

SYMPLECTIC GEOMETRY, LECTURE 15

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1. HODGE THEORY

Theorem 1 (Hodge). *For M a compact Kähler manifold, the deRham and Dolbeault cohomologies are related by $H_{dR}^k(M, \mathbb{C}) = \bigoplus_{p,q} H_{\bar{\partial}}^{p,q}(M)$, with $H^{p,q} \cong \overline{H^{q,p}}$.*

Before we discuss this theorem, we need to go over Hodge theory for a compact, oriented Riemannian manifold (M, g) .

Definition 1. *For V an oriented Euclidean vector space, the Hodge $*$ operator is the linear map $\bigwedge^k V \rightarrow \bigwedge^{n-k} V$ which, for any oriented orthonormal basis e_1, \dots, e_n , maps $e_1 \wedge \dots \wedge e_k \mapsto e_{k+1} \wedge \dots \wedge e_n$.*

Example. For any V , $*(1) = e_1 \wedge \dots \wedge e_n$, and $** = (-1)^{k(n-k)}$.

Applying this to $T_x^* M$, we obtain a map on forms.

Remark. Note that,

$$(1) \quad \forall \alpha, \beta \in \Omega^k, \alpha \wedge * \beta = \langle \alpha, \beta \rangle \cdot \text{vol}$$

Definition 2. *The codifferential is the map*

$$(2) \quad d^* = (-1)^{n(k-1)+1} * d * : \Omega^k(M) \rightarrow \Omega^{k-1}(M)$$

Proposition 1. *d^* is the L^2 formal adjoint to the deRham operator d , i.e. on a compact closed Riemannian manifold, $\forall \alpha \in \Omega^k, \beta \in \Omega^{k+1}$, we have*

$$(3) \quad \langle d\alpha, \beta \rangle_{L^2} = \int_M \langle d\alpha, \beta \rangle d\text{vol} = \langle \alpha, d^* \beta \rangle_{L^2}$$

Proof. This follows from

$$(4) \quad \begin{aligned} \int_M \langle d\alpha, \beta \rangle d\text{vol} &= \int_M d\alpha \wedge * \beta = \int_M d(\alpha \wedge * \beta) - (-1)^k \int_M \alpha \wedge d * \beta \\ &= (-1)^{k+1} \int_M \alpha \wedge d * \beta = (-1)^{k+1} \int_M \alpha \wedge *(* d * \beta) (-1)^{k(n-k)} \\ &= (-1)^{kn+1} \int_M \langle \alpha, * d * \beta \rangle d\text{vol} \end{aligned}$$

□

Example. For \mathbb{R}^n with the standard metric,

$$(5) \quad \alpha = \sum_{I \subset \{1, \dots, n\}} \alpha_I dx_I \implies d\alpha = \sum_j dx_j \wedge \frac{\partial \alpha}{\partial x_j} \text{ and } d^* \alpha = - \sum_j i_{\frac{\partial}{\partial x_j}} \frac{\partial \alpha}{\partial x_j}$$

Definition 3. *The Laplacian is $\Delta = dd^* + d^*d : \Omega^k \rightarrow \Omega^k$.*

Note that, on $\Omega^*(M) = \bigoplus_{k=0}^n \Omega^k(M)$, $\Delta = (d + d^*)^2$. By the adjointness of d and d^* , we see that Δ is a self-adjoint, second order differential operator, i.e. $\langle \Delta \alpha, \beta \rangle_{L^2} = \langle \alpha, \Delta \beta \rangle_{L^2}$. Moreover,

$$(6) \quad \langle \Delta \alpha, \alpha \rangle_{L^2} = \langle dd^* \alpha, \alpha \rangle_{L^2} + \langle d^* d \alpha, \alpha \rangle_{L^2} = \|d^* \alpha\|^2 + \|d\alpha\|^2 \geq 0$$

so $\Delta \alpha = 0 \iff \alpha$ is closed and co-closed.

Definition 4. The space of harmonic forms is the set $\mathcal{H}^k = \{\alpha \in \Omega^k \mid \Delta\alpha = 0\}$.

We have a natural map $\mathcal{H}^k \rightarrow H^k, \alpha \mapsto [\alpha]$.

Theorem 2 (Hodge). For M a compact, oriented Riemannian manifold, every cohomology class has a unique harmonic representative, i.e. $\mathcal{H}^k \cong H^k$, and $\Omega^k(M) = \mathcal{H}^k \oplus_{L^2} d(\Omega^{k-1}) \oplus_{L^2} d^*(\Omega^{k+1})$.

Remark. Clearly $\mathcal{H}^k + d(\Omega^{k-1}) \subset \text{Ker } d = (\text{Im } d^*)^\perp$ and $\mathcal{H}^k + d^*(\Omega^{k+1}) \subset \text{Ker } d^* = (\text{Im } d)^\perp$, implying that the map $\mathcal{H}^k \rightarrow H^k$ is injective. Surjectivity (i.e. existence of harmonic representatives) is more difficult and requires elliptic theory.

Definition 5. A differential operator of order k is a linear map $L : \Gamma(E) \rightarrow \Gamma(F)$ s.t., locally in coordinates,

$$(7) \quad L(s) = \sum_{|\alpha| \leq k} A_\alpha \frac{\partial^{|\alpha|} s}{\partial x^\alpha}$$

where each A_α is a C^∞ function with values in matrices, i.e. a local section of $\text{Hom}(E, F)$. The symbol of L is the map

$$(8) \quad \sigma_k : T_x^* M \ni \xi \mapsto \sum_{|\alpha|=k} A_\alpha(x) \xi_1^{\alpha_1} \cdots \xi_n^{\alpha_n} \in \text{Hom}(E_x, F_x)$$

L is elliptic if for every nonzero ξ , $\sigma(\xi)$ is an isomorphism.

Example. For instance, in local coordinates, the symbol of the Laplacian is given by $\sigma(\xi) = -|\sigma|^2 \cdot \text{id}$.

Now, let L be a differential operator of order k : it extends from $L : C^\infty(E) \rightarrow C^\infty(F)$ to $L_s : W^s(E) \rightarrow W^{s-k}(F)$.

Definition 6. For $L : \Gamma(E) \rightarrow \Gamma(F)$ a differential operator, $P : \Gamma(F) \rightarrow \Gamma(E)$ is called a parametrix (or pseudoinverse) if $L \circ P - \text{id}_E$ and $P \circ L - \text{id}_F$ are smoothing operators, i.e. they extend continuously to $W^s(E) \rightarrow W^{s+1}(E)$.

Using Rellich's lemma on embedding of Sobolev spaces, we find that

Theorem 3. Every elliptic operator has a pseudoinverse.

Corollary 1. $\xi \in W^s(E)$, L is elliptic, and $L\xi \in C^\infty(F) \implies \xi \in C^\infty(E)$.

Proof. Let P be a parametrix. Let $S = P \circ L - I$, so

$$(9) \quad \xi = P \circ L\xi - S\xi$$

Since the former part lies in $C^\infty(E)$ and the latter in $W^{s+1}(E)$, we have that $\xi \in W^{s+1}(E)$. Iterating, $\xi \in C^\infty(E)$. \square