

MIT OpenCourseWare
<http://ocw.mit.edu>

18.085 Computational Science and Engineering I
Fall 2008

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.

Your name is: _____

Grading 1.
2.
3.
4.

OPEN BOOK EXAM

Write solutions onto these pages!

Circles around short answers please!!

1) (32 pts.) This problem is about the symmetric matrix

$$H = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

- (a) By elimination find the triangular L and diagonal D in $H = LDL^T$.
- (b) What is the smallest number q that could replace the corner entry $H_{33} = 1$ and still leave H positive *semidefinite*? $q = \underline{\hspace{2cm}}$
- (c) H comes from the 3-step framework for a hanging line of springs:
 displacements \xrightarrow{A} elongations \xrightarrow{C} spring forces $\xrightarrow{A^T}$ external force f
 What are the specific matrices A and C in $H = A^T C A$?
- (d) What are the requirements on any m by n matrix A and any symmetric matrix C for $A^T C A$ to be positive definite?

2) (24 pts.) Suppose we make three measurements b_1, b_2, b_3 at times t_1, t_2, t_3 . They would fit exactly on a straight line $b = C + Dt$ if we could solve

$$C + Dt_1 = b_1$$

$$C + Dt_2 = b_2$$

$$C + Dt_3 = b_3.$$

(a) If b_1, b_2, b_3 are equally reliable **what are the equations** for the best values \hat{C} and \hat{D} ? *Don't solve the equations—write them in terms of t 's and b 's (not just some letter A).*

(b) Suppose the errors in b_1, b_2, b_3 are independent with variances $\sigma_1^2, \sigma_2^2, \sigma_3^2$ (covariances = 0 because independent). **Find the new equations for the best \hat{C} and \hat{D} .** Use t 's, b 's and $c_i = 1/\sigma_i^2$ —by method ① or ②

① Remember how the covariance matrix Σ (called V in the book) enters the equations

② Divide the three equations above by $\sigma_1, \sigma_2, \sigma_3$. Then do ordinary least squares because the rescaled errors have variances = 1.

(c) Suppose $\sigma_1 = 1, \sigma_2 = 1$, but $\sigma_3 \rightarrow \infty$ so the third measurement is (*exactly reliable*) (*totally unreliable*) **CROSS OUT ONE.**

In this case the best straight line goes through which points?

- 3) (20 pts.) (a) Suppose $\frac{du}{dx}$ is approximated by a *centered* difference:

$$\frac{du}{dx} \approx \frac{u(x + \Delta x) - u(x - \Delta x)}{2 \Delta x}$$

With equally spaced points $x = h, 2h, 3h, 4h, 5h = \frac{1}{6}, \frac{2}{6}, \frac{3}{6}, \frac{4}{6}, \frac{5}{6}$ and zero boundary conditions $u_0 = u_6 = 0$, write down the 3 by 3 centered first difference matrix Δ :

$$(\Delta u)_i = \frac{u_{i+1} - u_{i-1}}{2h}.$$

Show that this matrix Δ is *singular* (because 3 is odd) by solving $\Delta u = 0$.

- (b) Removing the last row and column of a positive definite matrix K always leaves a positive definite matrix L . Why? Explain using one of the tests for positive definiteness.

XXX

4) (24 pts.) The equation to solve is $-u'' + u = \delta(x - \frac{1}{2})$ with a unit point load at $x = \frac{1}{2}$ and zero boundary conditions $u(0) = u(1) = 0$.

(a) Solve $-u'' - u = 0$ starting from $x = 0$ with $u(0) = 0$. There will be one arbitrary constant A . Replace x by $1 - x$ in your answer, to solve $-u'' - u = 0$ ending at $u(1) = 0$ with arbitrary constant B .

(b) Use the “jump conditions” at $x = \frac{1}{2}$ to find A and B .

XXXX