

# 6.252 NONLINEAR PROGRAMMING

## LECTURE 12: SUFFICIENCY CONDITIONS

### LECTURE OUTLINE

- Equality Constrained Problems/Sufficiency Conditions
- Convexification Using Augmented Lagrangians
- Proof of the Sufficiency Conditions
- Sensitivity

Equality constrained problem

minimize  $f(x)$

subject to  $h_i(x) = 0, \quad i = 1, \dots, m.$

where  $f : \mathcal{R}^n \mapsto \mathcal{R}$ ,  $h_i : \mathcal{R}^n \mapsto \mathcal{R}$ , are continuously differentiable. To obtain sufficiency conditions, assume that  $f$  and  $h_i$  are *twice* continuously differentiable.

## SUFFICIENCY CONDITIONS

**Second Order Sufficiency Conditions:** Let  $x^* \in \mathfrak{R}^n$  and  $\lambda^* \in \mathfrak{R}^m$  satisfy

$$\nabla_x L(x^*, \lambda^*) = 0, \quad \nabla_\lambda L(x^*, \lambda^*) = 0,$$

$$y' \nabla_{xx}^2 L(x^*, \lambda^*) y > 0, \quad \forall y \neq 0 \text{ with } \nabla h(x^*)' y = 0.$$

Then  $x^*$  is a strict local minimum.

**Example:** Minimize  $-(x_1 x_2 + x_2 x_3 + x_1 x_3)$  subject to  $x_1 + x_2 + x_3 = 3$ . We have that  $x_1^* = x_2^* = x_3^* = 1$  and  $\lambda^* = 2$  satisfy the 1st order conditions. Also

$$\nabla_{xx}^2 L(x^*, \lambda^*) = \begin{pmatrix} 0 & -1 & -1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{pmatrix}.$$

We have for all  $y \neq 0$  with  $\nabla h(x^*)' y = 0$  or  $y_1 + y_2 + y_3 = 0$ ,

$$\begin{aligned} y' \nabla_{xx}^2 L(x^*, \lambda^*) y &= -y_1(y_2 + y_3) - y_2(y_1 + y_3) - y_3(y_1 + y_2) \\ &= y_1^2 + y_2^2 + y_3^2 > 0. \end{aligned}$$

Hence,  $x^*$  is a strict local minimum.

## A BASIC LEMMA

Lemma: Let  $P$  and  $Q$  be two symmetric matrices. Assume that  $Q \geq 0$  and  $P > 0$  on the nullspace of  $Q$ , i.e.,  $x'Px > 0$  for all  $x \neq 0$  with  $x'Qx = 0$ . Then there exists a scalar  $\bar{c}$  such that

$$P + cQ : \text{positive definite}, \quad \forall c > \bar{c}.$$

**Proof:** Assume the contrary. Then for every  $k$ , there exists a vector  $x^k$  with  $\|x^k\| = 1$  such that

$$x^{k'}Px^k + kx^{k'}Qx^k \leq 0.$$

Consider a subsequence  $\{x^k\}_{k \in K}$  converging to some  $\bar{x}$  with  $\|\bar{x}\| = 1$ . Taking the limit superior,

$$\bar{x}'P\bar{x} + \limsup_{k \rightarrow \infty, k \in K} (kx^{k'}Qx^k) \leq 0. \quad (*)$$

We have  $x^{k'}Qx^k \geq 0$  (since  $Q \geq 0$ ), so  $\{x^{k'}Qx^k\}_{k \in K} \rightarrow 0$ . Therefore,  $\bar{x}'Q\bar{x} = 0$  and using the hypothesis,  $\bar{x}'P\bar{x} > 0$ . This contradicts (\*).

# PROOF OF SUFFICIENCY CONDITIONS

Consider the *augmented Lagrangian* function

$$L_c(x, \lambda) = f(x) + \lambda' h(x) + \frac{c}{2} \|h(x)\|^2,$$

where  $c$  is a scalar. We have

$$\nabla_x L_c(x, \lambda) = \nabla_x L(x, \tilde{\lambda}),$$

$$\nabla_{xx}^2 L_c(x, \lambda) = \nabla_{xx}^2 L(x, \tilde{\lambda}) + c \nabla h(x) \nabla h(x)'$$

where  $\tilde{\lambda} = \lambda + ch(x)$ . If  $(x^*, \lambda^*)$  satisfy the suff. conditions, we have using the lemma,

$$\nabla_x L_c(x^*, \lambda^*) = 0, \quad \nabla_{xx}^2 L_c(x^*, \lambda^*) > 0,$$

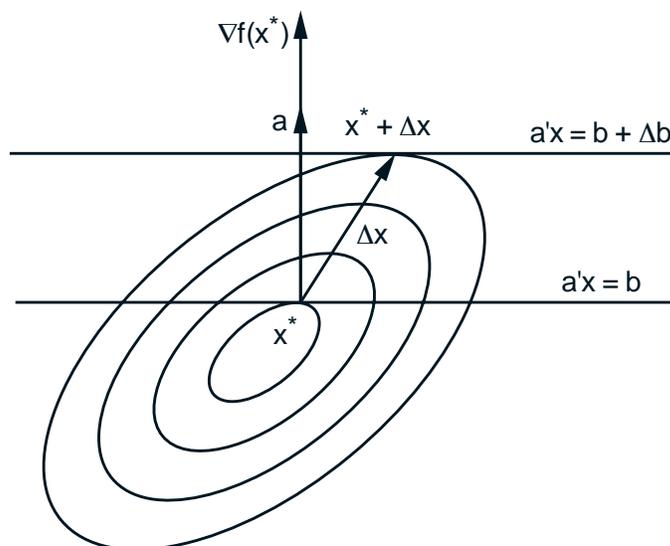
for suff. large  $c$ . Hence for some  $\gamma > 0$ ,  $\epsilon > 0$ ,

$$L_c(x, \lambda^*) \geq L_c(x^*, \lambda^*) + \frac{\gamma}{2} \|x - x^*\|^2, \quad \text{if } \|x - x^*\| < \epsilon.$$

Since  $L_c(x, \lambda^*) = f(x)$  when  $h(x) = 0$ ,

$$f(x) \geq f(x^*) + \frac{\gamma}{2} \|x - x^*\|^2, \quad \text{if } h(x) = 0, \|x - x^*\| < \epsilon.$$

# SENSITIVITY - GRAPHICAL DERIVATION



Sensitivity theorem for the problem  $\min_{a'x=b} f(x)$ . If  $b$  is changed to  $b + \Delta b$ , the minimum  $x^*$  will change to  $x^* + \Delta x$ . Since  $b + \Delta b = a'(x^* + \Delta x) = a'x^* + a'\Delta x = b + a'\Delta x$ , we have  $a'\Delta x = \Delta b$ . Using the condition  $\nabla f(x^*) = -\lambda^* a$ ,

$$\begin{aligned} \Delta \text{cost} &= f(x^* + \Delta x) - f(x^*) = \nabla f(x^*)' \Delta x + o(\|\Delta x\|) \\ &= -\lambda^* a' \Delta x + o(\|\Delta x\|) \end{aligned}$$

Thus  $\Delta \text{cost} = -\lambda^* \Delta b + o(\|\Delta x\|)$ , so up to first order

$$\lambda^* = -\frac{\Delta \text{cost}}{\Delta b}.$$

For multiple constraints  $a'_i x = b_i$ ,  $i = 1, \dots, n$ , we have

$$\Delta \text{cost} = -\sum_{i=1}^m \lambda_i^* \Delta b_i + o(\|\Delta x\|).$$

# SENSITIVITY THEOREM

Sensitivity Theorem: Consider the family of problems

$$\min_{h(x)=u} f(x) \quad (*)$$

parameterized by  $u \in \mathfrak{R}^m$ . Assume that for  $u = 0$ , this problem has a local minimum  $x^*$ , which is regular and together with its unique Lagrange multiplier  $\lambda^*$  satisfies the sufficiency conditions.

Then there exists an open sphere  $S$  centered at  $u = 0$  such that for every  $u \in S$ , there is an  $x(u)$  and a  $\lambda(u)$ , which are a local minimum-Lagrange multiplier pair of problem (\*). Furthermore,  $x(\cdot)$  and  $\lambda(\cdot)$  are continuously differentiable within  $S$  and we have  $x(0) = x^*$ ,  $\lambda(0) = \lambda^*$ . In addition,

$$\nabla p(u) = -\lambda(u), \quad \forall u \in S$$

where  $p(u)$  is the *primal function*

$$p(u) = f(x(u)).$$

# EXAMPLE

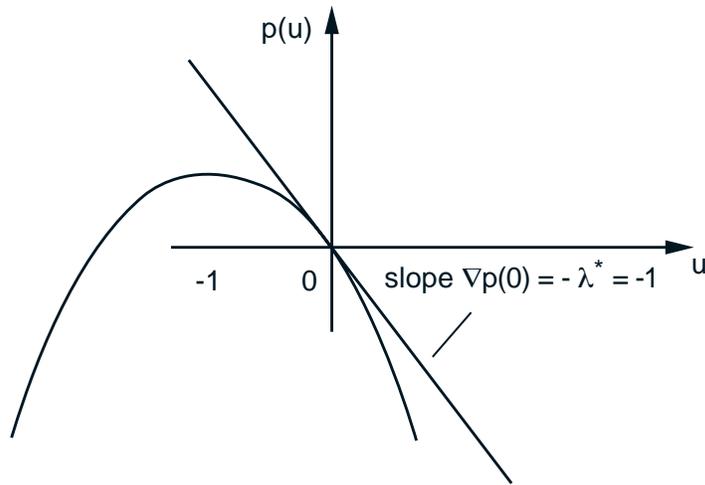


Illustration of the primal function  $p(u) = f(x(u))$  for the two-dimensional problem

$$\text{minimize } f(x) = \frac{1}{2} (x_1^2 - x_2^2) - x_2$$

$$\text{subject to } h(x) = x_2 = 0.$$

Here,

$$p(u) = \min_{h(x)=u} f(x) = -\frac{1}{2}u^2 - u$$

and  $\lambda^* = -\nabla p(0) = 1$ , consistently with the sensitivity theorem.

- **Need for regularity of  $x^*$ :** Change constraint to  $h(x) = x_2^2 = 0$ . Then  $p(u) = -u/2 - \sqrt{u}$  for  $u \geq 0$  and is undefined for  $u < 0$ .

# PROOF OUTLINE OF SENSITIVITY THEOREM

Apply implicit function theorem to the system

$$\nabla f(x) + \nabla h(x)\lambda = 0, \quad h(x) = u.$$

For  $u = 0$  the system has the solution  $(x^*, \lambda^*)$ , and the corresponding  $(n + m) \times (n + m)$  Jacobian

$$J = \begin{pmatrix} \nabla^2 f(x^*) + \sum_{i=1}^m \lambda_i^* \nabla^2 h_i(x^*) & \nabla h(x^*) \\ \nabla h(x^*)' & 0 \end{pmatrix}$$

is shown nonsingular using the sufficiency conditions. Hence, for all  $u$  in some open sphere  $S$  centered at  $u = 0$ , there exist  $x(u)$  and  $\lambda(u)$  such that  $x(0) = x^*$ ,  $\lambda(0) = \lambda^*$ , the functions  $x(\cdot)$  and  $\lambda(\cdot)$  are continuously differentiable, and

$$\nabla f(x(u)) + \nabla h(x(u))\lambda(u) = 0, \quad h(x(u)) = u.$$

For  $u$  close to  $u = 0$ , using the sufficiency conditions,  $x(u)$  and  $\lambda(u)$  are a local minimum-Lagrange multiplier pair for the problem  $\min_{h(x)=u} f(x)$ .

To derive  $\nabla p(u)$ , differentiate  $h(x(u)) = u$ , to obtain  $I = \nabla x(u)\nabla h(x(u))$ , and combine with the relations  $\nabla x(u)\nabla f(x(u)) + \nabla x(u)\nabla h(x(u))\lambda(u) = 0$  and  $\nabla p(u) = \nabla_u \{ f(x(u)) \} = \nabla x(u)\nabla f(x(u))$ .