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6.641 Electromagnetic Fields, Forces, and Motion
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Problem Set 1 - Solutions

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Problem 1.1**A**

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \leftarrow \text{Lorentz Force Law}$$

In the steady state $\vec{F} = 0$, so

$$q\vec{E} = -q\vec{v} \times \vec{B} \Rightarrow \vec{E} = -\vec{v} \times \vec{B}$$

$$\vec{v} = \begin{cases} v_y \hat{i}_y & \text{pos. charge carriers} \\ -v_y \hat{i}_y & \text{neg. charge carriers} \end{cases}$$

$$\vec{B} = B_0 \hat{i}_z$$

so

$$\vec{E} = \begin{cases} -v_y B_0 \hat{i}_x & \text{pos. charge carriers} \\ v_y B_0 \hat{i}_x & \text{neg. charge carriers} \end{cases}$$

B

$$v_H = \Phi(x=d) - \Phi(x=0) = -\int_0^d E_x dx = \int_d^0 E_x dx$$

$$v_H = \begin{cases} v_y B_0 d & \text{pos. charges} \\ -v_y B_0 d & \text{neg. charges} \end{cases}$$

C

As seen in part (b), positive and negative charge carriers give opposite polarity voltages, so answer is “yes.”

Problem 1.2

By problem:

$$\rho = \begin{cases} \rho_b & r < b \\ \rho_a & b < r < a \end{cases}$$

Also, no σ_s at $r = b$, but nonzero σ_s at $r = a$ such that $\vec{E} = 0$ for $r > a$.

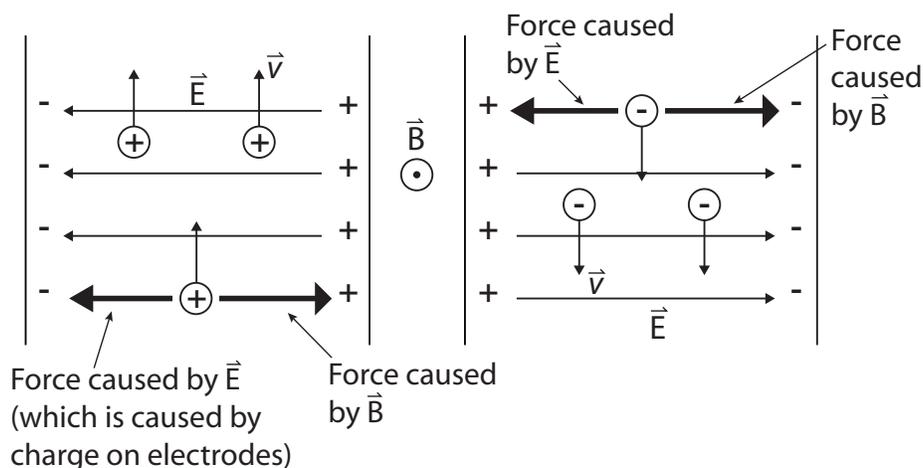


Figure 1: Figure for 1C. Opposite polarity voltages between holes and electrons (Image by MIT OpenCourseWare.)

A

By Gauss's Law

$$\oint_{S_R} \epsilon_0 \vec{E} \cdot d\vec{a} = \int_{V_R} \rho dV \quad S_R = \text{sphere with radius } r \tag{1}$$

As shown in class, symmetry ensures \vec{E} has only radial component: $\vec{E} = E_r \hat{i}_r$.

LHS of (1):

$$\begin{aligned} \oint_{S_R} \epsilon_0 \vec{E} \cdot d\vec{a} &= \int_0^{2\pi} \int_0^\pi \epsilon_0 (E_r \hat{i}_r) \cdot \underbrace{r^2 \sin \theta d\theta d\phi \hat{i}_r}_{d\vec{a} \text{ in spherical coordinates}} \\ &= \underbrace{4\pi r^2}_{\text{surface area of sphere of radius } r} E_r \epsilon_0 \end{aligned}$$

RHS of (1):

For $r < b$:

$$\begin{aligned} \int_{V_R} \rho dV &= \int_0^r \int_0^{2\pi} \int_0^\pi \rho_b \underbrace{r^2 \sin \theta d\theta d\phi dr}_{dV: \text{diff vol. element}} \\ &= \underbrace{\frac{4}{3}\pi r^3}_{\text{vol of sphere}} \rho_b \end{aligned}$$

For $r > b$ and $r < a$: ($b < r < a$):

$$\begin{aligned} \int_{V_R} \rho dV &= \int_0^b \int_0^{2\pi} \int_0^\pi \rho_b r^2 \sin \theta d\theta d\phi dr \\ &\quad + \int_b^r \int_0^{2\pi} \int_0^\pi \rho_a r^2 \sin \theta d\theta d\phi dr \\ &= \frac{4\pi \rho_b b^3}{3} + \frac{4\pi \rho_a (r^3 - b^3)}{3} \end{aligned}$$

Equating LHS and RHS:

$$4\pi r^2 E_r \epsilon_0 = \begin{cases} \frac{4\pi r^3}{3} \rho_b & r < b \\ \frac{4\pi \rho_b b^3}{3} + \frac{4\pi \rho_a (r^3 - b^3)}{3} & b < r < a \end{cases}$$

$$E_r = \begin{cases} \frac{r \rho_b}{3\epsilon_0} & r < b \\ \frac{b^3(\rho_b - \rho_a)}{3\epsilon_0 r^2} + \frac{\rho_a r}{3\epsilon_0} & b < r < a \end{cases}$$

B

Again: $\hat{n} \cdot (\epsilon_0 E^a - \epsilon_0 E^b) = \sigma_s$

$$\vec{E}(r = a^+) = 0$$

$$\vec{E}(r = a^-) = + \left[\frac{b^3(\rho_b - \rho_a)}{3\epsilon_0 a^2} + \frac{\rho_a a}{3\epsilon_0} \right] \hat{i}_r \quad \text{by part (a)}$$

$$\sigma_s = \hat{i}_r \cdot (-\epsilon_0 \vec{E}(r = a^-))$$

so

$$\sigma_s = - \left(\frac{b^3(\rho_b - \rho_a)}{3a^2} + \frac{\rho_a a}{3} \right)$$

C

$$r < b \quad Q_b = \frac{4}{3}\pi b^3 \rho_b \quad Q_\sigma(r = a) = \sigma_s 4\pi a^2$$

$$b < r < a \quad Q_a = \frac{4}{3}\pi(a^3 - b^3)\rho_a$$

$$Q_T = Q_b + Q_a + Q_\sigma = 0$$

Problem 1.3

a

We are told current going in $+z$ direction inside cylinder $r < b$. Current going through cylinder

$$= I_{\text{total}} = \int_S \vec{J} \cdot d\vec{a}$$

$$= \int_0^b \int_0^{2\pi} \underbrace{(J_0 \hat{i}_z)}_{\vec{J}} \cdot \underbrace{r d\phi dr \hat{i}_z}_{d\vec{a}}$$

$$= J_0 \pi b^2$$

$$|\vec{K}| = \frac{\text{Total current in sheet}}{\text{length of sheet (i.e. circumference of circle of radius } a)}$$

Thus, \vec{K} 's units are $\frac{\text{Amps}}{m}$, whereas \vec{J} 's units are $\frac{\text{Amps}}{m^2}$

$$|\vec{K}| = \frac{J_0 \pi b^2}{2\pi a} = \frac{J_0 b^2}{2a}$$

$$\vec{K} = -\frac{J_0 b^2}{2a} \hat{i}_z$$

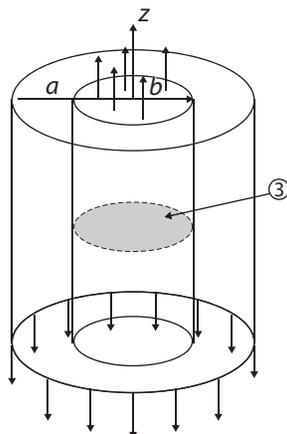


Figure 2: Figure for Problem 1.3 Part A. A cylinder with volume current going in the +z direction for $r < b$. (Image by MIT OpenCourseWare)

B

$$\oint_C \vec{H} \cdot d\vec{s} = \int_S \vec{J} \cdot d\vec{a} + \underbrace{\frac{d}{dt} \int_S \epsilon_0 \vec{E} \cdot d\vec{a}}_{\text{no } \vec{E} \text{ field, so this term is 0}} \quad (2)$$

Choose C as a circle and S as the minimum surface that circle bounds. Now, solve LHS of Ampere's Law

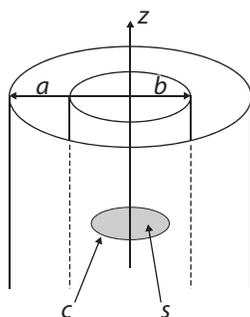


Figure 3: Choice of contour C and surface S (Image by MIT OpenCourseWare).

(2)

$$\oint_C \vec{H} \cdot d\vec{s} = \int_0^{2\pi} \underbrace{(H_\phi \hat{i}_\phi)}_{\vec{H}} \cdot \underbrace{(rd\phi \hat{i}_\phi)}_{d\vec{s}} = 2\pi r H_\phi$$

We assumed $H_z = H_r = 0$. This follows from the symmetry of the problem. $H_r = 0$ because $\oint_S \mu_0 \vec{H} \cdot d\vec{a} = 0$. In particular, choose S as shown in Figure 3. H_z is more difficult to see. It is discussed in Haus & Melcher. The basic idea is to use the contour, C , to show that if $H_z \neq 0$ it would have to be nonzero even at ∞ , which is not possible without sources at ∞ . Now for RHS of Ampere:

$r < b$:

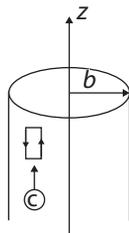


Figure 4: Illustration of the contour C (Image by MIT OpenCourseWare).

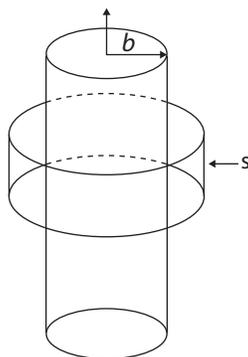


Figure 5: Diagram showing surface S (Image by MIT OpenCourseWare).

$$\begin{aligned} \int_S \vec{J} \cdot d\vec{a} &= \int_0^{2\pi} \int_0^r \underbrace{(J_0 \cdot \hat{i}_z)}_{\vec{J}} \cdot \underbrace{(r' dr' d\phi \hat{i}_z)}_{d\vec{a}} \\ &= J_0 r^2 \pi \\ a > r > b : \\ \int_S \vec{J} \cdot d\vec{a} &= \int_0^{2\pi} \int_0^b (J_0 \hat{i}_z) \cdot (r' dr' d\phi \hat{i}_z) + \underbrace{\int_0^{2\pi} \int_b^r (0 \cdot \hat{i}_z) \cdot (r' dr' d\phi \hat{i}_z)}_0 \\ &= J_0 b^2 \pi \end{aligned}$$

Equating LHS and RHS:

$$2\pi r H_\phi = \begin{cases} J_0 r^2 \pi & r < b \\ J_0 b^2 \pi & a > r > b \end{cases}$$

$$\vec{H} = \begin{cases} \frac{J_0 r}{2} \hat{i}_\phi & r < b \\ \frac{J_0 b^2}{2r} \hat{i}_\phi & a > r > b \end{cases}$$

C

From text, Ampere's continuity condition:

$$\hat{n} \times (\vec{H}^a - \vec{H}^b) = \vec{K}$$

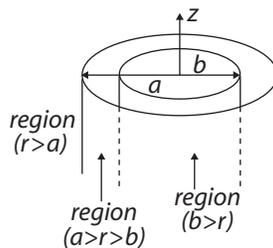


Figure 6: Ampere’s continuity condition for Problem 1.3 Part C (Image by MIT OpenCourseWare)

$$H_\phi(r = a_-) = -K_z$$

$$\frac{J_0 b^2}{2a} = -K_z = \frac{J_0 b^2}{2a}$$

Problem 1.4

A

We can simply add the fields of the two point charges. Start with the field of a point charge q at origin and let S_R be sphere of radius R centered at the origin. By Gauss:

$$\oint_{S_R} \epsilon_0 \vec{E} \cdot d\vec{a} = \int \rho dV$$

In this case $\rho = \delta(\vec{r})q$, so RHS is

$$\int \rho dV = \int \int \int \delta(\vec{r}) q dx dy dz = q$$

LHS is

$$\oint_{S_R} \epsilon_0 \vec{E}_r \cdot d\vec{a} = (\epsilon_0 \underbrace{E_r}_{\text{symmetry again}}) (\text{surface area of } S_r)$$

$$= 4\pi r^2 \epsilon_0 E_r$$

Equate LHS and RHS

$$4\pi r^2 \epsilon_0 E_r = q$$

$$\vec{E} = \frac{q}{4\pi r^2 \epsilon_0} \hat{i}_r$$

Convert to cartesian: Any point is given by

$$\vec{r} = x(r, \theta, \phi) \hat{i}_x + y(r, \theta, \phi) \hat{i}_y + z(r, \theta, \phi) \hat{i}_z$$

By spherical coordinates

$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

$$\vec{r} = r \sin \theta \cos \phi \hat{i}_x + r \sin \theta \sin \phi \hat{i}_y + r \cos \theta \hat{i}_z$$

\hat{i}_r || line formed by varying r and fixing ϕ and θ

$$\vec{r} = r \hat{i}_r$$

Thus,

$$\hat{i}_r = \sin \theta \cos \phi \hat{i}_x + \sin \theta \sin \phi \hat{i}_y + \cos \theta \hat{i}_z$$

$$= \frac{x}{\sqrt{x^2 + y^2 + z^2}} \hat{i}_x + \frac{y}{\sqrt{x^2 + y^2 + z^2}} \hat{i}_y + \frac{z}{\sqrt{x^2 + y^2 + z^2}} \hat{i}_z$$

so,

$$\vec{E} = \frac{q}{4\pi\epsilon_0(x^2 + y^2 + z^2)} \hat{i}_r$$

$$\vec{E}_{\text{total}} = \vec{E}_1 + \vec{E}_2$$

\vec{E}_1 is just \vec{E} with $y \rightarrow y - \frac{d}{2}$. \vec{E}_2 is just \vec{E} with $y \rightarrow y + \frac{d}{2}$. Problem has $y = 0$

(i)

$$\begin{aligned} \vec{E}_{\text{total}} = \vec{E}_1 &= \left[\frac{x}{\sqrt{x^2 + \frac{d^2}{4} + z^2}} \hat{i}_x + \frac{z}{\sqrt{x^2 + \frac{d^2}{4} + z^2}} \hat{i}_z - \frac{\frac{d}{2}}{\sqrt{x^2 + \frac{d^2}{4} + z^2}} \hat{i}_y \right] \cdot \left[\frac{q}{4\pi\epsilon_0(x^2 + \frac{d^2}{4} + z^2)} \right] \\ &= \frac{q}{4\pi\epsilon_0(x^2 + \frac{d^2}{4} + z^2)^{\frac{3}{2}}} \left[x \hat{i}_x - \frac{d}{2} \hat{i}_y + z \hat{i}_z \right] \end{aligned}$$

(ii)

$$\begin{aligned} \vec{E}_{\text{total}} &= \vec{E}_1 + \vec{E}_2 \\ &= q \frac{x \hat{i}_x + z \hat{i}_z}{2\pi\epsilon_0(x^2 + (\frac{d}{2})^2 + z^2)^{\frac{3}{2}}} \end{aligned}$$

(iii)

$$\begin{aligned} \vec{E}_{\text{total}} &= \vec{E}_1 + \vec{E}_2 \\ &= \frac{-dq \hat{i}_y}{4\pi\epsilon_0(x^2 + \frac{d^2}{4} + z^2)^{\frac{3}{2}}} \end{aligned}$$

B

$$\vec{F} = q_1 \vec{E} \quad \vec{E} \text{ doesn't include field of } q$$

(i)

$\vec{F} = 0$, by Newton's third law a body cannot exert a net force on itself.

(ii)

$$\begin{aligned} \vec{F} &= q_1 \vec{E} = q \vec{E}_2(x = 0, y = \frac{d}{2}, z = 0) \\ &= \frac{q^2 \vec{i}_y}{4\pi\epsilon_0(d^2)} = \frac{q^2 \vec{i}_y}{4\pi\epsilon_0 d^2} \end{aligned}$$

(iii)

$$\vec{F} = -\frac{q^2 \vec{i}_y}{4\pi\epsilon_0 d^2}$$