# 6.241 Spring 2011

#### Midterm Exam

3/16/2011

You have a total of three hours to complete this exam. These three hours can be chosen at your convenience.

# Problem 1

Let  $A \in \mathbb{C}^{n \times n}$ , and  $B \in \mathbb{C}^{m \times m}$ . Show that  $X(t) = e^{At}X(0)e^{Bt}$  is the solution to  $\dot{X} = AX + XB$ .

# Problem 2

Given two non-zero vectors  $v, w \in \mathbb{R}^n$ . Does there exist a matrix A such that v = Aw and

1. 
$$\sigma_{\max}(A) = \sqrt{v^T v / w^T w}$$
?

2. 
$$||A||_1 = ||v||_{\infty}/||w||_{\infty}$$
?

Prove or disprove each case separately.

# Problem 3

Let 
$$||A|| < 1$$
. Show that  $||(I - A)^{-1}|| \ge \frac{1}{1 + ||A||}$ .

#### Problem 4

Use the projection theorem to solve the problem:

$$\min x \in \mathbb{R}^n \{ x^T Q x : A x = b \},\$$

where Q is a positive-definite  $n \times n$  matrix, A is a  $m \times n$  real matrix, with rank m < n, and b is a real m-dimensional vector. Is the solution unique?

#### Problem 5

Consider a single-input discrete-time LTI system, described by

$$x[k+1] = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} x[k] + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u[k]$$
$$y[k] = x[k],$$

and the initial condition x[0] = 0. Given M > 1, what is the maximum value of  $||y[M]||_2$  that can be attained with an input of "unit energy,", i.e., such that  $u[0]^2 + u[1]^2 + \ldots + u[M-1]^2 = 1$ ? What is the input that attains such value? How would your answer change if you were to double M, i.e.,  $M \leftarrow 2M$ ?

#### Problem 6

Consider a physical system whose behavior is modeled, in continuous time, by the differential equation

$$\dot{x} = Ax + Bu.$$

Assume that you have two sensors. The first sensor yields measurements  $y_1 = C_1x$  for  $t = 0, 1, 2, 3, \ldots$ , and the second sensor yields measurements  $y_2 = C_2x$  for  $t = 0, 2, 4, \ldots$ . Assuming that  $u(t) = u(\lfloor t \rfloor)$ , for all  $t \geq 0$ , derive a discrete-time state-space model for the system, relating the inputs at times  $(u(0), u(1), u(2), \ldots)$  to the outputs at times  $(y(0), y(1), y(2), \ldots)$ .

6.241J / 16.338J Dynamic Systems and Control Spring 2011

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.