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6.006 Introduction to Algorithms
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Lecture 14: Searching III: Topological Sort and NP-completeness

Lecture Overview: Search 3 of 3 & NP-completeness

- BFS vs. DFS
- job scheduling
- topological sort
- intractable problems
- P, NP, NP-completeness

Readings

[CLRS, Sections 22.4 and 34.1-34.3 \(at a high level\)](#)

Recall:

- Breadth-First Search (BFS): level by level
- Depth-First Search (DFS): backtrack as necc.
- both $O(V + E)$ worst-case time \implies optimal
- BFS computes shortest paths (min. # edges)
- DFS is a bit simpler & has useful properties

Job Scheduling:

Given Directed Acyclic Graph (DAG), where vertices represent tasks & edges represent dependencies, order tasks without violating dependencies

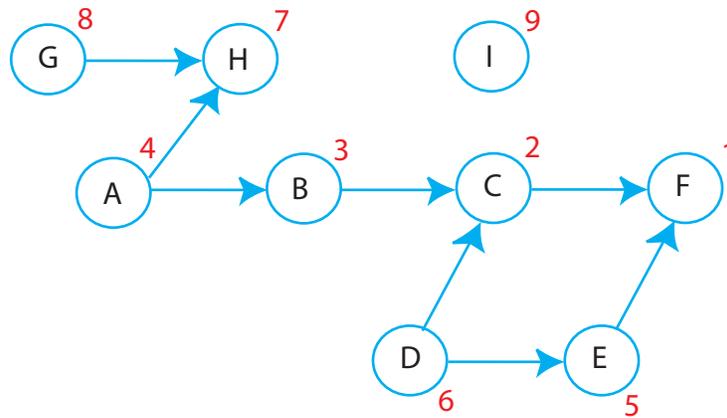


Figure 1: Dependence Graph

Source

Source = vertex with no incoming edges
 = schedulable at beginning (A,G,I)

Attempt

BFS from each source:

- from A finds H,B,C,F
 - from D finds C, E, F
 - from G finds H
- } need to merge
- costly

Figure 2: BFS-based Scheduling

Topological Sort

Reverse of DFS finishing times (time at which node's outgoing edges finished)

Exercise: prove that no constraints are violated

Intractability

- DFS & BFS are worst-case optimal if problem is really graph search (to look at graph)
- what if graph ...
 - is implicit?
 - has special structure?
 - is infinite?

The first 2 characteristics (implicitness and special structure) apply to the [Rubik's Cube problem](#).

The third characteristic (infiniteness) applies to the Halting Problem.

Halting Problem:

Given a computer program, does it ever halt (stop)?

decision problem: answer is YES or NO

UNDECIDABLE: no algorithm solves this problem (correctly in finite time on all inputs)

Most decision problems are undecidable:

- program \approx binary string \approx nonneg. integer $\in \aleph$
- decision problem = a function from [binary strings](#) to $\{\text{YES,NO}\}$. [Binary strings](#) refer to \approx [nonneg. integers](#) while $\{\text{YES,NO}\} \approx \{0,1\}$
- \approx infinite sequence of bits \approx real number $\in \mathfrak{R}$
- $\aleph \ll \mathfrak{R}$: non assignment of unique nonneg. integers to real numbers (\mathfrak{R} uncountable)
- \implies not nearly enough programs for all problems & each program solves only one problem
- \implies almost all problems cannot be solved

$n \times n \times n$ **Rubik's cube:**

- $n = 2$ or 3 is easy algorithmically: $O(1)$ time
in practice, $n = 3$ still unsolved
- graph size grows exponentially with n
- solvability decision question is easy (parity check)
- finding shortest solution: UNSOLVED

 $n \times n$ **Chess:**

Given $n \times n$ board & some configuration of pieces, can WHITE force a win?

- can be formulated as $(\alpha\beta)$ graph search
- every algorithm needs time exponential in n :
"EXPTIME-complete" [Fraenkel & Lichtenstein 1981]

 $n^2 - 1$ **Puzzle:**

Given $n \times n$ grid with $n^2 - 1$ pieces, sort pieces by sliding (see Figure 3).

- similar to Rubik's cube:
- solvability decision question is easy (parity check)
- finding shortest solution: NP-COMplete [Ratner & Warmuth 1990]

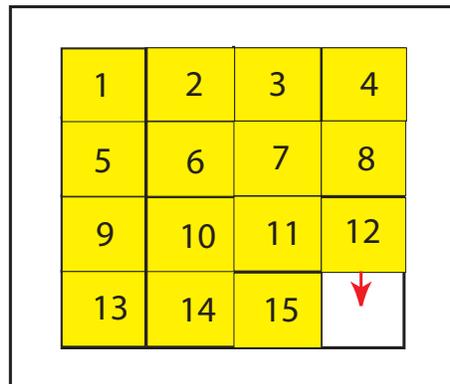


Figure 3: Puzzle

Tetris:

Given current board configuration & list of pieces to come, stay alive

- NP-COMplete [Demaine, Hohenberger, Liben-Nowell 2003]

P, NP, NP-completeness

P = all (decision) problems solvable by a polynomial ($O(n^c)$) time algorithm (efficient)

NP = all decision problems whose YES answers have short (polynomial-length) “proofs” checkable by a polynomial-time algorithm

e.g., Rubik’s cube and $n^2 - 1$ puzzle:

is there a solution of length $\leq k$?

YES \implies easy-to-check short proof(moves)

Tetris \in NP

but we conjecture Chess not NP (winning strategy is big- exponential in n)

P \neq NP: Big conjecture (worth \$1,000,000) \approx generating proofs/solutions is harder than checking them

NP-complete = in NP & NP-hard

NP-hard = as hard as every problem in NP

= every problem in NP can be efficiently converted into this problem

\implies if this problem \in P then P = NP (so probably this problem not in P)