

Recitation 11 Outline

April 21, 2004

Linear Detection from Continuous Time Processes

1. Problem: detection in continuous time white noise (not necessarily Gaussian)
2. Objective: Maximize SNR at output of linear processor
3. Solution: Matched filter

Karhunen–Loeve Expansions and Whitening Filters

1. Karhunen–Loeve expansions and Mercer’s theorem
2. Construction of whitening filter from KL expansion
 - Analogies to discrete time and PCA
3. Example: Hypothesis Testing in Correlated Gaussian Noise