Lecture 2

6.263/16.37

The Data Link Layer: Framing and Error Detection

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Data Link Layer (DLC)

- Responsible for reliable transmission of packets over a link
 - Framing: Determine the start and end of packets (sec 2.5)
 - Error Detection: Determine when a packet contains errors (sec 2.3)
 - Error recovery: Retransmission of packets containing errors (sec 2..4)

DLC layer recovery

May be done at higher layer

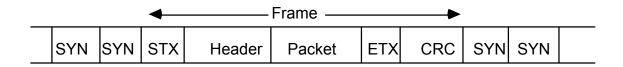
Framing

010100111010100100101010100111000100

Where is the DATA??

- Three approaches to find frame and idle fill boundaries:
 - 1) Character oriented framing
 - 2) Length counts
 - fixed length
 - 3) Bit oriented protocols (flags)

Character Based Framing



SYN is synchronous idle STX is start text FTX is end text

- Standard character codes such as ASCII and EBCDIC contain special communication characters that cannot appear in data
- Entire transmission is based on a character code

Issues With Character Based Framing

- Character code dependent
 - How do you send binary data?
- Frames must be integer number of characters
- Errors in control characters are messy

NOTE: Primary Framing method from 1960 to ~1975

Length field approach (DECNET)

- Use a header field to give the length of the frame (in bits or bytes)
 - Receiver can count until the end of the frame to find the start of the next frame
 - Receiver looks at the respective length field in the next packet header to find that packet's length
- Length field must be log₂ (Max_Size_Packet) + 1 bits long
 - This restricts the packet size to be used
- Issues with length counts
 - Difficult to recover from errors
 - Resynchronization is needed after an error in the length count

Fixed Length Packets (e.g., ATM)

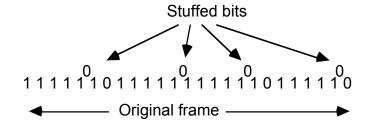
- All packets are of the same size
 - In ATM networks all packets are 53 Bytes
- Requires synchronization upon initialization
- Issues:
 - Message lengths are not multiples of packet size
 Last packet of a message must contain idle fill (efficiency)
 - Synchronization issues
 - Fragmentation and re-assembly is complicated at high rates

Bit Oriented Framing (Flags)

- A flag is some fixed string of bits to indicate the start and end of a packet
 - A single flag can be used to indicate both the start and the end of a packet
- In principle, any string could be used, but appearance of flag must be prevented somehow in data
 - Standard protocols use the 8-bit string 011111110 as a flag
 - Use 01111111..1110 (<16 bits) as abort under error conditions
 - Constant flags or 1's is considered an idle state
- Thus 0111111 is the actual bit string that must not appear in data
- INVENTED ~ 1970 by IBM for SDLC (synchronous data link protocol)

BIT STUFFING (Transmitter)

- Used to remove flag from original data
- A 0 is stuffed after each consecutive five 1's in the original frame



- Why is it necessary to stuff a 0 in 0111110?
 - If not, then

0111110111 -> 0111110111 01111111 -> 0111110111

– How do you differentiate at the receiver?

DESTUFFING (Receiver)

- If 0 is preceded by 011111 in bit stream, remove it
- If 0 is preceded by 01111111, it is the final bit of the flag.

Example: Bits to be removed are underlined below

10011111<u>0</u>1100111011111<u>0</u>110<u>01111110</u> flag

Overhead

- In general with a flag 01^k0 the bit stuffing is require whenever 01^{k-1} appears in the original data stream
- For a packet of length L this will happen about L/2^k times

$$E{OH} = L/2^k + (k+2)$$
 bits

- For 8 bit flag OH ~ 8 + L/64
 - For large packets efficiency ~ 1 1/64 = 98.5 (or 1.5% overhead)
- Optimal flag length
 - If packets are long want longer flag (less stuffing)
 - If packets are short want short flag (reduce overhead due to flag)

$$K_{opt} \sim log_2(L)$$

Framing Errors

- All framing techniques are sensitive to errors
 - An error in a length count field causes the frame to be terminated at the wrong point (and makes it tricky to find the beginning of the next frame)
 - An error in DLE, STX, or ETX causes the same problems
 - An error in a flag, or a flag created by an error causes a frame to disappear or an extra frame to appear
- Flag approach is least sensitive to errors because a flag will eventually appear again to indicate the end of a next packet
 - Only thing that happens is that an erroneous packet was created
 - This erroneous packet can be removed through an error detection technique

Error detection techniques

- Used by the receiver to determine if a packet contains errors
- If a packet is found to contain errors the receiver requests the transmitter to re-send the packet
- Error detection techniques
 - Parity check
 single bit
 Horizontal and vertical redundancy check
 - Cyclic redundancy check (CRC)

Effectiveness of error detection technique

- Effectiveness of a code for error detection is usually measured by three parameters:
 - 1) minimum distance of code (d) (min # bit errors undetected)
 The minimum distance of a code is the smallest number of errors that can map
 one codeword onto another. If fewer than d errors occur they will always
 detected. Even more than d errors will often be detected (but not always!)
 - 2) burst detecting ability (B) (max burst length always detected)
 - 3) probability of random bit pattern mistaken as error free (good estimate if # errors in a frame >> d or B)
 - Useful when framing is lost
 - K info bits => 2^k valid codewords
 - With r check bits the probability that a random string of length k+r maps onto one of the 2^k valid codewords is $2^k/2^{k+r} = 2^{-r}$

Parity check codes

k Data bits r Check bits

Each parity check is a modulo 2 sum of some of the data bits
 Example:

$$c_1 = x_1 + x_2 + x_3$$

 $c_2 = x_2 + x_3 + x_4$
 $c_3 = x_1 + x_2 + x_4$

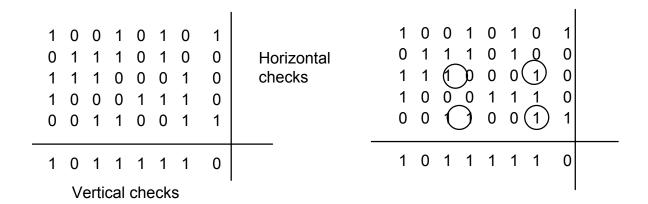
Single Parity Check Code

The check bit is 1 if frame contains odd number of 1's; otherwise it is 0

- Thus, encoded frame contains even number of 1's
- Receiver counts number of ones in frame
 - An even number of 1's is interpreted as no errors
 - An odd number of 1's means that an error must have occured
 A single error (or an odd number of errors) can be detected
 An even number of errors cannot be detected
 Nothing can be corrected
- Probability of undetected error (independent errors)

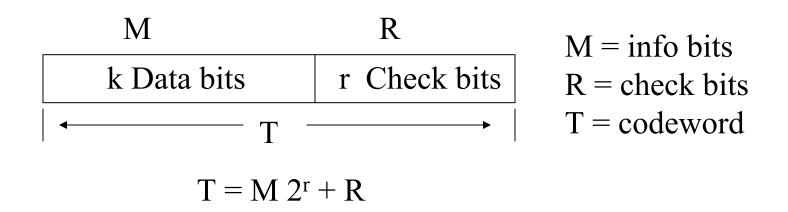
$$P(un \det ected) = \sum_{i \text{ even}} {N \choose i} p^{i} (1-p)^{N-i} \qquad \begin{aligned} N &= \text{ packet size} \\ p &= \text{ error prob.} \end{aligned}$$

Horizontal and Vertical Parity

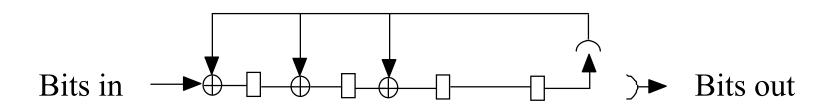


- The data is viewed as a rectangular array (i.e., a sequence of words)
- Minimum distance=4, any 4 errors in a rectangular configuration is undetectable

Cyclic Redundancy Checks (CRC)



A CRC is implemented using a feedback shift register



Cyclic redundancy checks

$$T = M 2^r + R$$

- How do we compute R (the check bits)?
 - Choose a generator string G of length r+1 bits
 - Choose R such that T is a multiple of G (T = A*G, for some A)
 - Now when T is divided by G there will be no remainder => no errors
 - All done using mod 2 arithmetic

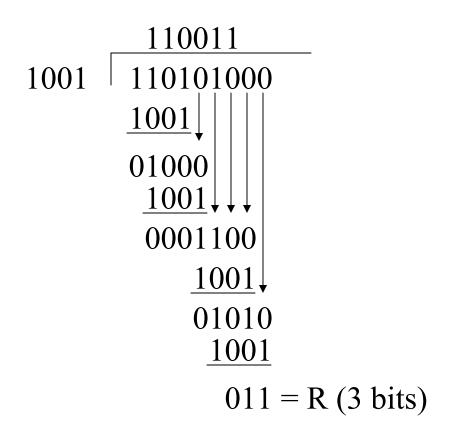
$$T = M 2^r + R = A*G \Rightarrow M 2^r = A*G + R \pmod{2}$$
 arithmetic)

Let R = remainder of M 2^r/G and T will be a multiple of G

Choice of G is a critical parameter for the performance of a CRC

Example

$$r = 3$$
, $G = 1001$
 $M = 110101 \implies M2^{r} = 110101000$



Modulo 2 Division

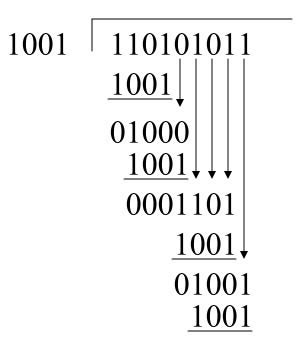
Checking for errors

- Let T' be the received sequence
- Divide T' by G
 - If remainder = 0 assume no errors
 - If remainder is non zero errors must have occurred

Example:

Send T = 110101011 Receive T' = 110101011 (no errors)

No way of knowing how many errors occurred or which bits are In error



Mod 2 division as polynomial division

Implementing a CRC

Performance of CRC

- For r check bits per frame and a frame length less than 2^{r-1}, the following can be detected
 - 1) All patterns of 1,2, or 3 errors (d > 3)
 - 2) All bursts of errors of r or fewer bits
 - 3) Random large numbers of errors with prob. 1-2-r
- Standard DLC's use a CRC with r=16 with option of r=32
 - CRC-16, $G = X^{16} + X^{15} + X^2 + 1 = 11000000000000101$

Physical Layer Error Characteristics

- Most Physical Layers (communications channels) are not well described by a simple BER parameter
- Most physical error processes tend to create a mix of random & bursts of errors
- A channel with a BER of 10⁻⁷ and a average burst size of 1000 bits is very different from one with independent random errors
- Example: For an average frame length of 10⁴ bits
 - random channel: E[Frame error rate] ~ 10⁻³
 - burst channel: E[Frame error rate] ~ 10⁻⁶
- Best to characterize a channel by its Frame Error Rate
- This is a difficult problem for real systems