

Lecture 32

Unstable Solutions

Last Time

Other Types of Phase Diagrams

Models for Solutions

Limiting Behavior for Dilute and nearly Pure Solutions

Non-Ideal Solution Behavior

In this section, a simple model for the enthalpy of mixing will be derived. It will be shown that a positive enthalpy of mixing tends to make a system separate and have a miscibility gap at low temperature. A negative enthalpy of mixing tends to favor stable homogeneous solutions.

Consider two neighbors in a solution. The probability that one of the neighbors is an A -type or a B -type is simply:

$$\pi_A = \frac{N_A}{N_A + N_B} = X_A \quad \text{and} \quad \pi_B = \frac{N_B}{N_A + N_B} = X_B \quad (32-1)$$

Therefore the probability that a given “bond” is an A - B type is:

$$\pi_{(AB)} = \pi_{AB} + \pi_{BA} = \frac{2N_A N_B}{(N_A + N_B)^2} = 2X_A X_B \quad (32-2)$$

If each atom has z nearest neighbors, the number of bonds, total, is

$$B^{\text{total}} = \frac{z}{2}(N_A + N_B) \implies \overline{B^{\text{total}}} = \frac{z}{2} \quad (32-3)$$

The bond density of A - B type is therefore:

$$\overline{B_{(AB)}} = zX_A X_B \quad (32-4)$$

If the energy per $A - B$ bond is ω_{AB} ³¹ then the enthalpy density (due to the A - B bonds) is:

$$\overline{H_{(AB)}^{\mathcal{RS}}} = z\omega_{AB}X_A X_B \quad (32-5)$$

Similarly, the bond density of A -types is $\overline{B_{AA}} = \frac{z}{2}X_A X_A$ so that $\overline{H_{AA}} = \frac{z}{2}X_A^2\omega_{AA}$. Similarly $\overline{H_{BB}} = \frac{z}{2}X_B^2\omega_{BB}$.

Putting this all together

$$\overline{H^{\text{total}}^{\mathcal{RS}}} = z(\omega_{AB}X_A X_B + \frac{\omega_{AA}}{2}X_A^2 + \frac{\omega_{BB}}{2}X_B^2) \quad (32-6)$$

$$\overline{H^{\text{total}}^{\mathcal{UM}}} = \frac{z\omega_{AA}}{2}X_A + \frac{z\omega_{BB}}{2}X_B \quad (32-7)$$

Therefore since, $\Delta\overline{H_{\text{mixing}}} = \overline{H^{\text{sol}}} - \overline{H^{\text{pure mix}}}$:

$$\begin{aligned} \overline{\Delta H^{\mathcal{RS}}} &= \frac{z}{2}X_A X_B(2\omega_{AB} - \omega_{AA} - \omega_{BB}) \\ &\equiv \frac{z}{2}X_A X_B \omega^{\mathcal{RS}} \end{aligned} \quad (32-8)$$

$$\begin{aligned} \overline{\Delta G^{\mathcal{RS}}} &= \overline{\Delta H^{\mathcal{RS}}} - T\overline{\Delta S^{\mathcal{TS}}} \\ &= \frac{z}{2}X_A X_B \omega^{\mathcal{RS}} - T[(-R)(X_A \log X_A + X_B \log X_B)] \end{aligned} \quad (32-9)$$

This is the *Regular Solution Model*

³¹relative to no bond having zero energy, i.e., $\omega_{AB} < 0$ is more stable.

Behavior of the Regular Solution Model

Above, a “first-order” correction to the ideal solution model based on an atomic averaging for the enthalpy of mixing.

This is called the regular solution model.

$$\overline{\Delta G^{\mathcal{RS}}} = \overline{\Delta H^{\mathcal{RS}}} - T\overline{\Delta S^{\mathcal{TS}}} \quad (32-10)$$

where

$$\overline{\Delta H^{\mathcal{RS}}} = \frac{z}{2}X_A X_B(2\omega_{AB} - \omega_{AA} - \omega_{BB}) = \frac{z}{2}X_A X_B \omega^{\mathcal{RS}} \quad (32-11)$$

and

$$\overline{\Delta S^{\mathcal{TS}}} = -R(X_A \log X_A + X_B \log X_B) \quad (32-12)$$

Consider both terms:

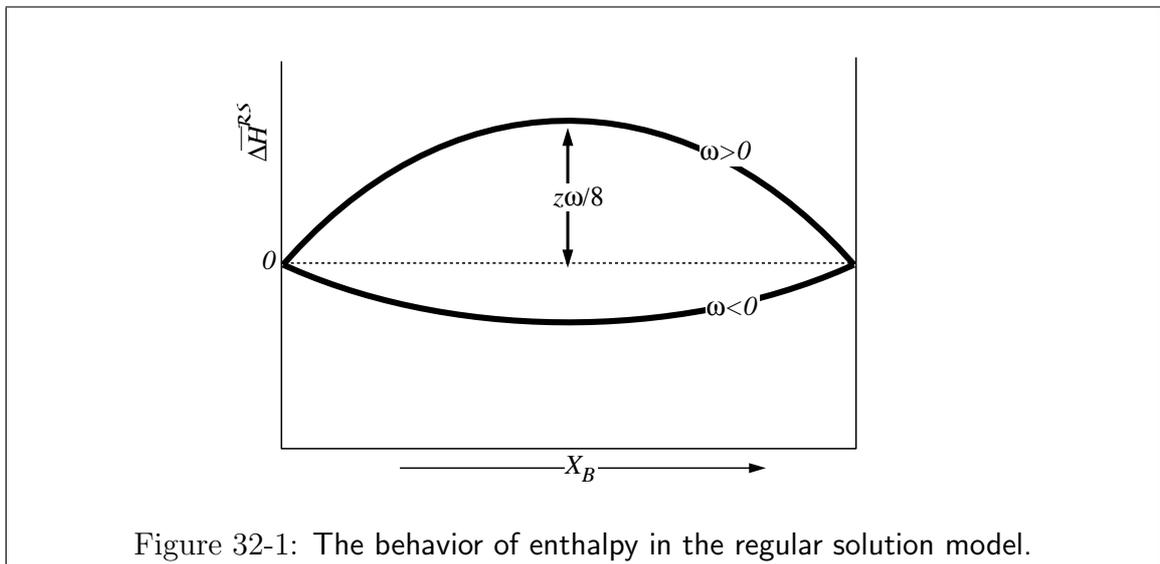
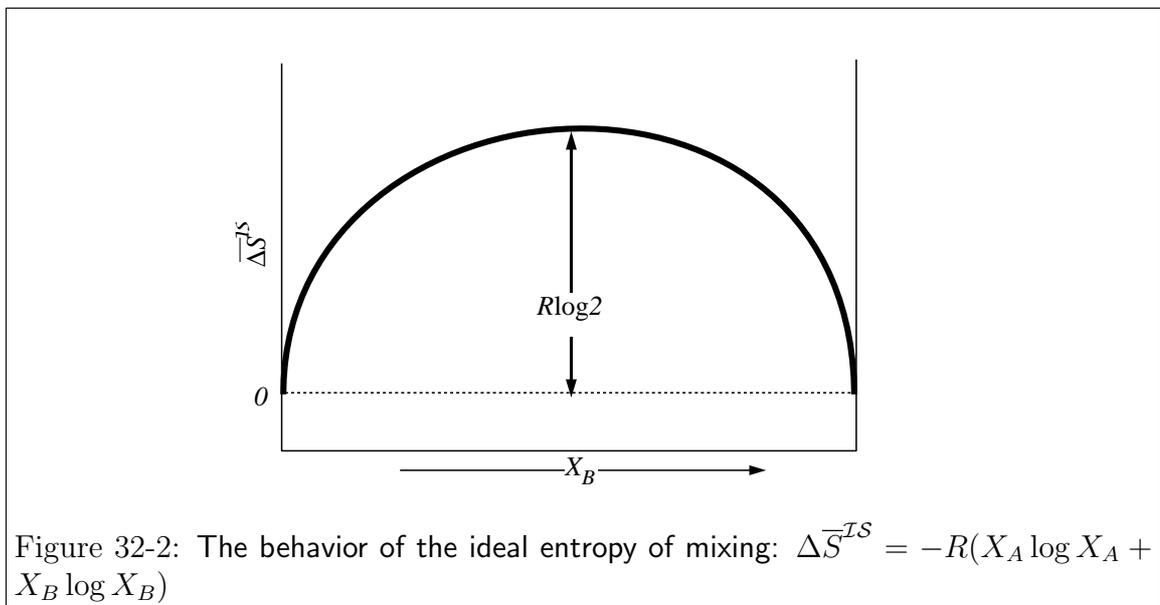
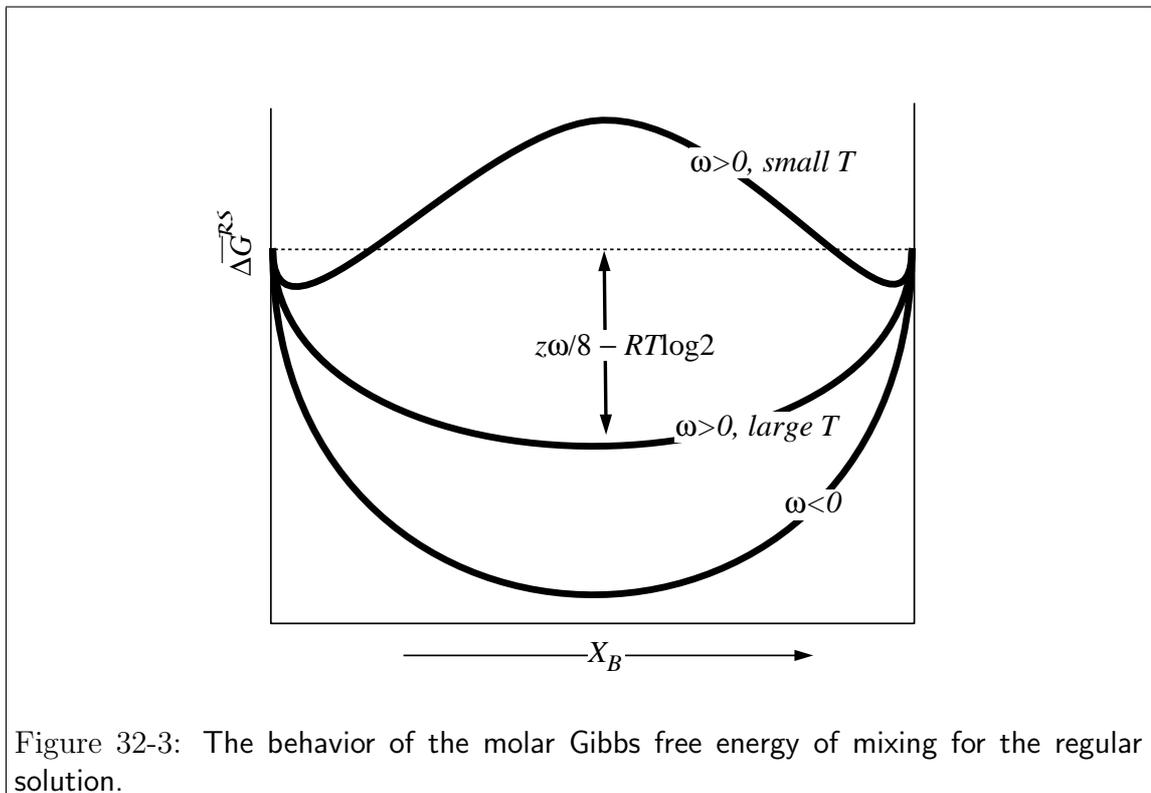


Figure 32-1: The behavior of enthalpy in the regular solution model.

Note that $\omega < 0$ favors mixing, and makes sense because ω_{AB} is more negative than $\langle \omega_{AA} + \omega_{BB} \rangle$.



So that, taken together: $\Delta \bar{G}^{mix} = \Delta \bar{H}^{mix} - T \Delta \bar{S}^{mix}$:



Note that the limiting behavior for pure or extremely dilute solutions is dictated by:

$$\lim_{x \rightarrow 0} \frac{\partial \Delta G^{\text{mixing}}}{\partial x} = -\infty \quad (32-13)$$

A solution can *always* lower its free energy by dissolving at least a small amount component. There is *thermodynamically always some finite solubility* (but it can be, and often is, very, very small). This implies that the width of a single-phase region must always be finite.

Consider the case where $\omega > 0$, so the system will tend to “unmix” at low temperatures.

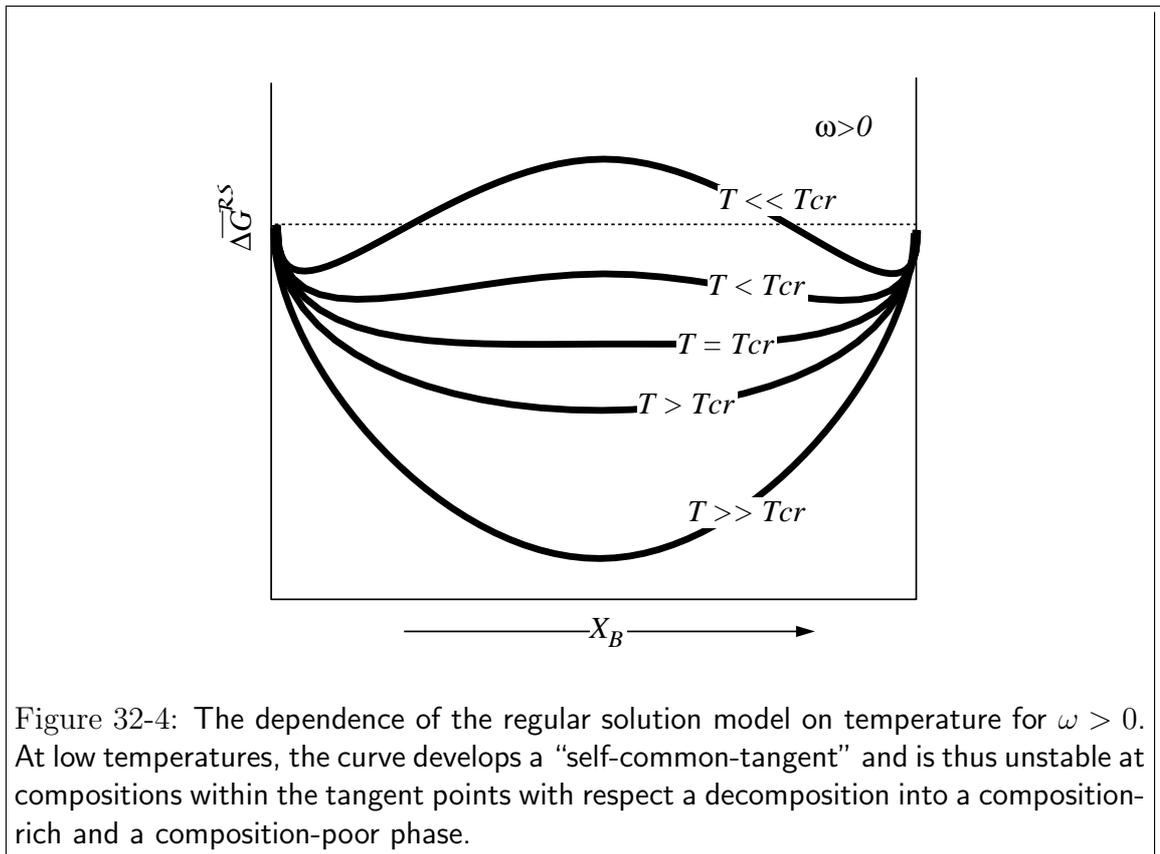


Figure 32-4: The dependence of the regular solution model on temperature for $\omega > 0$. At low temperatures, the curve develops a “self-common-tangent” and is thus unstable at compositions within the tangent points with respect a decomposition into a composition-rich and a composition-poor phase.

For the case of a regular solution, the curve is symmetric around $X = 1/2$, and in this case we can calculate the positions of the common tangents:³²

$$\frac{\partial \Delta \bar{G}^{\text{RS}}}{\partial x} = \frac{z\omega}{2} - z\omega X_B + RT[(1 + \log X_B) + (-1 - \log(1 - X_B))] = 0 \quad (32-14)$$

However, this is hard to solve (see Equation 32-15).

The critical temperature can be determined analytically by noting that as the common tangents form that the curvature changes sign at $X_B = 1/2$.

$$\begin{aligned} \Delta \bar{G}^{\text{RS}} &= \frac{z}{2}\omega X_B(1 - X_B) + RT(X_B \log X_B + (1 - X_B) \log(1 - X_B)) \\ \frac{\partial \Delta \bar{G}^{\text{RS}}}{\partial X_B} &= z\omega\left(\frac{1}{2} - X_B\right) + RT(\log X_B - \log(1 - X_B)) \\ \frac{\partial^2 \Delta \bar{G}^{\text{RS}}}{\partial X_B^2} &= -z\omega + RT\left(\frac{1}{X_B} + \frac{1}{1 - X_B}\right) = 0 \end{aligned} \quad (32-15)$$

At $X_B = 1/2$, the zero first appears at

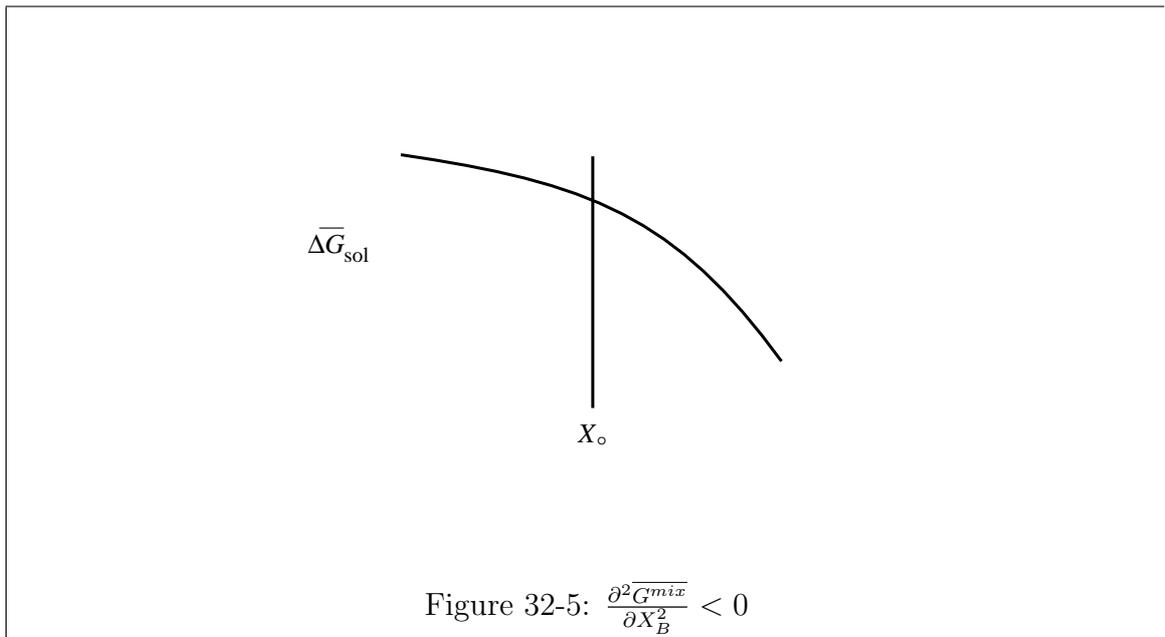
$$T_{\text{crit}}^{\text{RS}} = \frac{z\omega}{4R} \quad (32-16)$$

³²Because the curve is symmetric around $X = 1/2$ the common tangents, in this special case, will coincide with the minima of the molar free energy of solution.

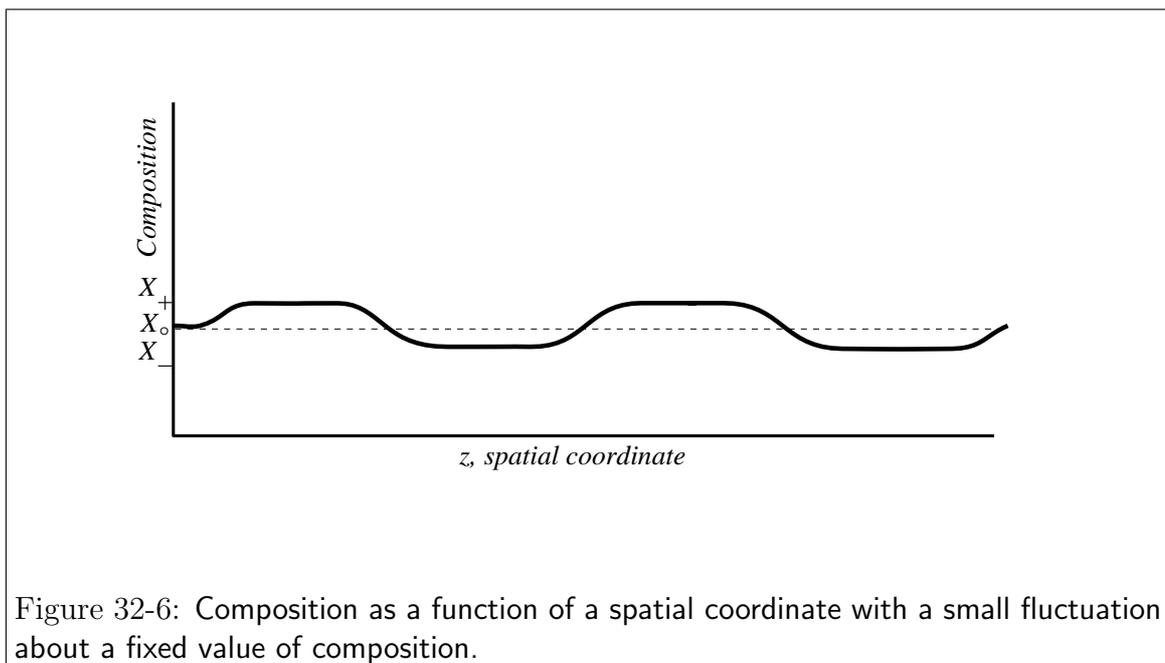
Spinodal Decomposition

For those cases in which the molar free energy of mixing has regions of negative curvature (as in the example of the regular solution model), the mechanism by which the system decomposes into its equilibrium phases is different than the mechanism when the curvature is positive. This distinction between mechanisms when the curvature is negative (called the spinodal decomposition mechanism) when the curvature is positive (called the nucleation and growth mechanism) is important for kinetics. It will be useful to discuss the spinodal mechanism in the context of free energy curves.

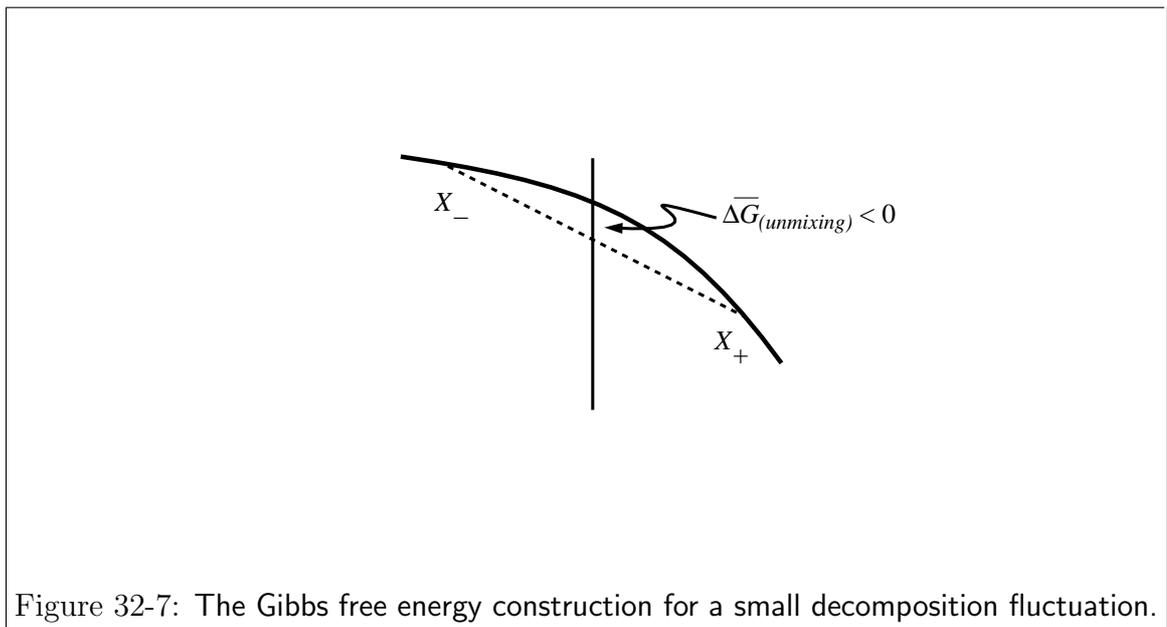
Consider a part of the free energy curve where the curvature is negative:



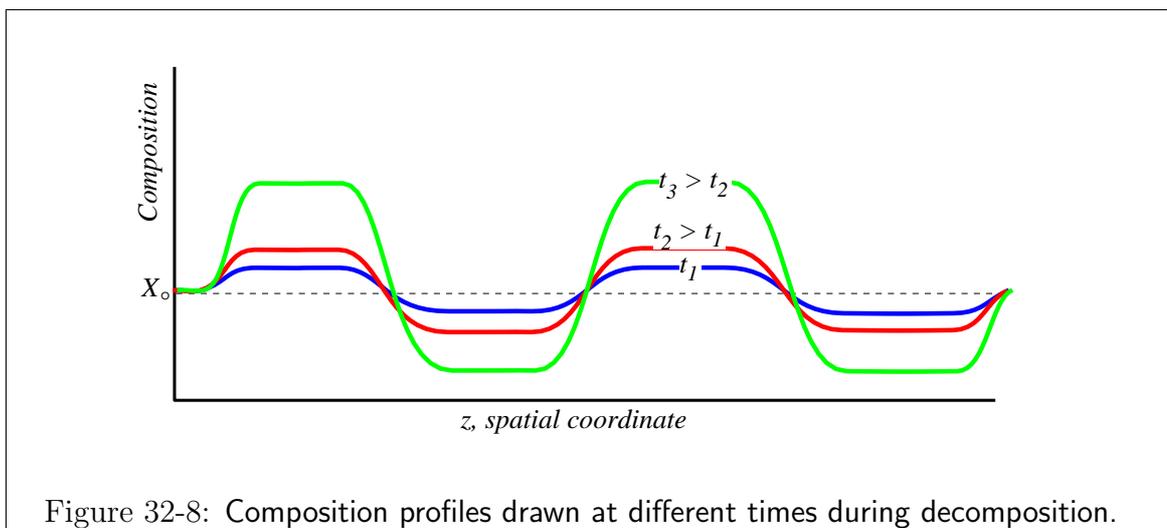
Suppose that a material is manufactured with a composition X_0 that is a function of some spatial coordinate z :



Suppose that a very small fluctuation occurs and consider what happens to the free energy for the small fluctuation:



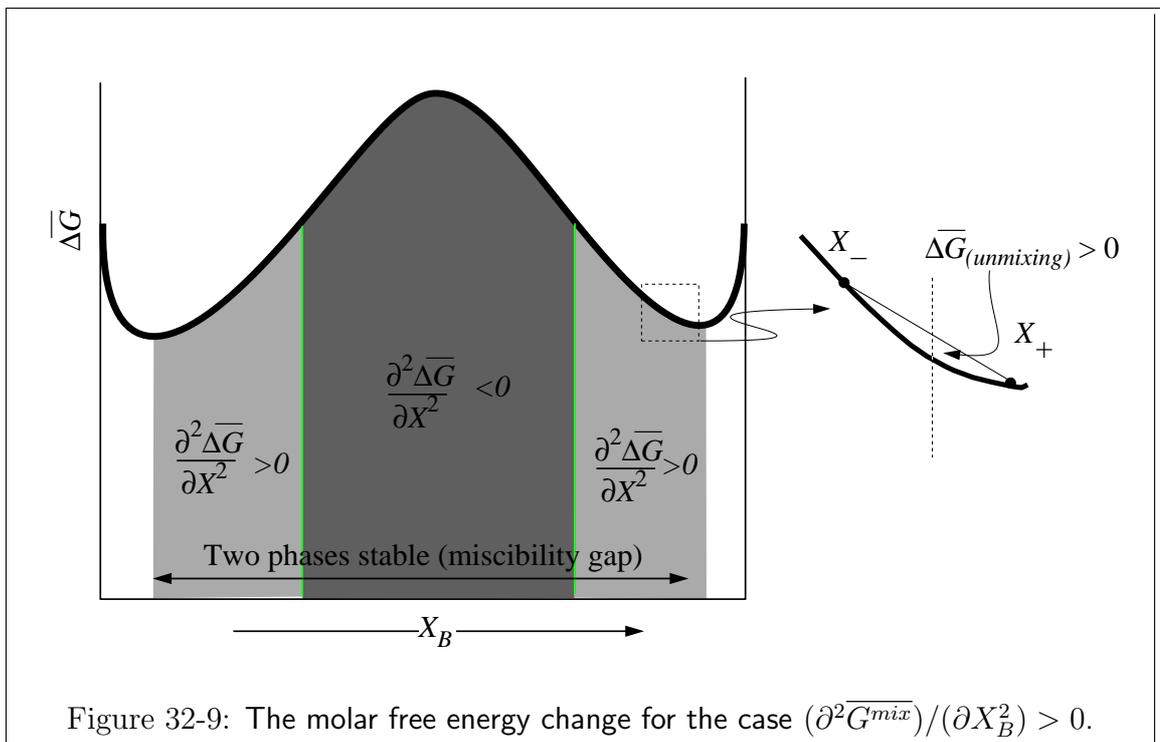
Apparently, the free-energy change is negative for an arbitrarily small fluctuation in composition such that one part of the system gets more concentrated at the expense of another. The system is inherently unstable and phase separation will proceed as illustrated:



This process is called spinodal decomposition and it occurs spontaneously when

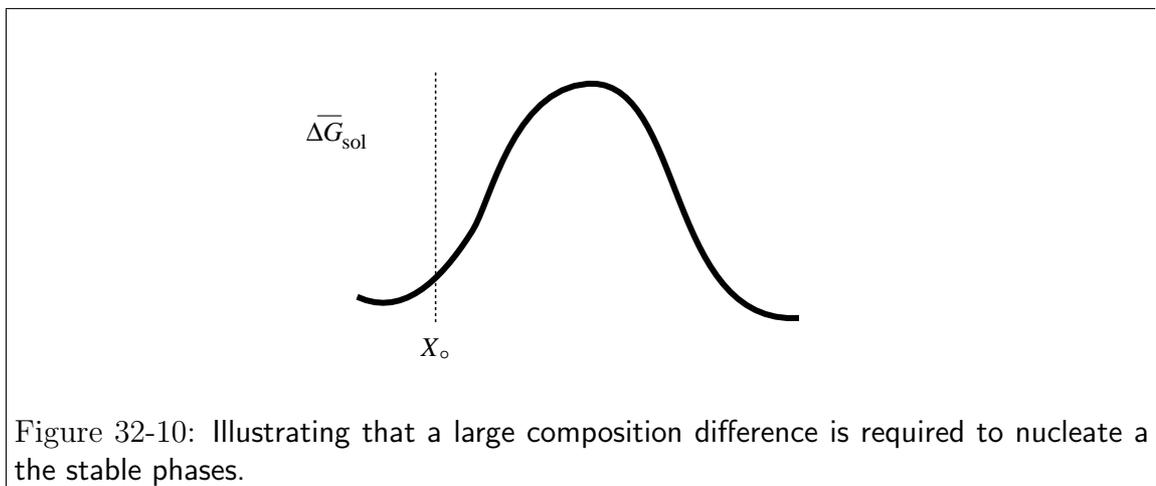
$$\frac{\partial^2 \overline{\Delta G^{\text{mixing}}}}{\partial X_B^2} < 0 \quad (\text{condition for spinodal decomposition}) \quad (32-17)$$

Consider the part of the curve where the curvature is positive but inside the miscibility gap (miscibility gap is another way of saying the two-phase region):



Apparently, the free energy increases. Therefore, the system is “stable” with respect to small fluctuations. In other words, it is metastable with respect to infinitesimal composition fluctuations.

Such a system is clearly unstable to the separation into the limiting compositions given by the common tangent construction. How does the system phase separate?



Apparently an average composition within the two phase region, but outside of the spinodal curves requires large composition fluctuations to decrease the energy. Therefore, the system phase separates as illustrated in the following cartoon:

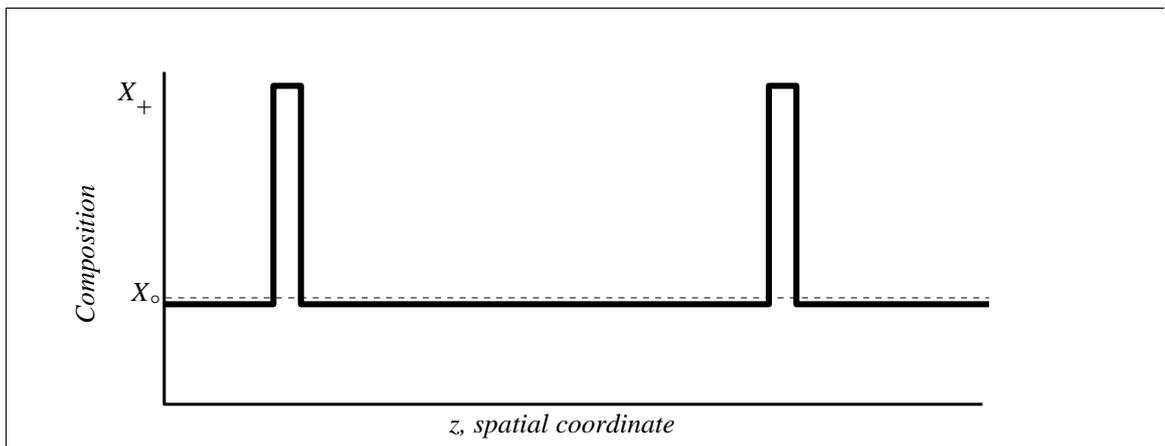


Figure 32-11: Illustration of the nucleation of an unstable phase. For nucleation—by contrast to phase separation by spinodal decomposition—the new phase must initiate with a composition that is *not* near that of the parent phase. Nucleation is a phase transition that is large in degree (composition change) but small in extent (size); whereas spinodal decomposition is small in degree but large in extent.

A process requiring a large composition fluctuation is called “nucleation.” After the nucleus forms, the new phase grows. Together, the process is called *nucleation and growth*. This kinetic information can be graphically codified into the phase diagram:

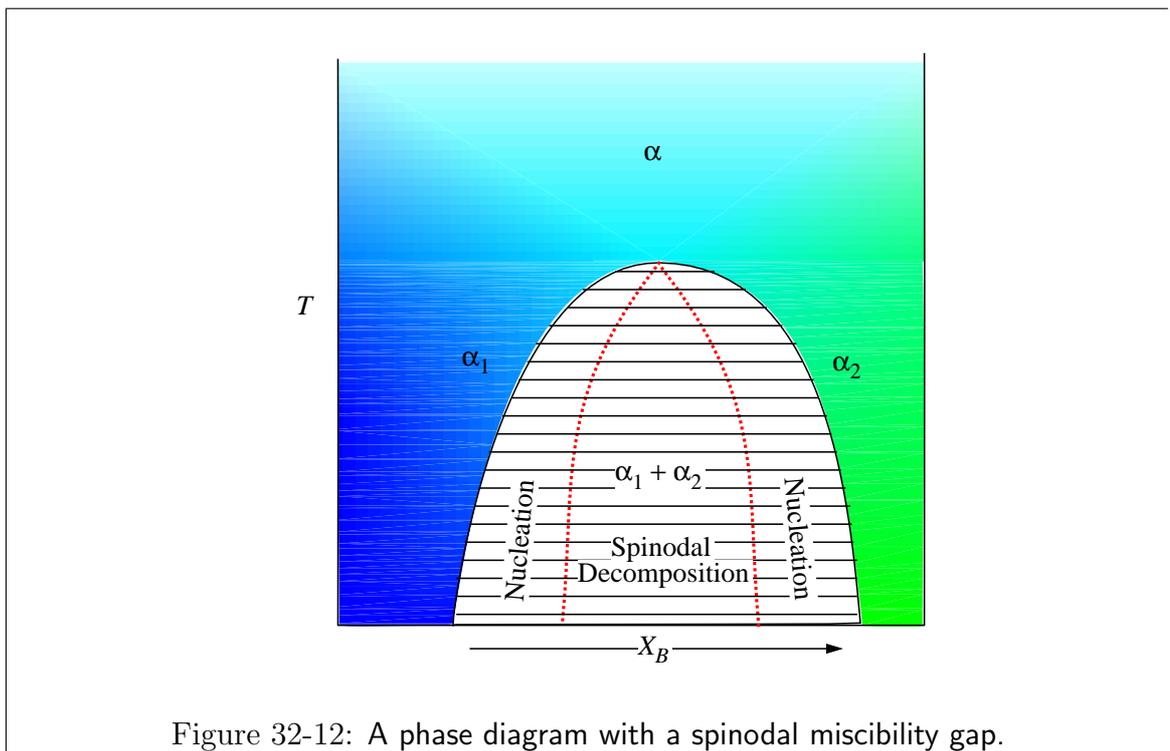
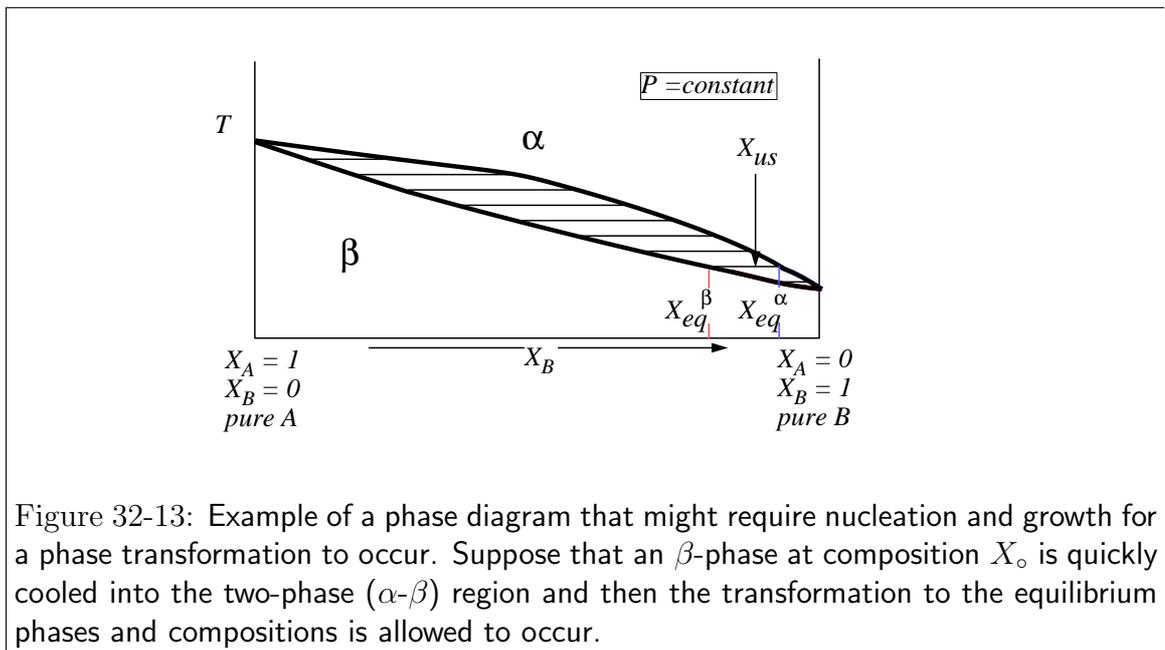


Figure 32-12: A phase diagram with a spinodal miscibility gap.

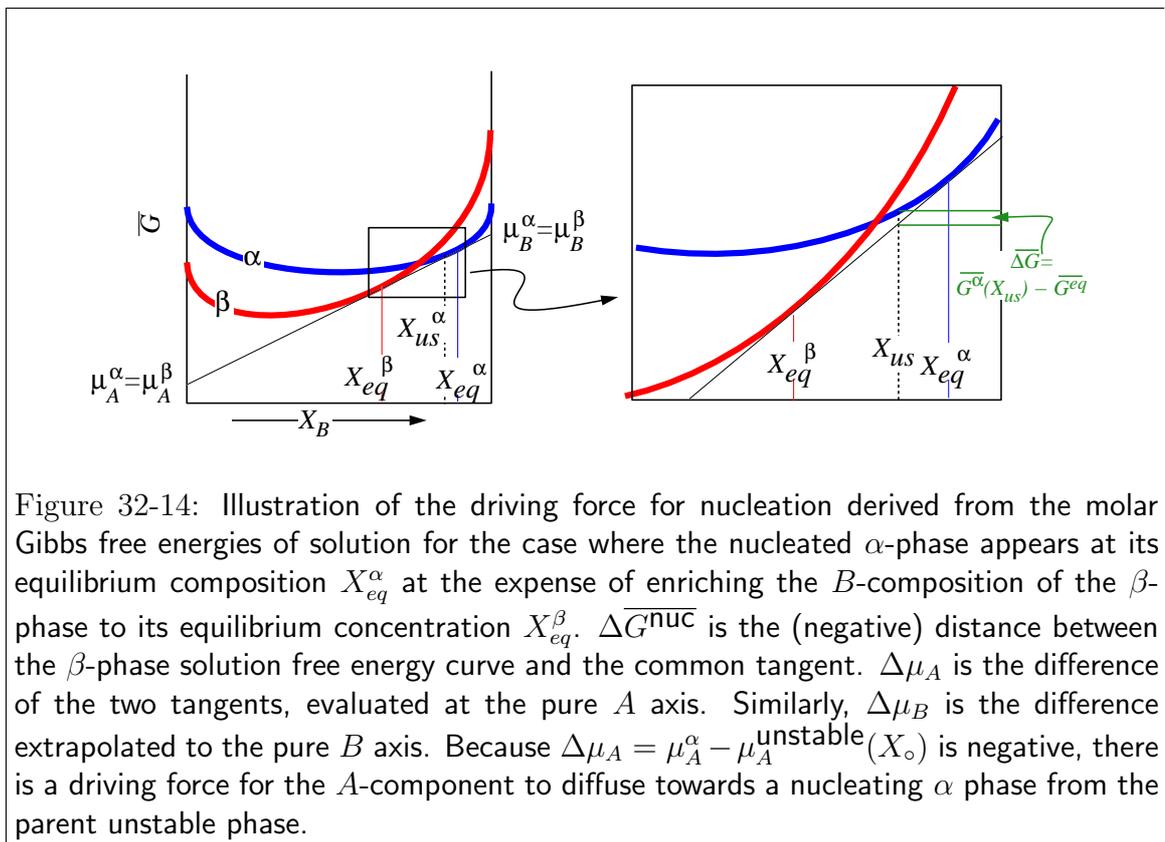
Nucleation and Growth

Nucleation of a new phase occurs when a phase in an alloy of composition X_o is unstable with respect a composition that is *not near* X_o .



The transformation will require nucleation of an α -phase at a composition that, when combined with the molar free energy of the resultant α -phase, gives a mixture with a molar Gibbs free energy that is less than the value of $\overline{G}^\beta(X_o)$

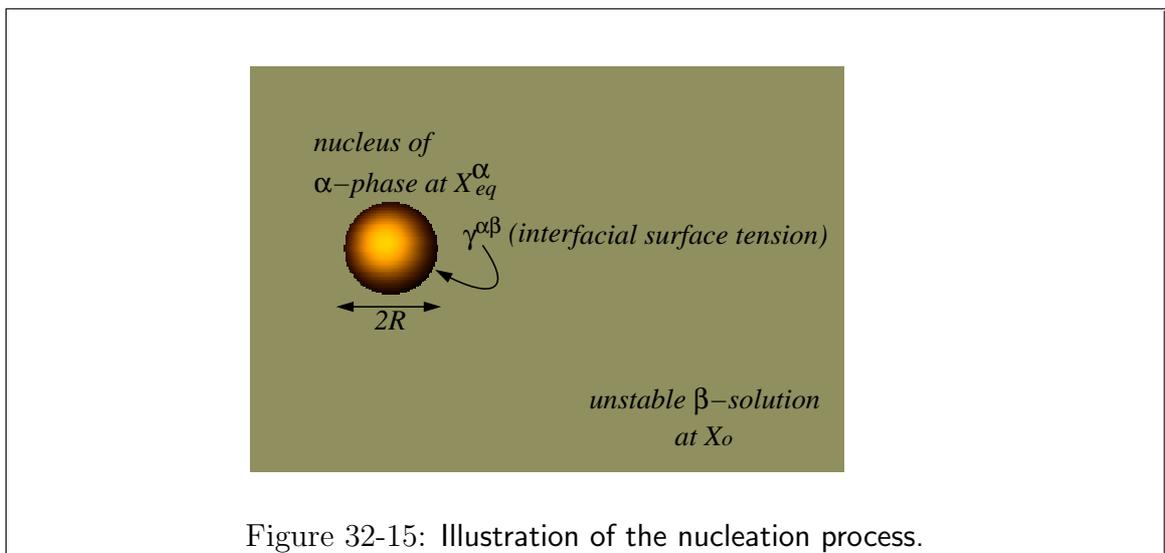
In other words, $\partial^2 \overline{G} / \partial X^2 > 0$ at $X = X_o$, but there is some X^{nuc} for which $\overline{G}^{\text{mixture}}(\langle X_o \rangle) - \overline{G}(X_o) = \Delta \overline{G}^{\text{nuc}} < 0$. The negative $\Delta \overline{G}^{\text{nuc}}$ is the driving force for the creation of a new phase.



Notice that the driving force for the phase transformation goes away as the unstable composition X_o approaches the limiting compositions on the tie-line.

The driving force for nucleation is important because it has to be utilized to overcome the additional energy associated with the interface between the α and the β phase. This is the interfacial energy.

The surface (or interfacial) tension is the amount of energy that is required to produce interface per unit area interface. Let the interfacial tension between the α and the β phase be $\gamma^{\alpha\beta}$ and suppose that when the α -phase nucleates, that it forms a little sphere of radius R :



The *total (extensive)* extra energy required for the phase transformation is:

$$\Delta G^{surface} = \gamma^{\alpha\beta} \text{surface area of nucleus} = 4\pi\gamma^{\alpha\beta} R^2 \quad (32-18)$$

Therefore the total free energy required to create a nucleus is given by

$$\Delta G^{nucleus} = 4\pi\gamma^{\alpha\beta} R^2 - \frac{4\pi}{3} |\Delta \overline{G}^{nuc}| \overline{V}^{\alpha} R^3 \quad (32-19)$$

where $|\Delta \overline{G}^{nuc}|$ is the (magnitude) of the molar driving force to create the nucleating α -phase and \overline{V}^{α} is its molar volume.

Therefore the total energy has contributions from two parts:

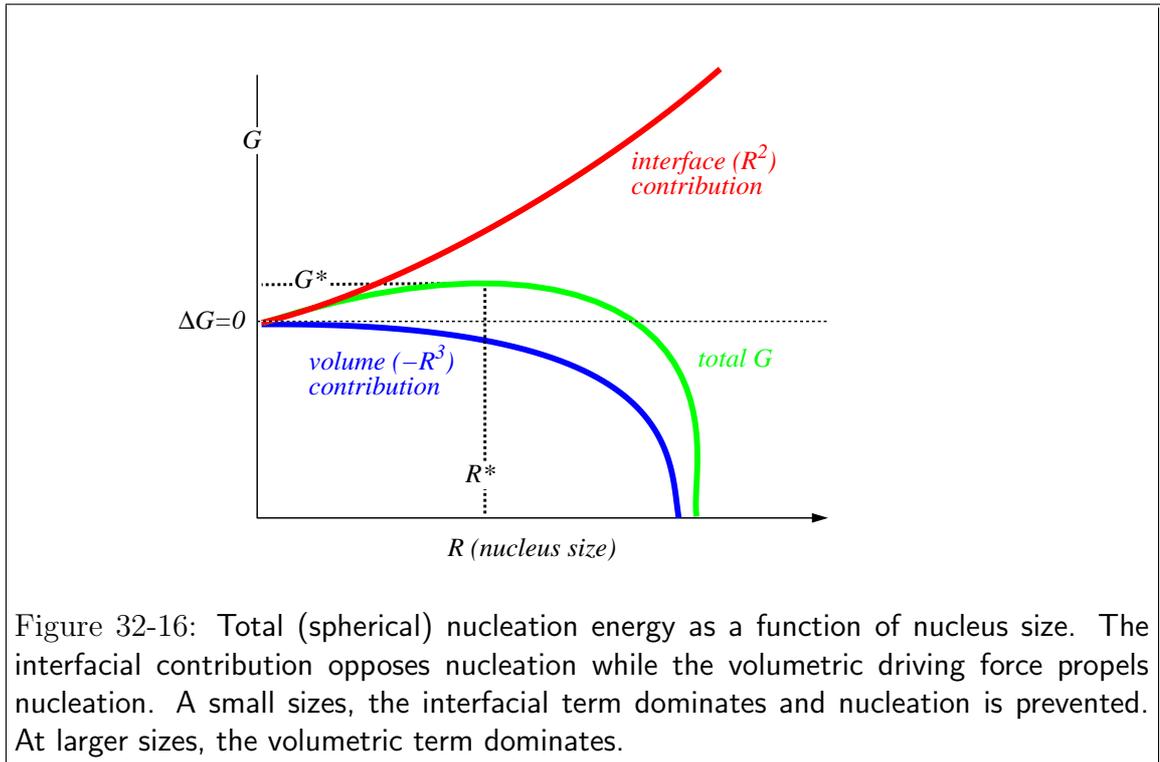


Figure 32-16: Total (spherical) nucleation energy as a function of nucleus size. The interfacial contribution opposes nucleation while the volumetric driving force propels nucleation. At small sizes, the interfacial term dominates and nucleation is prevented. At larger sizes, the volumetric term dominates.

If a nucleus can attain a size that exceeds the maximum, G^* of the curve in Fig. 32-16, then it can increase its size while continuously decreasing its free energy—therefore any nucleus with size R^* or larger will grow continuously.

To calculate this critical size, take the derivative of Eq. 32-19 and set it equal to zero and solve for R :

$$R^* = \frac{2\gamma^{\alpha\beta}}{|\Delta \overline{G}^{nuc}|} \quad (32-20)$$

and substituting this radius into the expression for the nucleation energy gives the nucleation barrier energy:

$$G^* = \frac{16\pi(\gamma^{\alpha\beta})^3}{3(\Delta \overline{G}^{nuc})^2} \quad (32-21)$$

This expression illustrates that nucleation must occur at a critical size and that the energy barrier to nucleation can be reduced by a decrease in the interfacial tension or by an increase

in the volumetric driving force.³³ The time required for the phase transition to occur is related to the time required for a critical composition fluctuation to occur that will produce a critical nucleus of size R^* —and that time increases exponentially with the barrier G^* .

³³By contrast, spinodal decomposition occurs without a nucleation barrier—it is a “barrierless” phase transformation.