

LECTURE 17

LECTURE OUTLINE

- Review of cutting plane method
- Simplicial decomposition
- Duality between cutting plane and simplicial decomposition

CUTTING PLANE METHOD

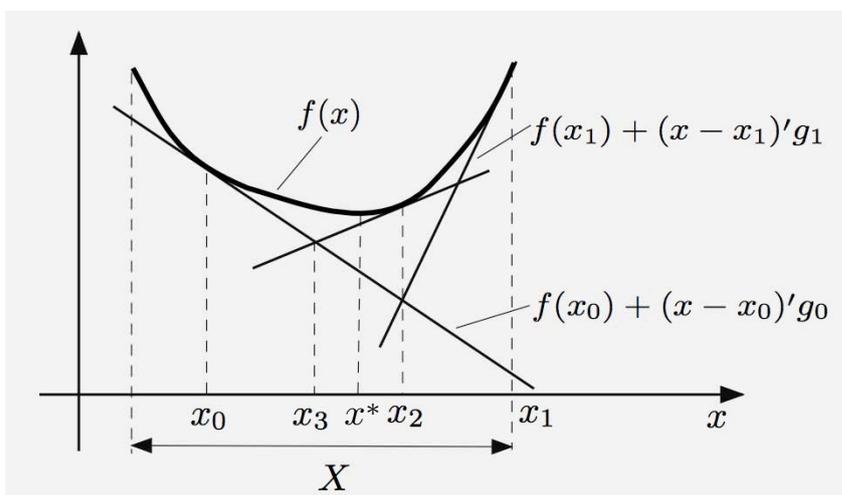
- Start with any $x_0 \in X$. For $k \geq 0$, set

$$x_{k+1} \in \arg \min_{x \in X} F_k(x),$$

where

$$F_k(x) = \max \{ f(x_0) + (x - x_0)' g_0, \dots, f(x_k) + (x - x_k)' g_k \}$$

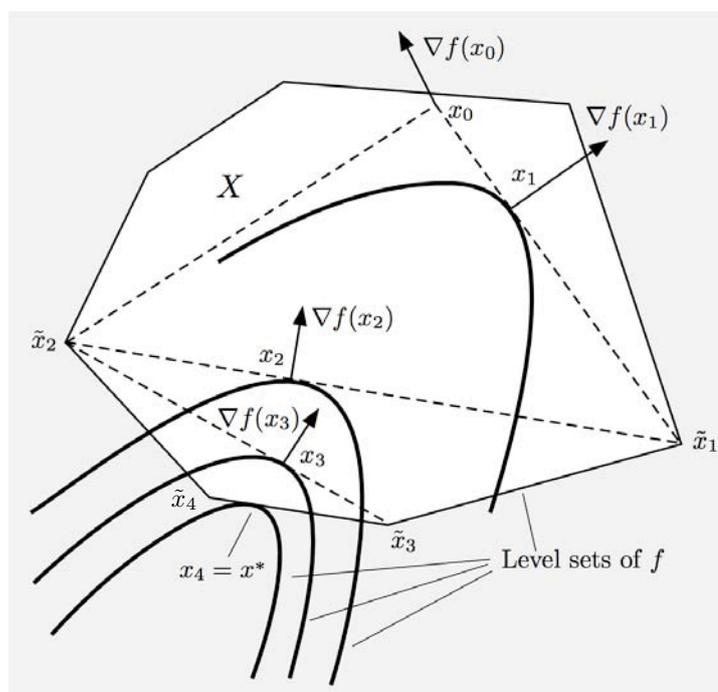
and g_i is a subgradient of f at x_i .



- We have $F_k(x) \leq f(x)$ for all x , and $F_k(x_{k+1})$ increases monotonically with k .
- These imply that all limit points of x_k are optimal.

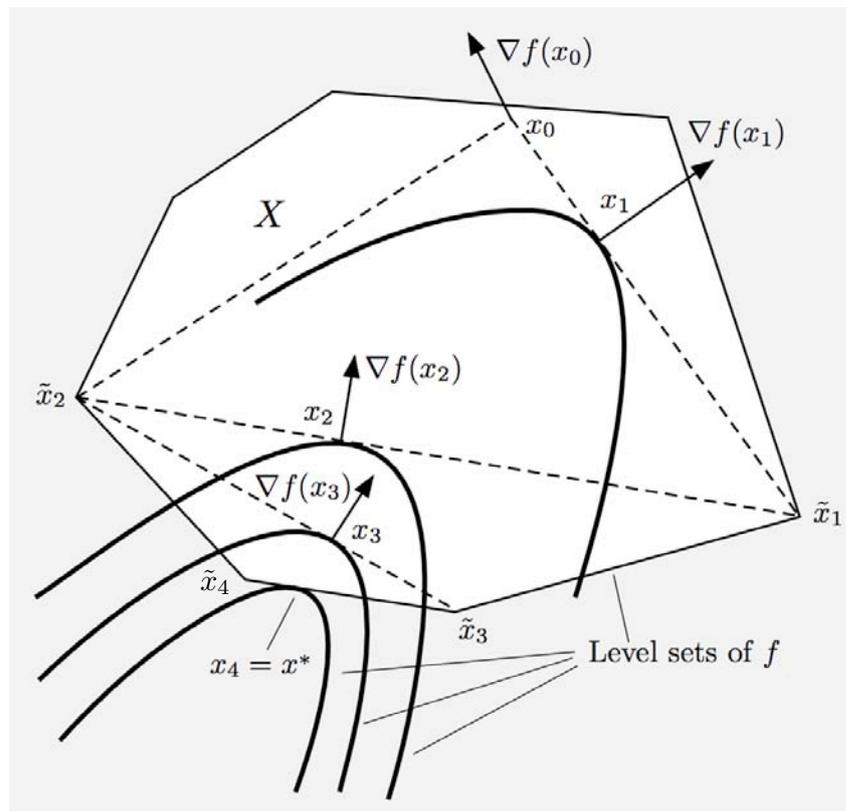
BASIC SIMPLICIAL DECOMPOSITION

- Minimize a *differentiable* convex $f : \mathbb{R}^n \mapsto \mathbb{R}$ over *bounded polyhedral constraint set* X .
- **Approximate** X with a simpler inner approximating polyhedral set.
- Construct a more refined problem by solving a **linear** minimization over the original constraint.



- The method is appealing under two conditions:
 - Minimizing f over the convex hull of a relative small number of extreme points is much simpler than minimizing f over X .
 - Minimizing a linear function over X is much simpler than minimizing f over X .

SIMPLICIAL DECOMPOSITION METHOD



- Given current iterate x_k , and finite set $X_k \subset X$ (initially $x_0 \in X$, $X_0 = \{x_0\}$).
- Let \tilde{x}_{k+1} be extreme point of X that solves

$$\begin{aligned} & \text{minimize} && \nabla f(x_k)'(x - x_k) \\ & \text{subject to} && x \in X \end{aligned}$$

and add \tilde{x}_{k+1} to X_k : $X_{k+1} = \{\tilde{x}_{k+1}\} \cup X_k$.

- Generate x_{k+1} as optimal solution of

$$\begin{aligned} & \text{minimize} && f(x) \\ & \text{subject to} && x \in \text{conv}(X_{k+1}). \end{aligned}$$

CONVERGENCE

- There are two possibilities for \tilde{x}_{k+1} :

(a) We have

$$0 \leq \nabla f(x_k)'(\tilde{x}_{k+1} - x_k) = \min_{x \in X} \nabla f(x_k)'(x - x_k)$$

Then x_k minimizes f over X (satisfies the optimality condition)

(b) We have

$$0 > \nabla f(x_k)'(\tilde{x}_{k+1} - x_k)$$

Then $\tilde{x}_{k+1} \notin \text{conv}(X_k)$, since x_k minimizes f over $x \in \text{conv}(X_k)$, so that

$$\nabla f(x_k)'(x - x_k) \geq 0, \quad \forall x \in \text{conv}(X_k)$$

- Case (b) cannot occur an infinite number of times ($\tilde{x}_{k+1} \notin X_k$ and X has finitely many extreme points), so case (a) must eventually occur.
- The method will find a minimizer of f over X in a finite number of iterations.

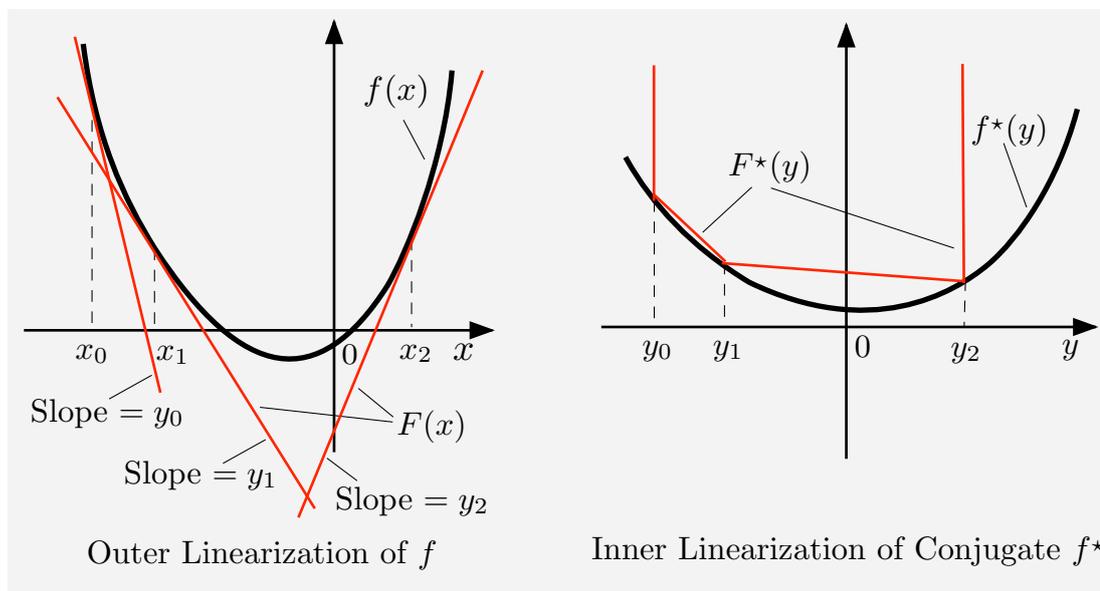
COMMENTS ON SIMPLICIAL DECOMP.

- Important specialized applications
- Variant to enhance efficiency. Discard some of the extreme points that seem unlikely to “participate” in the optimal solution, i.e., all \tilde{x} such that

$$\nabla f(x_{k+1})'(\tilde{x} - x_{k+1}) > 0$$

- Variant to remove the boundedness assumption on X (impose artificial constraints)
- Extension to X nonpolyhedral (method remains unchanged, but convergence proof is more complex)
- Extension to f nondifferentiable (requires use of subgradients in place of gradients, and more sophistication)
- **Duality relation with cutting plane methods**
- We will view cutting plane and simplicial decomposition as special cases of two polyhedral approximation methods that are dual to each other

OUTER LINEARIZATION OF FNS



- Outer linearization of closed proper convex function $f : \mathbb{R}^n \mapsto (-\infty, \infty]$
- Defined by set of “slopes” $\{y_1, \dots, y_\ell\}$, where $y_j \in \partial f(x_j)$ for some x_j
- Given by

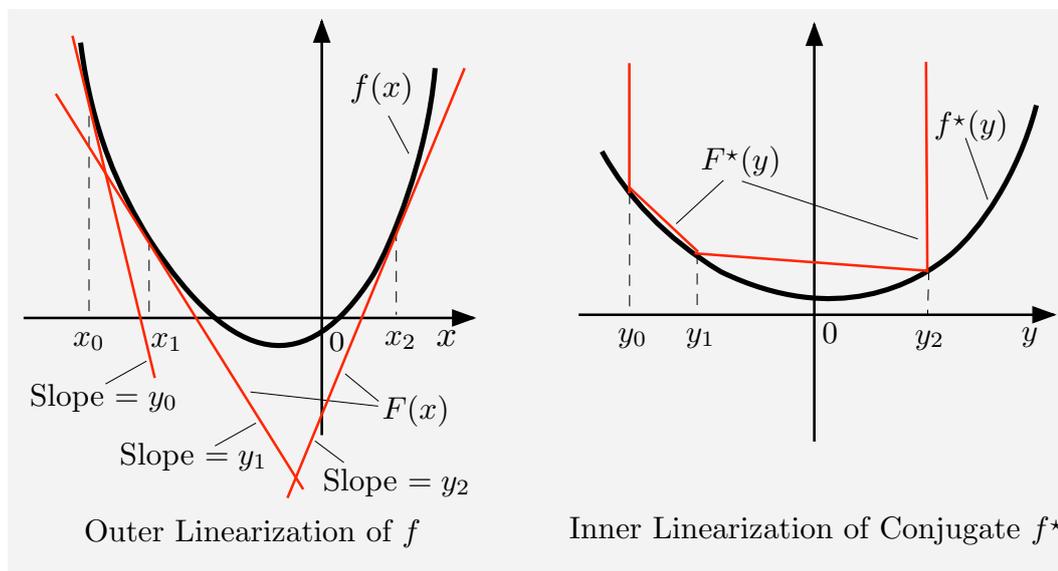
$$F(x) = \max_{j=1, \dots, \ell} \{f(x_j) + (x - x_j)'y_j\}, \quad x \in \mathbb{R}^n$$

or equivalently

$$F(x) = \max_{j=1, \dots, \ell} \{y_j'x - f^*(y_j)\}$$

[this follows using $x_j'y_j = f(x_j) + f^*(y_j)$, which is implied by $y_j \in \partial f(x_j)$ – the Conjugate Subgradient Theorem]

INNER LINEARIZATION OF FNS



- Consider conjugate F^* of outer linearization F
- After calculation using the formula

$$F(x) = \max_{j=1, \dots, \ell} \{y'_j x - f^*(y_j)\}$$

F^* is a piecewise linear approximation of f^* defined by “break points” at y_1, \dots, y_ℓ

- We have

$$\text{dom}(F^*) = \text{conv}(\{y_1, \dots, y_\ell\}),$$

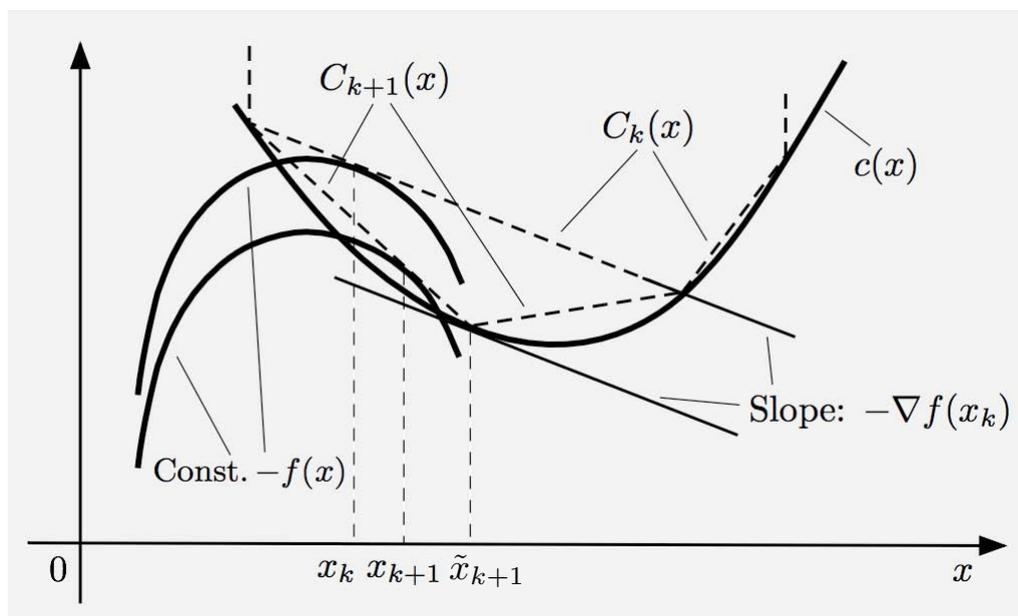
with values at y_1, \dots, y_ℓ equal to the corresponding values of f^*

- Epigraph of F^* is the convex hull of the union of the vertical halflines corresponding to y_1, \dots, y_ℓ :

$$\text{epi}(F^*) = \text{conv}\left(\cup_{j=1, \dots, \ell} \{(y_j, w) \mid f^*(y_j) \leq w\}\right)$$

GENERALIZED SIMPLICIAL DECOMPOSITION

- Consider minimization of $f(x) + c(x)$, over $x \in \mathbb{R}^n$, where f and c are closed proper convex
- Case where f is differentiable



- Given C_k : inner linearization of c , obtain

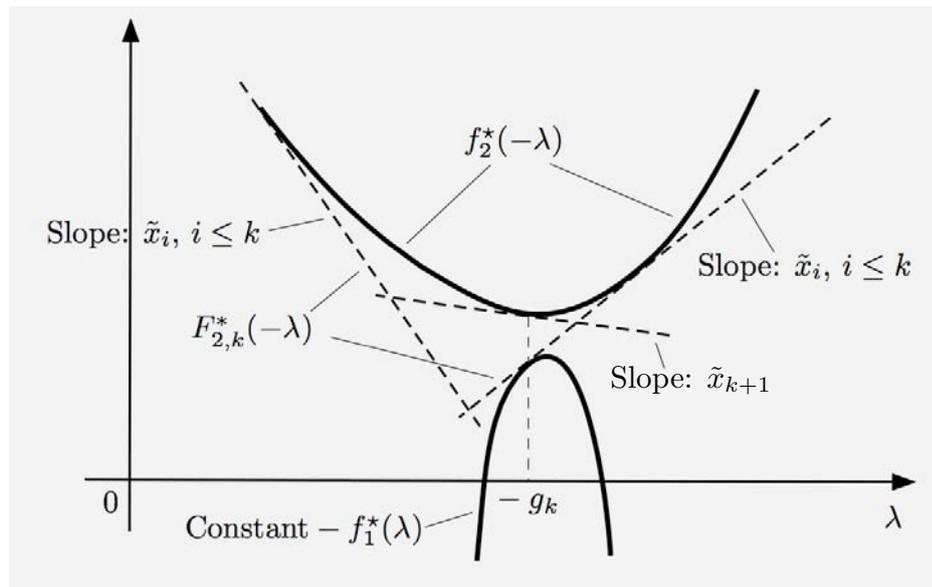
$$x_k \in \arg \min_{x \in \mathbb{R}^n} \{ f(x) + C_k(x) \}$$

- Obtain \tilde{x}_{k+1} such that

$$-\nabla f(x_k) \in \partial c(\tilde{x}_{k+1}),$$

and form $X_{k+1} = X_k \cup \{ \tilde{x}_{k+1} \}$

DUAL CUTTING PLANE IMPLEMENTATION



- Primal and dual Fenchel pair

$$\min_{x \in \mathfrak{R}^n} f_1(x) + f_2(x), \quad \min_{\lambda \in \mathfrak{R}^n} f_1^*(\lambda) + f_2^*(-\lambda)$$

- Primal and dual approximations

$$\min_{x \in \mathfrak{R}^n} f_1(x) + F_{2,k}(x) \quad \min_{\lambda \in \mathfrak{R}^n} f_1^*(\lambda) + F_{2,k}^*(-\lambda)$$

- $F_{2,k}$ and $F_{2,k}^*$ are inner and outer approximations of f_2 and f_2^*
- \tilde{x}_{i+1} and g_i are solutions of the primal or the dual approximating problem (and corresponding subgradients)

MIT OpenCourseWare
<http://ocw.mit.edu>

6.253 Convex Analysis and Optimization
Spring 2012

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.