

## 18.303 Problem Set 2

Due Monday, 22 September 2014.

### Problem 2: Modified inner products for column vectors

Consider the inner product  $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^* B \mathbf{y}$  from class (lecture 5.5 notes), where the vectors are in  $\mathbb{C}^N$  and  $B$  is an  $N \times N$  Hermitian positive-definite matrix.

- Show that this inner product satisfies the required properties of inner products from class:  $\langle \mathbf{x}, \mathbf{y} \rangle = \overline{\langle \mathbf{y}, \mathbf{x} \rangle}$ ,  $\langle \mathbf{x}, \mathbf{x} \rangle > 0$  except for  $\mathbf{x} = 0$ . (Linearity  $\langle \mathbf{x}, \alpha \mathbf{y} + \mathbf{z} \rangle = \alpha \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{x}, \mathbf{z} \rangle$  is obvious from linearity of the of matrix operations; you need not show it.)
- If  $M$  is an arbitrary (possibly complex)  $N \times N$  matrix, define the adjoint  $M^\dagger$  by  $\langle \mathbf{x}, M \mathbf{y} \rangle = \langle M^\dagger \mathbf{x}, \mathbf{y} \rangle$  (for all  $\mathbf{x}, \mathbf{y}$ ). (In this problem, we use  $\dagger$  instead of  $*$  for the adjoint in order to avoid confusion with the conjugate transpose: for this inner product, the adjoint  $M^\dagger$  is *not* the conjugate transpose  $M^* = \overline{M^T}$ .) Give an explicit formula for  $M^\dagger$  in terms of  $M$  and  $B$ .
- Using your formula from above, show that  $M^\dagger = M$  (i.e.,  $M$  is self-adjoint/Hermitian for *this* inner product) if  $M = B^{-1}A$  for some  $A = A^*$ .

### Problem 2: Finite-difference approximations

For this question you may find it helpful to refer to the notes and readings from lecture 3. Suppose that we want to compute the operation

$$\hat{A}u = \frac{d}{dx} \left[ c \frac{du}{dx} \right]$$

for some smooth function  $c(x)$  (you can assume  $c$  has a convergent Taylor series everywhere). Now, we want to construct a finite-difference approximation for  $\hat{A}$  with  $u(x)$  on  $\Omega = [0, L]$  and Dirichlet boundary conditions  $u(0) = u(L) = 0$ , similar to class, approximating  $u(m\Delta x) \approx u_m$  for  $M$  equally spaced points  $m = 1, 2, \dots, M$ ,  $u_0 = u_{M+1} = 0$ , and  $\Delta x = \frac{L}{M+1}$ .

- Using center-difference operations, construct a finite-difference approximation for  $\hat{A}u$  evaluated at  $m\Delta x$ . (Hint: use a centered first-derivative evaluated at grid points  $m + 0.5$ , as in class, followed by multiplication by  $c$ , followed by another centered first derivative. Do *not* separate  $\hat{A}u$  by the product rule into  $c'u' + cu''$  first, as that will make the factorization in part (d) more difficult.)
- Show that your finite-difference expressions correspond to approximating  $\hat{A}u$  by  $A\mathbf{u}$  where  $\mathbf{u}$  is the column vector of the  $M$  points  $u_m$  and  $A$  is a real-symmetric matrix of the form  $A = -D^T C D$  (give  $C$ , and show that  $D$  is the same as the 1st-derivative matrix from lecture).
- In Julia, the `diagm(c)` command will create a diagonal matrix from a vector `c`. The function `diff1(M) = [ [1.0 zeros(1,M-1)]; diagm(ones(M-1),1) - eye(M) ]` will allow you to create the  $(M+1) \times M$  matrix  $D$  from class via `D = diff1(M)` for any given value of  $M$ . Using these two commands, construct the matrix  $A$  from part (d) for  $M = 100$  and  $L = 1$  and  $c(x) = e^{3x}$  via

```
L = 1
M = 100
D = diff1(M)
dx = L / (M+1)
x = dx*0.5:dx:L # sequence of x values from 0.5*dx to <= L in steps of dx
C = ...something from c(x)...hint: use diagm...
```

$$A = -D' * C * D / dx^2$$

You can now get the eigenvalues and eigenvectors by  $\lambda, U = \text{eig}(A)$ , where  $\lambda$  is an array of eigenvalues and  $U$  is a matrix whose columns are the corresponding eigenvectors (notice that all the  $\lambda$  are  $< 0$  since  $A$  is negative-definite).

- (i) Plot the eigenvectors for the smallest-magnitude four eigenvalues. Since the eigenvalues are negative and are sorted in increasing order, these are the *last* four columns of  $U$ . You can plot them with:
- ```
using PyPlot
plot(dx:dx:L-dx, U[:,end-3:end])
xlabel("x"); ylabel("eigenfunctions")
legend(["fourth", "third", "second", "first"])
```

- (ii) Verify that the first two eigenfunctions are indeed orthogonal with `dot(U[:,end], U[:,end-1])` in Julia, which should be zero up to roundoff errors  $\lesssim 10^{-15}$ .
- (iii) Verify that you are getting second-order convergence of the eigenvalues: compute the smallest-magnitude eigenvalue  $\lambda_M[\text{end}]$  for  $M = 100, 200, 400, 800$  and check that the *differences* are decreasing by roughly a factor of 4 (i.e.  $|\lambda_{100} - \lambda_{200}|$  should be about 4 times larger than  $|\lambda_{200} - \lambda_{400}|$ , and so on), since doubling the resolution should multiply errors by 1/4.

- (d) For  $c(x) = 1$ , we saw in class that the eigenfunctions are  $\sin(n\pi x/L)$ . How do these compare to the eigenvectors you plotted in the previous part? Try changing  $c(x)$  to some other function (note: still needs to be real and  $> 0$ ), and see how different you can make the eigenfunctions from  $\sin(n\pi x/L)$ . Is there some feature that always remains similar, no matter how much you change  $c$ ?

### Problem 3: Discrete diffusion

In this problem, you will examine thermal conduction in a system of a finite number  $N$  of pieces, and then take the  $N \rightarrow \infty$  limit to recover the heat equation. In particular:

- You have a metal bar of length  $L$  and cross-sectional area  $a$  (hence a volume  $La$ ), with a varying temperature  $T$  along the rod. We conceptually subdivide the rod into  $N$  (touching) pieces of length  $\Delta x = L/N$ .
- If  $\Delta x$  is small, we can approximate each piece as having a uniform temperature  $T_n$  within the piece ( $n = 1, 2, \dots, N$ ), giving a vector  $\mathbf{T}$  of  $N$  temperatures.
- Suppose that the rate  $q$  (in units of W) at which heat flows across the boundary from piece  $n$  to piece  $n + 1$  is given by  $q = \frac{\kappa a}{\Delta x}(T_n - T_{n+1})$ , where  $\kappa$  is the metal's *thermal conductivity* (in units of W/m·K). That is, piece  $n$  *loses* energy at a rate  $q$ , and piece  $n + 1$  *gains* energy at the same rate, and the heat flows faster across bigger areas, over shorter distances, or for larger temperature differences. Note that  $q > 0$  if  $T_n > T_{n+1}$  and  $q < 0$  if  $T_n < T_{n+1}$ : heat flows from the hotter piece to the cooler piece.
- If an amount of heat  $\Delta Q$  (in J) flows into a piece, its temperature changes by  $\Delta T = \Delta Q / (c\rho a\Delta x)$ , where  $c$  is the specific heat capacity (in J/kg·K) and  $\rho$  is the density (kg/m<sup>3</sup>) of the metal.
- The rod is insulated: no heat flows out the sides or through the ends.

Given these assumptions, you should be able to answer the following:

- (a) “Newton’s law of cooling” says that the temperature of an object changes at a rate (K/s) proportional to the temperature difference with its surroundings. Derive the equivalent here: show that our assumptions above imply that  $\frac{dT_n}{dt} = \alpha(T_{n+1} - T_n) + \alpha(T_{n-1} - T_n)$  for some constant  $\alpha$ , for  $1 < n < N$ . Also give the (slightly different) equations for  $n = 1$  and  $n = N$ .
- (b) Write your equation from the previous part in matrix form:  $\frac{d\mathbf{T}}{dt} = A\mathbf{T}$  for some matrix  $A$ .
- (c) Let  $T(x, t)$  be the temperature along the rod, and suppose  $T_n(t) = T([n - 0.5]\Delta x, t)$  (the temperature at the *center* of the  $n$ -th piece). Take the limit  $N \rightarrow \infty$  (with  $L$  fixed, so that  $\Delta x = L/N \rightarrow 0$ ), and derive a partial differential equation  $\frac{\partial T}{\partial t} = \hat{A}T$ . What is  $\hat{A}$ ? (Don’t worry about the  $x = 0, L$  ends until the next part.)
- (d) What are the boundary conditions on  $T(x, t)$  at  $x = 0$  and  $L$ ? Check that if you go backwards, and form a center-difference approximation of  $\hat{A}$  with these boundary conditions, that you recover the matrix  $A$  from above.
- (e) How does your  $\hat{A}$  change in the  $N \rightarrow \infty$  limit if the conductivity is a function  $\kappa(x)$  of  $x$ ?
- (f) Suppose that instead of a thin metal bar (1d), you have an  $L \times L$  thin metal *plate* (2d), with a temperature  $T(x, y, t)$  and a constant conductivity  $\kappa$ . If you go through the steps above dividing it into  $N \times N$  little squares of size  $\Delta x \times \Delta y$ , what PDE do you get for  $T$  in the limit  $N \rightarrow \infty$ ? (Many of the steps should be similar to above.)

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