i.i.d. $N_m(\boldsymbol{\alpha}, \boldsymbol{\Sigma}_x)$
 - \mathbf{f}_t i.i.d. $N_K(\mathbf{0}_K, \mathbf{I}_K)$
 - $\boldsymbol{\epsilon}_t$ i.i.d. $N_m(\mathbf{0}_m, \boldsymbol{\Psi})$
- $\text{Cov}(\mathbf{x}_t) = \boldsymbol{\Sigma}_x = BB' + \boldsymbol{\Psi}$

Model Likelihood

$$\begin{aligned}
 L(\boldsymbol{\alpha}, \boldsymbol{\Sigma}_x) &= p(\mathbf{x}_1, \dots, \mathbf{x}_T \mid \boldsymbol{\alpha}, \boldsymbol{\Sigma}) \\
 &= \prod_{t=1}^T [p(\mathbf{x}_t \mid \boldsymbol{\alpha}, \boldsymbol{\Sigma})] \\
 &= \prod_{t=1}^T [(2\pi)^{-m/2} |\boldsymbol{\Sigma}|^{-1/2} \exp(-\frac{1}{2}(\mathbf{x}_t - \boldsymbol{\alpha})' \boldsymbol{\Sigma}_x^{-1} (\mathbf{x}_t - \boldsymbol{\alpha}))] \\
 &= (2\pi)^{-Tm/2} |\boldsymbol{\Sigma}|^{-T/2} \exp\left[-\frac{1}{2} \sum_{t=1}^T (\mathbf{x}_t - \boldsymbol{\alpha})' \boldsymbol{\Sigma}_x^{-1} (\mathbf{x}_t - \boldsymbol{\alpha})\right]
 \end{aligned}$$

Factor Analysis Model

Log Likelihood of the Factor Model

$$\begin{aligned}
 l(\alpha, \Sigma_x) &= \log L(\alpha, \Sigma_x) \\
 &= -\frac{TK}{2} \log(2\pi) - \frac{K}{2} \log(|\Sigma|) \\
 &\quad - \frac{1}{2} \sum_{t=1}^T (\mathbf{x}_t - \alpha)' \Sigma_x^{-1} (\mathbf{x}_t - \alpha)
 \end{aligned}$$

Maximum Likelihood Estimates (MLEs)

- The MLEs of α , B , Ψ are the values which
 Maximize $l(\alpha, \Sigma_x)$
 Subject to: $\Sigma_x = BB' + \Psi$
- The MLEs are computed numerically applying the
 Expectation-Maximization (EM) algorithm*

* Optional Reading: Dempster, Laird, and Rubin (1977), Rubin and Thayer (1983).

Factor Analysis Model

ML Specification of the Factor Model

- Apply EM algorithm to compute $\hat{\alpha}$ and \hat{B} and $\hat{\Psi}$.
- Estimate factor realizations $\{\mathbf{f}_t\}$
 - Apply the cross-sectional regression models for each time period t :

$$\mathbf{x}_t - \hat{\alpha} = \hat{B}\mathbf{f}_t + \hat{\epsilon}_t$$

Solving for $\hat{\mathbf{f}}$ as the regression parameter estimates of the regression of observed \mathbf{x}_t on the estimated factor loadings matrix. Taking account of the heteroscedasticity in ϵ , apply GLS estimates:

$$\hat{\mathbf{f}}_t = [\hat{B}'\hat{\Psi}^{-1}\hat{B}]^{-1}[\hat{B}'\hat{\Psi}^{-1}(\mathbf{x}_t - \hat{\alpha})]$$

- (Optional) Consider coordinate rotations of orthonormal factors as alternate interpretations of model.

Factor Analysis Model

Further Details of ML Specification

- Estimated factor realizations can be rescaled to represent **factor mimicking portfolios**
- Likelihood Ratio test can be applied to test for the number of factors.

Test Statistic: $LR(K) = 2[l(\tilde{\alpha}, \tilde{\Sigma}) - l(\hat{\alpha}, \hat{B}, \hat{\Psi})]$

where H_0 : K factors are sufficient to model Σ and $\tilde{\alpha}$ and $\tilde{\Sigma}$ are the MLEs with no factor-model restrictions.

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Principal Components Analysis (PCA)

- An m -variate random variable:

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}, \text{ with } E[\mathbf{x}] = \boldsymbol{\alpha} \in \mathfrak{R}^m, \text{ and } \text{Cov}[\mathbf{x}] = \boldsymbol{\Sigma} \text{ (} m \times m \text{)}$$

- Eigenvalues/eigenvectors of $\boldsymbol{\Sigma}$:

- $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_m \geq 0$: m eigenvalues.
- $\boldsymbol{\gamma}_1, \boldsymbol{\gamma}_2, \dots, \boldsymbol{\gamma}_m$: m orthonormal eigenvectors:

$$\boldsymbol{\Sigma} \boldsymbol{\gamma}_i = \lambda_i \boldsymbol{\gamma}_i, \quad i = 1, \dots, m$$

$$\boldsymbol{\gamma}_i' \boldsymbol{\gamma}_i = 1, \quad \forall i$$

$$\boldsymbol{\gamma}_i' \boldsymbol{\gamma}_{i'} = 0, \quad \forall i \neq i'$$

- $\boldsymbol{\Sigma} = \sum_{i=1}^m \lambda_i \boldsymbol{\gamma}_i \boldsymbol{\gamma}_i'$

- Principal Component Variables:

$$p_i = \boldsymbol{\gamma}_i' (\mathbf{x} - \boldsymbol{\alpha}), \quad i = 1, \dots, m$$

Principal Components Analysis

Principal Components in Vector/Matrix Form

- m -Variate \mathbf{x} : $E[\mathbf{x}] = \boldsymbol{\alpha}$, $Cov[\mathbf{x}] = \boldsymbol{\Sigma}$

- $\boldsymbol{\Sigma} = \boldsymbol{\Gamma}\boldsymbol{\Lambda}\boldsymbol{\Gamma}'$, where

$$\boldsymbol{\Lambda} = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_m)$$

$$\boldsymbol{\Gamma} = [\gamma_1 : \gamma_2 : \dots : \gamma_m]$$

$$\boldsymbol{\Gamma}'\boldsymbol{\Gamma} = \mathbf{I}_m$$

- $\mathbf{p} = \begin{bmatrix} p_1 \\ \vdots \\ p_m \end{bmatrix} = \boldsymbol{\Gamma}'(\mathbf{x} - \boldsymbol{\alpha})$, m -Variate PC variables

$$E[\mathbf{p}] = E[\boldsymbol{\Gamma}'(\mathbf{x} - \boldsymbol{\alpha})] = \boldsymbol{\Gamma}'E[(\mathbf{x} - E[\mathbf{x}])] = \mathbf{0}_m$$

$$\begin{aligned} Cov[\mathbf{p}] &= Cov[\boldsymbol{\Gamma}'(\mathbf{x} - \boldsymbol{\alpha})] = \boldsymbol{\Gamma}'Cov[\mathbf{x}]\boldsymbol{\Gamma} \\ &= \boldsymbol{\Gamma}'\boldsymbol{\Sigma}\boldsymbol{\Gamma} = \boldsymbol{\Gamma}'(\boldsymbol{\Gamma}\boldsymbol{\Lambda}\boldsymbol{\Gamma}')\boldsymbol{\Gamma} = \boldsymbol{\Lambda} \end{aligned}$$

- \mathbf{p} is a vector of zero-mean, uncorrelated random variables that provides an *orthogonal basis* for \mathbf{x} .

Principal Components Analysis

m -Variate \mathbf{x} in Principal Components Form

- $\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix} = \boldsymbol{\alpha} + \boldsymbol{\Gamma}\mathbf{p}$, where $E[\mathbf{p}] = \mathbf{0}_m$, $Cov[\mathbf{p}] = \boldsymbol{\Lambda}$
- Partition $\boldsymbol{\Gamma} = [\boldsymbol{\Gamma}_1 \boldsymbol{\Gamma}_2]$ where $\boldsymbol{\Gamma}_1$ corresponds to the K ($< m$) largest eigenvalues of $\boldsymbol{\Sigma}$.
- Partition $\mathbf{p} = \begin{bmatrix} \mathbf{p}_1 \\ \mathbf{p}_2 \end{bmatrix}$ where \mathbf{p}_1 contains the first K elements.
- $\mathbf{x} = \boldsymbol{\alpha} + \boldsymbol{\Gamma}_1 \mathbf{p}_1 + \boldsymbol{\Gamma}_2 \mathbf{p}_2 = \boldsymbol{\alpha} + B\mathbf{f} + \boldsymbol{\epsilon}$

where

$$B = \boldsymbol{\Gamma}_1 \quad (m \times K)$$

$$\mathbf{f} = \mathbf{p}_1 \quad (K \times 1)$$

$$\boldsymbol{\epsilon} = \boldsymbol{\Gamma}_2 \mathbf{p}_2 \quad (m \times 1)$$

Like factor model except $Cov[\boldsymbol{\epsilon}] = \boldsymbol{\Gamma}_2 \boldsymbol{\Lambda}_2 \boldsymbol{\Gamma}_2'$, where $\boldsymbol{\Lambda}_2$ is diagonal matrix of last $(m - K)$ eigenvalues.

Empirical Principal Components Analysis

The principal components analysis of

$$\mathbf{X} = [\mathbf{x}_1 : \cdots : \mathbf{x}_T] \quad (m \times T)$$

consists of the following computational steps:

- Component/row means : $\bar{\mathbf{x}} = \left(\frac{1}{T}\right)\mathbf{X}\mathbf{1}_T$
- 'De-meanned' matrix: $\mathbf{X}^* = \mathbf{X} - \bar{\mathbf{x}}\mathbf{1}'_T$
- Sample covariance matrix: $\hat{\Sigma}_X = \frac{1}{T}\mathbf{X}^*(\mathbf{X}^*)'$
- Eigenvalue/vector decomposition: $\hat{\Sigma}_X = \hat{\Gamma}\hat{\Lambda}\hat{\Gamma}'$
yielding estimates of Γ and Λ .
- Sample Principal Components:

$$\mathbf{P} = [\mathbf{p}_1 : \cdots : \mathbf{p}_T] = \hat{\Gamma}'\mathbf{X}^*. \quad (m \times T)$$

Empirical Principal Components Analysis

PCA Using Singular Value Decomposition

Consider the Singular Value Decomposition (SVD) of the de-meaned matrix:

$$\mathbf{X}^* = \mathbf{V}\mathbf{D}\mathbf{U}'$$

where

- \mathbf{V} : $(m \times m)$ orthogonal matrix, $\mathbf{V}\mathbf{V}' = \mathbf{I}_m$.
- \mathbf{U} : $(m \times T)$ row-orthonormal matrix, $\mathbf{U}\mathbf{U}' = \mathbf{I}_m$.
- \mathbf{D} : $(m \times m)$ diagonal matrix, $\mathbf{D} = \text{diag}(d_1, \dots, d_m)$
with $d_1 \geq d_2 \geq \dots \geq 0$.

Exercise: Show that

- $\hat{\mathbf{\Lambda}} = \frac{1}{T}\mathbf{D}^2$
- $\hat{\mathbf{\Gamma}} = \mathbf{V}$
- $\mathbf{P} = \hat{\mathbf{\Gamma}}'\mathbf{X}^* = \mathbf{D}\mathbf{U}'$

Alternate Definition of PC Variables

Given the m -variate \mathbf{x} : $E[\mathbf{x}] = \boldsymbol{\alpha}$ and $Cov[\mathbf{x}] = \boldsymbol{\Sigma}$

- Define the **First Principal Component Variable** as

$$p_1 = \mathbf{w}'\mathbf{x} = (w_1x_1 + w_2x_2 + \cdots + w_mx_m)$$

where the coefficients $\mathbf{w} = (w_1, w_2, \dots, w_m)'$ are chosen to

$$\text{maximize: } Var(p_1) = \mathbf{w}'\boldsymbol{\Sigma}_x\mathbf{w}$$

$$\text{subject to: } |\mathbf{w}|^2 = \sum_{i=1}^m w_i^2 = 1.$$

- Define the **Second Principal Component Variable** as

$$p_2 = \mathbf{v}'\mathbf{x} = (v_1x_1 + v_2x_2 + \cdots + v_mx_m)$$

where the coefficients $\mathbf{v} = (v_1, v_2, \dots, v_m)'$ are chosen to

$$\text{maximize: } Var(p_2) = \mathbf{v}'\boldsymbol{\Sigma}_x\mathbf{v}$$

$$\text{subject to: } |\mathbf{v}|^2 = \sum_{i=1}^m v_i^2 = 1, \text{ and } \mathbf{v}'\mathbf{w} = 0.$$

- Etc., defining up to p_m , The coefficient vectors are given by

$$[\mathbf{w} : \mathbf{v} : \cdots] = [\gamma_1 : \gamma_2 : \cdots] = \boldsymbol{\Gamma}$$

Principal Components Analysis

Further Details

- PCA provides a decomposition of the **Total Variance**:

$$\begin{aligned}
 \text{Total Variance } (\mathbf{x}) &= \sum_{i=1}^m \text{Var}(\mathbf{x}_i) = \text{trace}(\boldsymbol{\Sigma}_x) \\
 &= \text{trace}(\boldsymbol{\Gamma}\boldsymbol{\Lambda}\boldsymbol{\Gamma}') = \text{trace}(\boldsymbol{\Lambda}\boldsymbol{\Gamma}'\boldsymbol{\Gamma}) = \text{trace}(\boldsymbol{\Lambda}) \\
 &= \sum_{k=1}^m \lambda_k \\
 &= \sum_{k=1}^m \text{Var}(p_k) \\
 &= \text{Total Variance } (\mathbf{p})
 \end{aligned}$$

- The transformation from \mathbf{x} to \mathbf{p} is a change in coordinate system which shifts the origin to the mean/expectation $E[\mathbf{x}] = \boldsymbol{\alpha}$ and rotates the coordinate axes to align with the Principal Component Variables. Distance in the space is preserved (due to orthogonality of the rotation).

Outline

- 1 Factor Models
 - Linear Factor Model
 - Macroeconomic Factor Models
 - Fundamental Factor Models
 - Statistical Factor Models: Factor Analysis
 - Principal Components Analysis
 - **Statistical Factor Models: Principal Factor Method**

Factor Analysis Model

For $\{\mathbf{x}_t, t = 1, \dots, T\}$, the factor model is:

$$\mathbf{x}_t = \boldsymbol{\alpha} + B\mathbf{f}_t + \boldsymbol{\epsilon}_t$$

- $\boldsymbol{\alpha}$ and B are vector/matrix constants.
- All random variables are Normal/Gaussian:
 - \mathbf{x}_t i.i.d. $N_m(\boldsymbol{\alpha}, \boldsymbol{\Sigma}_x)$
 - \mathbf{f}_t i.i.d. $N_K(\mathbf{0}_K, \mathbf{I}_K)$
 - $\boldsymbol{\epsilon}_t$ i.i.d. $N_m(\mathbf{0}_m, \boldsymbol{\Psi})$
- $\text{Cov}(\mathbf{x}_t) = \boldsymbol{\Sigma}_x = BB' + \boldsymbol{\Psi}$

Principal Factor Method of Estimation

To fit a K -factor model with fixed $K < m$, define

$$\mathbf{X} = [\mathbf{x}_1 : \cdots : \mathbf{x}_T] \quad (m \times T)$$

Principal Factor Method of Estimation

Step 1: Conduct the computational steps of principal components analysis:

- Component/row means : $\bar{\mathbf{x}} = (\frac{1}{T})\mathbf{X}\mathbf{1}_T$
- 'De-means' matrix: $\mathbf{X}^* = \mathbf{X} - \bar{\mathbf{x}}\mathbf{1}'_T$
- Sample covariance matrix: $\hat{\Sigma}_x = \frac{1}{T}\mathbf{X}^*(\mathbf{X}^*)'$
- Eigenvalue/vector decomposition: $\hat{\Sigma}_x = \hat{\Gamma}\hat{\Lambda}\hat{\Gamma}'$
yielding estimates of Γ and Λ .

Step 2: Specify initial estimates (index $s = 0$)

- $\tilde{\alpha}_0 = \bar{\mathbf{x}}$
- $\tilde{B}_0 = \hat{\Gamma}^{(K)}(\hat{\Lambda}^{(K)})^{\frac{1}{2}}$, where
 $\hat{\Gamma}^{(K)}$ is submatrix of $\hat{\Gamma}$ (first K columns)
 $\hat{\Lambda}^{(K)}$ is submatrix of $\hat{\Lambda}$ (first K columns)
- $\tilde{\Psi}_0 = \text{diag}(\hat{\Sigma}_x) - \text{diag}(\tilde{B}_0\tilde{B}_0')$
- $\tilde{\Sigma}_0 = \tilde{B}_0\tilde{B}_0' + \tilde{\Psi}_0$

Principal Factor Method of Estimation

Step 3: Adjust the sample covariance matrix to

$$\hat{\Sigma}_x^* = \hat{\Sigma}_x - \tilde{\Psi}_0$$

- Compute the eigenvalue/vector decomposition:

$$\hat{\Sigma}_x^* = \tilde{\Gamma} \tilde{\Lambda} \tilde{\Gamma}'$$

yielding updated estimates of Γ and Λ

- Repeat Step 2 with these new estimates obtaining \tilde{B}_1 , $\tilde{\Psi}_1$, $\tilde{\Sigma}_1 = \tilde{B}_1 \tilde{B}_1' + \tilde{\Psi}_1$

Step 4: Repeat Step 3 generating a sequence of estimates $(\tilde{B}_s, \tilde{\Psi}_s, \tilde{\Sigma}_s)$ $s = 1, 2, \dots$, until successive changes in $\tilde{\Psi}_s$ are sufficiently negligible.

Step 5: Use the estimates from the last iteration in Step 4.

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