## 18.03 Recitation 21, April 27, 2010

## First order linear systems

**Vocabulary/Concepts:** system of differential equations; linear, time-independent, homogeneous; matrix, matrix multiplication; solution, trajectory, phase portrait; companion matrix.

11. Practice in matrix multiplication: Compute the following products:

$$\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}, \qquad \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} x & y \end{bmatrix}, \qquad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}, \qquad \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x & u \\ y & v \end{bmatrix}.$$
$$[x+2y], \begin{bmatrix} x & y \\ 2x & 2y \end{bmatrix}, \begin{bmatrix} ax+by \\ cx+dy \end{bmatrix}, \begin{bmatrix} x+2y & u+2v \\ 3x+4y & 3u+4v \end{bmatrix}.$$

**2.** Multiplying by a matrix  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  sends a vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  to another vector  $A \begin{bmatrix} x \\ y \end{bmatrix}$ . This operation can be visualized by thinking about where it sends the square with corners  $\mathbf{0} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{i} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{j} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ,  $\mathbf{i} + \mathbf{j} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

For each of the following matrices A, draw segments connecting the dots  $\mathbf{0}$ ,  $A\mathbf{i}$ ,  $A(\mathbf{i}+\mathbf{j})$ ,  $A\mathbf{j}$ ,  $\mathbf{0}$ , and invent verbal description or name for the operation.

$$A = \left[ \begin{array}{cc} 1 & 0 \\ 0 & 2 \end{array} \right], \quad A = \left[ \begin{array}{cc} 1 & 1 \\ 0 & 1 \end{array} \right], \quad A = \left[ \begin{array}{cc} 1 & 0 \\ 0 & -1 \end{array} \right], \quad A = \left[ \begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array} \right], \quad A = \left[ \begin{array}{cc} 1 & 1 \\ 1 & -1 \end{array} \right].$$

 $A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ : holding x-direction unchanged, but lengthening y-direction by a factor of 2.

 $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ : holding the bottom two vertices on x-axis fixed, but moving the upper two vertices hortizontally to the right by unit 1.

 $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ : keeping the dimensions unchanged, but being reflected with respect to x-axis..

 $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ : keeping the dimensions unchanged, but being reflected with respect to the line y = x.

 $A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ : holding the vertex at the origin fixed, first rotating the square 45 degrees clockwise, then flipping it with respect to x-axis, and finally streching the four sides to the length of  $\sqrt{2}$ .

**3.** What is the companion matrix A of the second order equation  $\ddot{x} + 2\dot{x} + 2x = 0$ ? Find two independent real solutions of this second order equation. Let  $x_1(t)$  denote the solution with initial condition  $x_1(0) = 0$ ,  $\dot{x}_1(0) = 1$ . Find it, and then write down the corresponding solution  $\mathbf{u}_1(t) = \begin{bmatrix} x_1(t) \\ \dot{x}_1(t) \end{bmatrix}$  of the equation  $\dot{\mathbf{u}} = A\mathbf{u}$ . What is  $\mathbf{u}_1(0)$ ? Sketch the graphs of  $x_1(t)$  and of  $\dot{x}_1(t)$ , and sketch the trajectory of the solution  $\mathbf{u}_1(t)$ . Compare these pictures.

Sketch a few more trajectories to fill out the phase portrait. In particular sketch the trajectory of  $\mathbf{u_2}(t)$  with  $\mathbf{u_2}(0) = \mathbf{i}$ .

When trajectories of this companion equation cross the x axis, at what angle do they cross it?

The companion matrix is  $\begin{bmatrix} 0 & 1 \\ -2 & -2 \end{bmatrix}$ . The characteristic polynomial is  $p(s) = s^2 + 2s + 2$  with roots  $s = -1 \pm i$ , so two independent complex solutions are  $e^{(-1+i)t}$  and  $e^{(-1-i)t}$ . We can combine them to form independent real solutions  $e^{-t}\cos t$  and  $e^{-t}\sin t$ . Considering the given initial condition, we choose  $x_1(t) = e^{-t}\sin t$ , so  $\mathbf{u}_1(t) = \begin{bmatrix} e^{-t}\sin t \\ e^{-t}(\cos t - \sin t) \end{bmatrix}$ .

 $x_1$  has envelope  $\pm e^{-t}$ , which decays exponentially. The graph of  $x_1$  oscillates inside the envelope, and it touches the envelope at odd multiples of  $\pi/2$ .  $\dot{x}_1$  has envelope  $\pm\sqrt{2}e^t$ , and the graph touches the envelope when t has the form  $\frac{4k-1}{4}\pi$ . The trajectory is an inward spiral, elongated in the northwest-southeast direction. When trajectories cross the x axis, they cross at an angle of  $\pi/2$ .

**4.** Let a + bi be a general complex number. There is a matrix A such that if (a + bi)(x + yi) = (v + wi) then

$$A\left[\begin{array}{c} x \\ y \end{array}\right] = \left[\begin{array}{c} v \\ w \end{array}\right]$$

Find it. What is it for a + bi = 2? For a + bi = i? For a + bi = 1 + i? Draw the parallelograms discussed in (2) for these matrices.

We have v=ax-by, w=ay+bx, so  $A=\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ . For a+bi=2,  $A=\begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$ , and the parallelogram is a square of length 2. For a+bi=i,  $A=\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ , and the parallelogram is a square of length 1, rotated by 90 degrees counterclockwise around the origin. For a+bi=1+i,  $A=\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$ , and the parallelogram is a square of length  $\sqrt{2}$ , rotated by 45 degrees counterclockwise around the origin.

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