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6.641 Electromagnetic Fields, Forces, and Motion  
Spring 2005

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## Problem Set 3 - Solutions

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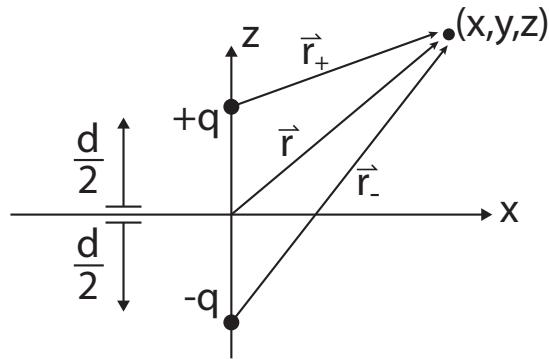
**Problem 3.1****A**

Figure 1: Addition of potential contributions from 2 point charges. (Image by MIT OpenCourseWare.)

We can simply add the potential contributions of each point charge:

$$\begin{aligned}\Phi &= \frac{q}{4\pi\epsilon_0 r_+} - \frac{q}{4\pi\epsilon_0 r_-} \\ r_+ &= \sqrt{x^2 + y^2 + (z - \frac{d}{2})^2} \\ r_- &= \sqrt{x^2 + y^2 + (z + \frac{d}{2})^2} \\ \Phi &= \frac{q}{4\pi\epsilon_0} \left[ \frac{1}{\sqrt{x^2 + y^2 + (z - \frac{d}{2})^2}} - \frac{1}{\sqrt{x^2 + y^2 + (z + \frac{d}{2})^2}} \right]\end{aligned}$$

**B**

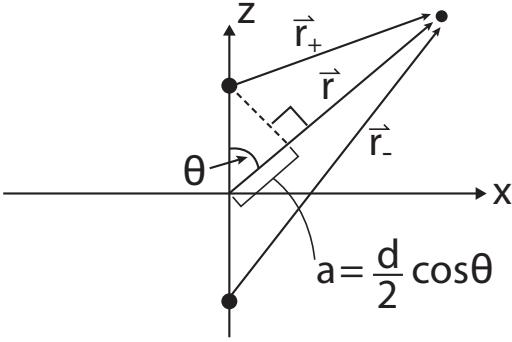
$p = qd$ . We must make some approximations. As  $r \rightarrow \infty$ ,  $\vec{r}_+$ ,  $\vec{r}_-$ , and  $\vec{r}$  become nearly parallel. Thus,

$$r_+ \approx r - a = r - \frac{d}{2} \cos \theta$$

$$r_+ \approx r(1 - \frac{d}{2r} \cos \theta)$$

Similarly,

$$r_- \approx r(1 + \frac{d}{2r} \cos \theta)$$

Figure 2: Differences in lengths between  $\vec{r}_+$ ,  $\vec{r}_-$ , and  $\vec{r}$  (Image by MIT OpenCourseWare.)

By part (a):  $\Phi = \frac{q}{4\pi\epsilon_0} \left[ \frac{1}{r_+} - \frac{1}{r_-} \right]$ . If  $|x| \ll 1$ , then  $\frac{1}{1+x} \approx 1-x$

$$\left| \frac{d}{2r} \cos \theta \right| \ll 1$$

so

$$\frac{1}{r_+} \approx \frac{1}{r} \frac{1}{1 - \frac{d}{2r} \cos \theta} \approx \frac{1}{r} \left( 1 + \frac{d}{2r} \cos \theta \right)$$

$$\frac{1}{r_-} \approx \frac{1}{r} \frac{1}{1 + \frac{d}{2r} \cos \theta} \approx \frac{1}{r} \left( 1 - \frac{d}{2r} \cos \theta \right)$$

$$\Rightarrow \frac{1}{r_+} - \frac{1}{r_-} \approx \frac{1}{r} \frac{d}{r} \cos \theta = \frac{d}{r^2} \cos \theta$$

$$\Phi \approx \frac{qd \cos \theta}{4\pi\epsilon_0 r^2} = \frac{p \cos \theta}{4\pi\epsilon_0 r^2}$$

## C

$$\vec{E} = -\nabla\Phi = -\frac{\partial\Phi}{\partial r}\hat{i}_r - \frac{1}{r} \frac{\partial\Phi}{\partial\theta}\hat{i}_\theta - \frac{1}{r \sin\theta} \frac{\partial\Phi}{\partial\phi}\hat{i}_\phi$$

$$\frac{\partial\Phi}{\partial r} = -\frac{p \cos \theta}{2\pi\epsilon_0 r^3}; \frac{\partial\Phi}{\partial\theta} = -\frac{p \sin \theta}{4\pi\epsilon_0 r^2}$$

$$\frac{\partial\Phi}{\partial\phi} = 0$$

$$\vec{E} = \frac{p \cos \theta}{2\pi\epsilon_0 r^3} \hat{i}_r + \frac{1}{r} \frac{p \sin \theta}{4\pi\epsilon_0 r^2} \hat{i}_\theta$$

$$\vec{E} = \frac{p}{4\pi\epsilon_0 r^3} [2 \cos \theta \hat{i}_r + \sin \theta \hat{i}_\theta]$$

**D**

$$\frac{dr}{rd\theta} = \frac{E_r}{E_\theta} = \frac{2 \cos \theta}{\sin \theta} = 2 \cot \theta$$

$$\frac{1}{r} dr = 2 \cot \theta d\theta$$

$$\int \frac{1}{r} dr = \int 2 \cot \theta d\theta$$

$$\ln r = 2 \ln(\sin \theta) + k$$

$$r = C \sin^2 \theta; \quad \text{when } \theta = \frac{\pi}{2}, r = C = r_0$$

Thus,

$$C = r_0, \frac{r}{r_0} = \sin^2 \theta$$

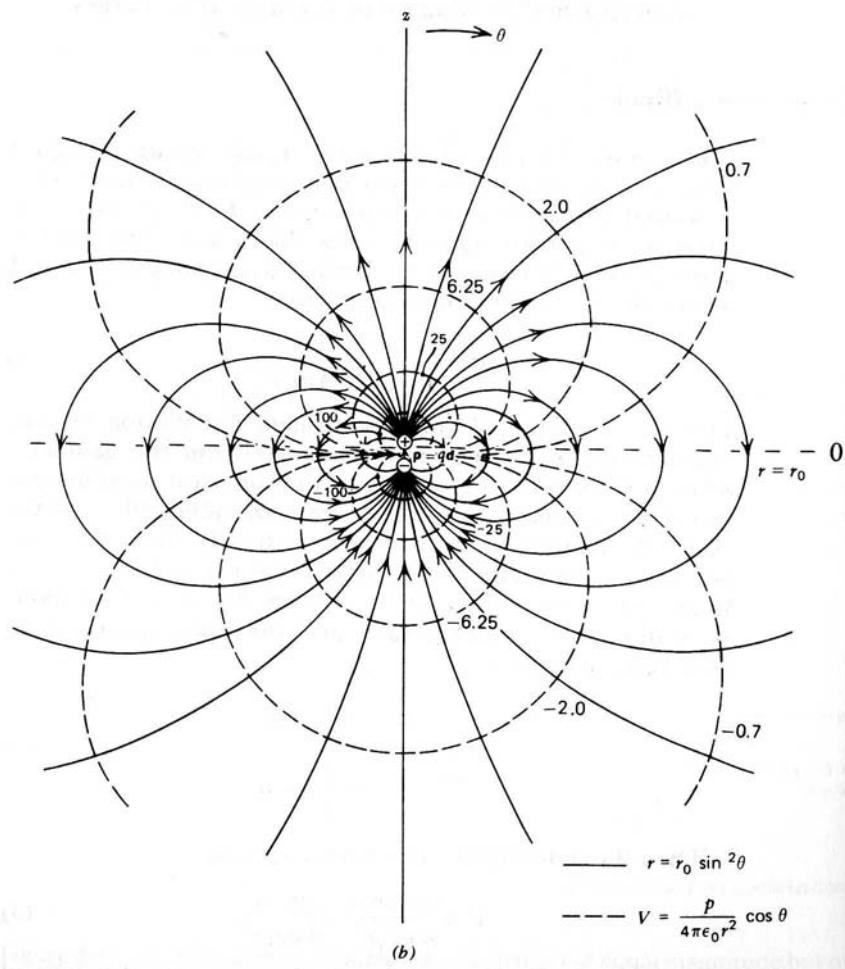


Figure 3.2b) Used with permission.

Zahn, Markus. In *Electromagnetic Field Theory: A Problem Solving Approach*, 1987.

## Plots of Equipotential and Field Lines

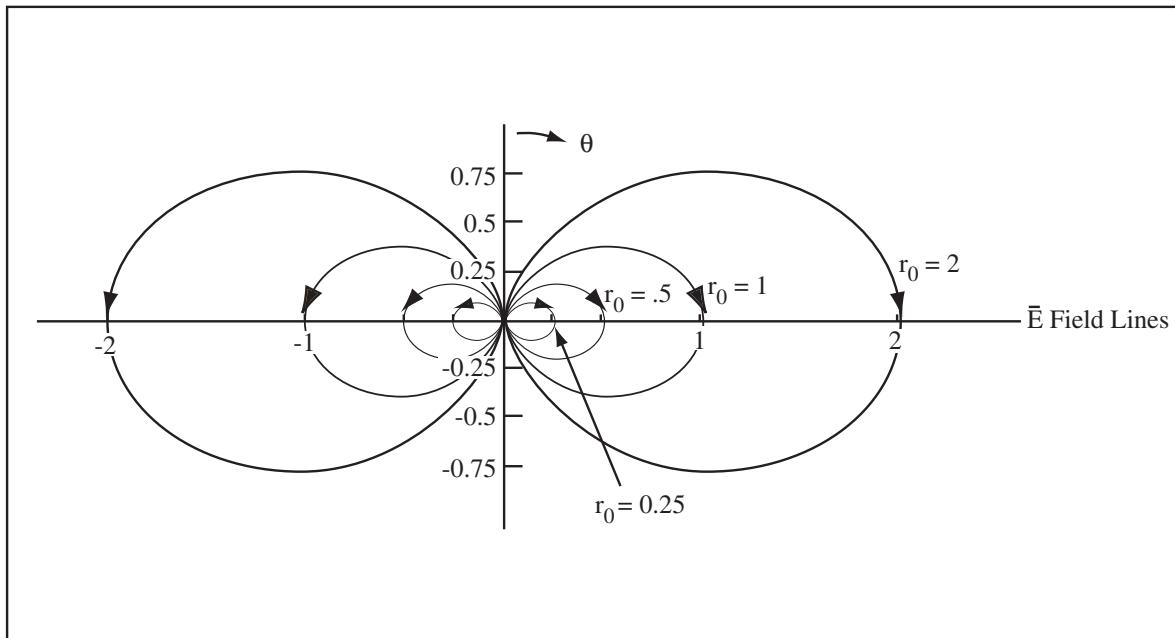


Figure 4: Polar plot of  $r_0 \sin^2 \theta$  for  $0 \leq \theta \leq \pi$  and for  $r_0 = 0.25, 0.5, 1$ , and  $2$  meters with  $\frac{4\pi\varepsilon_0}{p} = 100$  volt $^{-1}$ -m $^{-2}$  (Image by MIT OpenCourseWare.)

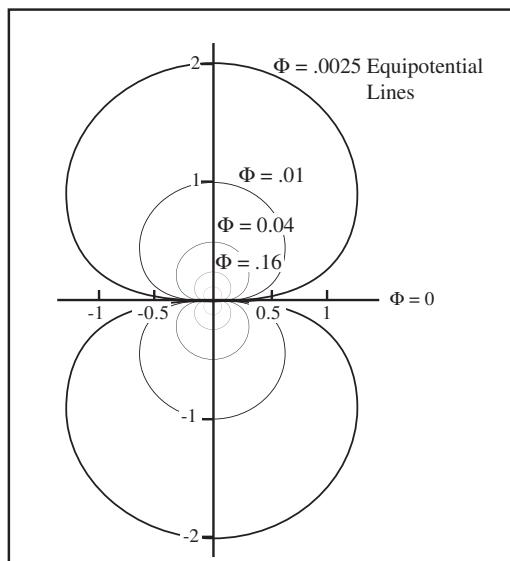


Figure 5: Polar plot of equipotential lines  $\Phi = \frac{p \cos \theta}{4\pi\varepsilon_0 r^2}$  for  $0 \leq \theta \leq \pi$ ,  $\Phi = 0, \pm 0.0025, \pm 0.01, \pm 0.04, \pm 0.16$ , and  $\pm 0.64$  volts with  $\frac{4\pi\varepsilon_0}{p} = 100$  volt $^{-1}$ -m $^{-2}$  (Image by MIT OpenCourseWare.)

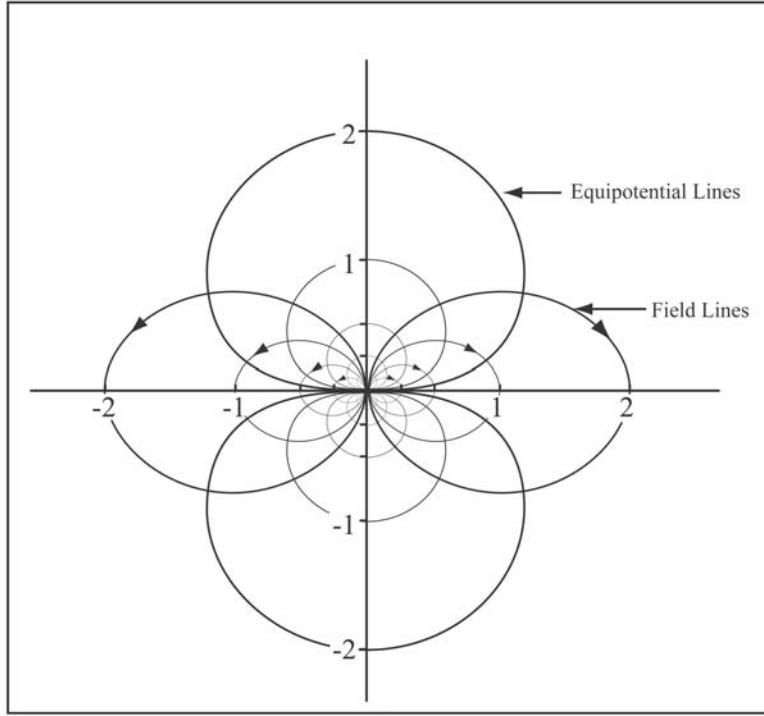


Figure 6: The superposition of the previous two plots of perpendicular equipotential and field lines (Image by MIT OpenCourseWare.)

## Problem 3.2

### A

We can think of the bird as a perfectly conducting small sphere when it lands on the uninsulated wire, it must become the same potential as the wire. This forces it to acquire a charge. When it flies away, the charge stays with it because air is a poor conductor.

### B, C

For B and C, use the method of images. We can use superposition to get total potential.

$$\Phi = \frac{q}{4\pi\epsilon_0} \left[ \frac{1}{[(x-Ut)^2 + (y-h)^2 + z^2]^{\frac{1}{2}}} - \frac{1}{[(x-Ut)^2 + (y+h)^2 + z^2]^{\frac{1}{2}}} \right]$$

where  $q$  is the charged bird modeled as a point charge.

### D

By boundary condition found using Gauss' Law

$$\hat{n} \cdot (\epsilon_a \vec{E}^a - \epsilon_b \vec{E}^b) = \sigma_s$$

at  $y = 0$  ground plane boundary

$$\vec{E}^b = 0$$

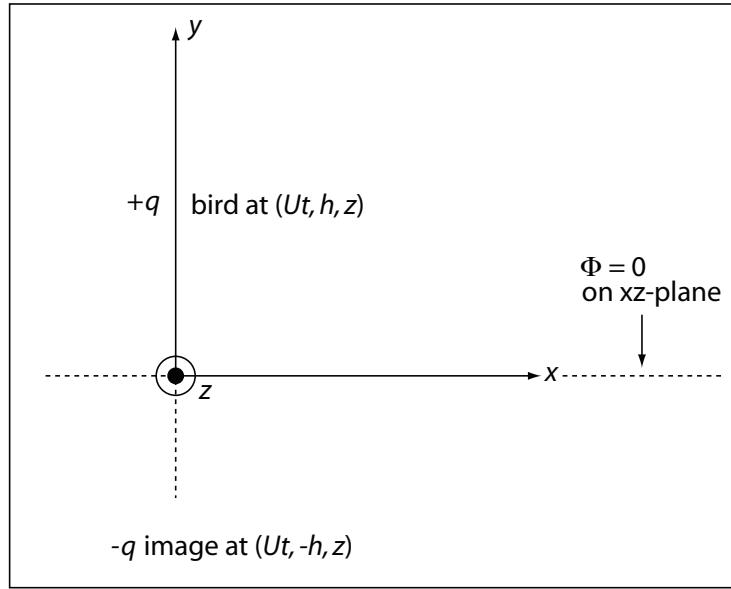


Figure 7: Figure for 3.2 B, C. Method of Images for charged bird taken as a point charge (Image by MIT OpenCourseWare.)

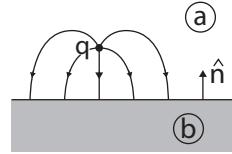


Figure 8: Figure for 3.2 D. Field lines from point charge above a perfectly conducting ground plane (Image by MIT OpenCourseWare.)

Because we can consider ground plane to be a perfect conductor,  $\hat{n} \cdot \vec{E}^a = \frac{\sigma_s}{\epsilon_0}$ .

$$(\hat{i}_y) \cdot (\vec{E}(x, y = 0^+, z)) = \frac{\sigma_s}{\epsilon_0} \text{ implies we only care about } y \text{ components of } \vec{E}$$

$$E_y(x, y = 0^+, z) = \frac{\sigma_s}{\epsilon_0} \quad (1)$$

$$E_y = -\frac{\partial}{\partial y} \Phi = \frac{q}{4\pi\epsilon_0} \left[ \frac{(y-h)}{[(x-Ut)^2 + (y-h)^2 + z^2]^{\frac{3}{2}}} - \frac{(y+h)}{[(x-Ut)^2 + (y+h)^2 + z^2]^{\frac{3}{2}}} \right]$$

Evaluate at  $y = 0$  and substitute into (1) above:

$$E_y(x, y = 0, z) = \frac{q}{4\pi\epsilon_0} \left[ \frac{-2h}{[(x-Ut)^2 + h^2 + z^2]^{\frac{3}{2}}} \right]$$

So  $\sigma_s = \epsilon_0 E_y(x, y = 0, z)$

$$\sigma_s = \frac{-qh}{2\pi [(x-Ut)^2 + h^2 + z^2]^{\frac{3}{2}}}$$

**E**

$$Q = \int_0^w \int_0^l \frac{-qh}{2\pi [(x-Ut)^2 + h^2 + z^2]^{\frac{3}{2}}} dx dz$$

For  $w$  very small,  $\sigma_s$  does not change significantly from  $z = 0$  to  $z = w$ , so integral in  $z$  becomes just multiplication at  $z = 0$ .

$$Q = \int_0^l \frac{-qhw}{2\pi [(x-Ut)^2 + h^2]} dx$$

Let  $x' = x - Ut \Rightarrow dx' = dx$  So:

$$\begin{aligned} Q &= \int_{-Ut}^{l-Ut} \frac{-qhw}{2\pi [((x')^2 + h^2)^{\frac{3}{2}}]} dx' \\ Q &= -\frac{qw}{2\pi h} \left[ \frac{l-Ut}{\sqrt{(l-Ut)^2 + h^2}} + \frac{Ut}{\sqrt{(Ut)^2 + h^2}} \right] \end{aligned}$$

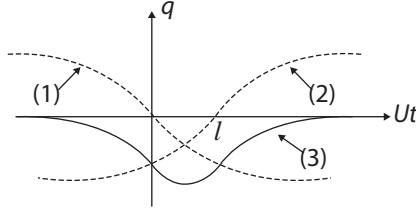


Figure 9: Representative shape  $q = Q$  versus  $Ut$  (Image by MIT OpenCourseWare.)

**F**

$$\begin{aligned} i &= \frac{dQ}{dt} = \frac{-qw}{2\pi h} \left[ \frac{-Uh^2}{[(l-Ut)^2 + h^2]^{\frac{3}{2}}} + \frac{Uh^2}{[(Ut)^2 + h^2]^{\frac{3}{2}}} \right] \\ V &= -iR = \frac{qwR}{2\pi h} \left[ \frac{-Uh^2}{[(l-Ut)^2 + h^2]^{\frac{3}{2}}} + \frac{Uh^2}{[(Ut)^2 + h^2]^{\frac{3}{2}}} \right] \end{aligned}$$

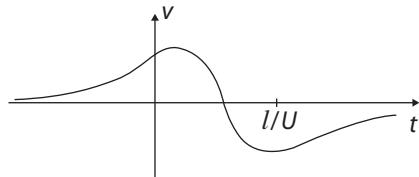


Figure 10: Voltage  $V$  versus time across small electrode resistance  $R$  (Image by MIT OpenCourseWare.)

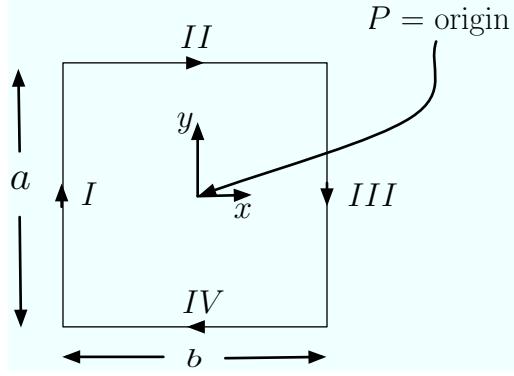


Figure 11: Magnetic field from rectangular line current (Image by MIT OpenCourseWare.)

**Problem 3.3****A**

$$\vec{H} = \frac{1}{4\pi} \int \frac{J(\vec{r}') \times \hat{i}_{r'r}}{|\vec{r} - \vec{r}'|^2} dv'$$

$$\begin{aligned} \vec{H} &= \frac{1}{4\pi} \underbrace{\int_{y=-\frac{a}{2}}^{y=\frac{a}{2}} \frac{(I\hat{i}_y) \times \left(\frac{b}{2}\hat{i}_x - y\hat{i}_y\right) dy}{\left(\left(\frac{b}{2}\right)^2 + y^2\right)^{\frac{1}{2}}} + \int_{x=-\frac{b}{2}}^{x=\frac{b}{2}} \frac{(I\hat{i}_x) \times \left(-x\hat{i}_x - \frac{a}{2}\hat{i}_y\right) dx}{\left(\left(\frac{a}{2}\right)^2 + x^2\right)^{\frac{1}{2}}} +}_{\substack{| \vec{r} - \vec{r}' |^2 \\ \text{normalization for } \hat{i}_{r'r}}} \\ &\quad \int_{y=-\frac{a}{2}}^{y=\frac{a}{2}} \frac{(-I\hat{i}_y) \times \left(-\frac{b}{2}\hat{i}_x - y\hat{i}_y\right) dy}{\left(\left(\frac{b}{2}\right)^2 + x^2\right)^{\frac{1}{2}}} + \int_{x=-\frac{b}{2}}^{x=\frac{b}{2}} \frac{(-I\hat{i}_x) \times \left(-x\hat{i}_x + \frac{a}{2}\hat{i}_y\right) dx}{\left(\left(\frac{a}{2}\right)^2 + x^2\right)^{\frac{1}{2}}} \\ &= \frac{1}{4\pi} \left[ 2 \int_{x=-\frac{b}{2}}^{x=\frac{b}{2}} \frac{a}{2} \frac{I(-\hat{i}_z) dx}{\left(\left(\frac{a}{2}\right)^2 + x^2\right)^{\frac{3}{2}}} + 2 \int_{y=-\frac{a}{2}}^{y=\frac{a}{2}} \frac{b}{2} \frac{I(-\hat{i}_z) dy}{\left(\left(\frac{b}{2}\right)^2 + y^2\right)^{\frac{3}{2}}} \right] \\ &= -\frac{I\hat{i}_z}{4\pi} \left[ \frac{ax}{\left(\frac{a}{2}\right)^2 \left(\left(\frac{a}{2}\right)^2 + x^2\right)^{\frac{1}{2}}} \Big|_{-\frac{b}{2}}^{\frac{b}{2}} + \frac{by}{\left(\frac{b}{2}\right)^2 \left(\left(\frac{b}{2}\right)^2 + y^2\right)^{\frac{1}{2}}} \Big|_{-\frac{a}{2}}^{\frac{a}{2}} \right] \end{aligned}$$

$$\vec{H} = -\frac{I\hat{i}_z}{4\pi} \left[ \frac{\cancel{ab}}{a^2 \left(\left(\frac{a}{2}\right)^2 + \left(\frac{b}{2}\right)^2\right)^{\frac{1}{2}}} + \frac{\cancel{ab}}{b^2 \left(\left(\frac{b}{2}\right)^2 + \left(\frac{a}{2}\right)^2\right)^{\frac{1}{2}}} \right]$$

$$\vec{H} = \frac{-2I(a^2 + b^2)\hat{i}_z}{\pi ab(a^2 + b^2)^{\frac{1}{2}}}$$

$$\vec{H} = \frac{-2I(a^2 + b^2)^{\frac{1}{2}}}{\pi ab} \hat{i}_z$$

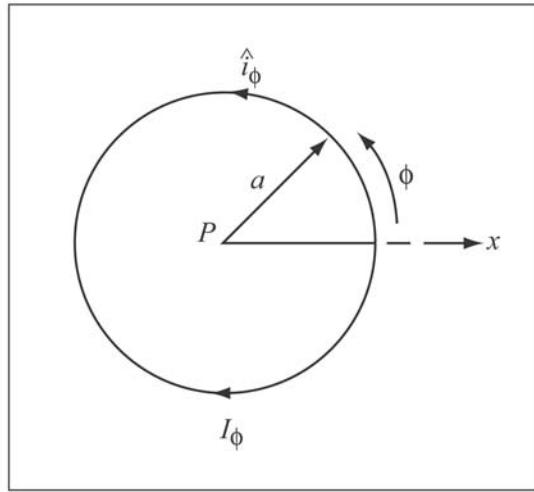
**B**

Figure 12: Line current in circular coil (Image by MIT OpenCourseWare.)

$$\vec{I} = -I \hat{i}_\phi$$

$$\begin{aligned}\vec{H} &= \frac{1}{4\pi} \int_0^\pi \frac{(-I \hat{i}_\phi) \times (-\hat{i}_r) ad\phi}{a^2} \\ &= \frac{1}{4\pi} \int_0^{2\pi} \frac{-\hat{i}_z I a d\phi}{a^2}\end{aligned}$$

$$\vec{H} = -\frac{I}{2a} \hat{i}_z$$

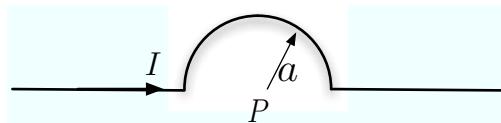
**C**

Figure 13: Line current with semi-circular bump (Image by MIT OpenCourseWare.)

$$\vec{H} = \frac{1}{4\pi} \int_0^\pi \frac{(-I \hat{i}_\phi) \times (-\hat{i}_r) ad\phi}{a^2}$$

$$\vec{H} = -\frac{I}{4a}\hat{i}_z$$

D

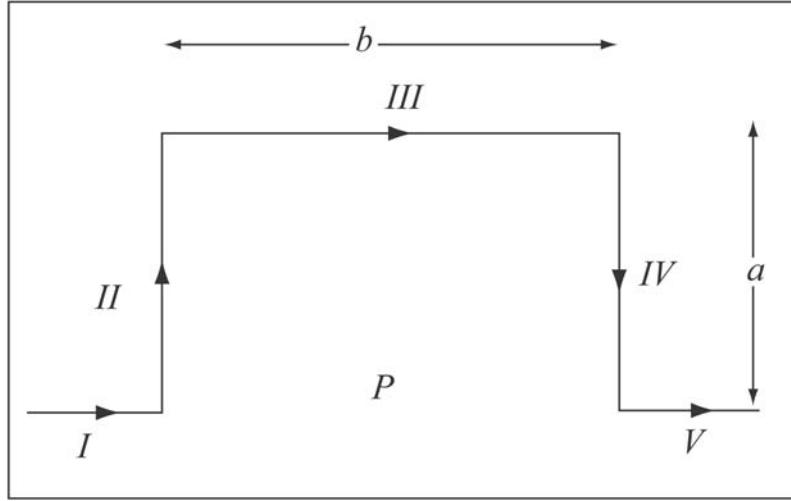


Figure 14: Line current with rectangular bump (Image by MIT OpenCourseWare.)

As in part (c), contributions from segments I and V are zero (see Fig. 14). Segments II, III, and IV are just like part (a), except integrals in  $y$  are from 0 to  $a$  and only one integral in  $x$  and  $(\frac{a}{2}) \rightarrow a$ .

$$\vec{H} = \frac{-I \left( a^2 + \left(\frac{b}{2}\right)^2 \right)^{\frac{1}{2}}}{\pi ab} \hat{i}_z$$

### Problem 3.4

A

$$\vec{H} = \frac{1}{4\pi} \int_0^\pi \int_0^{2\pi} \frac{(K_0 \hat{i}_\phi) \times \hat{i}_{r'} r R^2 \sin \theta d\phi d\theta}{|\vec{r} - \vec{r}'|^2} \quad (\vec{r} = 0)$$

$$\hat{i}_{r'r} = \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|} = -\frac{\vec{r}'}{|\vec{r}'|} = -\hat{i}_r$$

$$\vec{H} = \frac{K_0}{4\pi} \int_0^\pi \int_0^{2\pi} \frac{(\hat{i}_\phi) \times (-\hat{i}_r) R^2}{R^2} \sin \theta d\phi d\theta$$

$$= -\frac{K_0}{4\pi} \int_0^\pi \int_0^{2\pi} (\sin \theta)(\cos \theta \cos \phi \hat{i}_x + \cos \theta \sin \phi \hat{i}_y - \sin \theta \hat{i}_z) d\phi d\theta$$

Any term with an odd power of sin or cos in  $\phi$  integrates to 0 in  $\phi$  because integral is over one period.

$$\vec{H} = \hat{i}_z \frac{2\pi K_0}{4\pi} \int_0^\pi \sin^2 \theta d\theta = \frac{K_0 \pi}{4} \hat{i}_z = \vec{H}$$

**B**

This requires us to integrate an infinite number of infinitesimal current shells of the type in (a) from  $r = R_1$  to  $R_2$ .

$$\vec{H} = \int_{R_1}^{R_2} \frac{\overbrace{(J_0 dr)}^{K_0} \pi}{4} \hat{i}_z dr \Rightarrow \vec{H} = \frac{J_0 \pi}{4} (R_2 - R_1) \hat{i}_z$$

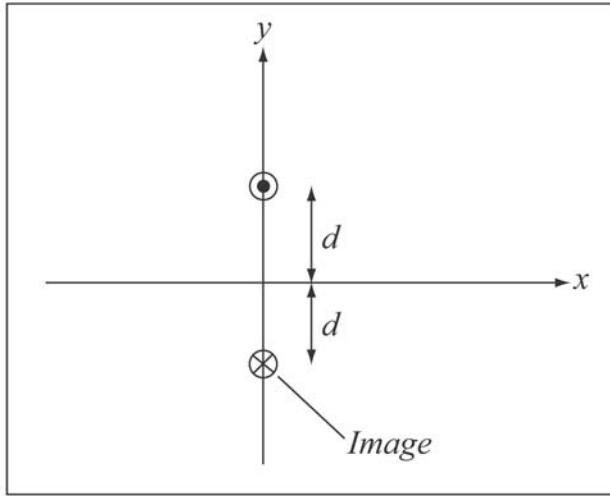
**Problem 3.5**

Figure 15: Line current above perfectly conducting plane with image current (Image by MIT OpenCourseWare.)

**A**

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{-\infty}^{\infty} \frac{Idz' \hat{i}_z}{\sqrt{x^2 + (y-d)^2 + (z-z')^2}} - \frac{\mu_0}{4\pi} \int_{-\infty}^{\infty} \frac{Idz' \hat{i}_z}{\sqrt{x^2 + (y+d)^2 + (z-z')^2}}$$

Let  $\xi \equiv z' - z \Rightarrow d\xi = dz'$ . Both integrands are even functions in  $\xi$ .

$$\begin{aligned} \vec{A} &= \hat{i}_z \frac{\mu_0 I}{2\pi} \int_0^{\infty} \left( \frac{1}{\sqrt{x^2 + (y-d)^2 + \xi^2}} - \frac{1}{\sqrt{x^2 + (y+d)^2 + \xi^2}} \right) d\xi \\ &= \hat{i}_z \frac{\mu_0 I}{2\pi} \left[ \ln \left\{ \frac{\sqrt{x^2 + (y-d)^2 + \xi^2}}{\sqrt{x^2 + (y-d)^2}} + \frac{\xi}{\sqrt{x^2 + (y-d)^2}} \right\} \right]_{\xi=0}^{\xi=\infty} \\ &\quad - \left[ \hat{i}_z \frac{\mu_0 I}{2\pi} \ln \left\{ \frac{\sqrt{x^2 + (y+d)^2 + \xi^2}}{\sqrt{x^2 + (y+d)^2}} + \frac{\xi}{\sqrt{x^2 + (y+d)^2}} \right\} \right]_{\xi=0}^{\xi=\infty} \end{aligned}$$

$$\vec{A} = \frac{\mu_0 I}{2\pi} \ln \left[ \frac{\sqrt{x^2 + (y+d)^2}}{\sqrt{x^2 + (y-d)^2}} \right] \hat{i}_z$$

**B**

$$\begin{aligned}\vec{H} &= \frac{1}{\mu_0} \nabla \times \vec{A} \\ &= \left[ \frac{I(y+d)}{2\pi(x^2 + (y+d)^2)} - \frac{I(y-d)}{2\pi(x^2 + (y-d)^2)} \right] \hat{i}_x - \left[ \frac{Ix}{2\pi(x^2 + (y+d)^2)} - \frac{Ix}{2\pi(x^2 + (y-d)^2)} \right] \hat{i}_y\end{aligned}$$

**C**

$$\begin{aligned}-H_x|_{y=0^+} &= K_z \\ \vec{K} &= -\frac{Id}{\pi(x^2 + d^2)} \hat{i}_z\end{aligned}$$

**D**

Force comes from the image current

$$\begin{aligned}\vec{F} &= (Il\hat{i}_z) \times (\mu_0 \vec{H}(x=0, y=d)) \\ &= \frac{\mu_0 I^2 l}{4\pi d} \hat{i}_y \\ \frac{F}{l} &= \frac{\mu_0 I^2}{4\pi d} \hat{i}_y\end{aligned}$$