

MIT OpenCourseWare
<http://ocw.mit.edu>

6.854J / 18.415J Advanced Algorithms
Fall 2008

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.

Lecture 3

Lecturer: Michel X. Goemans

Scribe: Abhinav Kumar, Nodari Sitchinava

1 Proof of Farkas' Lemma

Theorem 1 [Farkas' Lemma] *Either*

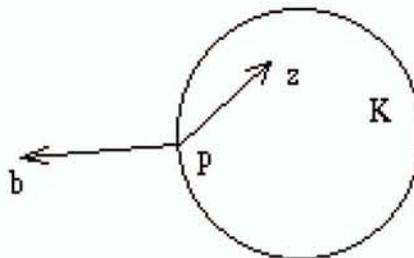
1. $Ax = b, x \geq 0$ has a solution, or
2. $A^T y \geq 0$ and $y^T b < 0$ has a solution,

but not both.

The reason that 1 and 2 cannot both occur is that $(y^T A)x = y^T b$, so if $y^T A$ is non-negative and x is non-negative, then $y^T b$ can't be negative.

To prove Farkas' Lemma we need the Projection Theorem:

Theorem 2 *Let K be a closed, convex and non-empty set in \mathbb{R}^n , and $b \in \mathbb{R}^n, b \notin K$. Define projection p of b onto K to be $x \in K$ such that $\|b - x\|$ is minimized. Then for all $z \in K$: $(b - p)^T(z - p) \leq 0$.*



Proof of Farkas' Lemma: Assume $Ax = b, x \geq 0$ is not feasible. Let $K = \{Ax : x \geq 0\}$. Therefore, $b \notin K$. Let $p = Aw, w \geq 0$ be the projection of b onto K . Then we know that

$$(b - Aw)^T(Ax - Aw) \leq 0 \text{ for all } x \geq 0 \quad (1)$$

Define $y = p - b = Aw - b$. Therefore,

$$(x - w)^T A^T y \geq 0 \text{ for all } x \geq 0 \quad (2)$$

Let e_i be the $n \times 1$ vector that has 1 in its i 'th component and 0 everywhere else. Take $x = w + e_i$. Therefore, $x - w = e_i$, and by (2),

$$e_i^T A^T y \geq 0 \Rightarrow (A^T y)_i \geq 0 \text{ for all } i$$

Thus since each element of $A^T y$ is non-negative, $A^T y \geq 0$.

Now, $y^T b = y^T(p - y) = y^T p - y^T y$. From (1) if $x = 0$,

$$\begin{aligned} (b - Aw)^T(Ax - Aw) &= (b - Aw)^T(-Aw) \\ &= -y^T(-Aw) \\ &= y^T Aw \\ &= y^T p \leq 0 \end{aligned}$$

and

$$y^T p - y^T y \leq -y^T y < 0$$

The last inequality comes from the fact that $y = b - p, b \notin K$, so $b - p \neq 0 \Rightarrow y^T y > 0$ □

Theorem 3 [Another variant of Farkas' Lemma] *Either*

1. $Ax \leq b$ has a solution, or
2. $A^T y = 0, b^T y < 0, y \geq 0$ has a solution,
but not both (for then we would have $0 = y^T Ax \leq y^T b < 0$.)

2 Duality

Consider an LP P in the standard form (we call this LP the primal). We can write a “dual” LP D as follows:

$$\begin{array}{ll} \text{Primal } P: & z^* = \min c^T x \\ & \text{subj to} \\ & Ax = b \\ & x \geq 0 \end{array} \qquad \begin{array}{ll} \text{Dual } D: & w^* = \max b^T y \\ & \text{subj to} \\ & A^T y \leq c \end{array}$$

Weak duality states the following.

Theorem 4 [Weak Duality] *Let x be feasible in P , and let y be feasible in D . Then*

$$c^T x \geq b^T y$$

Proof of Theorem 4:

$$\begin{aligned} c^T x - b^T y &= x^T c - x^T A^T y \\ &= x^T (c - A^T y) \\ &\geq 0, \end{aligned}$$

since x and $c - A^T y$ both have nonnegative coordinates. □

The following three cases are possible for an LP:

Primal	Dual
1) infeasible ($z^* = +\infty$)	1') infeasible ($w^* = -\infty$)
2) unbounded ($z^* = -\infty$)	2') unbounded ($w^* = +\infty$)
3) finite ($z^* = \text{finite real number}$)	3') finite ($w^* = \text{finite real number}$)

Then $2 \Rightarrow 1'$ because if the dual were feasible, any value $b^T y$ for the dual would be a lower bound for the primal, which could therefore not be unbounded. Similarly $2' \Rightarrow 1$. Note that we can have 1 and $1'$ occurring simultaneously.

Theorem 5 [Strong duality] *If P or D is feasible then $z^* = w^*$.*

Proof of Theorem 2: It suffices to treat the case when the primal is feasible, because the primal and dual are interchangeable. So assume P is feasible. If P is unbounded then weak duality implies that D is infeasible, and then $z^* = w^* = -\infty$. So from now on assume that the primal is finite.

Claim 6 *There exists a solution of dual of value at least z^* , i.e.,*

$$\exists y : A^T y \leq c, b^T y \geq z^*$$

Proof of Claim 3: We wish to prove that there is a y satisfying

$$\begin{pmatrix} A^T \\ -b^T \end{pmatrix} y \leq \begin{pmatrix} c \\ -z^* \end{pmatrix}.$$

Assume the claim is wrong. Then the variant of Farkas' Lemma implies that the LP

$$\begin{aligned} (A \quad -b) \begin{pmatrix} x \\ \lambda \end{pmatrix} &= 0 \\ (c^T \quad -z^*) \begin{pmatrix} x \\ \lambda \end{pmatrix} &< 0 \\ x \in \mathbb{R}^n, \lambda \in \mathbb{R}, \quad x, \lambda &\geq 0 \end{aligned}$$

has a solution. That is, there exist nonnegative x, λ with

$$\begin{aligned} Ax - b\lambda &= 0 \\ c^T x - z^* \lambda &< 0 \end{aligned}$$

Case 1: $\lambda > 0$. Then $A(\frac{x}{\lambda}) = b$, $c^T(\frac{x}{\lambda}) < z^*$. This contradicts the minimality of z^* for the primal, hence this case cannot occur.

Case 2: $\lambda = 0$. Then $Ax = 0$, $c^T x < 0$. Take any feasible solution \hat{x} for P . Then for every $\mu \geq 0$, $\hat{x} + \mu x$ is feasible for P , since

- a) $\hat{x} + \mu x \geq 0$ because $\hat{x} \geq 0, x \geq 0, \mu \geq 0$.
- b) $A(\hat{x} + \mu x) = A\hat{x} + \mu Ax = b + \mu \cdot 0 = b$.

But $c^T(\hat{x} + \mu x) = c^T \hat{x} + \mu c^T x \rightarrow -\infty$ as $\mu \rightarrow \infty$. This contradicts the assumption that the primal has finite solution.

□

The above claim shows that if P or D is finite then the other is too, and the optimums are equal ($z^* \geq w^*$ is weak duality and the claim shows $w^* \geq z^*$.) This concludes the proof of the strong duality theorem. □

3 Complementary Slackness

Consider the following primal LP.

$$\begin{aligned} \min \quad & c^T x \\ & Ax = b \\ & x \geq 0 \end{aligned}$$

We write the dual as follows:

$$\begin{aligned} \max \quad & b^T y \\ & A^T y + s = c \\ & s \geq 0, \quad y \in \mathbb{R}^m, s \in \mathbb{R}^n \end{aligned}$$

Theorem 7 *Let x be feasible for the primal, and y be feasible for the dual. Then x is optimal for P and y is optimal for D if and only if $x_j s_j = 0$ for all j .*

Proof: We have

$$\begin{aligned} c^T x - b^T y &= x^T c - x^T A^T y \\ &= x^T (c - A^T y) \\ &= x^T s \end{aligned}$$

When both x and y are optimal, the above difference must be zero, and conversely, if the difference is zero, both must be optimal by weak duality. But since x, s are nonnegative, $x^T s$ is zero if and only if $x_j s_j = 0$ for all j . \square

So, to prove that a solution to an LP is optimal, all we need to do is to give an x and a (y, s) and show that both are feasible and the complementary slackness condition is satisfied.

4 Size of a linear program

Let's think about how we encode the LP. We can use binary encoding to give the entries of A, b, c , that defines the LP in standard form. For an integer k , it takes $size(k) = 1 + \lceil \log_2(|k| + 1) \rceil$ bits to encode k . So,

$$size(LP) = \sum_{i,j} size(a_{ij}) + \sum_j size(c_j) + \sum_i size(b_i)$$

A polynomial-time algorithm for linear programming is an algorithm whose worst-case running time is bounded by a polynomial in the size of the input LP.