

6.641 Electromagnetic Fields, Forces, and Motion
Spring 2009

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Problem 1

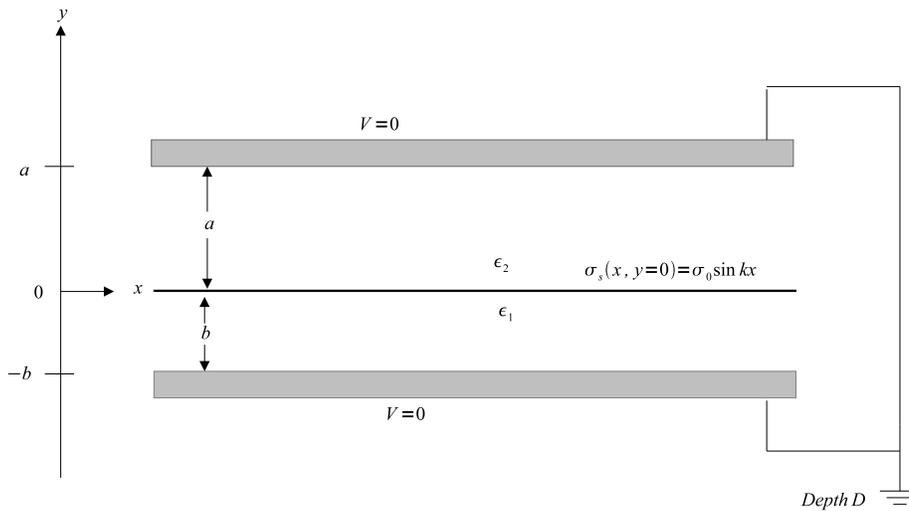


Figure 1: A diagram of a sheet of surface charge at $y = 0$ between two grounded perfect conductors at $y = -b$ and $y = a$ (Image by MIT OpenCourseWare).

A sheet of surface charge with surface charge distribution $\sigma_s(x, y = 0) = \sigma_0 \sin kx$ is placed at $y = 0$, parallel and between two parallel grounded perfect conductors at zero potential at $y = -b$ and $y = a$. The regions above and below the potential sheet have dielectric permittivities of ϵ_2 and ϵ_1 . Neglect fringing field effects.

A

Question: What are the electric potential solutions in the regions $0 \leq y \leq a$ and $-b \leq y \leq 0$?

Solution:

$$\Phi(x, y) = \begin{cases} A \sinh k(y - a) \sin kx & 0 < y < a \\ B \sinh k(y + b) \sin kx & -b < y < 0 \end{cases}$$

$$\Phi(x, y = 0_-) = \Phi(x, y = 0_+) \Rightarrow -A \sinh ka = B \sinh kb$$

$$E_y(x, y = 0_+) = -\frac{\partial \Phi}{\partial y} \Big|_{y=0_+} = -Ak \cosh k(y - a) \sin kx \Big|_{y=0_+} = -Ak \cosh ka \sin kx$$

$$E_y(x, y = 0_-) = -\frac{\partial \Phi}{\partial y} \Big|_{y=0_-} = -Bk \cosh k(y + b) \sin kx \Big|_{y=0_-} = -Bk \cosh kb \sin kx$$

$$\sigma_s(x, y = 0) = \sigma_0 \sin kx = \epsilon_2 E_y(x, y = 0_+) - \epsilon_1 E_y(x, y = 0_-) = -\epsilon_2 Ak \cosh ka \sin kx + \epsilon_1 Bk \cosh kb \sin kx$$

$$\sigma_0 = -\epsilon_2 Ak \cosh ka + \epsilon_1 Bk \cosh kb$$

$$\begin{aligned} B &= -\frac{A \sinh ka}{\sinh kb} \Rightarrow -\epsilon_2 Ak \cosh ka - \epsilon_1 k \frac{A \sinh ka \cosh kb}{\sinh kb} = \sigma_0 \\ &\Rightarrow -Ak \left[\epsilon_2 \cosh ka + \frac{\epsilon_1 \sinh ka \cosh kb}{\sinh kb} \right] = \sigma_0 \end{aligned}$$

$$A = \frac{-\sigma_0 \sinh kb}{k[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]}$$

$$B = \frac{-A \sinh ka}{\sinh kb} = \frac{\sigma_0 \sinh ka}{k[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]}$$

$$\Phi(x, y) = \begin{cases} A \sinh k(y-a) \sin kx = \frac{-\sigma_0 \sinh kb \sinh k(y-a) \sin kx}{k[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]} & 0 < y < a \\ B \sinh k(y+b) \sin kx = \frac{\sigma_0 \sinh ka \sinh k(y+b) \sin kx}{k[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]} & -b < y < 0 \end{cases}$$

B

Question: What are the electric field distributions in the regions $0 < y < a$ and $-b < y < 0$?

Solution:

$$\begin{aligned} 0 < y < a \quad \vec{E} &= -\nabla\Phi = -\left[\frac{\partial\Phi}{\partial x} \vec{i}_x + \frac{\partial\Phi}{\partial y} \vec{i}_y \right] = -Ak \left[\cosh kx \sinh k(y-a) \vec{i}_x + \sin kx \cosh k(y-a) \vec{i}_y \right] \\ -b < y < 0 \quad \vec{E} &= -Bk \left[\cos kx \sinh k(y+b) \vec{i}_x + \sin kx \cosh k(y+b) \vec{i}_y \right] \end{aligned}$$

C

Question: What are the free surface charge distributions at $y = -b$ and $y = a$?

Solution:

$$\begin{aligned} \sigma_s(x, y = -b) &= \epsilon_2 E_y(x, y = -b) \\ &= -\epsilon_2 Bk \sin kx \\ &= \frac{-\sigma_0 \epsilon_2 \sinh ka \sin kx}{[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]} \end{aligned}$$

$$\begin{aligned} \sigma_s(x, y = a) &= -\epsilon_1 E_y(x, y = a) \\ &= \epsilon_1 Ak \sin kx \\ &= \frac{-\epsilon_1 \sigma_0 \sinh kb \sin kx}{[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]} \end{aligned}$$

D

Question: What is the potential distribution at $y = 0$?

Solution:

$$\Phi(x, y = 0) = \frac{\sigma_0 \sinh ka \sinh kb \sin kx}{k[\epsilon_2 \cosh ka \sinh kb + \epsilon_1 \sinh ka \cosh kb]}$$

Problem 2

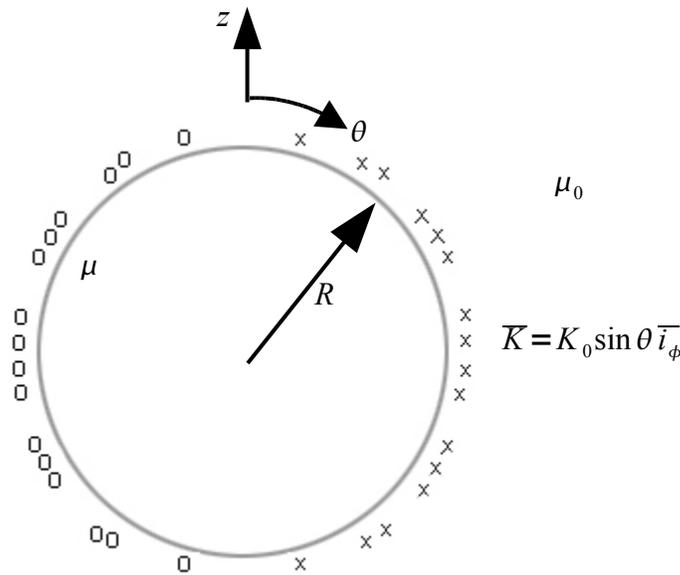


Figure 2: A diagram of a surface current sheet placed on the surface of a sphere of radius R (Image by MIT OpenCourseWare).

A surface current sheet $\vec{K} = K_0 \sin \theta \vec{i}_\phi$ is placed on the surface of a sphere of radius R . The inside of the sphere ($r < R$) has magnetic permeability μ and the outside region ($r > R$) is free space with magnetic permeability μ_0 . The magnetic field at $r = \infty$ is zero.

A

Question: What are the boundary conditions on the magnetic field at $r = 0$ and $r = R$?

Solution:

$$\vec{H}(r = 0) = \text{finite}, \quad H_\theta(r = R_+, \theta) - H_\theta(r = R_-, \theta) = K_0 \sin \theta$$

$$\mu H_r(r = R_-, \theta) = \mu_0 H_r(r = R_+, \theta)$$

B

Question: What are the general form of the solutions for the magnetic scalar potential inside and outside the sphere?

Solution:

$$\nabla \times H = 0 \Rightarrow \bar{H} = -\nabla\chi$$

$$\chi(r, \theta) = \begin{cases} Ar \cos \theta & 0 < r < R \\ \frac{C}{r^2} \cos \theta & R < r < \infty \end{cases}$$

C

Question: Use the boundary conditions of part (a) and solve for the magnetic scalar potential and the magnetic field \bar{H} inside and outside the sphere.

Solution:

$$H_\theta = -\frac{1}{r} \frac{\partial \chi}{\partial \theta} = \begin{cases} A \sin \theta & 0 < r < R \\ \frac{C}{r^3} \sin \theta & R < r < \infty \end{cases}$$

$$H_r = -\frac{\partial \chi}{\partial r} = \begin{cases} -A \cos \theta & 0 < r < R \\ \frac{2C}{r^3} \cos \theta & R < r < \infty \end{cases}$$

$$H_\theta(r = R_+, \theta) - H_\theta(r = R_-, \theta) = K_0 \sin \theta \Rightarrow \frac{C}{R^3} - A = K_0$$

$$\mu H_r(r = R_-, \theta) - \mu_0 H_r(r = R_+, \theta) \Rightarrow -\mu A = \frac{\mu_0 2C}{R^3}$$

$$A = -\frac{\mu_0 2C}{\mu R^3} \Rightarrow \frac{C}{R^3} \left(1 + \frac{2\mu_0}{\mu}\right) = K_0$$

$$C = \frac{K_0 R^3}{1 + \frac{2\mu_0}{\mu}}, \quad A = -\frac{2\mu_0}{\mu} \frac{C}{R^3} = -\frac{2\mu_0}{\mu} \frac{K_0}{1 + \frac{2\mu_0}{\mu}}$$

$$\chi(r, \theta) = \begin{cases} -\frac{2\mu_0}{\mu} \frac{K_0}{1 + \frac{2\mu_0}{\mu}} r \cos \theta & 0 < r < R \\ \frac{K_0 R^3}{1 + \frac{2\mu_0}{\mu}} \frac{\cos \theta}{r^2} & R < r < \infty \end{cases}$$

$$\bar{H}(r, \theta) = \begin{cases} -A(\cos \theta \bar{i}_r - \sin \theta \bar{i}_\theta) = -A \bar{i}_z = \frac{2\mu_0}{\mu} \frac{K_0}{1 + \frac{2\mu_0}{\mu}} \bar{i}_z & 0 < r < R \\ \frac{K_0}{1 + \frac{2\mu_0}{\mu}} \frac{R^3}{r^3} (2 \cos \theta \bar{i}_r + \sin \theta \bar{i}_\theta) & R < r < \infty \end{cases}$$

D

Question: The scalar magnetic potential for a point magnetic dipole of moment $m\bar{i}_z$ at the origin is $\bar{H} = -\nabla\chi$, $\chi = \frac{m \cos \theta}{4\pi r^2}$

What is the effective magnetic moment of the sphere and the surface current sheet for $r > R$?

Solution:

$$\frac{m}{4\pi} = \frac{K_0 R^3}{1 + \frac{2\mu_0}{\mu}} \Rightarrow m = \frac{4\pi K_0 R^3}{1 + \frac{2\mu_0}{\mu}}$$

E

Question: What is the equation for the magnetic field line that passes through the point $(r = R_0, \theta = \frac{\pi}{2})$ where $R_0 > R$.

Solution:

$$\frac{dr}{r d\theta} = \frac{H_r}{H_\theta} = \frac{2 \cos \theta}{\sin \theta} \quad R < r < \infty$$

$$\frac{dr}{r} = \frac{2 \cos \theta d\theta}{\sin \theta}$$

$$\int \frac{dr}{r} = \int \frac{2 \cos \theta}{\sin \theta} d\theta$$

$$\ln r = \int \frac{2 \cos \theta}{\sin \theta} d\theta$$

$$\text{Let } u = \sin \theta, du = \cos \theta d\theta$$

$$\ln r = \int \frac{2 du}{u} = 2 \ln u + C_1 = \ln u^2 + C_1 = \ln(\sin^2 \theta) + C_1$$

$$\ln \frac{r}{\sin^2 \theta} = C_1 \Rightarrow \frac{r}{\sin^2 \theta} = e^{C_1} = C_2$$

$$r = R_0, \theta = \frac{\pi}{2} \Rightarrow C_2 = R_0 \Rightarrow r = R_0 \sin^2 \theta$$

F

Question: For the field line in (e), if $R_0 = 2R$, at what angles of θ does the field line contact the sphere?

Solution:

$$R_0 = 2R \Rightarrow \frac{R}{R_0} = \frac{1}{2} = \sin^2 \theta$$

$$\sin \theta = \frac{1}{\sqrt{2}} \Rightarrow \theta = \frac{\pi}{4}, \frac{3\pi}{4} \quad (45^\circ, 135^\circ)$$

Problem 3

A reluctance motor is made by placing a high permeability material, which is free to rotate, in the air gap of a magnetic circuit excited by a current $i(t)$.

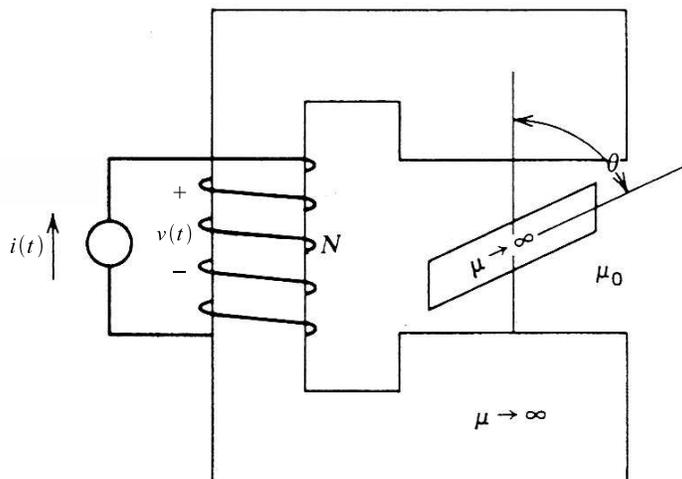


Figure 3: A diagram of a reluctance motor (Image by MIT OpenCourseWare).

The inductance of the magnetic circuit varies with rotor angle θ as

$$L(\theta) = L_0 + L_1 \cos 2\theta, L_0 > 0, 0 < L_1 < L_0$$

where the maximum inductance $L_0 + L_1$ occurs when $\theta = 0$ or $\theta = \pi$ and the minimum inductance $L_0 - L_1$ occurs when $\theta = \pm \frac{\pi}{2}$.

A

Question: What is the magnetic torque, T_{mag} , on the rotor as a function of the angle θ and current $i(t)$?

Solution:

$$T_{mag} = \frac{1}{2} i^2 \frac{dL(\theta)}{d\theta} = \frac{1}{2} i^2 (-L_1 2 \sin 2\theta) = -L_1 i^2 \sin 2\theta$$

B

Question: With $i(t)$ a DC current I , a constant positive mechanical stress $T_{mech} > 0$ is applied. What is the largest value of $T_{mech} = T_{max}$ for which the rotor can be in static equilibrium?

Solution:

$$T_{mech} + T_{mag} = T_{mech} - L_1 i^2 \sin 2\theta = 0$$

$$\text{maximum of } \sin 2\theta = 1$$

$$T_{mech} = T_{max} = L_1 I^2$$

C

Question: If $T_{mech} = \frac{1}{2}T_{max}$, plot the total torque $T_{mag} + T_{mech}$. Use a graphical method to determine the equilibrium values of θ and label which are stable and which are unstable.

Solution:

$$T_T = T_{mech} + T_{mag} = L_1 I^2 \left(\frac{1}{2} - \sin 2\theta \right) = 0$$

$$\sin 2\theta = \frac{1}{2} \Rightarrow 2\theta = \frac{\pi}{6}, \frac{5\pi}{6} \quad (30^\circ, 150^\circ)$$

$$\theta = \frac{\pi}{12}, \frac{5\pi}{12}, \frac{13\pi}{12}, \frac{17\pi}{12} \quad (15^\circ, 75^\circ, 195^\circ, 255^\circ)$$

$$\text{Stable if } \left. \frac{\partial T_T}{\partial \theta} \right|_{T_T=0} < 0 \quad \theta = 15^\circ, 195^\circ \text{ Stable}$$

$$\text{Unstable if } \left. \frac{\partial T_T}{\partial \theta} \right|_{T_T=0} > 0 \quad \theta = 75^\circ, 255^\circ \text{ Unstable}$$

D

Question: If the rotor has moment of inertia J and is slightly perturbed from a stable equilibrium position θ_{eq} at $t = 0$ by an angle position $\theta'(t)$, what is the general frequency of oscillation? What is the oscillation frequency for θ_{eq} found for stable equilibrium in part (c)?

Solution:

$$\theta = \theta_{eq} + \theta'(t)$$

$$T_T(\theta) = T_{mech} + T_{mag}(\theta = \theta_{eq}) = 0$$

$$T_T(\theta = \theta_{eq} + \theta'(t)) = \cancel{T_T(\theta = \theta_{eq})} + \left. \frac{dT_T}{d\theta} \right|_{\theta=\theta_{eq}} \theta'(t)$$

$$\frac{Jd^2\theta}{dt^2} = \frac{Jd^2\theta'}{dt^2} = \left. \frac{dT_T}{d\theta} \right|_{\theta=\theta_{eq}} \theta'$$

$$\frac{d^2\theta'}{dt^2} - \frac{1}{J} \left. \frac{dT_T}{d\theta} \right|_{\theta=\theta_{eq}} \theta' = 0$$

$$\text{Let } \omega_0^2 = -\frac{1}{J} \left. \frac{dT_T}{d\theta} \right|_{\theta_{eq}} \Rightarrow \frac{d^2\theta'}{dt^2} + \omega_0^2 \theta' = 0$$

$$\omega_0^2 > 0 \text{ if } \left. \frac{dT_T}{d\theta} \right|_{\theta_{eq}} < 0$$

% Mathematica code for generating the graph

```
In[1] = f[angle_] = .5 - Sin[2*angle*2*Pi/360]
```

```
Out[1] = 0.5 - Sin[angle*Pi/90]
```

```
In[2] = Plot[f[angle],{angle,0,360},AxesLabel -> {"Angle Theta in Degrees", "Total Torque/(L1*I^2)"}]
```

```
Out[2] = %See Figure 4
```

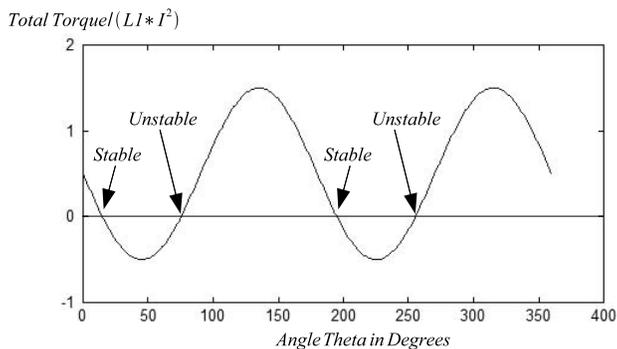


Figure 4: A graph plotting Total Torque versus Angle Theta in Degrees (Image by MIT OpenCourseWare).

$$\theta'(t) = A_1 \sin \omega_0 t + A_2 \cos \omega_0 t$$

Perturbations are bounded if ω_0 real ($\omega_0^2 > 0$)

This requires $\left. \frac{dT_T}{d\theta} \right|_{\theta_{eq}} < 0$

$$\left. \frac{dT_T}{d\theta} \right|_{\theta_{eq}} = -2L_1 I^2 \cos 2\theta_{eq} \Rightarrow \cos 2\theta_{eq} > 0 \text{ for stability}$$

θ_{eq}	$\cos 2\theta_{eq}$	Stability
15°	$\sqrt{3}/2$	Stable
75°	$-\sqrt{3}/2$	Unstable
195°	$\sqrt{3}/2$	Stable
255°	$-\sqrt{3}/2$	Unstable

E

Question: If the initial conditions of the perturbation are $\left. \frac{d\theta'}{dt} \right|_{t=0}$ and $\theta'(t=0) = \Delta\theta$ what is $\theta'(t)$ for $t > 0$. Neglect any damping.

Solution:

$$\left. \frac{d\theta'}{dt} \right|_{t=0} = \omega_0 (A_1 \cos \omega_0 t - A_2 \sin \omega_0 t) \Big|_{t=0} = A_1 \omega_0 = 0$$

$$A_1 = 0$$

$$\theta(t=0) = \Delta\theta = A_2 \Rightarrow \theta(t) = \Delta\theta \cos \omega_0 t$$

$$\omega_0 = \left[\frac{1}{J} 2L_1 I^2 \right]^{1/2}$$

F

Question: If $i(t)$ is a DC current I and a motor drives the rotor angle θ at constant angular speed Ω so that $\theta = \Omega t$, what is the voltage $v(t)$ across the coil?

Solution:

$$v(t) = \frac{d\lambda}{dt} = \frac{d[L(\theta)I]}{dt} = I \frac{dL(\theta)}{dt} = I \frac{dL(\theta)}{d\theta} \frac{d\theta}{dt}$$

$$v(t) = -2L_1 I \Omega \sin 2\Omega t$$

Problem 4

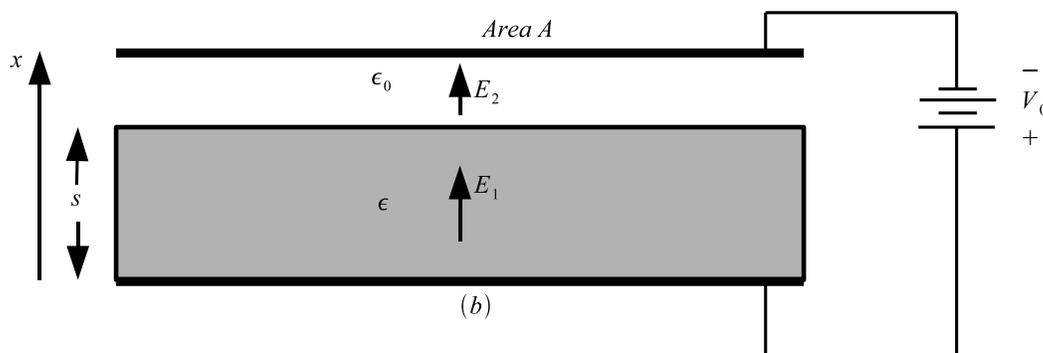


Figure 5: A diagram of a parallel plate capacitor with two dielectrics in series (Image by MIT OpenCourseWare).

A parallel plate capacitor with electrodes of area A has its upper electrode in a free space region in series with a solid dielectric of thickness s and dielectric permittivity ϵ . The $x = s$ interface has no free surface charge.

A

Question: What are the electric fields E_1 and E_2 in the dielectric and free space regions?

Solution:

$$V_0 = E_1 s + E_2 (x - s)$$

$$\epsilon E_1 = \epsilon_0 E_2 \Rightarrow E_2 = \frac{\epsilon}{\epsilon_0} E_1$$

$$E_1 \left[s + \frac{\epsilon}{\epsilon_0} (x - s) \right] = V_0$$

$$E_1 = \frac{\epsilon_0 V_0}{[\epsilon_0 s + \epsilon (x - s)]}$$

$$E_2 = \frac{\epsilon V_0}{[\epsilon_0 s + \epsilon (x - s)]}$$

B**Question:** What is the free surface charge density on the lower electrode?**Solution:**

$$\sigma_s(x=0) = \epsilon E_1 = \frac{\epsilon \epsilon_0 V_0}{\epsilon_0 s + \epsilon(x-s)}$$

C**Question:** What is the capacitance $C(x)$ of the capacitor?**Solution:**

$$C(x) = \frac{\sigma_s A}{V_0} = \frac{\epsilon \epsilon_0 A}{\epsilon_0 s + \epsilon(x-s)}$$

D**Question:** what is the electric force on the upper electrode?**Solution:**

$$f_x = \frac{1}{2} V_0^2 \frac{dC(x)}{dx} = -\frac{1}{2} \frac{V_0^2 \epsilon^2 \epsilon_0 A}{[\epsilon_0 s + \epsilon(x-s)]^2}$$