# 6.035

# **Unoptimized Code Generation**

• Last time we left off on the procedure abstraction ...

#### The Stack

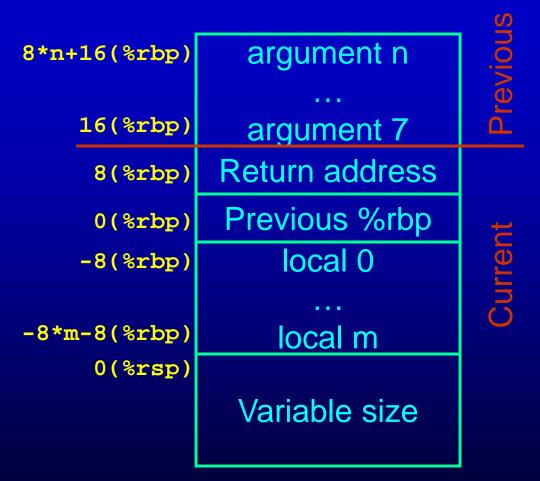
- Arguments 0 to 6 are in:
  - %rdi, %rsi, %rdx,%rcx, %r8 and %r9

#### %rbp

marks the beginning
 of the current frame

#### %rsp

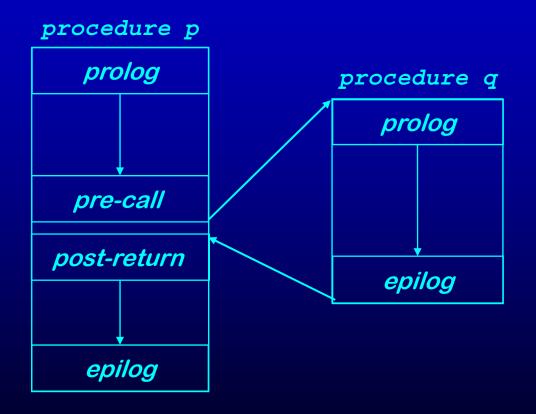
- marks the end



• Why use a stack? Why not use the heap or preallocated in the data segment?

# Procedure Linkages

#### Standard procedure linkage



#### Pre-call:

- •Save caller-saved registers
- Push arguments

#### **Prolog:**

- Push old frame pointer
- •Save calle-saved registers
- •Make room for temporaries

#### **Epilog:**

- Restore callee-saved
- •Pop old frame pointer
- Store return value

#### **Post-return:**

- Restore caller-saved
- Pop arguments

- Calling: Caller
  - Assume %rcx is live and is caller save
  - Call foo(A, B, C, D, E, F, G, H, I)
    - A to I are at -8(%rbp) to -72(%rbp)

push	%rcx
push	-72(%rbp)
push	-64(%rbp)
push	-56(%rbp)
mov	-48(%rbp), %r9
mov	-40(%rbp), %r8
mov	-32(%rbp), %rcx
mov	-24(%rbp), %rdx
mov	-16(%rbp), %rsi
mov	-8(%rbp), %rdi
call	foo

return address -rbp previous frame pointer calliee saved registers local variables stack temporaries dynamic area rsp caller saved registers argument 9 argument 8 argument 7 return address

- Calling: Calliee
  - Assume %rbx is used in the function and is calliee save
  - Assume 40 bytes are required for locals

#### foo:



return address rbp previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address rsp previous frame pointer calliee saved registers local variables stack temporaries

dynamic area

- Arguments
- Call foo(A, B, C, D, E, F, G, H, I)
  - Passed in by pushing before the call

```
      push
      -72(%rbp)

      push
      -64(%rbp)

      push
      -56(%rbp)

      mov
      -48(%rbp), %r9

      mov
      -40(%rbp), %r8

      mov
      -32(%rbp), %rcx

      mov
      -24(%rbp), %rdx

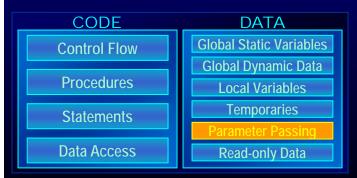
      mov
      -16(%rbp), %rsi

      mov
      -8(%rbp), %rdi

      call
      foo
```

- Access A to F via registers
  - or put them in local memory
- Access rest using 16+xx(%rbp)

```
mov 16(%rbp), %rax mov 24(%rbp), %r10
```



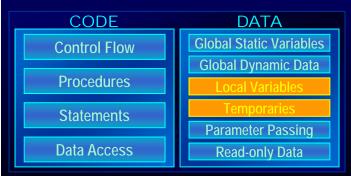
return address previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address previous frame pointer calliee saved registers local variables stack temporaries rsp dynamic area

- Locals and Temporaries
  - Calculate the size and allocate space on the stack

sub \$48, %rsp or enter \$48, 0

Access using -8-xx(%rbp)

mov -28(%rbp), %r10 mov %r11, -20(%rbp)



return address previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address previous frame pointer calliee saved registers local variables stack temporaries rsp

dynamic area

#### Returning Calliee

- Assume the return value is the first temporary
- Restore the caller saved register
- Put the return value in %rax
- Tear-down the call stack

mov	-8(%rbp), %	krbx
mov	-16(%rbp),	%rax
mov leave	%rbp, %rsp	
pop	%rbp	
ret		

return address previous frame pointer calliee saved registers local variables stack temporaries dynamic area caller saved registers argument 9 argument 8 argument 7 return address previous frame pointer calliee saved registers local variables stack temporaries rsp dynamic area

- Returning Caller
- (Assume the return value goes to the first temporary)
  - Restore the stack to reclaim the argument space
  - Restore the caller save registers
  - Save the return value

return address previous frame pointer calliee saved registers	<b>←</b> rbp
local variables	
stack temporaries	
dynamic area	
caller saved registers	
argument 9 argument 8 argument 7	rsp

call	foo
add	\$24, %rsp
pop	%rcx
mov	<pre>%rax, 8(%rbp)</pre>
•••	



- Do you need the \$rbp?
- What are the advantages and disadvantages of having \$rbp?

### So far we covered...

CODE

DATA

**Procedures** 

**Control Flow** 

**Statements** 

**Data Access** 

Global Static Variables

Global Dynamic Data

**Local Variables** 

**Temporaries** 

Parameter Passing

Read-only Data

#### Outline

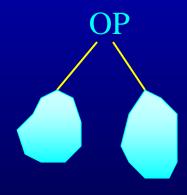
- Generation of expressions and statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

# Expressions

- Expressions are represented as trees
  - Expression may produce a value
  - Or, it may set the condition codes (boolean exprs)
- How do you map expression trees to the machines?
  - How to arrange the evaluation order?
  - Where to keep the intermediate values?
- Two approaches
  - Stack Model
  - Flat List Model

# Evaluating expression trees

- Stack model
  - Eval left-sub-treePut the results on the stack
  - Eval right-sub-treePut the results on the stack
  - Get top two values from the stack
     perform the operation OP
     put the results on the stack



Very inefficient!

# Evaluating expression trees

- Flat List Model
  - The idea is to linearize the expression tree
  - Left to Right Depth-First Traversal of the expression tree
    - Allocate temporaries for intermediates (all the nodes of the tree)
      - New temporary for each intermediate
      - All the temporaries on the stack (for now)
  - Each expression is a single 3-addr op
    - $\bullet$  x = y op z
    - Code generation for the 3-addr expression
      - Load y into register %r10
      - Load z into register %r11
      - Perform op %r10, %r11
      - Store %r11 to x

# Issues in Lowering Expressions

- Map intermediates to registers?
  - registers are limited
    - when the tree is large, registers may be insufficient ⇒ allocate space in the stack
- No machine instruction is available
  - May need to expand the intermediate operation into multiple machine ops.
- Very inefficient
  - too many copies
  - don't worry, we'll take care of them in the optimization passes
  - keep the code generator very simple

#### What about statements?

- Assignment statements are simple
  - Generate code for RHS expression
  - Store the resulting value to the LHS address

But what about conditionals and loops?

#### Outline

- Generation of statements
- Generation of control flow
- Guidelines in writing a code generator

# Two Approaches

- Template Matching Approach
  - Peephole Optimization
- Algorithmic Approach

- Both are based on structural induction
  - Generate a representation for the sub-parts
  - Combine them into a representation for the whole

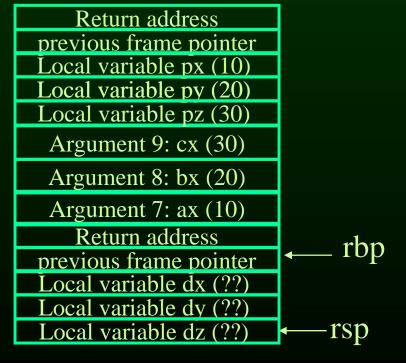
# Generation of control flow: Template Matching Approach

- Flatten the control structure
  - use a template
- Put unique labels for control join points
- Now generate the appropriate code

# Template for conditionals

```
if (test)
  true_body
else
  false_body
```

```
<do test>
        joper
                .LO
        <FALSE BODY>
        qmt
                .L1
.L0:
       <TRUE BODY>
.L1:
```



```
movq 16(%rbp), %r10
movq 24(%rbp), %r11
cmpq %r10, %r11
jg .L0
```

<FALSE BODY>

jmp .L1

.LO:

<TRUE BODY>

.L1:

Return address
previous frame pointer
Local variable px (10)
Local variable py (20)
Local variable pz (30)
Argument 9: cx (30)
Argument 8: bx (20)
Argument 7: ax (10)
Return address
previous frame pointer
Local variable dx (??)
Local variable dy (??)
Local variable dz (??)

Local variable dz (??)

Local variable dz (??)

	movq	16(%rbp), %r10
	movq	24(%rbp), %r11
	cmpq	%r10, %r11
	jg	.LO
	movq	24(%rbp), %r10
	movq	16(%rbp), %r11
	subq	%r10, %r11
	movq	%r11, -8(%rbp)
	jmp	.L1
.LO:		

<TRUE BODY>

.L1:

Return address	
previous frame pointer	
Local variable px (10)	
Local variable py (20)	
Local variable pz (30)	
Argument 9: cx (30)	
Argument 8: bx (20)	
Argument 7: ax (10)	
Return address	rhn
previous frame pointer	← rbp
Local variable dx (??)	
Local variable dy (??)	
Local variable dz (??)	<b>←</b> rsp

	movq	16(%rbp), %r10
	movq	24(%rbp), %r11
	cmpq	%r10, %r11
	jg	.LO
	movq	24(%rbp), %r10
	movq	16(%rbp), %r11
	subq	%r10, %r11
	movq	%r11, -8(%rbp)
	jmp	.L1
.LO:		
	movq	16(%rbp), %r10
	movq	24(%rbp), %r11
	subq	%r10, %r11
	movq	%r11, -8(%rbp)
.L1:		

Return address	
previous frame pointer	
Local variable px (10)	
Local variable py (20)	
Local variable pz (30)	
Argument 9: cx (30)	
Argument 8: bx (20)	
Argument 7: ax (10)	
Return address	← rbp
previous frame pointer	← rυp
Local variable dx (??)	
Local variable dy (??)	
Local variable dz (??)	<b>←</b> rsp

# Template for while loops

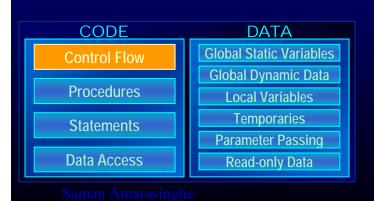
while (test) body

# Template for while loops

```
while (test)
body
```

### Template for while loops

An optimized template



• What is the template for?

```
do
  body
while (test)
```

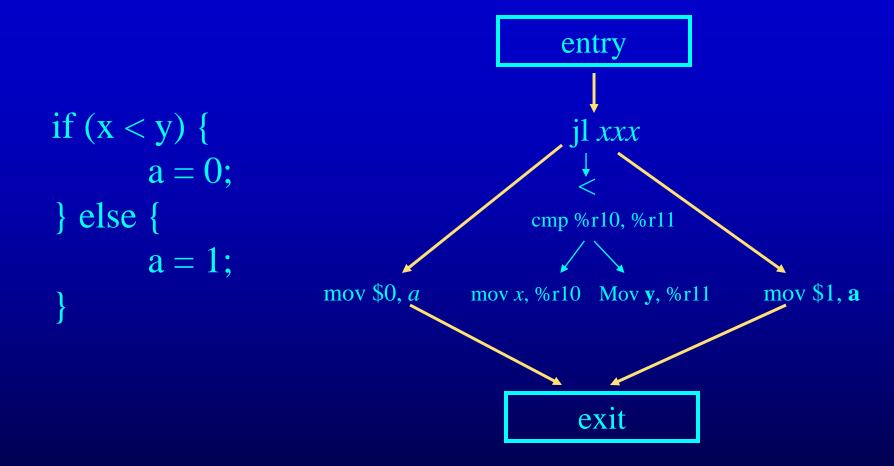
• What is the template for?

```
do
  body
while (test)
```

 What is a drawback of the template based approach?

# Control Flow Graph (CFG)

- Starting point: high level intermediate format, symbol tables
- Target: CFG
  - CFG Nodes are Instruction Nodes
  - CFG Edges Represent Flow of Control
  - Forks At Conditional Jump Instructions
     Merges When Flow of Control Can Reach A Point Multiple Ways
  - Entry and Exit Nodes



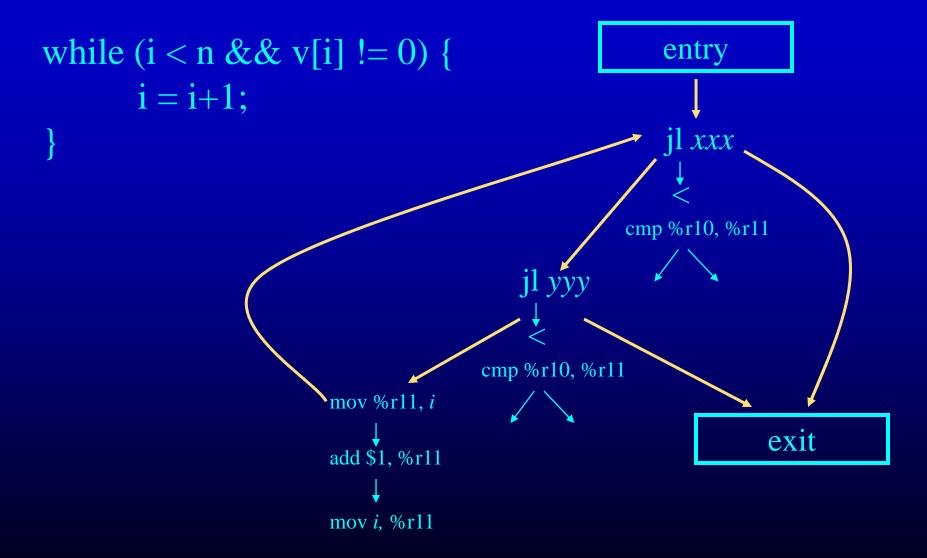
#### Pattern for if then else

#### **Short-Circuit Conditionals**

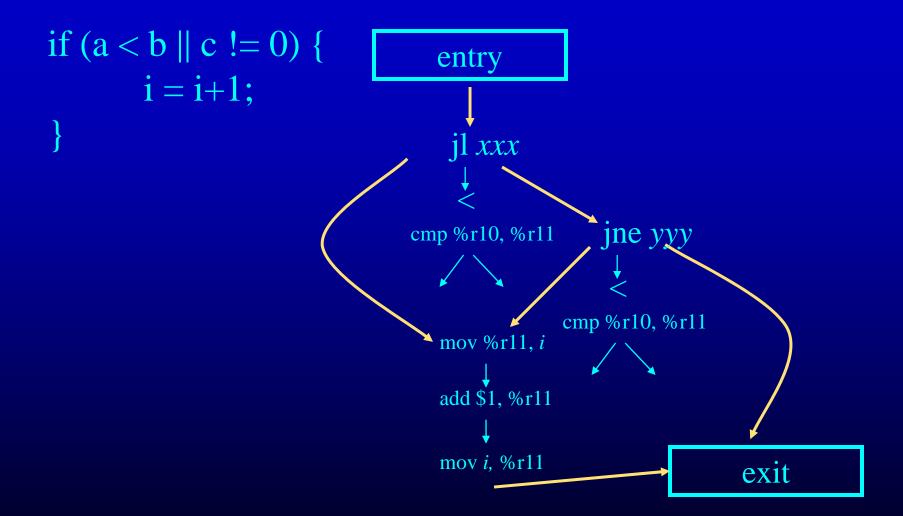
In program, conditionals have a condition written as a boolean expression
 ((i < n) && (v[i]!=0)) || i > k)

- Semantics say should execute only as much as required to determine condition
  - Evaluate (v[i] != 0) only if (i < n) is true
  - Evaluate i > k only if ((i < n) && (v[i] != 0)) is false
- Use control-flow graph to represent this short-circuit evaluation

### **Short-Circuit Conditionals**



### More Short-Circuit Conditionals



# Routines for Destructuring Program Representation

#### destruct(n)

generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form

#### shortcircuit(c, t, f)

generates short-circuit form of conditional represented by c if c is true, control flows to t node if c is false, control flows to f node returns b - b is begin node for condition evaluation

new kind of node - nop node

#### destruct(n)



#### destruct(n)

1: 
$$(b_x, e_x) = destruct(x)$$
;

#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

#### destruct(n)

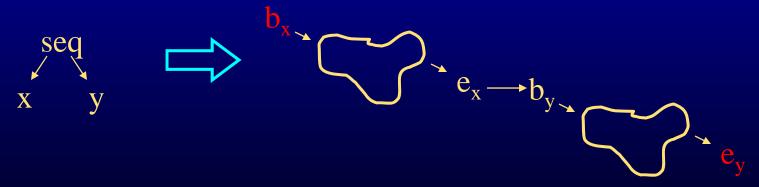
1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

3: 
$$next(e_x) - b_y$$
;

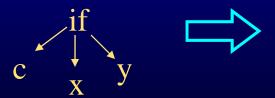
#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

3: 
$$next(e_x) - b_y$$
; 4:  $return(b_x, e_y)$ ;



#### destruct(n)



#### destruct(n)

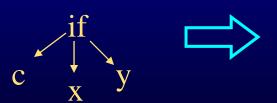
1: 
$$(b_x, e_x) = destruct(x)$$
;



$$b_x \rightarrow \bigcirc \bigcirc \rightarrow e_x$$

#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;



$$b_{x} \xrightarrow{b_{x}} e_{x}$$

$$b_{y} \xrightarrow{e_{y}}$$

#### destruct(n)



$$b_{x} \xrightarrow{} e_{x}$$

$$b_{y} \xrightarrow{} e_{y}$$

$$e$$

#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

3: 
$$e = new nop;$$
 4:  $next(e_x) = e;$  5:  $next(e_y) = e;$ 



$$b_{x} \xrightarrow{b_{x}} e_{x}$$

$$b_{y} \xrightarrow{e_{y}} e$$

#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

3: 
$$e = new nop;$$
 4:  $next(e_x) = e;$  5:  $next(e_y) = e;$ 

**6:** 
$$b_c = \text{shortcircuit}(c, b_x, b_v);$$

$$c \xrightarrow{if} b_{c} \xrightarrow{b_{x}} e_{x}$$

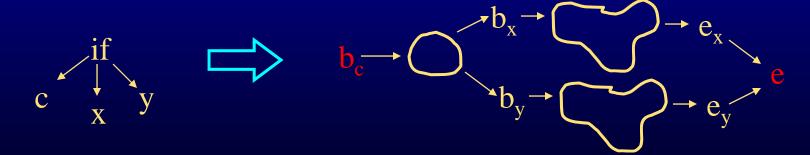
$$c \xrightarrow{x} y \xrightarrow{b_{x}} e_{y}$$

#### destruct(n)

1: 
$$(b_x,e_x) = destruct(x)$$
; 2:  $(b_y,e_y) = destruct(y)$ ;

3: 
$$e = new nop;$$
 4:  $next(e_x) = e;$  5:  $next(e_y) = e;$ 

6: 
$$b_c = \text{shortcircuit}(c, b_x, b_y)$$
; 7: return  $(b_c, e)$ ;



#### destruct(n)

#### destruct(n)

generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form if n is of the form while c x

1: 
$$e = new nop$$
;

e

#### destruct(n)

1: 
$$e = new nop;$$
 2:  $(b_x, e_x) = destruct(x);$ 

$$e_{x}$$
  $b_{x}$   $e$ 

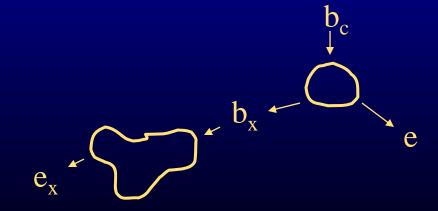
#### destruct(n)

generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form if n is of the form while c x

1: e = new nop; 2:  $(b_x, e_x) = destruct(x);$ 

3:  $b_c$  - shortcircuit(c,  $b_x$ , e);



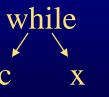


#### destruct(n)

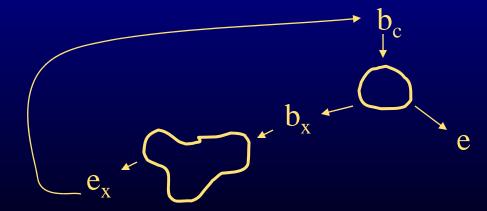
generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form if n is of the form while c x

1:  $e = new nop; 2: (b_x, e_x) = destruct(x);$ 

3:  $b_c$  - shortcircuit(c,  $b_x$ , e); 4:  $next(e_x) - b_c$ ;







#### destruct(n)

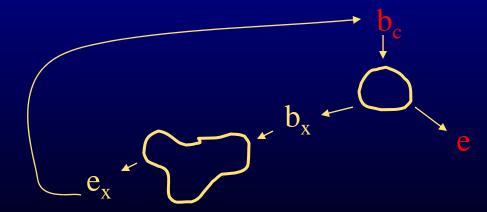
generates lowered form of structured code represented by n returns (b,e) - b is begin node, e is end node in destructed form if n is of the form while c x

1:  $e = new nop; 2: (b_x, e_x) = destruct(x);$ 

3:  $b_c$  - shortcircuit(c,  $b_x$ , e); 4: next( $e_x$ ) -  $b_c$ ; 5: return ( $b_c$ , e);







shortcircuit(c, t, f)

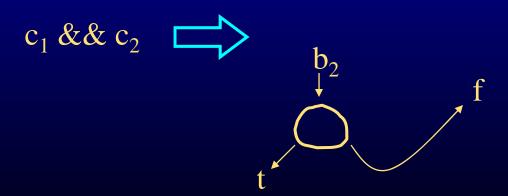
generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form  $c_1 \&\& c_2$ 

$$c_1 \&\& c_2$$

shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form  $c_1 \&\& c_2$ 

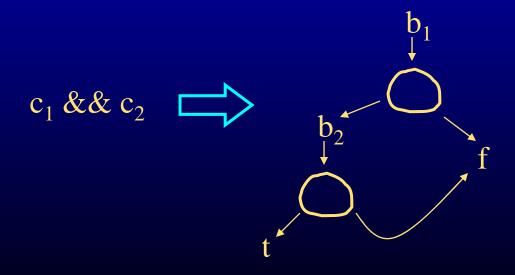
1:  $b_2$  = shortcircuit( $c_2$ , t, f);



#### shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form  $c_1 \&\& c_2$ 

1:  $b_2$  = shortcircuit( $c_2$ , t, f); 2:  $b_1$  = shortcircuit( $c_1$ ,  $b_2$ , f);



```
shortcircuit(c, t, f)
   generates shortcircuit form of conditional represented by c
   returns b - b is begin node of shortcircuit form
   if c is of the form c_1 && c_2
        1: b_2 = \text{shortcircuit}(c_1, t, f); 2: b_1 = \text{shortcircuit}(c_1, b_2, f);
        3: return (b_1);
                c_1 \&\& c_2
```

shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by  $\mathbf{c}$  returns  $\mathbf{b}$  -  $\mathbf{b}$  is begin node of shortcircuit form if  $\mathbf{c}$  is of the form  $\mathbf{c}_1 \parallel \mathbf{c}_2$ 

$$c_1 \parallel c_2$$

shortcircuit(c, t, f)

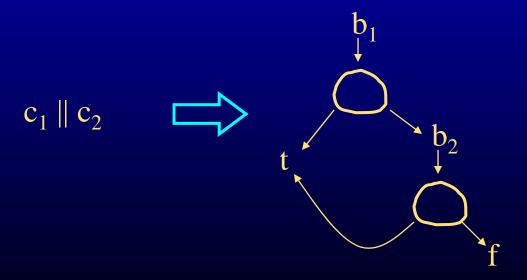
generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form  $c_1 \parallel c_2$ 

1:  $b_2$  = shortcircuit( $c_2$ , t, f);

shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by  ${\bf c}$  returns  ${\bf b}$  -  ${\bf b}$  is begin node of shortcircuit form if  ${\bf c}$  is of the form  ${\bf c}_1 \parallel {\bf c}_2$ 

1:  $b_2$  = shortcircuit( $c_2$ , t, f); 2:  $b_1$  = shortcircuit( $c_1$ , t,  $b_2$ );

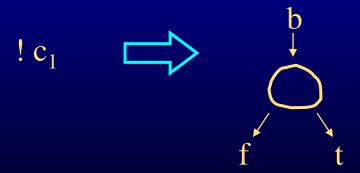


```
shortcircuit(c, t, f)
   generates shortcircuit form of conditional represented by c
   returns b - b is begin node of shortcircuit form
   if c is of the form c_1 \parallel c_2
        1: b_2 = shortcircuit(c_2, t, f); 2: b_1 = shortcircuit(c_1, t, b_2);
        3: return (b_1);
                c_1 \parallel c_2
```

shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by  $\mathbf{c}$  returns  $\mathbf{b}$  -  $\mathbf{b}$  is begin node of shortcircuit form if  $\mathbf{c}$  is of the form !  $\mathbf{c}_1$ 

1:  $b = \text{shortcircuit}(c_1, f, t)$ ; return(b);



### Computed Conditions

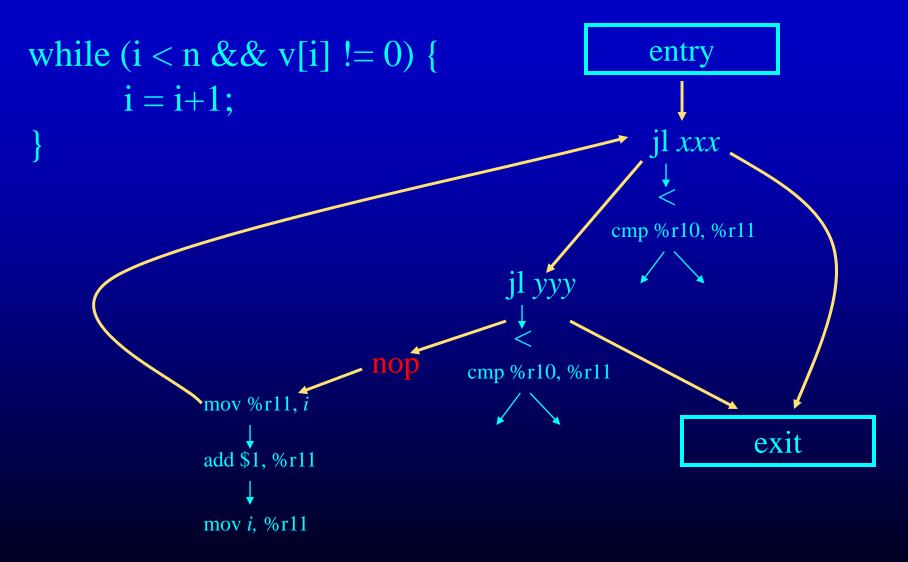
shortcircuit(c, t, f)

generates shortcircuit form of conditional represented by c returns b - b is begin node of shortcircuit form if c is of the form  $e_1 < e_2$ 

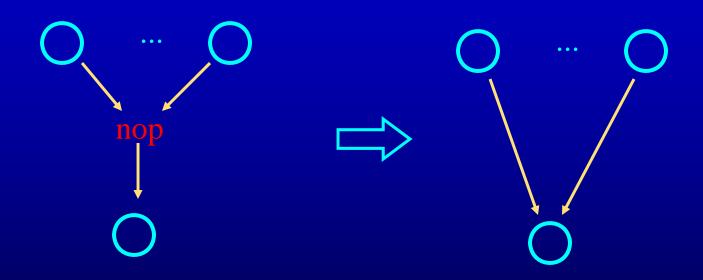
1:  $b = \text{new cbr}(e_1 < e_2, t, f)$ ; 2: return (b);

$$e_1 < e_2$$
 $t$ 
 $e_1$ 
 $e_1$ 
 $e_2$ 
 $e_1$ 
 $e_2$ 

# Nops In Destructured Representation



# Eliminating Nops Via Peephole Optimization



### Question:

• What are the pros and cons of template matching vs. algorithmic approach?

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### Outline

- Generation of statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

### Guidelines for the code generator

- Lower the abstraction level slowly
  - Do many passes, that do few things (or one thing)
    - Easier to break the project down, generate and debug
- Keep the abstraction level consistent
  - IR should have 'correct' semantics at all time
    - At least you should know the semantics
  - You may want to run some of the optimizations between the passes.
- Use assertions liberally
  - Use an assertion to check your assumption

### Guidelines for the code generator

- Do the simplest but dumb thing
  - it is ok to generate 0 + 1\*x + 0\*y
  - Code is painful to look at; let optimizations improve it

- Make sure you know want can be done at...
  - Compile time in the compiler
  - Runtime using generated code

### Guidelines for the code generator

- Remember that optimizations will come later
  - Let the optimizer do the optimizations
  - Think about what optimizer will need and structure your code accordingly
  - Example: Register allocation, algebraic simplification, constant propagation
- Setup a good testing infrastructure
  - regression tests
    - If a input program creates a bug, use it as a regression test
  - Learn good bug hunting procedures
    - Example: binary search, delta debugging

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