



6.976

*High Speed Communication Circuits and Systems*  
*Lecture 7*  
*Noise Modeling in Amplifiers*

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## **Notation for Mean, Variance, and Correlation**

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- Consider random variables  $x$  and  $y$  with probability density functions  $f_x(x)$  and  $f_y(y)$  and joint probability function  $f_{xy}(x,y)$ 
  - Expected value (mean) of  $x$  is

$$\bar{x} = E(x) = \int_{-\infty}^{\infty} x f_x(x) dx$$

- Note: we will often abuse notation and denote  $\bar{x}$  as a random variable (i.e., noise) rather than its mean
  - The variance of  $x$  (assuming it has zero mean) is

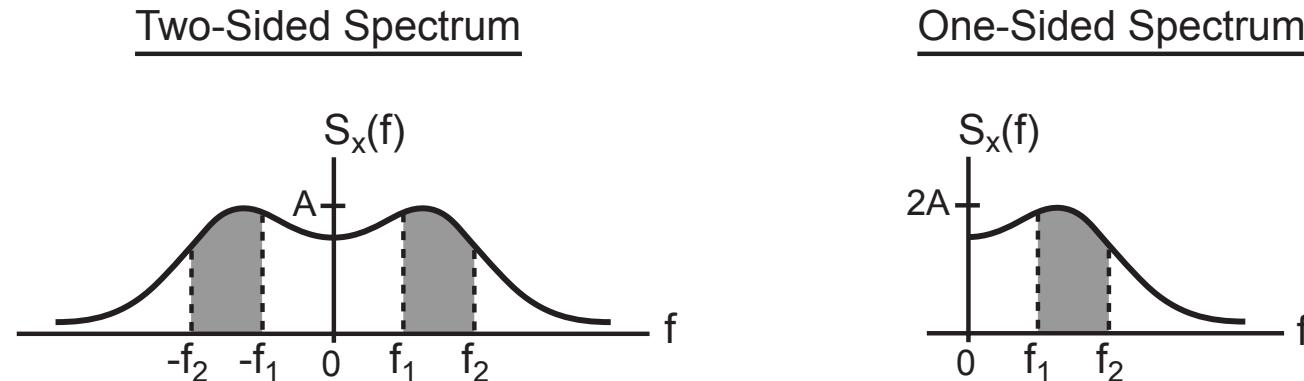
$$\overline{x^2} = E(x^*x) = \int_{-\infty}^{\infty} x^*x f_x(x) dx$$

- A useful statistic is

$$\overline{xy} = E(xy) = \int_{-\infty}^{\infty} xy f_{xy}(x, y) dx dy$$

- If the above is zero,  $x$  and  $y$  are said to be uncorrelated

# *Relationship Between Variance and Spectral Density*



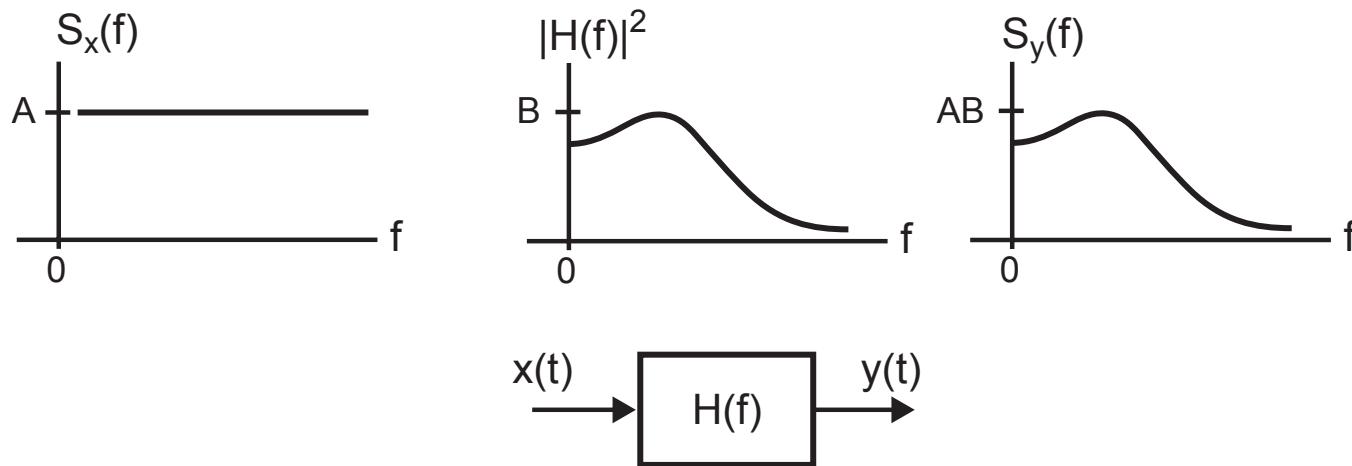
- **Two-sided spectrum**

$$\overline{x^2} = \int_{-f_2}^{-f_1} S_x(f) df + \int_{f_1}^{f_2} S_x(f) df$$

- Since spectrum is symmetric  $\Rightarrow \overline{x^2} = 2 \int_{f_1}^{f_2} S_x(f) df$

- **One-sided spectrum defined over positive frequencies**
  - Magnitude defined as twice that of its corresponding two-sided spectrum
- **In the next few lectures, we assume a one-sided spectrum for all noise analysis**

# The Impact of Filtering on Spectral Density



- For the random signal passing through a linear, time-invariant system with transfer function  $H(f)$

$$S_y(f) = |H(f)|^2 S_x(f)$$

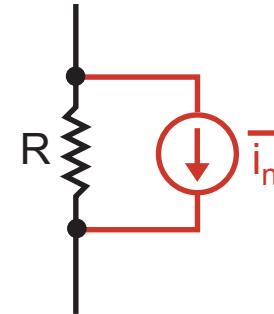
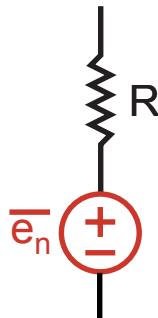
- We see that if  $x(t)$  is amplified by gain  $A$ , we have

$$S_y(f) = A^2 S_x(f) \Rightarrow \overline{y^2} = A^2 \overline{x^2}$$

# Noise in Resistors

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- Can be described in terms of either voltage or current



$$\overline{e_n^2} = 4kT R \Delta f$$

$$\overline{i_n^2} = 4kT \frac{1}{R} \Delta f$$

- k is Boltzmann's constant

$$k = 1.38 \times 10^{-23} J/K$$

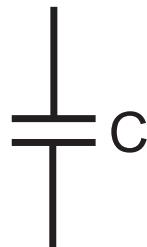
- T is temperature (in Kelvins)
  - Usually assume room temperature of 27 degrees Celsius

$$\Rightarrow T = 300K$$

# Noise In Inductors and Capacitors

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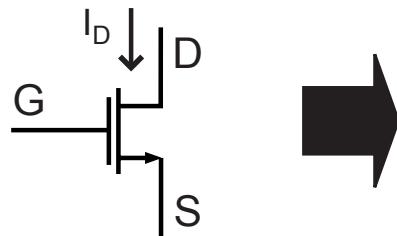
- Ideal capacitors and inductors have no noise!



- In practice, however, they will have parasitic resistance
  - Induces noise
  - Parameterized by adding resistances in parallel/series with inductor/capacitor
    - Include parasitic resistor noise sources

# Noise in CMOS Transistors (Assumed in Saturation)

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## Transistor Noise Sources

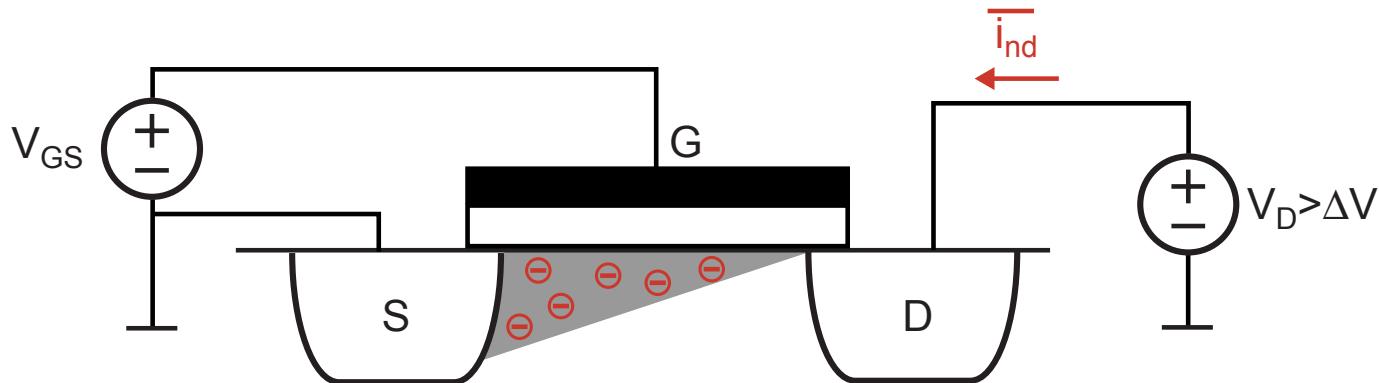
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Drain Noise (Thermal and 1/f)

Gate Noise (Induced and Routing Parasitic)

- Modeling of noise in transistors must include several noise sources
  - Drain noise
    - Thermal and 1/f – influenced by transistor size and bias
  - Gate noise
    - Induced from channel – influenced by transistor size and bias
    - Caused by routing resistance to gate (including resistance of polysilicon gate)
      - Can be made negligible with proper layout such as fingering of devices

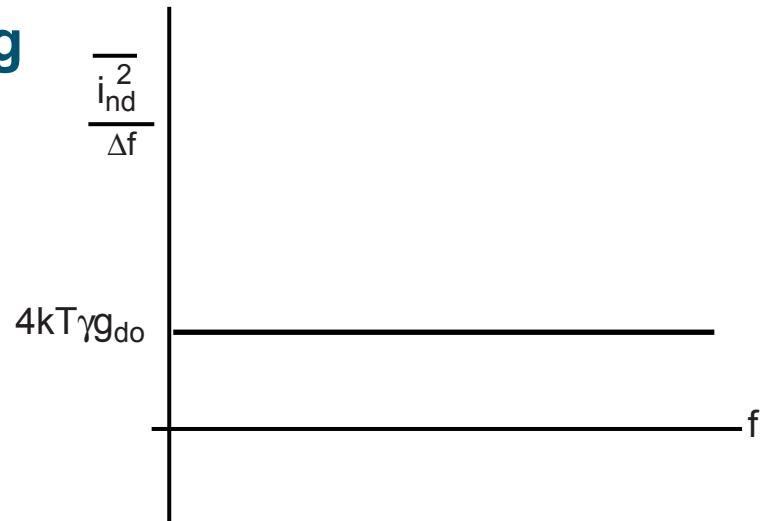
## Drain Noise – Thermal (Assume Device in Saturation)



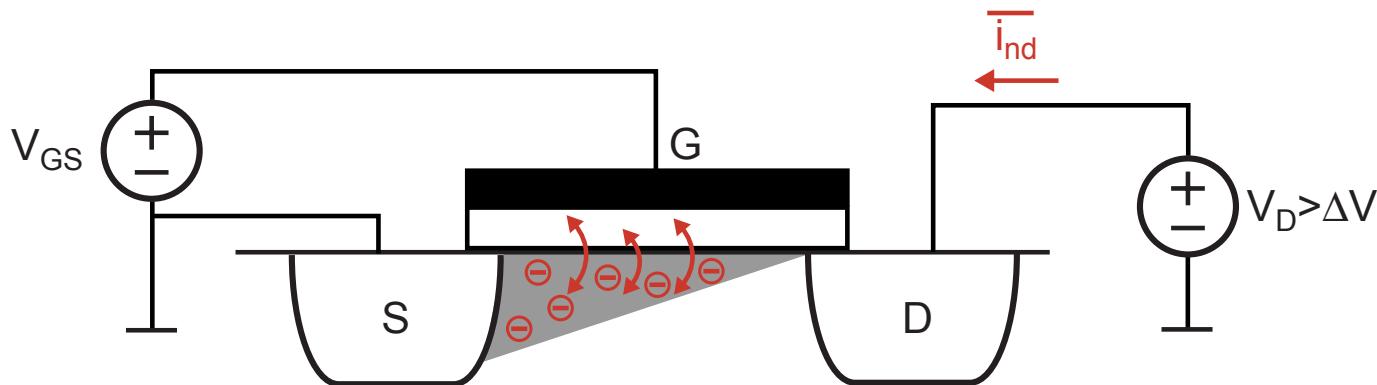
- Thermally agitated carriers in the channel cause a randomly varying current

$$\overline{i_{nd}^2} \Big|_{th} = 4kT\gamma g_{do}\Delta f$$

- $\gamma$  is called excess noise factor
    - = 2/3 in long channel
    - = 2 to 3 (or higher!) in short channel NMOS (less in PMOS)
  - $g_{do}$  will be discussed shortly (Note:  $g_{do} = g_m/\alpha$ )



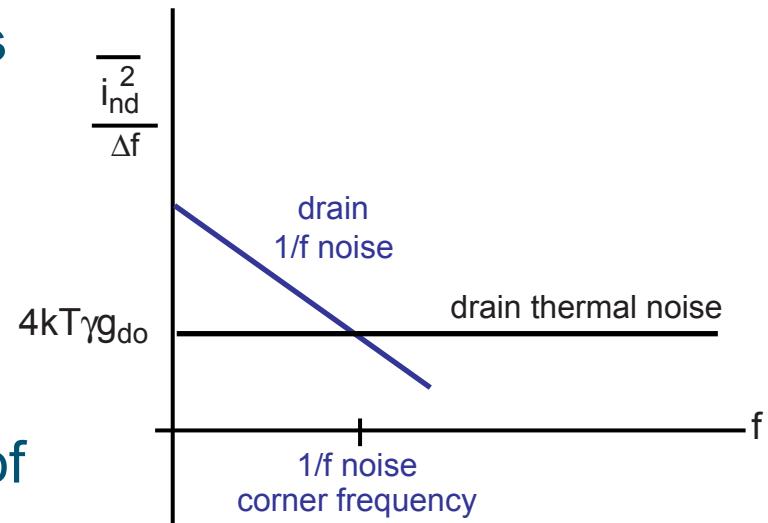
## Drain Noise – 1/f (Assume Device in Saturation)



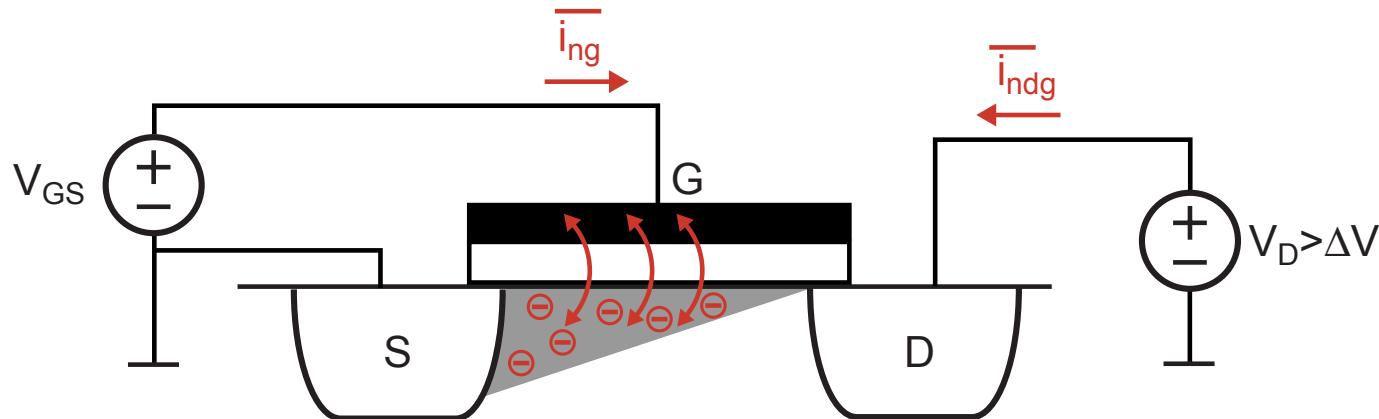
- Traps at channel/oxide interface randomly capture/release carriers

$$\overline{i_{nd}^2} \Big|_{1/f} = \frac{K_f}{f^n} \Delta f \approx \frac{K}{f} \frac{g_m^2}{WLC_{ox}^2} \Delta f$$

- Parameterized by  $K_f$  and  $n$ 
  - Provided by fab (note  $n \approx 1$ )
  - Currently:  $K_f$  of PMOS  $\ll K_f$  of NMOS due to buried channel
- To minimize: want large area (high WL)



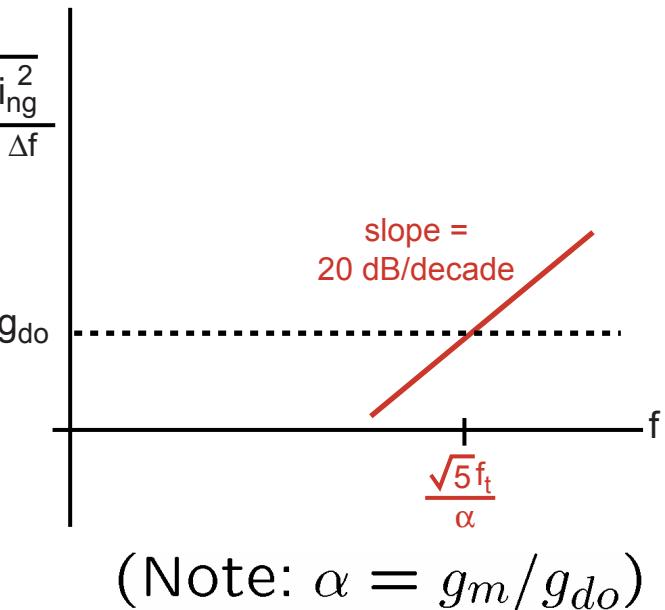
## Induced Gate Noise (Assume Device in Saturation)



- Fluctuating channel potential couples capacitively into the gate terminal, causing a noise gate current

$$\overline{i_{ng}^2} = 4kT\delta g_{do} \left( \frac{2\pi f}{\sqrt{5}/\alpha(g_m/C_{gs})} \right)^2 \Delta f$$

- δ is gate noise coefficient**
  - Typically assumed to be  $2\gamma$
- Correlated to drain noise!**



# *Useful References on MOSFET Noise*

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- **Thermal Noise**
  - B. Wang et. al., “MOSFET Thermal Noise Modeling for Analog Integrated Circuits”, JSSC, July 1994
- **Gate Noise**
  - Jung-Suk Goo, “High Frequency Noise in CMOS Low Noise Amplifiers”, PhD Thesis, Stanford University, August 2001
    - <http://www-tcad.stanford.edu/tcad/pubs/theses/goo.pdf>
  - Jung-Suk Goo et. al., “The Equivalence of van der Ziel and BSIM4 Models in Modeling the Induced Gate Noise of MOSFETS”, IEDM 2000, 35.2.1-35.2.4
  - Todd Sepke, “Investigation of Noise Sources in Scaled CMOS Field-Effect Transistors”, MS Thesis, MIT, June 2002
    - <http://www-mtl.mit.edu/research/sodini/sodinitheses.html>

## Drain-Source Conductance: $g_{do}$

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- $g_{do}$  is defined as channel resistance with  $V_{ds}=0$ 
  - Transistor in triode, so that

$$I_d = \mu_n C_{ox} \frac{W}{L} \left( (V_{gs} - V_T) V_{ds} - \frac{V_{ds}^2}{2} \right)$$

$$\Rightarrow g_{do} = \left. \frac{dI_d}{dV_{ds}} \right|_{V_{ds}=0} = \mu_n C_{ox} \frac{W}{L} (V_{gs} - V_T)$$

- Equals  $g_m$  for long channel devices
- Key parameters for 0.18 $\mu$  NMOS devices

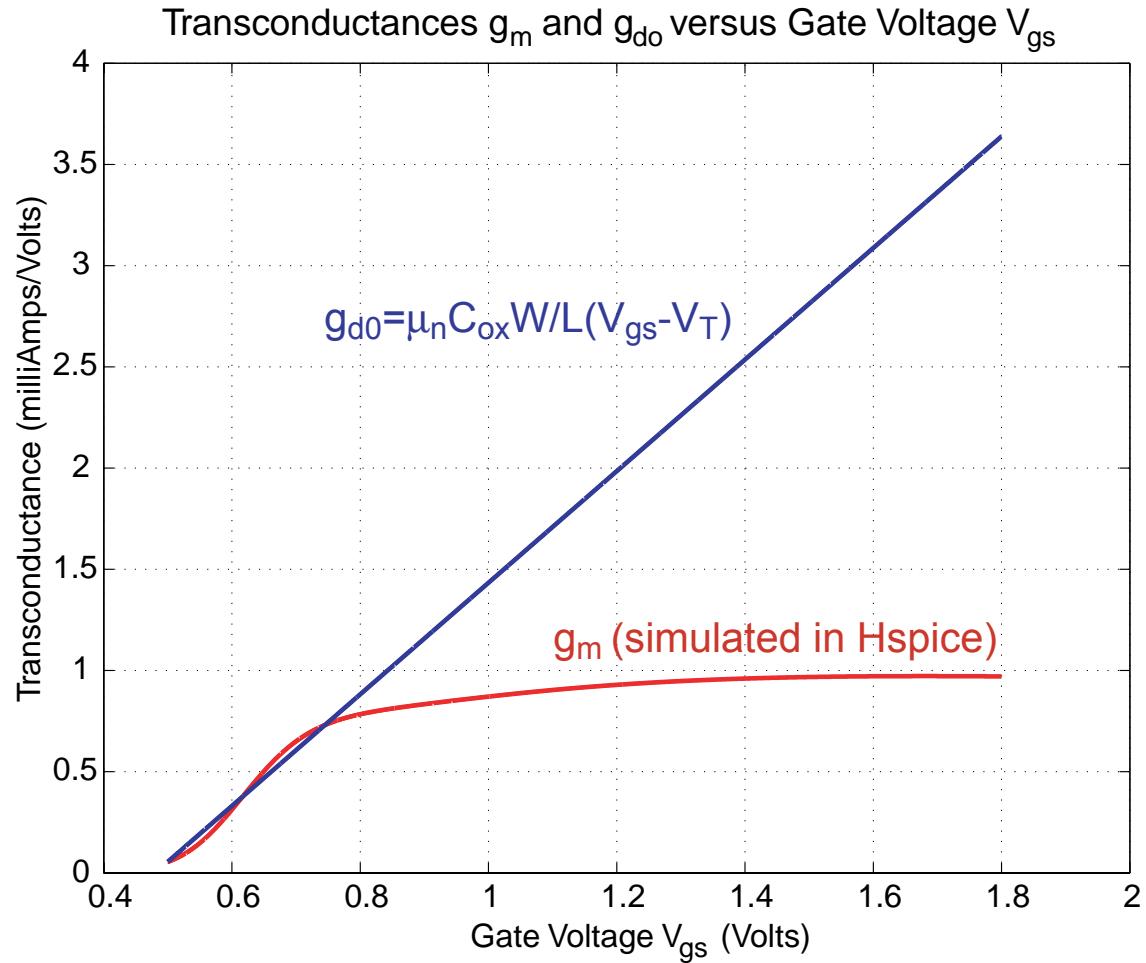
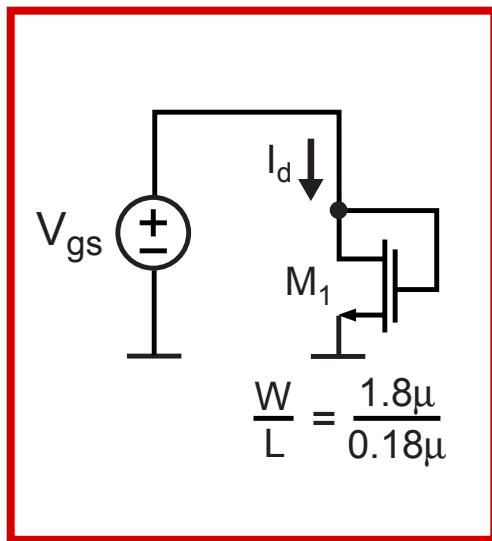
$$\mu_n = 327.4 \text{ cm}^2 / (\text{V} \cdot \text{s})$$

$$t_{ox} = 4.1 \times 10^{-9} \text{ m} \quad \epsilon_o = 3.9 (8.85 \times 10^{-12}) \text{ F/m}$$

$$\Rightarrow \mu_n C_{ox} = \mu_n \frac{\epsilon_o}{t_{ox}} = 275.6 \times 10^{-6} \text{ F}/(\text{V} \cdot \text{s})$$

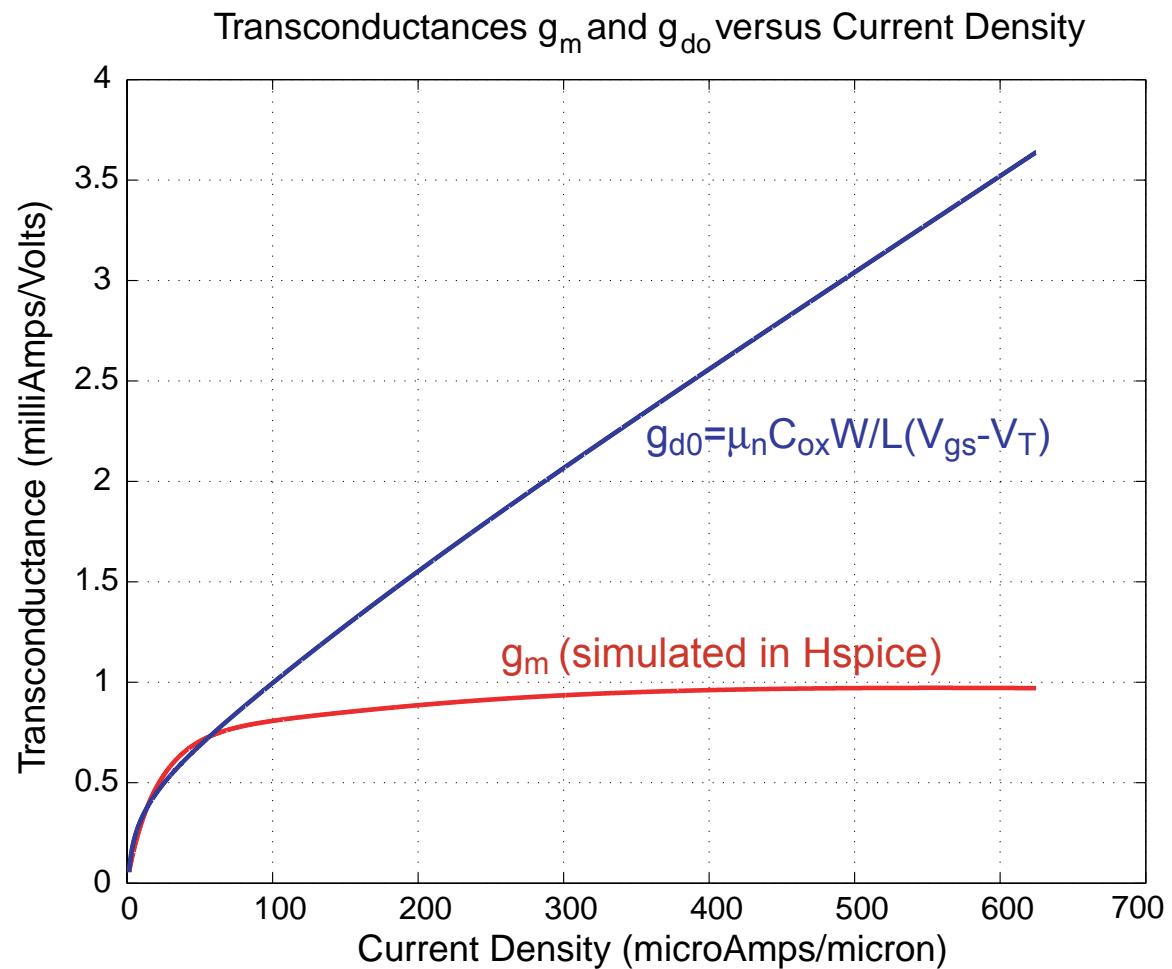
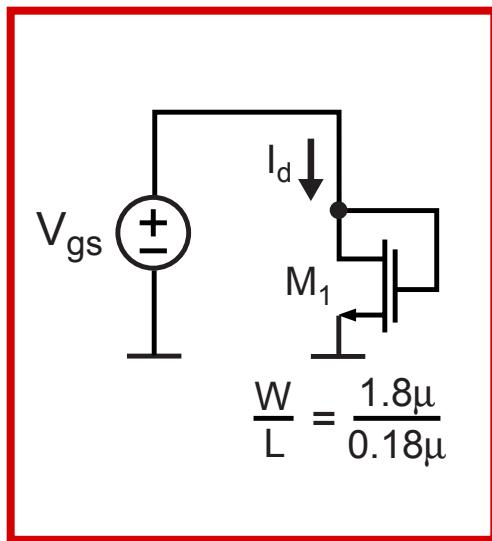
$$V_T = 0.48 \text{ V}$$

# Plot of $g_m$ and $g_{do}$ versus $V_{gs}$ for $0.18\mu$ NMOS Device

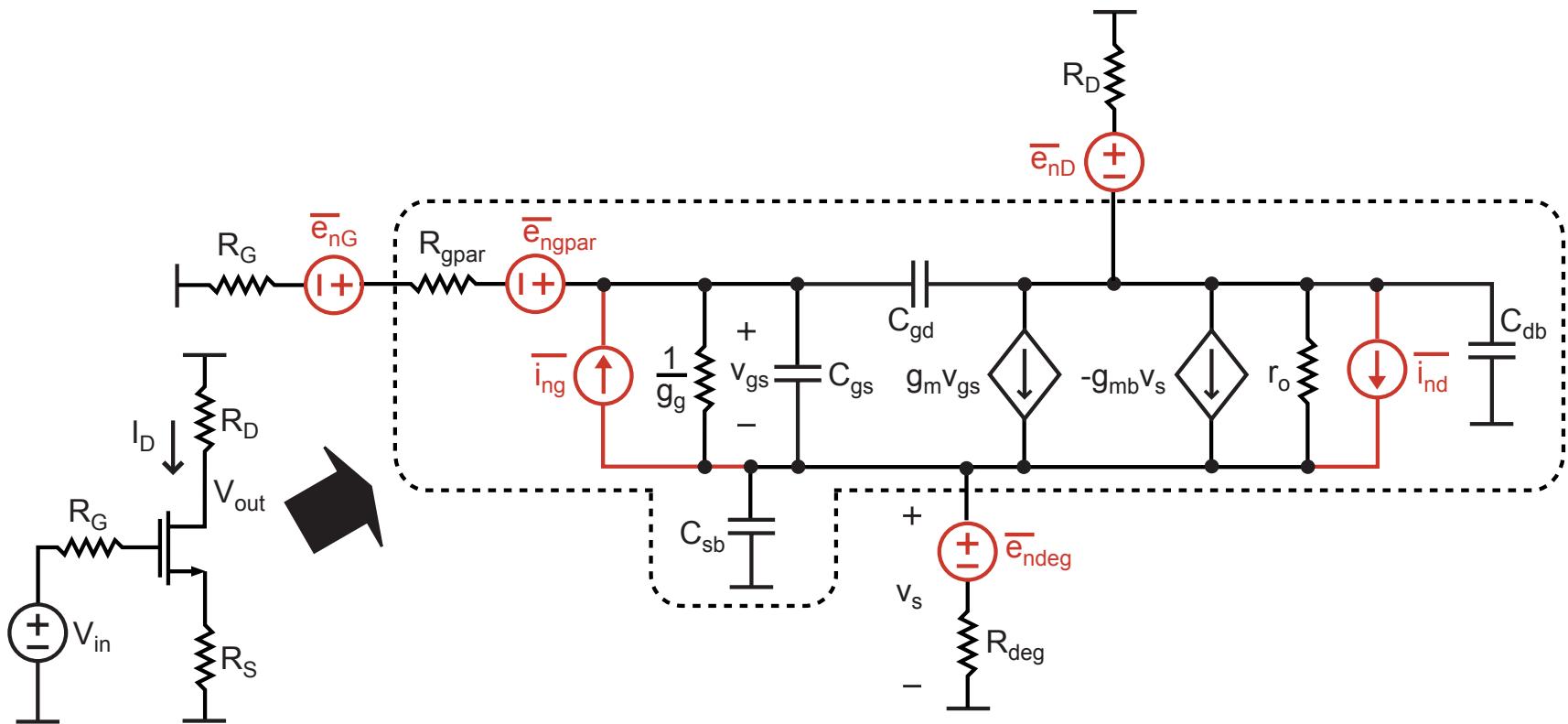


- For  $V_{gs}$  bias voltages around 1.2 V:  $\alpha = \frac{g_m}{g_{do}} \approx \frac{1}{2}$

# Plot of $g_m$ and $g_{do}$ versus $I_{dens}$ for $0.18\mu$ NMOS Device



# Noise Sources in a CMOS Amplifier



$\overline{e_{nG}}, \overline{e_{nD}}, \overline{e_{ndeg}}$  : noise sources of external resistors

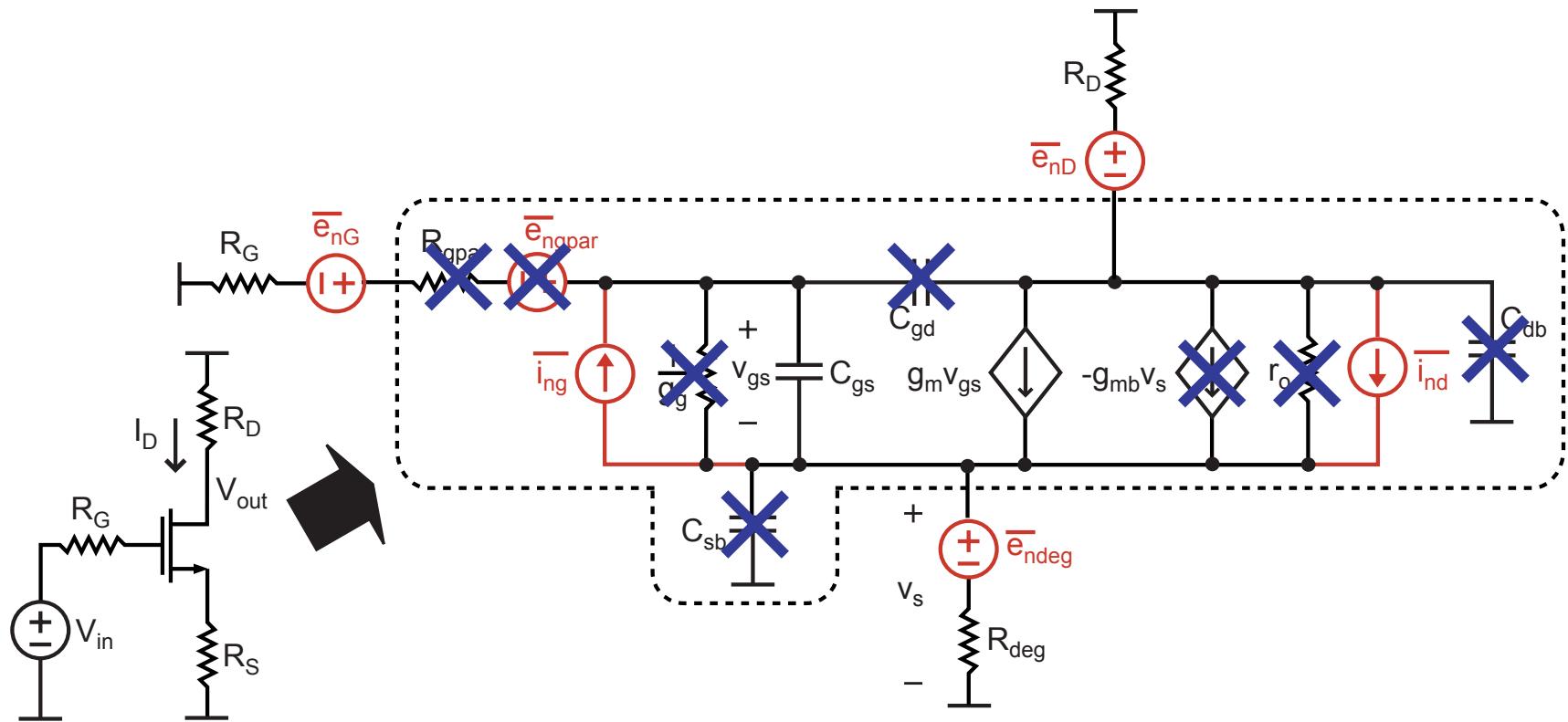
$R_{gpar}, \overline{e_{ngpar}}$  : parasitic gate resistance and its noise

$\overline{i_{ng}}$  : induced gate noise,

$\overline{g_g}$  : caused by distributed nature of channel  $\left( g_g = \frac{w^2 C_{gs}^2}{5 g_{d0}} \right)$

$\overline{i_{nd}}$  : drain noise (thermal and 1/f)

## Remove Model Components for Simplicity



$R_{qpar}, \overline{e}_{ngpar}$  : can make negligible with proper layout

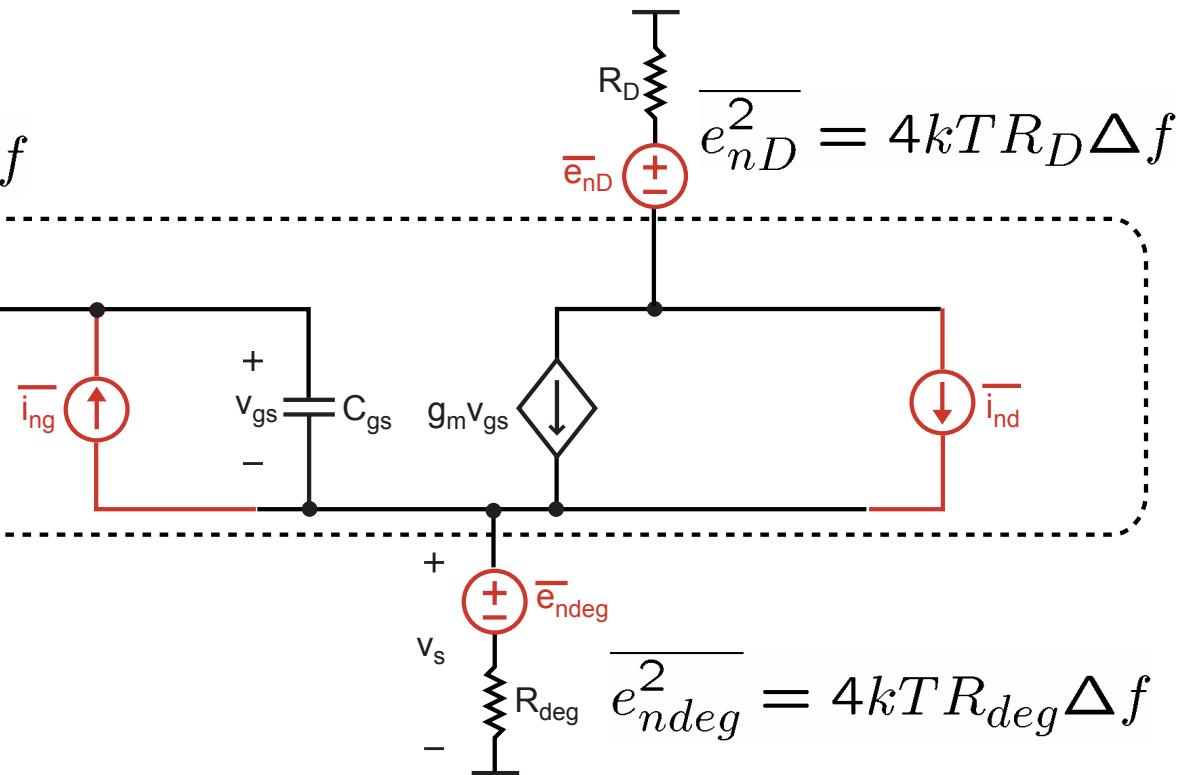
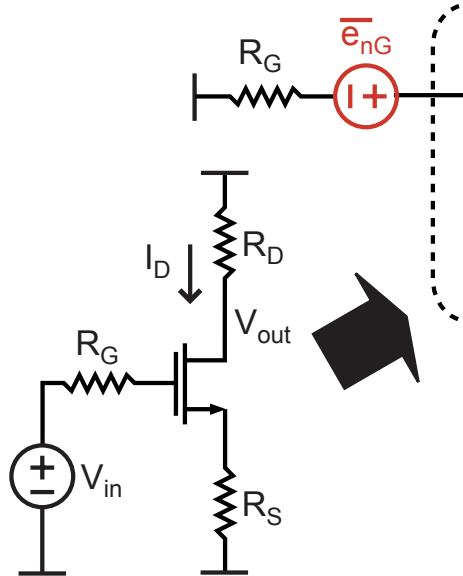
$g_g$  : assume to be negligible (for  $w \ll w_t$ )

$C_{sb}, C_{gd}, C_{db}, g_{mb}$  : too painful to include for calculations

$r_o$  : impact is minor since  $R_D$  is small (for high bandwidth)

# Key Noise Sources for Noise Analysis

$$\overline{e_{nG}^2} = 4kTR_G\Delta f$$



- **Transistor gate noise**

$$\overline{i_{ng}^2} = 4kT\delta g_g \Delta f,$$

where  $g_g = \frac{w^2 C_{gs}^2}{5g_{d0}}$

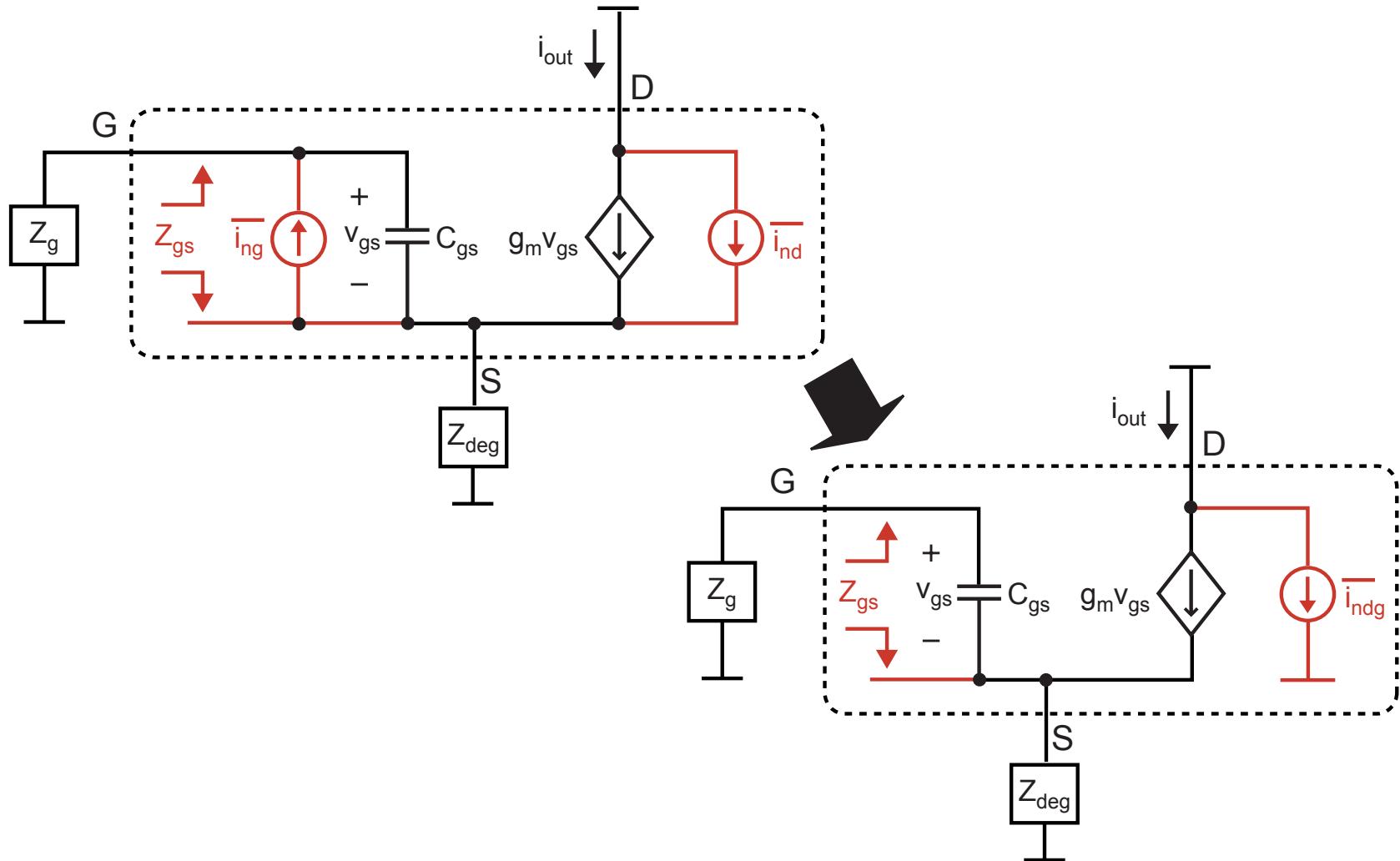
- **Transistor drain noise**

$$\overline{i_{nd}^2} = 4kT\gamma g_{do} \Delta f + \frac{K_f}{f^n} \Delta f$$

**Thermal noise**

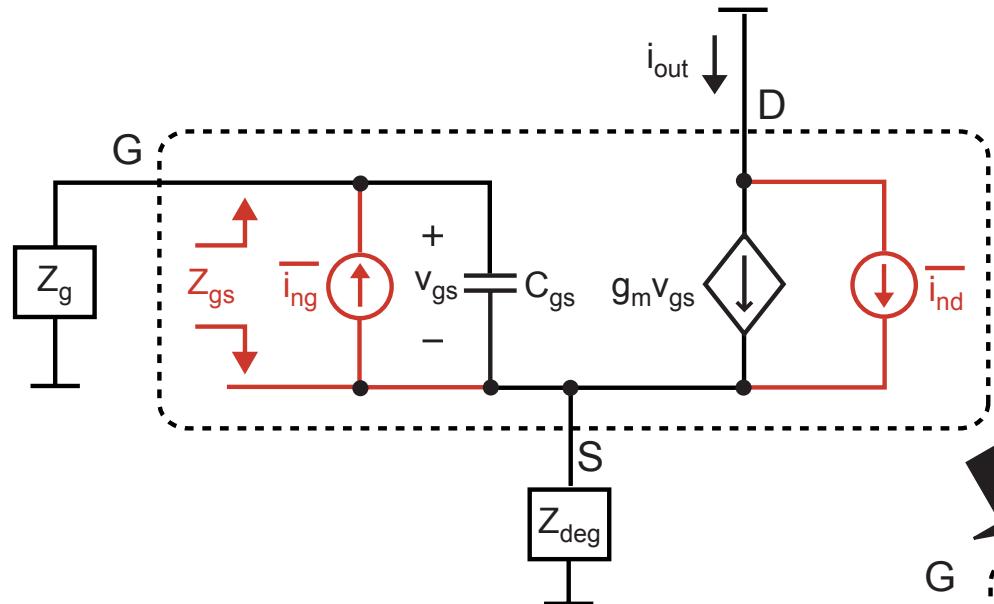
**1/f noise**

# Apply Thevenin Techniques to Simplify Noise Analysis

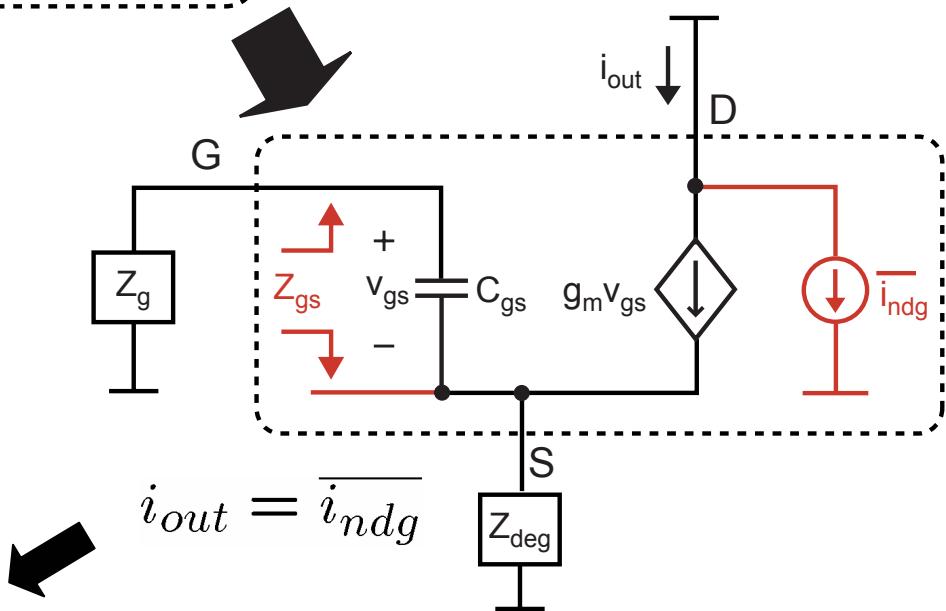


- Assumption: noise independent of load resistor on drain

# Calculation of Equivalent Output Noise for Each Case

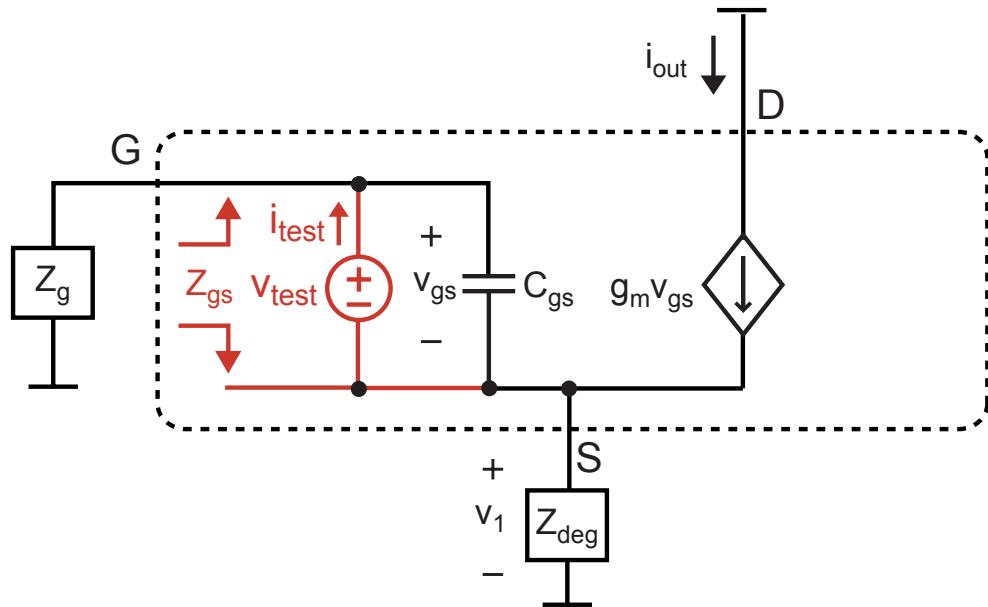


$$i_{out} = g_m Z_{gs} \overline{i_{ng}} + \eta \overline{i_{nd}}$$



$$\overline{i_{ndg}} = g_m Z_{gs} \overline{i_{ng}} + \eta \overline{i_{nd}}$$

## Calculation of $Z_{gs}$



### Write KCL equations

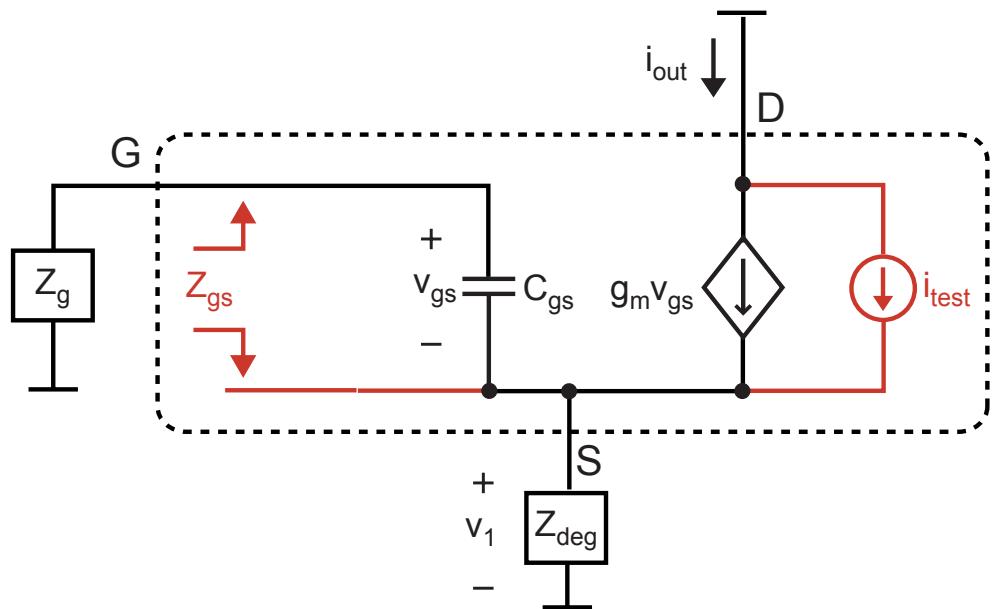
$$(1) -i_{test} + \frac{v_{test}}{1/(sC_{gs})} + g_m v_{test} = \frac{v_1}{Z_{deg}}$$

$$(2) \frac{v_{test} + v_1}{Z_g} + \frac{v_1}{Z_{deg}} = g_m v_{test}$$

### After much algebra:

$$Z_{gs} = \frac{v_{test}}{i_{test}} = \boxed{\frac{1}{sC_{gs}} \parallel \frac{Z_{deg} + Z_g}{1 + g_m Z_{deg}}}$$

## Calculation of $\eta$



- Determine  $V_{gs}$  to find  $i_{out}$  in terms of  $i_{test}$

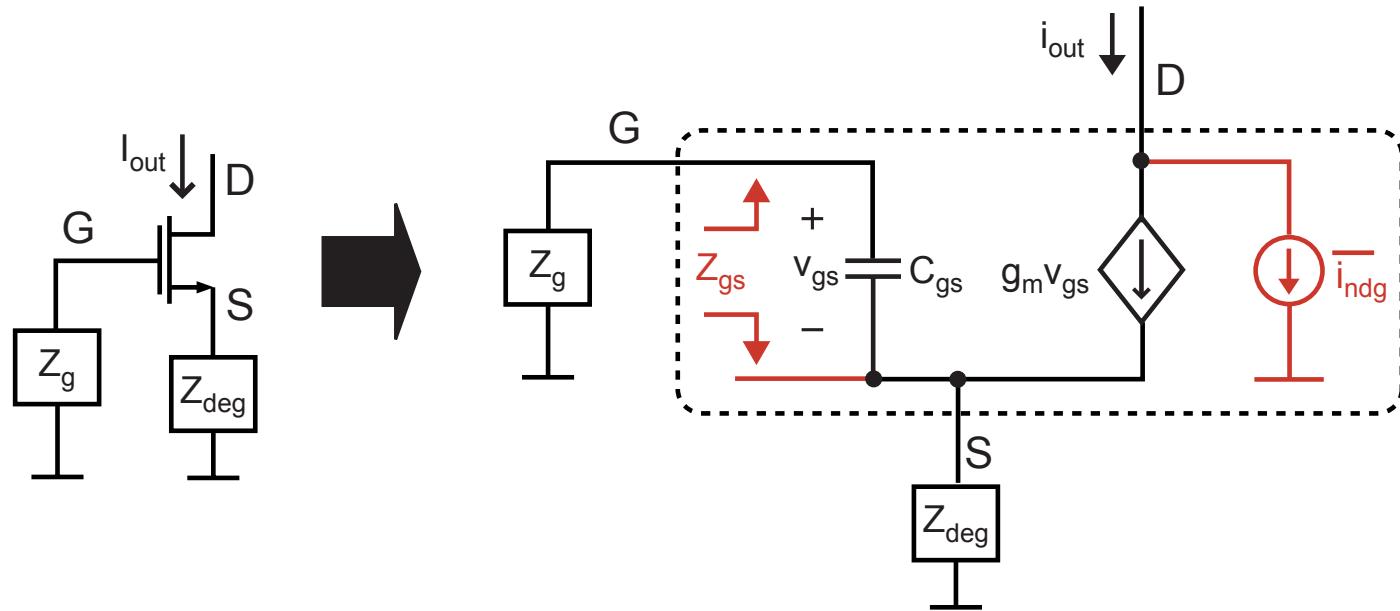
$$(1) i_{out} = i_{test} + g_m v_{gs} \quad (2) v_{gs} = -v_1 \frac{1/(sC_{gs})}{1/(sC_{gs}) + Z_g}$$

$$(3) v_1 = i_{out}(Z_{deg} || (\frac{1}{sC_{gs}} + Z_g))$$

- After much algebra:

$$\eta = \frac{i_{out}}{i_{test}} = \boxed{1 - \left( \frac{g_m Z_{deg}}{Z_{deg} + Z_g} \right) Z_{gs}}$$

# Calculation of Output Current Noise Variance (Power)



$$i_{out} = \overline{i_{ndg}} = \eta \overline{i_{nd}} + g_m Z_{gs} \overline{i_{ng}}$$

- To find noise variance:

$$\overline{i_{ndg}^2} = \overline{i_{ndg}^* i_{ndg}} = \overline{(\eta^* i_{nd}^* + g_m Z_{gs}^* i_{ng}^*)(\eta i_{nd} + g_m Z_{gs} i_{ng})}$$

## Variance (i.e., Power) Calc. for Output Current Noise

### ■ Noise variance calculation

$$\begin{aligned}\overline{i_{ndg}^2} &= |\eta|^2 \overline{i_{nd}^* i_{nd}} + \overline{i_{nd}^* i_{ng}} g_m \eta^* Z_{gs} + \overline{i_{nd} i_{ng}^*} (g_m \eta Z_{gs})^* + \overline{i_{ng} i_{ng}^*} |g_m Z_{gs}|^2 \\&= |\eta|^2 \overline{i_{nd}^2} + 2 \operatorname{Re} \{ \overline{i_{nd}^* i_{ng}} g_m \eta^* Z_{gs} \} + \overline{i_{ng}^2} |g_m Z_{gs}|^2 \\&= |\eta|^2 \overline{i_{nd}^2} + 2 \operatorname{Re} \left\{ \frac{\overline{i_{nd}^* i_{ng}}}{\sqrt{\overline{i_{nd}^2} \overline{i_{ng}^2}}} \sqrt{\overline{i_{nd}^2} \overline{i_{ng}^2}} g_m \eta^* Z_{gs} \right\} + \overline{i_{ng}^2} |g_m Z_{gs}|^2\end{aligned}$$

### ■ Define correlation coefficient $c$ between $i_{ng}$ and $i_{nd}$

$$c = \frac{\overline{i_{nd}^* i_{ng}}}{\sqrt{\overline{i_{nd}^2} \overline{i_{ng}^2}}} \Rightarrow \overline{i_{ntot}^2} = |\eta|^2 \overline{i_{nd}^2} + 2 \operatorname{Re} \{ c \sqrt{\overline{i_{nd}^2} \overline{i_{ng}^2}} g_m \eta^* Z_{gs} \} + \overline{i_{ng}^2} |g_m Z_{gs}|^2$$

$$\boxed{\overline{i_{ndg}^2} = \overline{i_{nd}^2} \left( |\eta|^2 + 2 \operatorname{Re} \left\{ c \sqrt{\frac{\overline{i_{ng}^2}}{\overline{i_{nd}^2}}} g_m \eta^* Z_{gs} \right\} + \frac{\overline{i_{ng}^2}}{\overline{i_{nd}^2}} g_m^2 |Z_{gs}|^2 \right)}$$

# Parameterized Expression for Output Noise Variance

- Key equation from last slide

$$\overline{i_{ndg}^2} = \overline{i_{nd}^2} \left( |\eta|^2 + 2\operatorname{Re} \left\{ c \sqrt{\frac{\overline{i_{ng}^2}}{\overline{i_{nd}^2}}} g_m \eta^* Z_{gs} \right\} + \frac{\overline{i_{ng}^2}}{\overline{i_{nd}^2}} g_m^2 |Z_{gs}|^2 \right)$$

- Solve for noise ratio

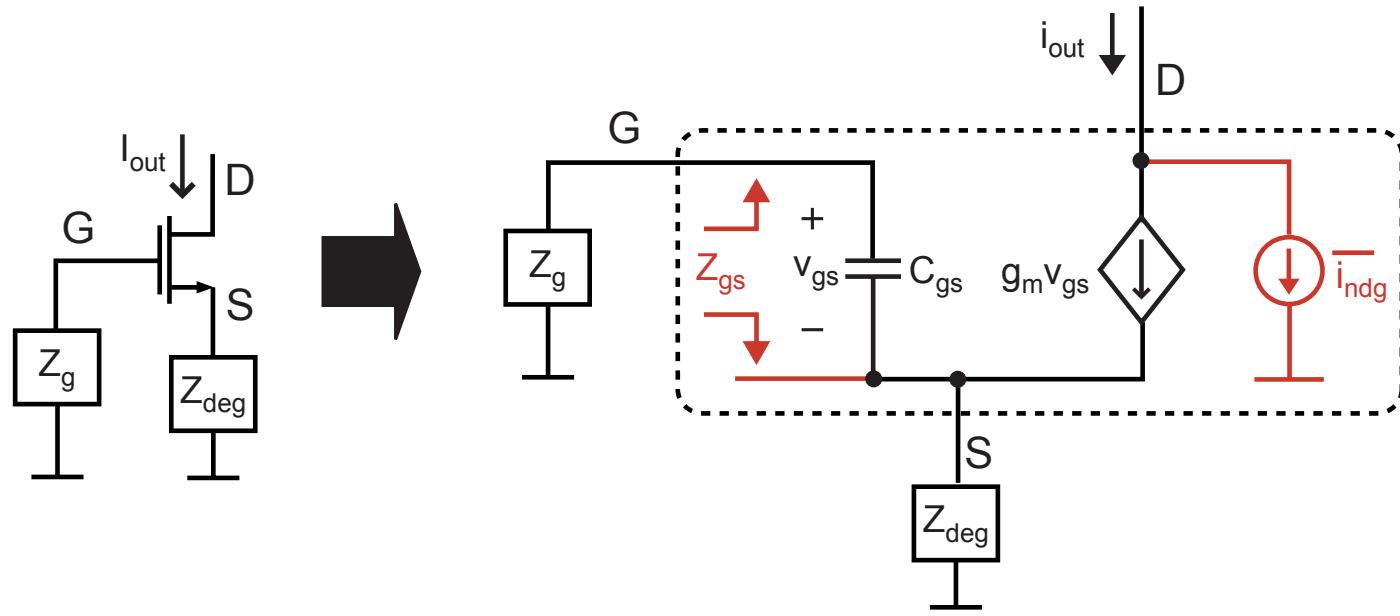
$$\sqrt{\frac{\overline{i_{ng}^2}}{\overline{i_{nd}^2}}} g_m = g_m \sqrt{\frac{4kT\delta(wC_{gs})^2/(5g_{do})}{4kT\gamma g_{do}}} = \frac{g_m}{g_{do}} \sqrt{\frac{\delta}{5\gamma}} (wC_{gs})$$

- Define parameters  $Z_{gsw}$  and  $\chi_d$

$$Z_{gsw} = wC_{gs}Z_{gs}, \quad \chi_d = \frac{g_m}{g_{do}} \sqrt{\frac{\delta}{5\gamma}}$$

$$\Rightarrow \overline{i_{ndg}^2} = \overline{i_{nd}^2} \left( |\eta|^2 + 2\operatorname{Re} \{ c\chi_d \eta^* Z_{gsw} \} + \chi_d^2 |Z_{gsw}|^2 \right)$$

# Small Signal Model for Noise Calculations



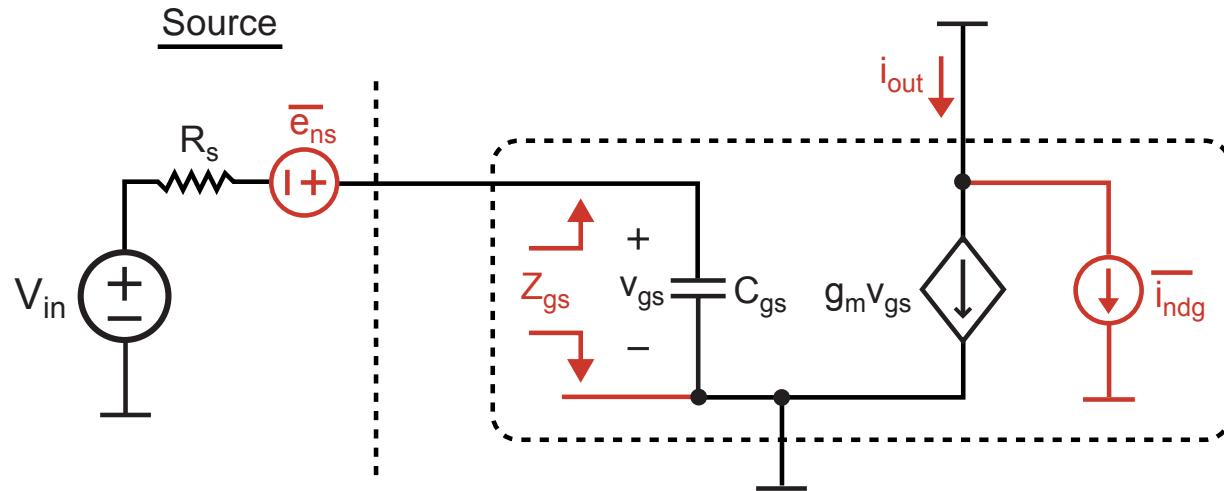
$$\frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \left( |\eta|^2 + 2 \operatorname{Re} \{ c \chi_d \eta^* Z_{gsw} \} + \chi_d^2 |Z_{gsw}|^2 \right)$$

where:  $\frac{\overline{i_{nd}^2}}{\Delta f} = 4kT\gamma g_{do}$ ,  $\chi_d = \frac{g_m}{g_{do}} \sqrt{\frac{\delta}{5\gamma}}$ ,  $Z_{gsw} = wC_{gs}Z_{gs}$

$$Z_{gs} = \frac{1}{sC_{gs}} \left| \left| \frac{Z_{deg} + Z_g}{1 + g_m Z_{deg}} \right| \right|$$

$$\eta = 1 - \left( \frac{g_m Z_{deg}}{Z_{deg} + Z_g} \right) Z_{gs}$$

## Example: Output Current Noise with $Z_s = R_s$ , $Z_{deg} = 0$



- Step 1: Determine key noise parameters
  - For 0.18 $\mu$  CMOS, we will assume the following

$$c = -j0.55, \quad \gamma = 3, \quad \delta = 2\gamma = 6, \quad \frac{g_m}{g_{do}} = \frac{1}{2} \Rightarrow \chi_d = 0.32$$

- Step 2: calculate  $\eta$  and  $Z_{gsw}$

$$\eta = 1,$$

$$Z_{gsw} = wC_{gs} \left( R_s \parallel \frac{1}{jwC_{gs}} \right) = \frac{wC_{gs}R_s}{1 + jwC_{gs}R_s}$$

## *Calculation of Output Current Noise (continued)*

- Step 3: Plug values into the previously derived expression

$$\frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \left( 1 + 2\text{Re} \{ -j|c|\chi_d Z_{gsw} \} + \chi_d^2 |Z_{gsw}|^2 \right)$$

**Drain Noise Multiplying Factor**

- For  $w \ll 1/(R_s C_{gs})$ :

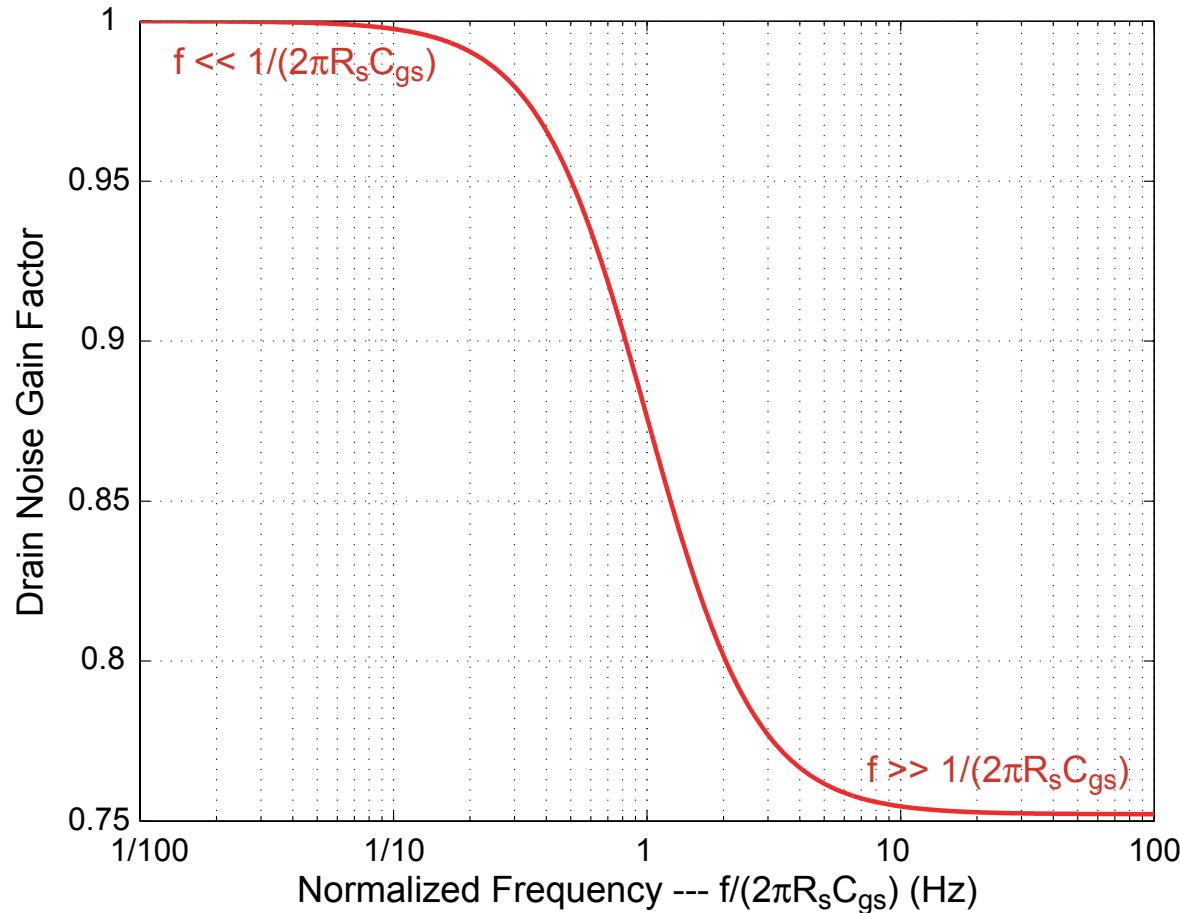
$$Z_{gsw} \approx wC_{gs}R_s \quad \Rightarrow \quad \frac{\overline{i_{ndg}^2}}{\Delta f} \approx \frac{\overline{i_{nd}^2}}{\Delta f} \underbrace{\left( 1 + \chi_d^2 (wC_{gs}R_s)^2 \right)}_{\text{Gate noise contribution}}$$

- For  $w \gg 1/(R_s C_{gs})$ :

$$Z_{gsw} \approx 1/j \quad \Rightarrow \quad \frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \underbrace{\left( 1 - 2|c|\chi_d + \chi_d^2 \right)}_{\text{Gate noise contribution}}$$

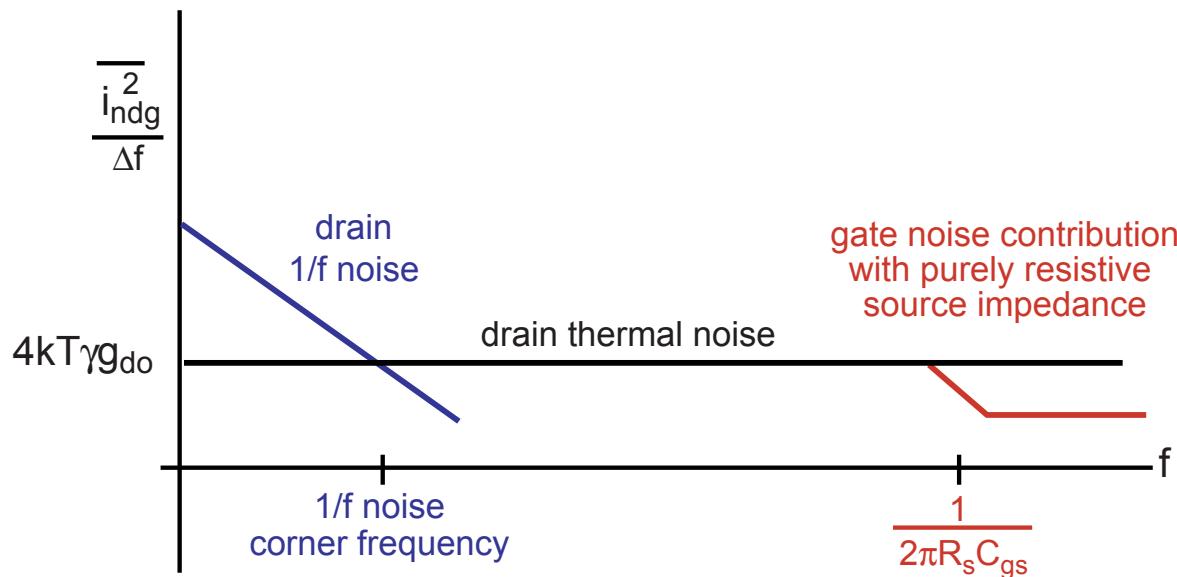
# Plot of Drain Noise Multiplying Factor (0.18 $\mu$ NMOS)

Drain Noise Multiplying Factor Versus Frequency for 0.18 $\mu$  NMOS Device



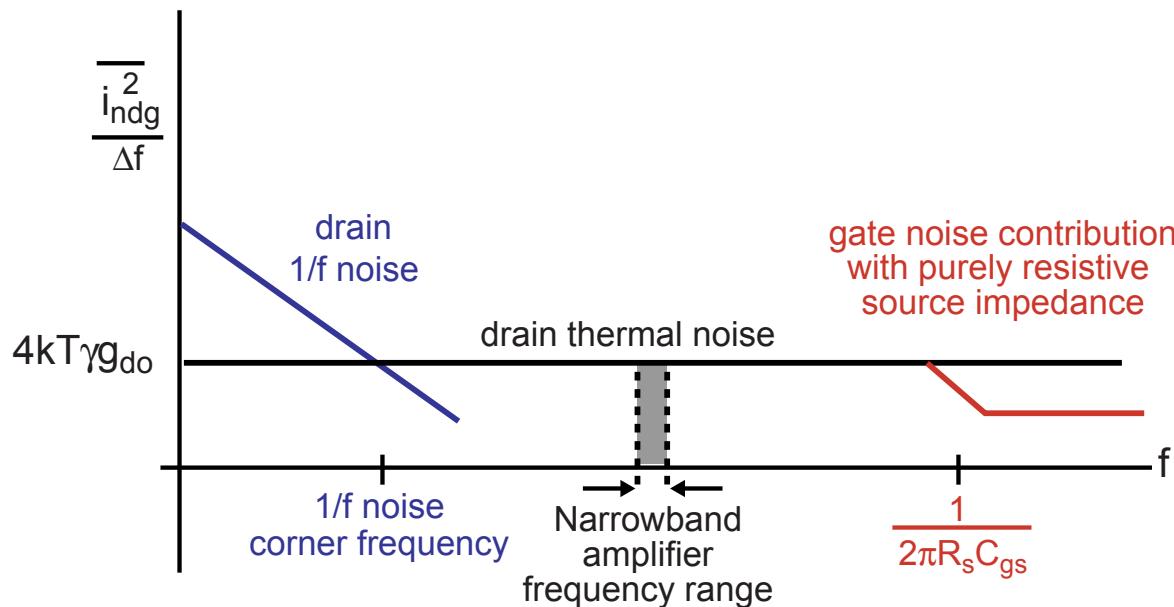
- Conclusion: gate noise has little effect on common source amp when source impedance is purely resistive!

# Broadband Amplifier Design Considerations for Noise



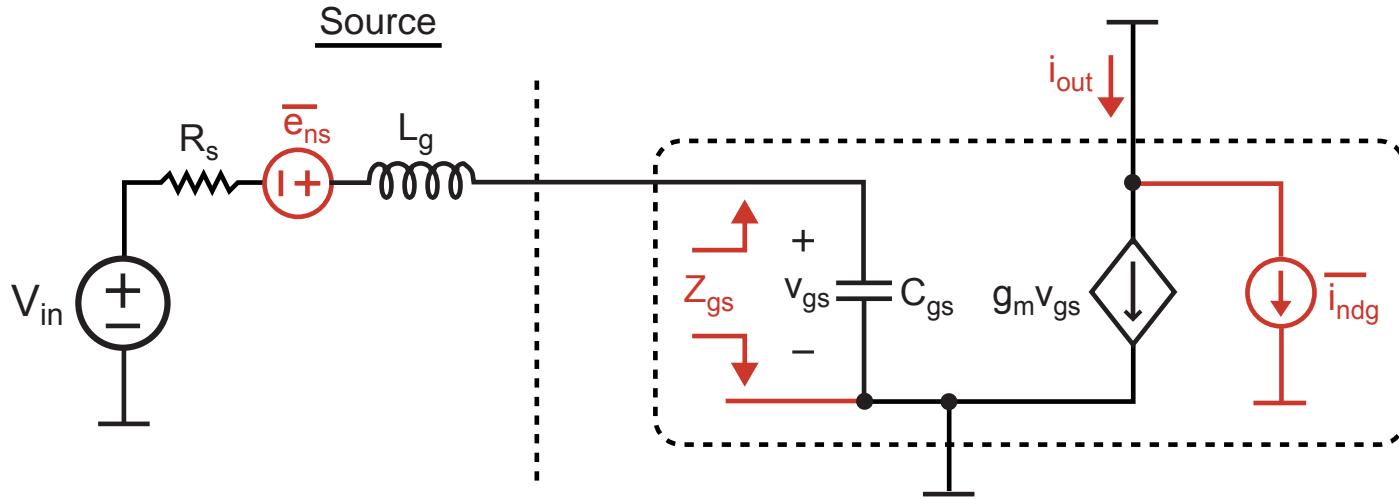
- Drain thermal noise is the chief issue of concern when designing amplifiers with  $> 1 \text{ GHz}$  bandwidth
  - 1/f noise corner is usually less than 1 MHz
  - Gate noise contribution only has influence at high frequencies (such noise will likely be filtered out)
- Noise performance specification is usually given in terms of input referred voltage noise

# Narrowband Amplifier Noise Requirements



- Here we focus on a narrowband of operation
  - Don't care about noise outside that band since it will be filtered out
- Gate noise is a significant issue here
  - Using reactive elements in the source dramatically impacts the influence of gate noise
- Specification usually given in terms of Noise Figure

# The Impact of Gate Noise with $Z_s = R_s + sL_g$



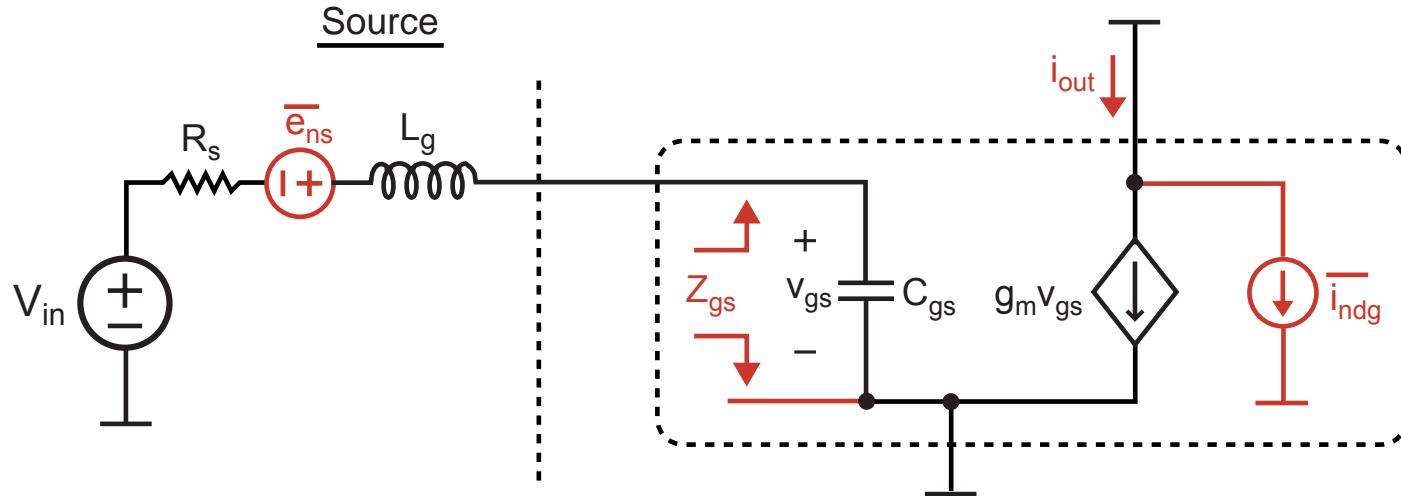
- Step 1: Determine key noise parameters
  - For 0.18 $\mu$  CMOS, again assume the following

$$c = -j0.55, \quad \gamma = 3, \quad \delta = 2\gamma = 6, \quad \frac{g_m}{g_{do}} = \frac{1}{2} \Rightarrow \chi_d = 0.32$$

- Step 2: Note that  $\eta = 1$ , calculate  $Z_{gsw}$

$$Z_{gsw} = wC_{gs} \left( (R_s + jwL_g) \parallel \frac{1}{jwC_{gs}} \right) = \frac{wC_{gs}(R_s + jwL_g)}{1 - w^2 L_g C_{gs} + jwC_{gs} R_s}$$

# Evaluate $Z_{gsw}$ At Resonance



- Set  $L_g$  such that it resonates with  $C_{gs}$  at the center frequency ( $w_o$ ) of the narrow band of interest

$$\Rightarrow \frac{1}{\sqrt{L_g C_{gs}}} = w_o$$

Note:  $Q = \frac{1}{w_o C_{gs} R_s} = \frac{w_o L_g}{R_s}$

- Calculate  $Z_{gsw}$  at frequency  $w_o$

$$\begin{aligned} Z_{gsw} &= \frac{w_o C_{gs} (R_s + j w_o L_g)}{1 - w_o^2 L_g C_{gs} + j w_o C_{gs} R_s} = w_o C_{gs} (Q^2 R_s - j \sqrt{L_g / C_{gs}}) \\ &= Q - j \end{aligned}$$

## The Impact of Gate Noise with $Z_s = R_s + sL_g$ (Cont.)

- Key noise expression derived earlier

$$\frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \left( 1 + 2\text{Re} \{-j|c|\chi_d Z_{gsd}\} + \chi_d^2 |Z_{gsd}|^2 \right)$$

- Substitute in for  $Z_{gsd}$

$$2\text{Re} \{-j|c|\chi_d Z_{gsd}\} = 2\text{Re} \{-j|c|\chi_d(Q - j)\} = -2|c|\chi_d$$

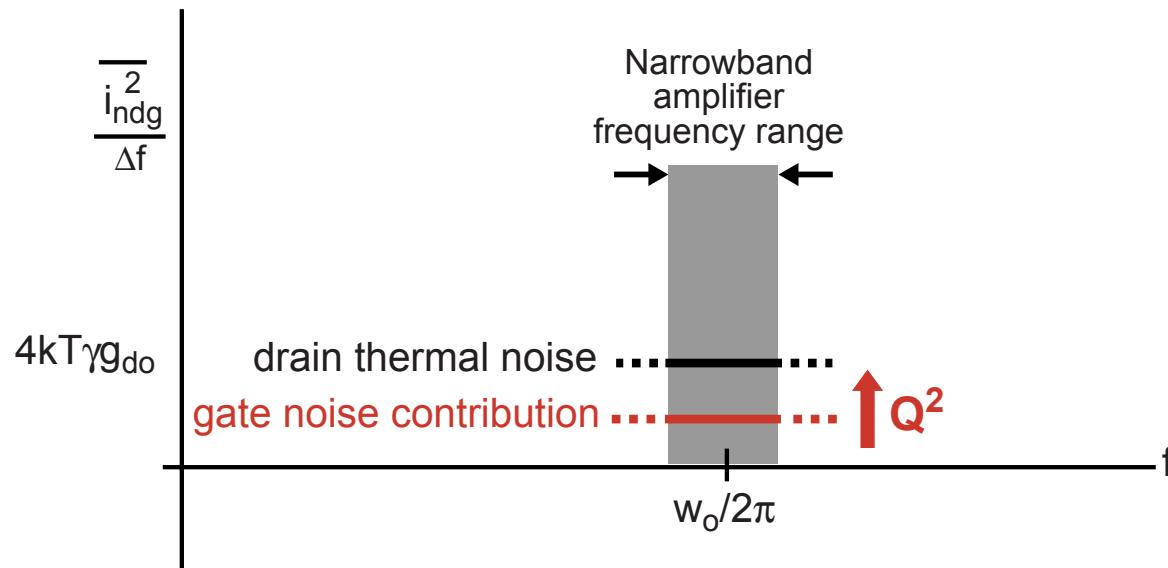
$$\chi_d^2 |Z_{gsd}|^2 = \chi_d^2 |Q - j|^2 = \chi_d^2 (Q^2 + 1)$$

$$\Rightarrow \frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \left( 1 - 2|c|\chi_d + \chi_d^2 (Q^2 + 1) \right)$$

Gate noise contribution

- Gate noise contribution is a function of Q!
  - Rises monotonically with Q

# At What Value of Q Does Gate Noise Exceed Drain Noise?

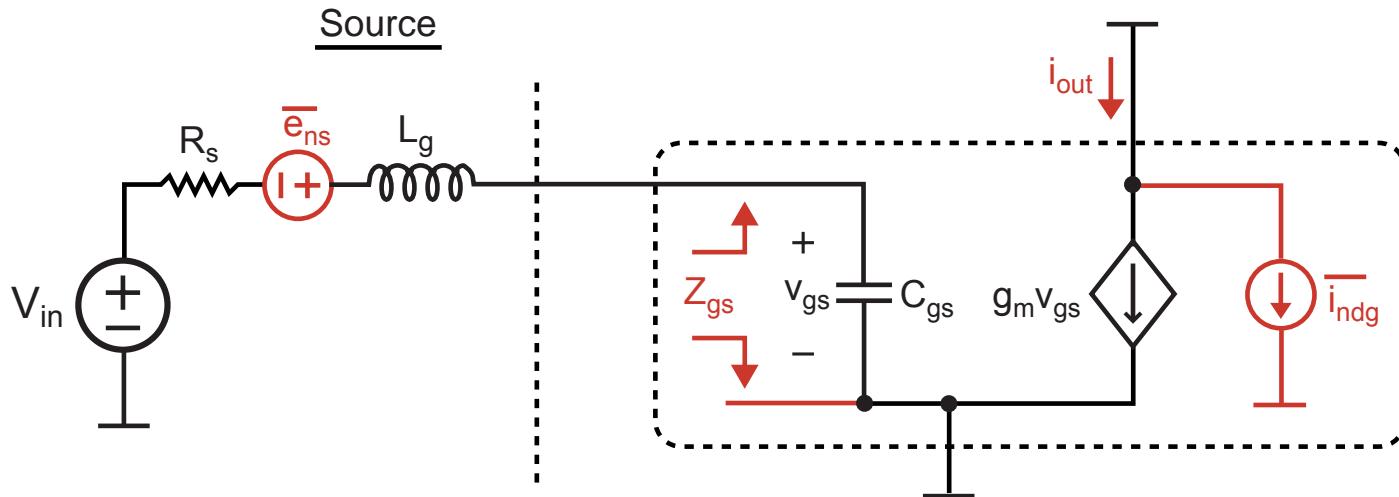


- Determine crossover point for Q value

$$\frac{\overline{i_{ndg}^2}}{\Delta f} = \frac{\overline{i_{nd}^2}}{\Delta f} \left( 1 - 2|c|\chi_d + \chi_d^2(Q^2 + 1) \right) = 1$$
$$\Rightarrow Q = \sqrt{1/\chi_d^2 - 1 + 2|c|/\chi_d} \quad (= 3.5 \text{ for } 0.18\mu \text{ specs})$$

- Critical Q value for crossover is primarily set by process

# Calculation of the Signal Spectrum at the Output



- First calculate relationship between  $v_{in}$  and  $i_{out}$

$$i_{out,sig} = g_m v_{gs} = g_m \frac{1}{1 - w^2 L_g C_{gs} + j w R_s C_{gs}} V_{in}$$

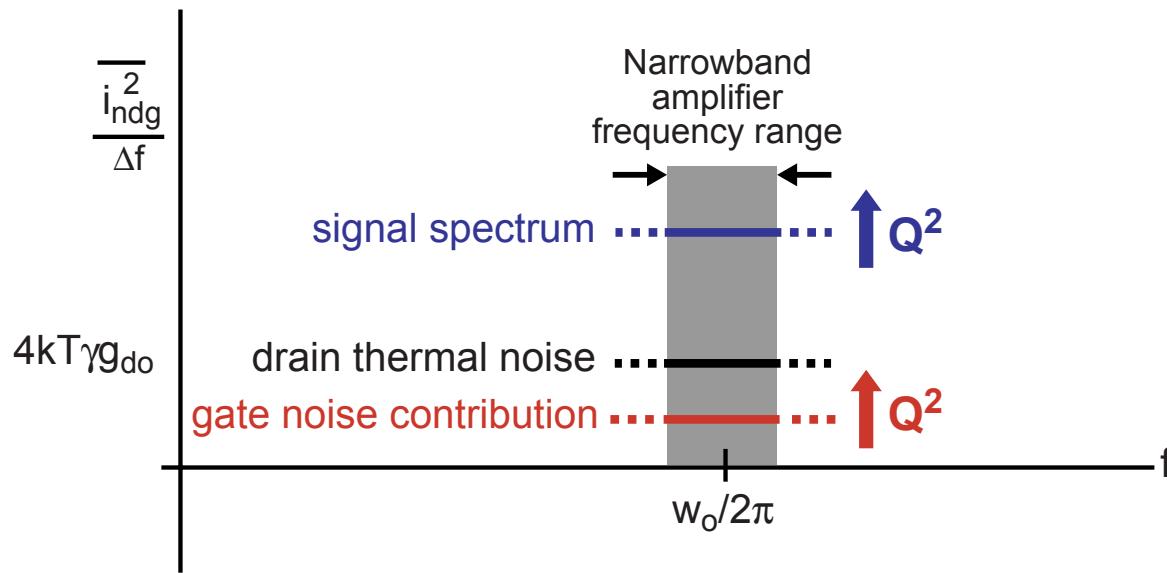
- At resonance:

$$i_{out,sig} = g_m v_{gs} = g_m \frac{1}{j w_o R_s C_{gs}} v_{in} = g_m (-j Q) v_{in}$$

- Spectral density of signal at output at resonant frequency

$$S_{iout,sig}(f) = |g_m(-jQ)|^2 S_{in}(f) = (g_m Q)^2 S_{in}(f)$$

## Impact of Q on SNR (Ignoring $R_s$ Noise)

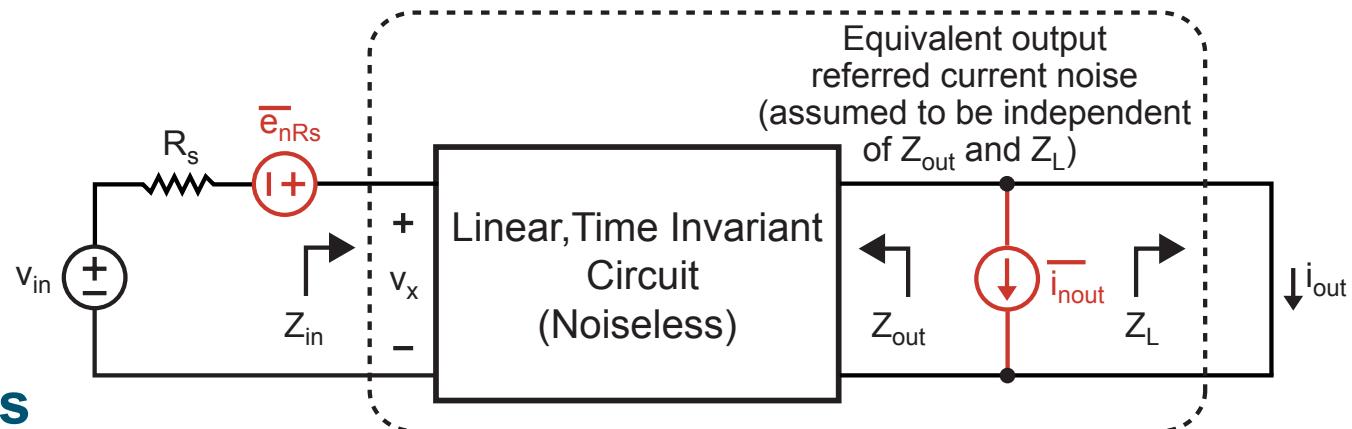


- **SNR (assume constant spectra, ignore noise from  $R_s$ ):**

$$SNR_{out} = \frac{S_{iout,sig}(f)}{S_{iout,noise}(f)} \approx \frac{(gmQ)^2 S_{in}(f)}{\overline{i_{ndg}^2}/\Delta f}$$

- **For small Q such that gate noise < drain noise**
  - $SNR_{out}$  improves dramatically as Q is increased
- **For large Q such that gate noise > drain noise**
  - $SNR_{out}$  improves very little as Q is increased

# Noise Factor and Noise Figure



## ■ Definitions

$$\text{Noise Factor} = F = \frac{SNR_{in}}{SNR_{out}}$$

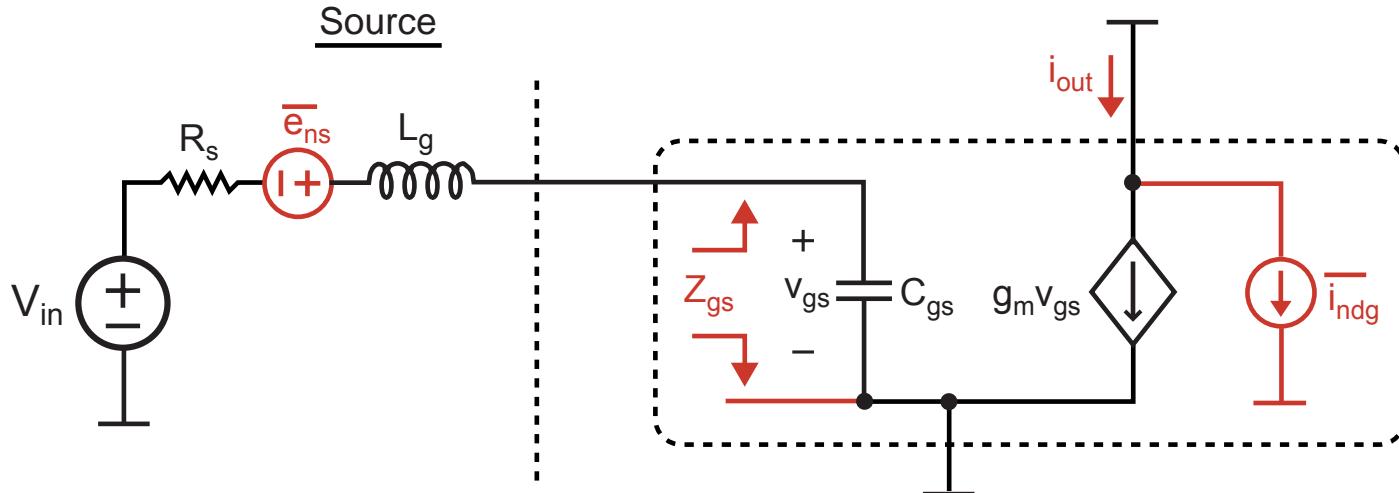
$$\text{Noise Figure} = 10 \log(\text{Noise Factor})$$

## ■ Calculation of $SNR_{in}$ and $SNR_{out}$

$$SNR_{in} = \frac{|\alpha|^2 v_{in}^2}{|\alpha|^2 e_{nRs}^2} = \frac{v_{in}^2}{e_{nRs}^2} \quad \text{where } \alpha = \frac{Z_{in}}{R_s + Z_{in}}$$

$$SNR_{out} = \frac{|\alpha|^2 |G_m|^2 v_{in}^2}{|\alpha|^2 |G_m|^2 e_{nRs}^2 + i_{nout}^2} \quad \text{where } G_m = \frac{i_{out}}{v_x}$$

# Calculate Noise Factor (Part 1)



- First calculate  $SNR_{out}$  (must include  $R_s$  noise for this)
  - $R_s$  noise calculation (same as for  $V_{in}$ )
$$i_{out,Rs} = g_m(-jQ) \overline{e_{ns}} \Rightarrow S_{iout,Rs}(f) = (g_m Q)^2 4kT R_s$$
  - $SNR_{out}$ : 
$$SNR_{out} = \frac{(g_m Q)^2 S_{in}(f)}{i_{ndg}^2 / \Delta f + (g_m Q)^2 4kT R_s}$$
- Then calculate  $SNR_{in}$ : 
$$SNR_{in} = \frac{S_{in}(f)}{\overline{e_{ns}^2} / \Delta f} = \frac{S_{in}(f)}{4kT R_s}$$

## Calculate Noise Factor (Part 2)

$$SNR_{out} = \frac{|g_m Q|^2 S_{in}(f)}{\overline{i_{ndg}^2}/\Delta f + (g_m Q)^2 4kTR_s} \quad SNR_{in} = \frac{S_{in}(f)}{\overline{e_{ns}^2}/\Delta f} = \frac{S_{in}(f)}{4kTR_s}$$

- **Noise Factor calculation:**

$$\begin{aligned} \text{Noise Factor} &= \frac{SNR_{in}}{SNR_{out}} = \frac{\overline{i_{ndg}^2}/\Delta f + |g_m Q|^2 4kTR_s}{(g_m Q)^2 4kTR_s} \\ &= 1 + \frac{\overline{i_{ndg}^2}/\Delta f}{(g_m Q)^2 4kTR_s} \end{aligned}$$

- **From previous analysis**

$$\overline{i_{ndg}^2}/\Delta f = 4kT\gamma g_{do} \left( 1 - 2|c|\chi_d + (Q^2 + 1)\chi_d^2 \right)$$

$$\Rightarrow \text{Noise Factor} = 1 + \frac{\gamma g_{do} \left( 1 - 2|c|\chi_d + (Q^2 + 1)\chi_d^2 \right)}{(g_m Q)^2 R_s}$$

## Calculate Noise Factor (Part 3)

$$\text{Noise Factor} = 1 + \frac{\gamma g_{do} (1 - 2|c|\chi_d + (Q^2 + 1)\chi_d^2)}{(g_m Q)^2 R_s}$$

- Modify denominator using expressions for  $Q$  and  $w_t$

$$Q = \frac{1}{w_o R_s C_{gs}}, \quad w_t \approx \frac{g_m}{C_{gs}}$$

$$\Rightarrow (g_m Q)^2 R_s = g_m^2 Q \frac{R_s}{w_o R_s C_{gs}} = g_m Q \frac{g_m}{C_{gs} w_o} \frac{1}{w_o} = g_m Q \frac{w_t}{w_o}$$

- Resulting expression for noise factor:

$$\text{Noise Factor} = 1 + \left( \frac{w_o}{w_t} \right) \gamma \left( \frac{g_{do}}{g_m} \right) \frac{1}{Q} (1 - 2|c|\chi_d + (Q^2 + 1)\chi_d^2)$$

**Noise Factor scaling coefficient**

- Noise factor primarily depends on  $Q$ ,  $w_o/w_t$ , and process specs

## **Minimum Noise Factor**

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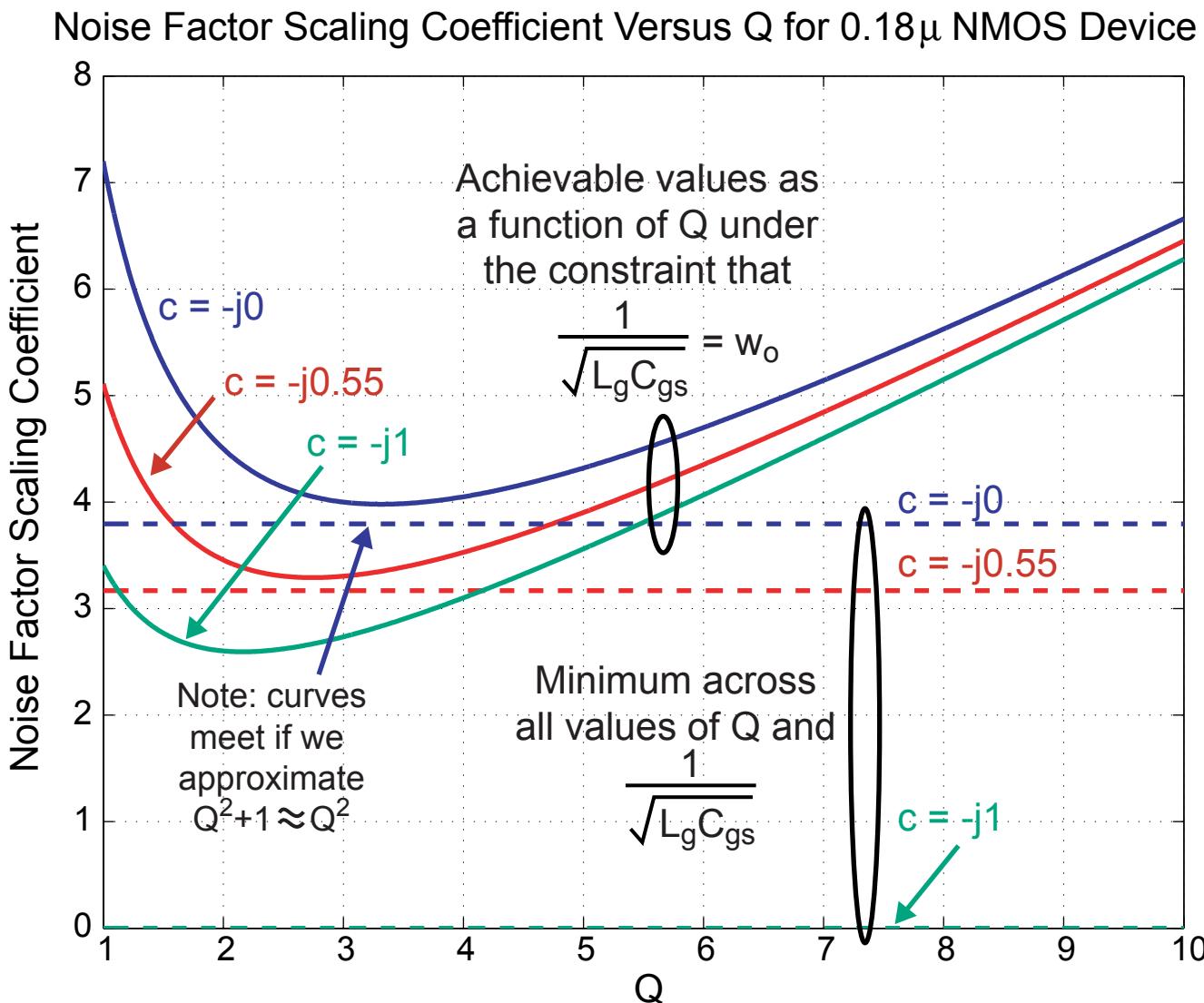
$$\text{Noise Factor} = \frac{1 + \left(\frac{w_o}{w_t}\right) \gamma \left(\frac{g_{do}}{g_m}\right) \frac{1}{Q} (1 - 2|c|\chi_d + (Q^2 + 1)\chi_d^2)}{\text{Noise Factor scaling coefficient}}$$

- We see that the noise factor will be minimized for some value of Q
  - Could solve analytically by differentiating with respect to Q and solving for peak value (i.e. where deriv. = 0)
- In Tom Lee's book (pp 272-277), the minimum noise factor for the MOS common source amplifier (i.e. no degeneration) is found to be:

$$\text{Min Noise Factor} = \frac{1 + \left(\frac{w_o}{w_t}\right) \frac{2}{\sqrt{5}} \sqrt{\gamma \delta (1 - |c|^2)}}{\text{Noise Factor scaling coefficient}}$$

- How do these compare?

# Plot of Minimum Noise Factor and Noise Factor Vs. Q



## *Achieving Minimum Noise Factor*

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- For common source amplifier without degeneration
  - Minimum noise factor can only be achieved at resonance if gate noise is uncorrelated to drain noise (i.e., if  $c = 0$ ) – we'll see this next lecture
  - We typically must operate slightly away from resonance in practice to achieve minimum noise factor since  $c$  will be nonzero
- How do we determine the optimum source impedance to minimize noise figure in classical analysis?
  - Next lecture!