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6.854J / 18.415J Advanced Algorithms
Fall 2008

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Problem Set 3

1. Consider the following optimization problem:

Given $c \in \mathbb{R}^n$, $c \geq 0$, n even, find

$$\min\{c^T x : \sum_{i \in S} x_i \geq 1 \quad \forall S \subset \{1, \dots, n\}, |S| = \frac{n}{2}, \\ x_j \geq 0 \quad \forall j\}.$$

In class, it was shown that this can be solved by the ellipsoid method because there is an efficient separation algorithm. However, this problem has a more straightforward solution.

Develop an algorithm which finds the optimum in $O(n \log n)$ time. Prove its correctness.

2. Fill a gap in the analysis of the interior point algorithm:

Suppose that (x, y, s) is a feasible vector, i.e. $x > 0$, $s > 0$,

$$Ax = b,$$

$$A^T y + s = c$$

and we perform one Newton step by solving for $\Delta x, \Delta y, \Delta s$:

$$A\Delta x = 0$$

$$A^T \Delta y + \Delta s = 0$$

$$\forall j; \quad x_j s_j + \Delta x_j s_j + x_j \Delta s_j = \mu$$

where $\mu > 0$. The proximity function is defined as

$$\sigma(x, s, \mu) = \sqrt{\sum_j \left(\frac{x_j s_j}{\mu} - 1\right)^2}.$$

Prove that if

$$\sigma(x + \Delta x, s + \Delta s, \mu) < 1$$

then $(x + \Delta x, y + \Delta y, s + \Delta s)$ is a feasible vector for $Ax = b, x > 0$ and $A^T y + s = c, s > 0$.

3. Given a directed graph $G = (V, E)$ and two vertices s and t , we would like to find the maximum number of edge-disjoint paths between s and t (two paths are edge-disjoint if they don't share an edge). Denote the number of vertices by n and the number of edges by m .

- (a) Argue that this problem can be solved as a maximum flow problem with unit capacities. Explain.
- (b) Consider now the maximum flow problem on directed graphs $G = (V, E)$ with unit capacity edges (although some of the questions below would also apply to the more general case).

Given a feasible flow f , we can construct the *residual network* $G_f = (V, E_f)$ where

$$E_f = \{(i, j) : ((i, j) \in E \ \& \ f_{ij} < u_{ij}) \text{ or } ((j, i) \in E \ \& \ f_{ji} > 0)\}.$$

The residual capacity of an edge $(i, j) \in E_f$ is equal to $u_{ij} - f_{ij}$ or to f_{ji} depending on the case above. Since we are dealing with the unit capacity case, all the u_{ij} 's are 1 and therefore for 0 – 1 flows f (i.e. flows for which the value on any edge is 0 or 1), all residual capacities will be 1.

We define the distance of a vertex $l_f(v)$ as the length of the shortest path from s to v in E_f (∞ for vertices which are not reachable from s in E_f). Further, define the *levelled residual network* as

$$E_f^l = \{(i, j) \in E_f : l_f(j) = l_f(i) + 1\}$$

and a *saturating flow* g in E_f^l as a flow in E_f^l (with capacities being the residual capacities) such that every directed $s - t$ path in E_f^l has at least one saturated edge (i.e. an edge whose flow equals the residual capacity).

For a unit capacity graph and a given 0 – 1 flow f , show how we can find the levelled residual network and a saturating flow in $O(m)$ time.

- (c) Prove that if the levelled residual network has no path from s to t ($l_f(t) = \infty$), then the flow f is maximum.
- (d) For a flow f , define

$$d(f) = l_f(t)$$

(the distance from s to t in the residual network). Prove that if g is a saturating flow for f then

$$d(f + g) > d(f),$$

where $f + g$ denotes the flow obtained from f by either increasing the flow f_{ij} by g_{ij} or decreasing the flow f_{ji} by g_{ij} for every edge $(i, j) \in G_f$.

- (e) Prove that if f is a feasible 0 – 1 flow with distance $d = d(f)$ and f^* is an optimum flow, then

$$\text{value}(f^*) \leq \text{value}(f) + \frac{m}{d}$$

and also

$$\text{value}(f^*) \leq \text{value}(f) + \frac{n^2}{d^2}.$$

- (f) Design a maximum flow algorithm (for unit capacities) which proceeds by finding a saturating flow repeatedly. Try to optimize its running time. Using the observations above, you should achieve a running time bounded by $O(\min(mn^{2/3}, m^{3/2}))$.
- (g) Can we now justify that, for 0 – 1 capacities, there is always an optimum flow that takes values 0 or 1 on every edge?