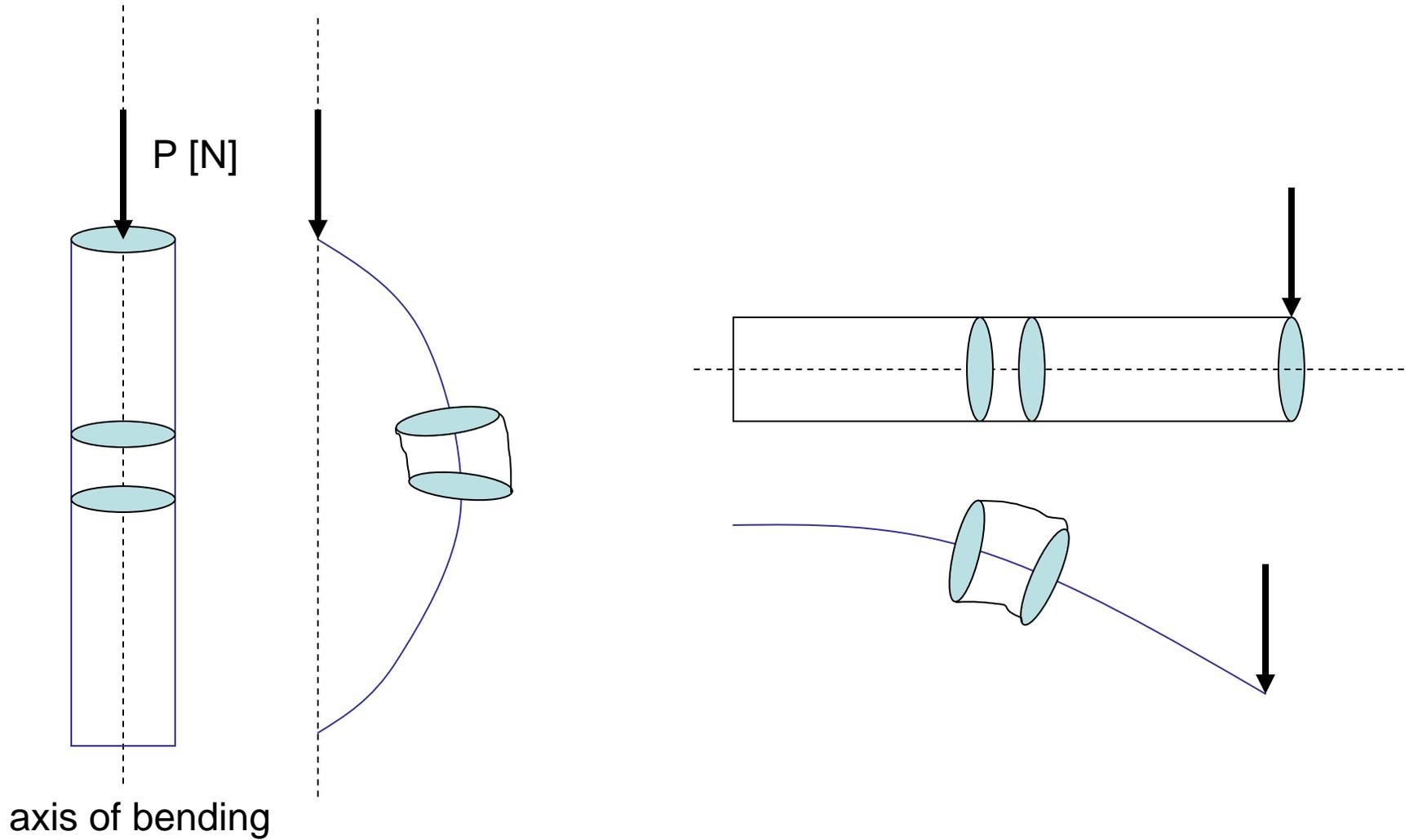


# Which cross-section do I choose for moment of inertia, $I$ ?

In equilibrium, the beam resists any bending due to applied loads, so we choose the cross-section that is perpendicular to the axis of that intended bending:



# What is the moment of inertia ...and why are there multiple $I_x$ in Appendix D?

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Strictly speaking, we mean the **area moment of inertia**, which relates to the resistance of that area to bending. It is also called the second moment of inertia or the second moment of area about the x-axis, taken over the tiny area  $dA$ , where  $y$  is the distance from the x-axis to  $dA$ :

$$I_x = \int y^2 dA$$

Appendix D from Bedford/Liechti in your 3.032 Course Reader (p. 1-28) doesn't annotate this well, and for some cross-sections like a rectangle gives  $I_x$  and  $I_x'$ . Both are area moments of inertia, but differ depending on whether they assume the x-axis is located along the centroid ( $x'$ ) or located at the bottom of the shape ( $x$ ).

Neither is "incorrect", but if we assume that the cross-section is made of a homogeneous material, we typically take this moment about the centroid or center of mass. In other words, the  $I_x'$  in this appendix are the more standard expressions.

Here is simpler table of centroids and area moments of inertia for solid cross-sections, and also for a hollow cylinder:

