

## Repeated Eigenvalues

### 1. Repeated Eigenvalues

Again, we start with the real  $2 \times 2$  system

$$\dot{\mathbf{x}} = A\mathbf{x}. \quad (1)$$

We say an eigenvalue  $\lambda_1$  of  $A$  is **repeated** if it is a multiple root of the characteristic equation of  $A$ ; in our case, as this is a quadratic equation, the only possible case is when  $\lambda_1$  is a double real root.

We need to find two linearly independent solutions to the system (1). We can get one solution in the usual way. Let  $\mathbf{v}_1$  be an eigenvector corresponding to  $\lambda_1$ . This is found by solving the system

$$(A - \lambda_1 I)\mathbf{a} = \mathbf{0}. \quad (2)$$

This gives the solution  $\mathbf{x}_1 = e^{\lambda_1 t}\mathbf{v}_1$  to the system (1). Our problem is to find a second solution. To do this we have to distinguish two cases, called complete and defective. The first one is easier, especially in the  $2 \times 2$  case.

#### A. The complete case.

Still assuming  $\lambda_1$  is a real double root of the characteristic equation of  $A$ , we say  $\lambda_1$  is a **complete** eigenvalue if there are two linearly independent eigenvectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  corresponding to  $\lambda_1$ ; i.e., if these two vectors are two linearly independent solutions to the system (2).

In the  $2 \times 2$  case, this only occurs when  $A$  is a *scalar matrix* that is, when  $A = \lambda_1 I$ . In this case,  $A - \lambda_1 I = \mathbf{0}$ , and every vector is an eigenvector. It is easy to find two independent solutions; the usual choices are

$$e^{\lambda_1 t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad e^{\lambda_1 t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

So the general solution is

$$c_1 e^{\lambda_1 t} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 e^{\lambda_1 t} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = e^{\lambda_1 t} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}.$$

Of course, we could choose any other pair of independent eigenvectors to generate the solutions, e.g.,

$$e^{\lambda_1 t} \begin{pmatrix} 5 \\ 1 \end{pmatrix} \quad \text{and} \quad e^{\lambda_1 t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

**Remark.** For  $n = 3$  and above the situation is more complicated. We will not discuss it here. The interested reader can consult, for instance, the textbook by Edwards and Penney.

### B. The defective case.

If the eigenvalue  $\lambda$  is a double root of the characteristic equation, but the system (2) has only one non-zero solution  $\mathbf{v}_1$  (up to constant multiples), then the eigenvalue is said to be **incomplete** or **defective** and  $\mathbf{x}_1 = e^{\lambda_1 t} \mathbf{v}_1$  is the unique normal mode. However, a second order system needs two independent solutions. Our experience with repeated roots in second order ODE's suggests we try multiplying our normal solution by  $t$ . It turns out this doesn't quite work, but it can be fixed as follows: a second independent solution is given by

$$\mathbf{x}_2 = e^{\lambda_1 t}(t\mathbf{v}_1 + \mathbf{v}_2). \quad (3)$$

where  $\mathbf{v}_2$  is any vector satisfying

$$(A - \lambda_1 I) \mathbf{v}_2 = \mathbf{v}_1.$$

(You can easily, if tediously, check by substitution that this does give a solution. You need to remember that  $A\mathbf{v}_1 = \lambda_1 \mathbf{v}_1$ .)

**Fact.** The equation for  $\mathbf{v}_2$  is guaranteed to have a solution, provided that the eigenvalue  $\lambda_1$  really is defective. When solving for  $\mathbf{v}_2 = (b_1, b_2)^T$ , try setting  $b_1 = 0$ , and solving for  $b_2$ . If that does not work, try setting  $b_2 = 0$  and solving for  $b_1$ .

**Remarks 1.** Some people do not bother with (3). When they encounter the defective case (at least when  $n = 2$ ), they give up on eigenvalues, and simply solve the original system (1) by elimination.

2. Although we will not go into it in this course, there is a well developed theory of defective matrices which gives insight into where this formula comes from. You will learn about all this when you study linear algebra.

We will now do a worked example.

## 2. Worked example: Defective Repeated Eigenvalue

**Problem.** Solve  $\dot{\mathbf{u}} = A\mathbf{u}$ , where  $A = \begin{pmatrix} -2 & 1 \\ -1 & 0 \end{pmatrix}$ .

*Comments are given in italics.*

**Solution.**

Step 0. Write down  $A - \lambda I$ :  $A - \lambda I = \begin{pmatrix} -2 - \lambda & 1 \\ -1 & -\lambda \end{pmatrix}$ .

Step 1. Find the characteristic equation of  $A$ :

$\text{tr}(A) = -2 + 0 = -2$ ,  $\det(A) = -2 \times 0 - 1 \times (-1) = 1$ . Thus,

$$p_A(\lambda) = \det(A - \lambda I) = \lambda^2 - \text{tr}(A)\lambda + \det(A) = \lambda^2 + 2\lambda + 1 = 0.$$

Step 2. Find the eigenvalues of  $A$ .

The characteristic polynomial factors:  $p_A(\lambda) = (\lambda + 1)^2$ . This has a repeated root,  $\lambda_1 = -1$ .

As the matrix  $A$  is not the identity matrix, we must be in the defective repeated root case.

Step 3. Find an eigenvector.

This is vector  $\mathbf{v}_1 = (a_1, a_2)^T$  that must satisfy:

$$\begin{aligned} (A + I)\mathbf{v}_1 = 0 &\Leftrightarrow \begin{pmatrix} -2+1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \\ &\Leftrightarrow \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}. \end{aligned}$$

*Check: this gives two identical equations, which is good.*

The equation is  $-a_1 + a_2 = 0$ . Setting  $a_1 = 1$  gives  $a_2 = 1$ . Thus, one eigenvector for  $\lambda_1$  is  $\mathbf{v}_1 = (1, 1)^T$ . All other eigenvectors for  $\lambda_1$  are multiples of this.

Step 4. Find  $\mathbf{v}_2$ : This vector  $\mathbf{v}_2 = (b_1, b_2)^T$  must satisfy

$$(A - \lambda_1 I)\mathbf{v}_2 = \mathbf{v}_1 \Leftrightarrow \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Leftrightarrow -b_1 + b_2 = 1.$$

Setting  $b_1 = 0$  gives  $b_2 = 1$ ; so  $\mathbf{v}_2 = (0, 1)^T$  is suitable.

Step 5. General solution.

The general solution is

$$\mathbf{u}(t) = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 (t e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{-t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}) = e^{-t} \left( c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1+t \\ 1+2t \end{pmatrix} \right).$$

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