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6.006 Introduction to Algorithms  
Spring 2008

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# 6.006 Recitation

Build 2008.25

# 6.006 Proudly Presents

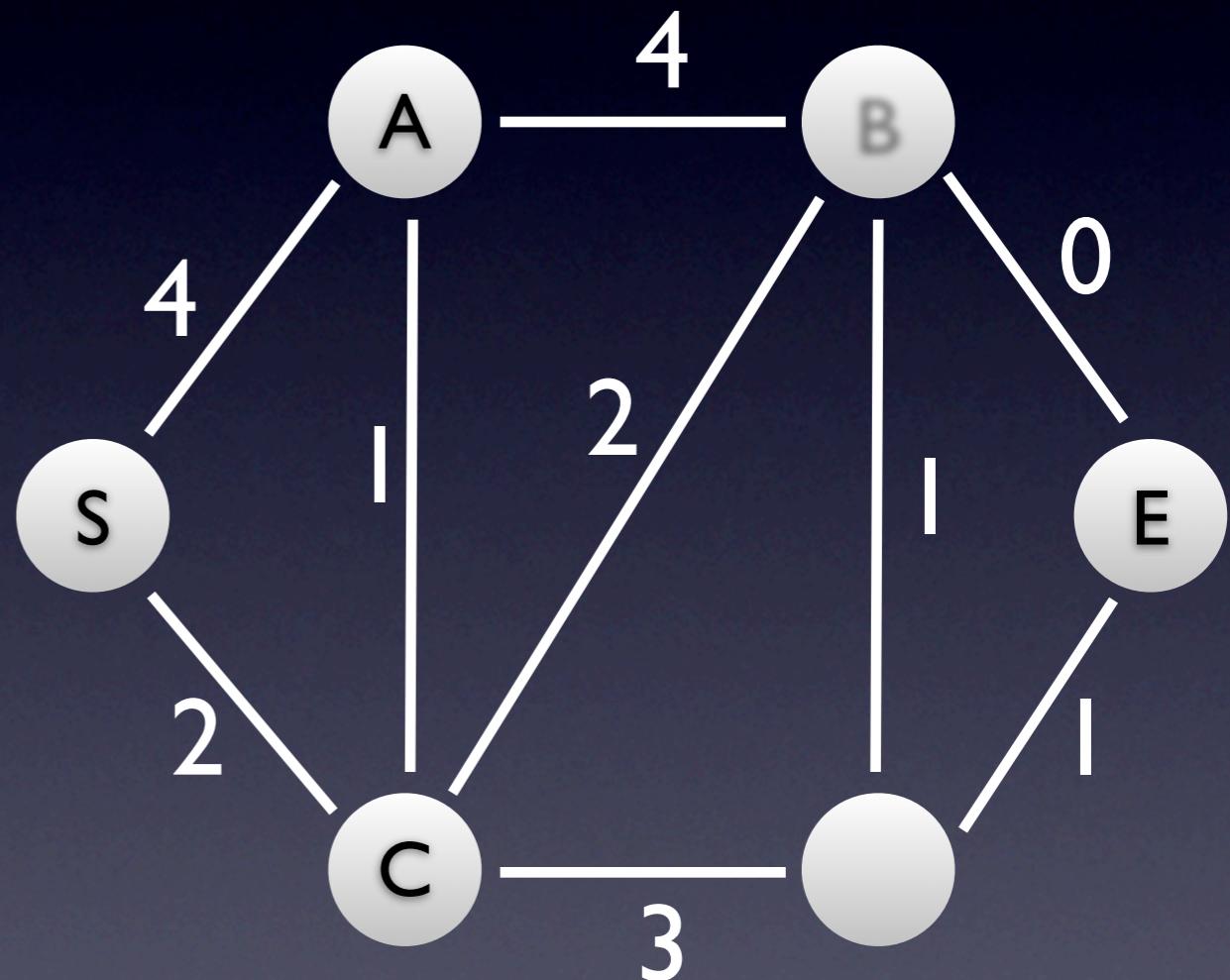
- Dijkstra: minimum-cost paths on crack
  - Algorithm
  - Concepts
  - Implementation
- Data structures come back from the dead  
(not talking about the quiz)

# Minimum-Path Problem

- Given: graph  $G$ , source vertex  $s$ , edge costs
- Want: paths from  $s$  to everything else with minimum costs (sum of edge costs)
- Approach: let  $d[v]$  be upper bounds for the real minimum costs,  $\delta[v]$
- Start out easy:  $d[v] = \infty$ ,  $d[s] = 0$
- Relax until values in  $d$  converge to  $\delta$

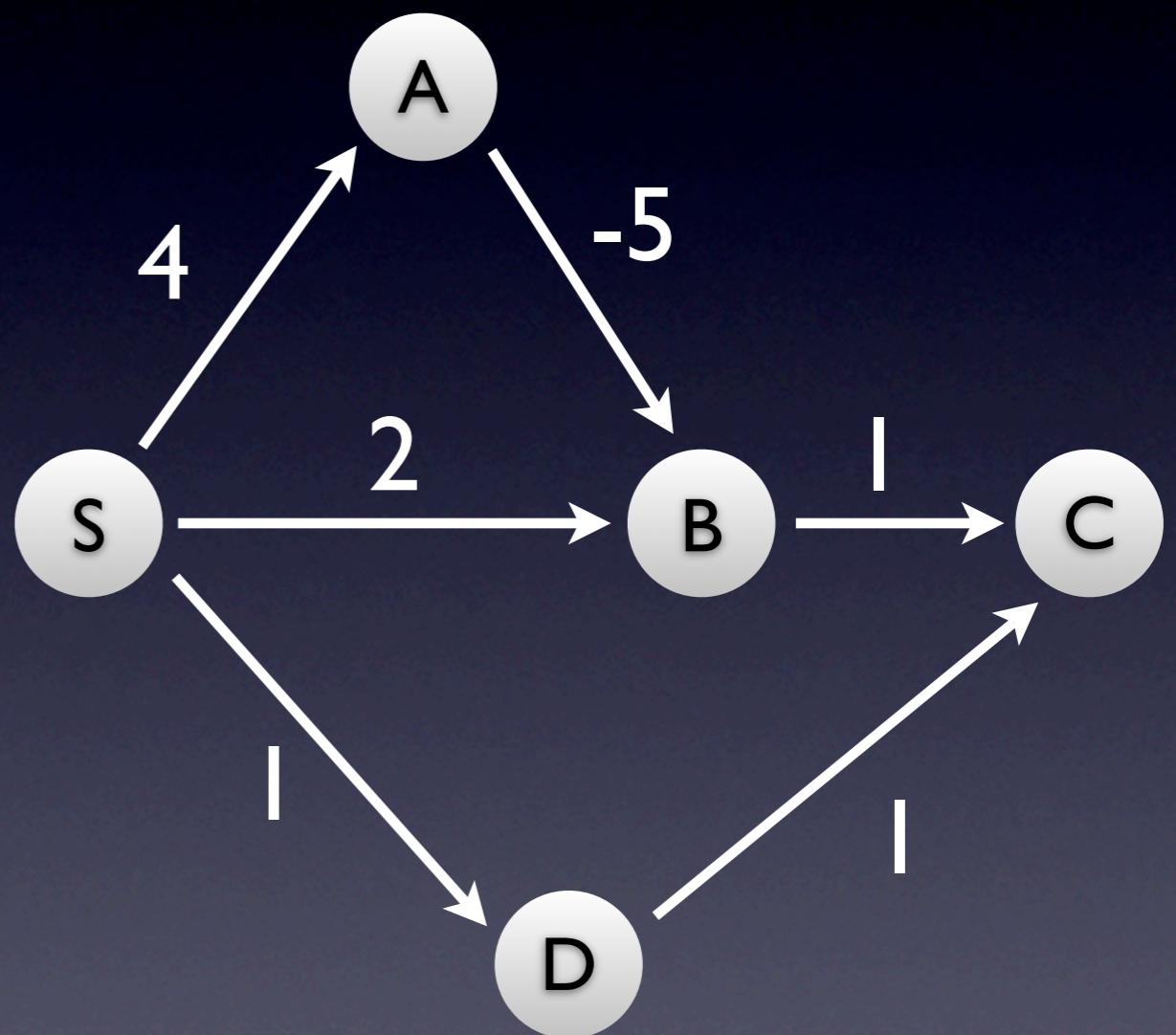
# Good Dijkstra

- Generic initialization
- $U = V$
- Choose  $v = \operatorname{argmin} d[v]$  in  $U$ , remove  $v$  from  $U$
- Notice  $d[v] = \delta[v]$
- Relax  $v$ 's outgoing edges
- Rinse, repeat



# Bad Dijkstra

- Generic initialization
- $U = V$
- Choose  $v = \operatorname{argmin} d[v \text{ in } U]$ , remove  $v$  from  $U$
- Notice  $d[v] = \delta[v]$
- Relax  $v$ 's outgoing edges
- Rinse, repeat



# Dijkstra Overview

- Nice and fast (that's why it's on crack)
- With limitations (crack impacts judgement)
  - Doesn't handle negative-cost edges
    - DOES handle 0-cost edges
  - Harder to code than Bellman-Ford

# Dijkstra Works: Intuition

# Dijkstra Works: Formal

# Making Dijkstra Fast (its crack dealer)

- Generic initialization:  
 $d[v] \leftarrow \infty, d[S] = 0$
- Choose  $v = \operatorname{argmin} d[v]$ ,  
by now  $d[v] = \delta[v]$
- Relax all edges going out  
of  $v$
- Rinse, repeat
- Computing  $\operatorname{argmin}$ 
  - $V$  times
- Relaxing
  - $E$  times
- Looks like we need a  
Data Structure

# Min-Priority Queues

- Data Structure
  - **insert(key)** : adds to the queue
  - **min()** : returns the minimum key
  - **delete-min()** : deletes the min key
  - **delete(key)** : deletes the given key
  - optional (only needed in some apps)

# Priority Queues with Min-Heaps

- Costs (see above line for explanations)
  - insert:  $O(\log(N))$
  - min:  $O(1)$
  - delete-min:  $O(\log(N))$
  - delete:  $O(\log(N))$  - only if given the index of the node containing the key

# Priority Queues with PS3

- Is this priority queue monotone?
- Profit

# Cool Python: Generators

## I. Iterators

- used in for loops
- objects implementing next()

## 2. Generators

- express iterator functionality in a cooler way

```
1 def counter():
2     i = 0
3     while True:
4         yield i
5         i += 1
```

----  
c = counter()  
c.next()

>> 0  
c.next()  
>> 1

d = counter()  
d.next()

>> 0  
c.next()  
>> 2

d.next()  
>> 1  
c.next()  
>> 3

# Dijkstra-Ready Priority Queues

```
1 class heap_id:
2     def __init__(self):
3         self.A = [None]
4         self.heapsize = 0
5         self.ID_to_index = {}
6         self._ID = self._ID_generator()
7     def insert(self, key):
8         """Returns an ID that is associated with the item."""
9         self.heapsize += 1
10        ID = self._ID.next()
11        self.ID_to_index[ID] = self.heapsize
12        self.A.append([positive_infinity(), ID])
13        self.decrease_key(self.heapsize, key)
14        return ID
15    def _ID_generator(self):
16        ID = 0
17        while True:
18            yield ID
19            ID += 1
```

# Dijkstra-Ready Priority Queues II

```
1 class heap_id:
2     def decrease_key_using_id(self, ID, key):
3         """Decrease key given ID."""
4         self.decrease_key(self.ID_to_index[ID], key)
5     def extract_min(self):
6         """Extracts min and returns key."""
7         return self.extract_min_with_id()[0]
8     def extract_min_with_id(self):
9         """Extracts min and returns (key, ID) pair."""
10    if self.heapsize < 1:
11        print "error: empty heap"
12        return
13    self._swap(1, self.heapsize)
14    self.heapsize -= 1
15    min_pair = self.A.pop()
16    del self.ID_to_index[min_pair[1]]
17    self.min_heapify(1)
18    return tuple(min_pair)
```