
Theory of the Firm

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1.201 / 11.545 / ESD.210

Transportation Systems Analysis: Demand & Economics

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Outline

- Basic Concepts
- Production functions
- Profit maximization and cost minimization
- Average and marginal costs

Basic Concepts

- Describe behavior of a firm
- Objective: maximize profit

$$\max \pi = R(a) - C(a)$$

$$s.t. \quad a \geq 0$$

– R, C, a – revenue, cost, and activities, respectively

- Decisions: amount & price of inputs to buy
 amount & price of outputs to produce
- Constraints: technology constraints
 market constraints

Production Function

- Technology: method for turning inputs (including raw materials, labor, capital, such as vehicles, drivers, terminals) into outputs (such as trips)
- Production function: description of the technology of the firm. Maximum output produced from given inputs.

$$q = q(X)$$

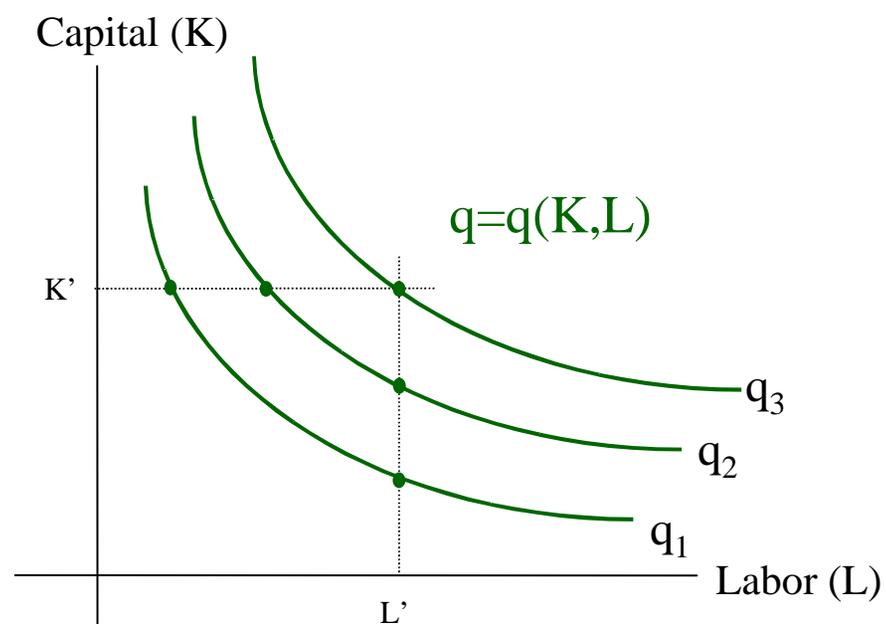
- q – vector of outputs
- X – vector of inputs (capital, labor, raw material)

Using a Production Function

- The production function predicts what resources are needed to provide different levels of output
- Given prices of the inputs, we can find the most efficient (i.e. minimum cost) way to produce a given level of output

Isoquant

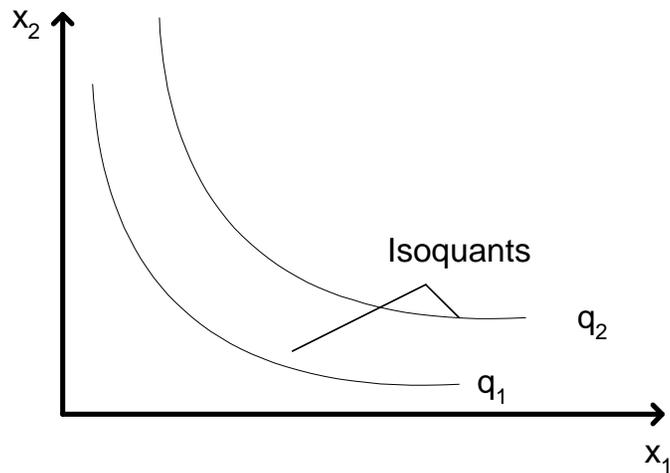
- For two-input production:



Production Function: Examples

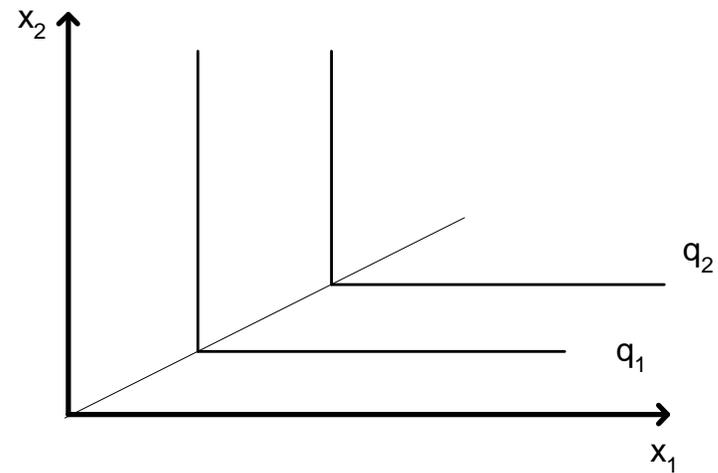
- Cobb-Douglas :

$$q = \alpha x_1^a x_2^b$$



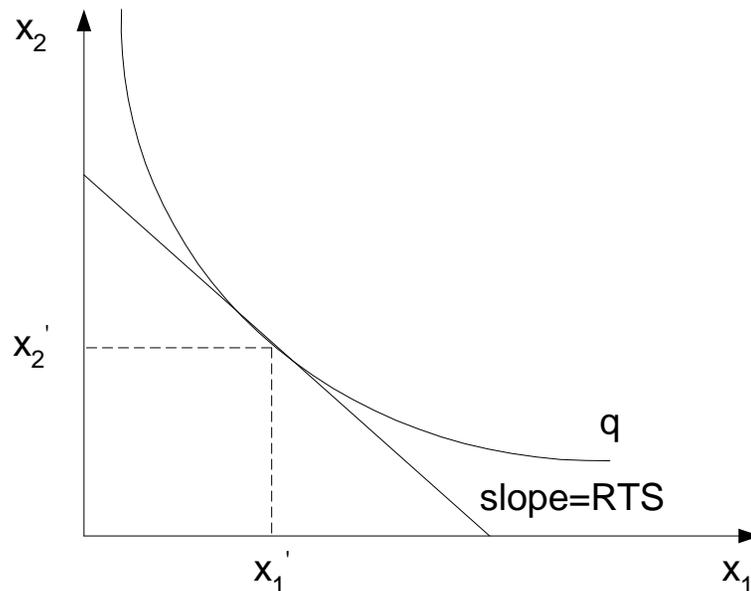
- Input-Output:

$$q = \min(ax_1, bx_2)$$



Rate of Technical Substitution (RTS)

- Substitution rates for inputs
 - Replace a unit of input 1 with RTS units of input 2 keeping the same level of production



$$RTS = \left. \frac{\partial x_2}{\partial x_1} \right|_q = - \frac{\partial q / \partial x_1}{\partial q / \partial x_2}$$

RTS: An Example

- Cobb-Douglas Technology $q = \alpha x_1^a x_2^b$

$$\frac{\partial q}{\partial x_1} = \alpha a x_1^{a-1} x_2^b$$

$$\frac{\partial q}{\partial x_2} = \alpha b x_1^a x_2^{b-1}$$

$$RTS = \left. \frac{\partial x_2}{\partial x_1} \right|_q = -\frac{a}{b} \frac{x_2}{x_1}$$

Elasticity of Substitution

- The elasticity of substitution measures the percentage change in factor proportion due to 1 % change in marginal rate of technical substitution

$$s = \frac{\partial(x_2 / x_1)}{\partial[RTS]} \frac{RTS}{(x_2 / x_1)}$$

$$s = \frac{\partial \ln(x_2 / x_1)}{\partial \ln(RTS)}$$

- For Cobb-Douglas:

$$\begin{aligned} \frac{\partial(x_2 / x_1)}{\partial[RTS]} &= 1 / \frac{\partial[RTS]}{\partial(x_2 / x_1)} \\ &= 1 / \frac{-a}{b} = -\frac{b}{a} \end{aligned} \quad \longrightarrow \quad s = (-b / a) \frac{(-a / b) / (x_2 / x_1)}{(x_2 / x_1)} = 1$$

Other Production Functions

- Constant Elasticity of Substitution (CES):

$$q = (ax_1^t + bx_2^t)^{s/t}$$

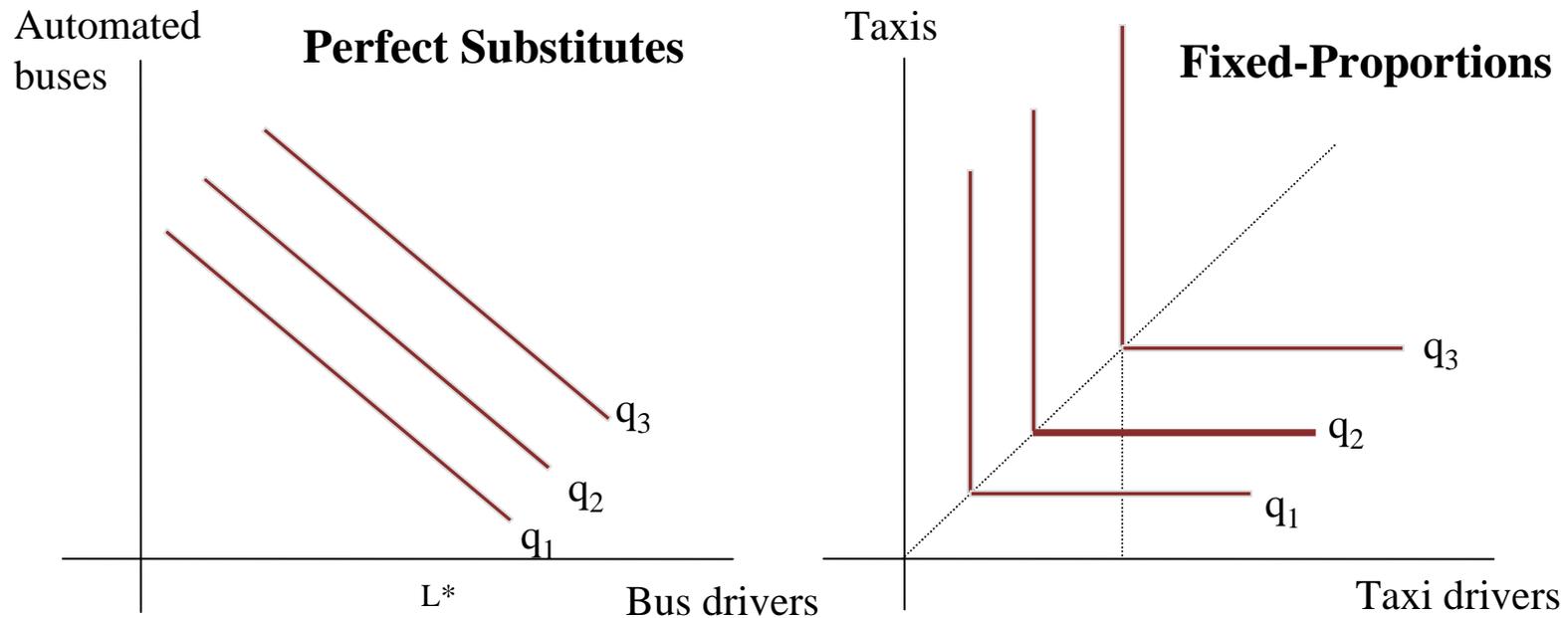
- Elasticity of Substitution = $1/(1-t)$
- Translog
 - State of the Art
 - Variable Elasticities, Interaction Terms
 - More in Next Lecture

Transit Production

- Inputs: capital, labor, fuel, maintenance
- Rejected the Cobb-Douglas form (Viton 1981, Berechman 1993, and others)
 - Implying significant interactions among inputs
- Low substitution rates among inputs
 - In particular capital and labor (one-vehicle-one-driver operations)
 - Suggests fixed proportions type of technology (Input-Output)

Perfect Substitutes and Fixed Proportions

- Does the technology allow substitution among inputs or not?



Joint Production Function

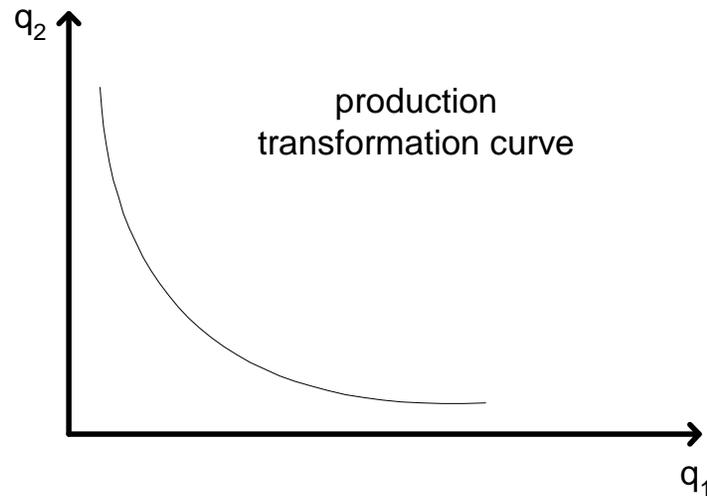
- Describes the production of several outputs
- Railroad companies:
 - Klein 1974: $(q_1)^r (q_2)^s = \alpha K^a L^b F^c$
 - Hasenkamp 1976:

$$\left[b_1 (q_1)^r + b_2 (q_2)^r \right]^{s/r} = \left(a_1 K^t + a_2 L^t + a_3 F^t \right)^{u/t}$$

- q_1, q_2 - passenger-miles, freight ton-miles
- K, L, F - capital input, labor, fuel respectively
- Constant elasticity of marginal rate of substitution among inputs
- Constant elasticity of transformation among outputs

Production Transformation Curve

- Convex shape: economies of specialization
- Firm can produce a relatively large amount of one (passenger or freight) service or a limited amount of both.
- Conforms with industry trends



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- Basic Concepts
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- **Profit maximization and cost minimization**
- Average and marginal costs

Profit Maximization

- Joint choice of input and production levels
 - For a single product:

$$\left. \begin{array}{l} \max_x \pi = pq - WX \\ s.t. \quad q = q(X) \end{array} \right\} \Rightarrow \max_x pq(X) - WX$$

- W – input prices
 - p – output price
- Assume W and p are fixed

The Competitive Firm

- Price taker does not influence input and output prices
- Applies when:
 - Large number of selling firms
 - Identical products
 - Well informed customers

Optimal Production

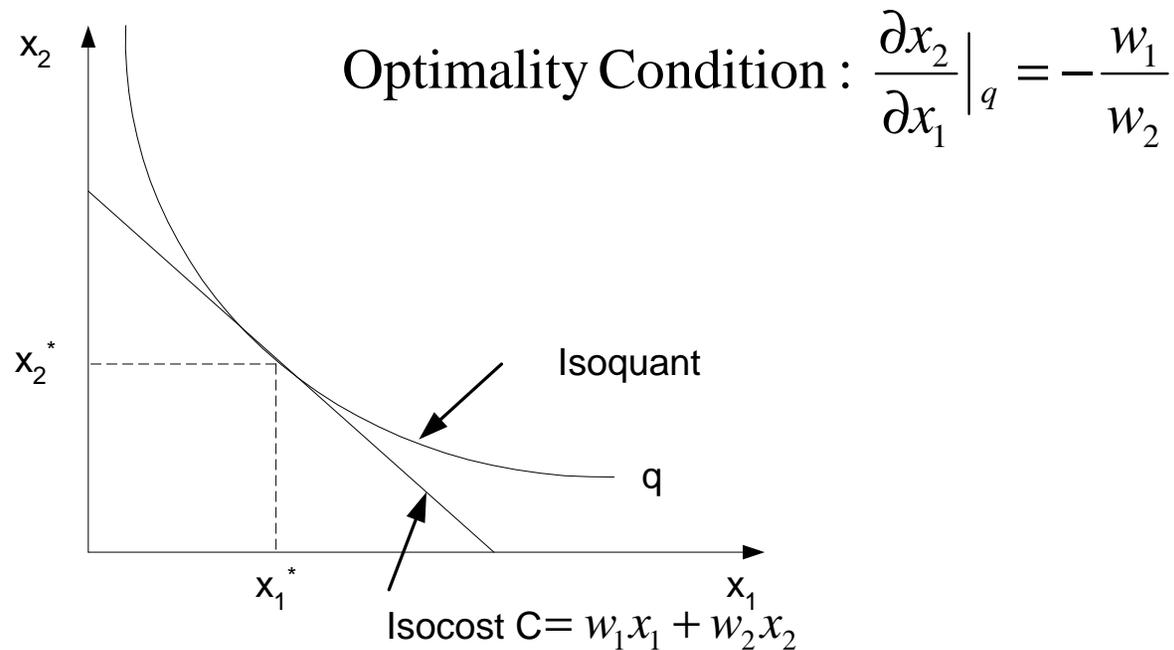
- At the optimum:

$$\underbrace{p \frac{\partial q(X^*)}{\partial x_i}}_{\text{marginal revenue from input unit}} = \underbrace{w_i}_{\text{marginal cost}} \quad \forall i$$

- Marginal revenue = Marginal cost
 - If marginal cost is lower, the firm would profit from using 1 extra unit of input i .
 - If marginal cost is higher, the firm would profit from using 1 less unit of input i .

Cost Minimization

- Given input prices and a required level of production, the firm chooses amounts of inputs that will minimize its cost



Mathematical Formulation for Cost Minimization

$$\begin{aligned} \min_x C &= WX \\ \text{s.t. } q(X) &= q \end{aligned}$$

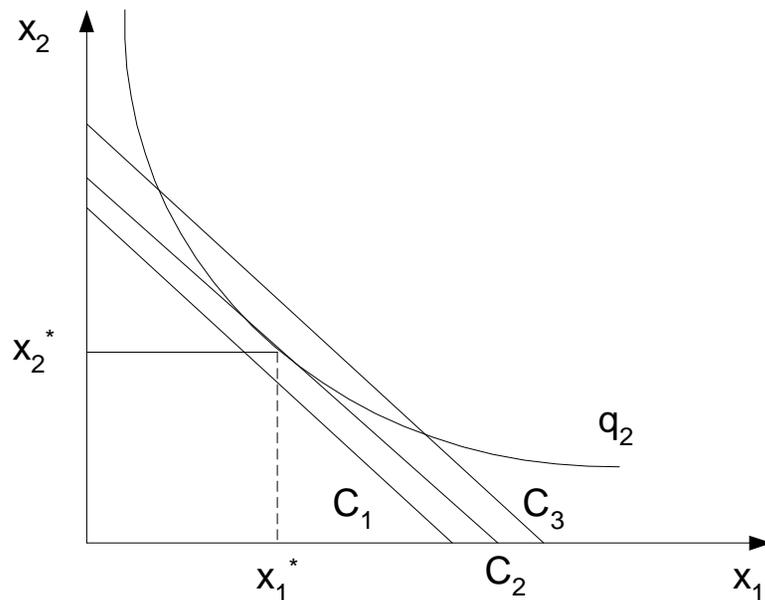
- Solution: $X^* = X(W, q)$ defined as the conditional factor demand function
- Substitute in and obtain the cost function:
 $C = WX^* = C(W, q)$

Dual Views of the Same Problem

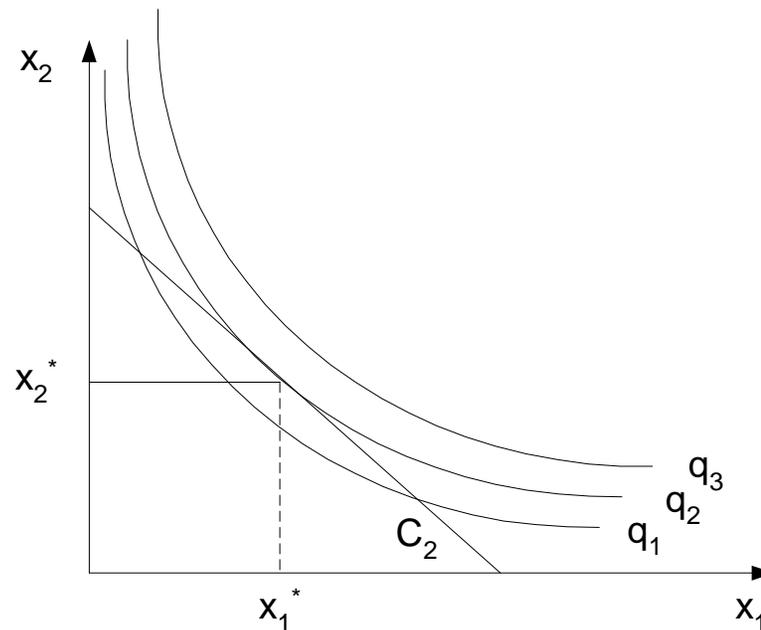
- Production problem: maximize production given level of cost
- Cost problem: minimize cost given a desired level of production.

Cost and Production Duality

Minimizing cost for a given level of production



Maximizing production level for a given level of cost



Deriving Cost Functions from Production Functions: Example

- Production function: $q = \alpha x_1^a x_2^b$
- Cost minimization problem:

$$\left. \begin{array}{l} C(w, q) = \min w_1 x_1 + w_2 x_2 \\ s.t. \quad \alpha x_1^a x_2^b = q \end{array} \right\} \Rightarrow \min w_1 x_1 + w_2 \alpha^{-1/b} q^{1/b} x_1^{-a/b}$$

- First order conditions:

$$w_1 - \frac{a}{b} w_2 \alpha^{-1/b} q^{1/b} x_1^{-(a+b)/b} = 0$$

Example (cont)

- Conditional demand function for input 1:

$$x_1(w_1, w_2, q) = \alpha^{-1/a+b} \left[\frac{aw_2}{bw_1} \right]^{b/a+b} q^{1/a+b}$$

- Conditional demand function for input 2:

$$x_2(w_1, w_2, q) = \alpha^{-1/a+b} \left[\frac{aw_2}{bw_1} \right]^{-a/a+b} q^{1/a+b}$$

- Cost function:

$$\begin{aligned} C(w_1, w_2, q) &= w_1 x_1(w_1, w_2, q) + w_2 x_2(w_1, w_2, q) \\ &= \alpha^{-1/a+b} \left[\left(\frac{a}{b} \right)^{b/a+b} + \left(\frac{a}{b} \right)^{-a/a+b} \right] w_1^{a/a+b} w_2^{b/a+b} q^{1/a+b} \end{aligned}$$

Example: TL vs. LTL Carriers

Truckload (TL) Carriers

| | Labor | Capital | Fuel | Purchased Transportation |
|-----------------------------------|--------|---------|--------|--------------------------|
| Own-Price Elasticity | -0.566 | -0.683 | -0.582 | -1.920 |
| <i>Elasticity of Substitution</i> | | | | |
| Labor | | 0.590 | 0.177 | 2.300 |
| Capital | 0.590 | | 0.514 | 2.190 |
| Fuel | 0.177 | 0.514 | | 2.780 |
| Purchased Transportation | 2.300 | 2.190 | 2.780 | |

Less-Than-Truckload (LTL) Carriers

| | Labor | Capital | Fuel | Purchased Transportation |
|-----------------------------------|--------|---------|--------|--------------------------|
| Own-Price Elasticity | -0.372 | -0.762 | -0.724 | -0.973 |
| <i>Elasticity of Substitution</i> | | | | |
| Labor | | 0.968 | 0.766 | 0.947 |
| Capital | 0.968 | | 0.762 | 1.440 |
| Fuel | 0.766 | 0.762 | | 0.856 |
| Purchased Transportation | 0.947 | 1.440 | 0.856 | |

1988 and 1990 Case Studies in:
 McCarthy, P. *Transportation Economics: Theory and Practice: A Case Study Approach.*
 Blackwell Publishers, 2001

- LTL has more reliance on purchased transport
- LTL has greater substitution between factors (eg. Replace warehouse workers with logistics systems)



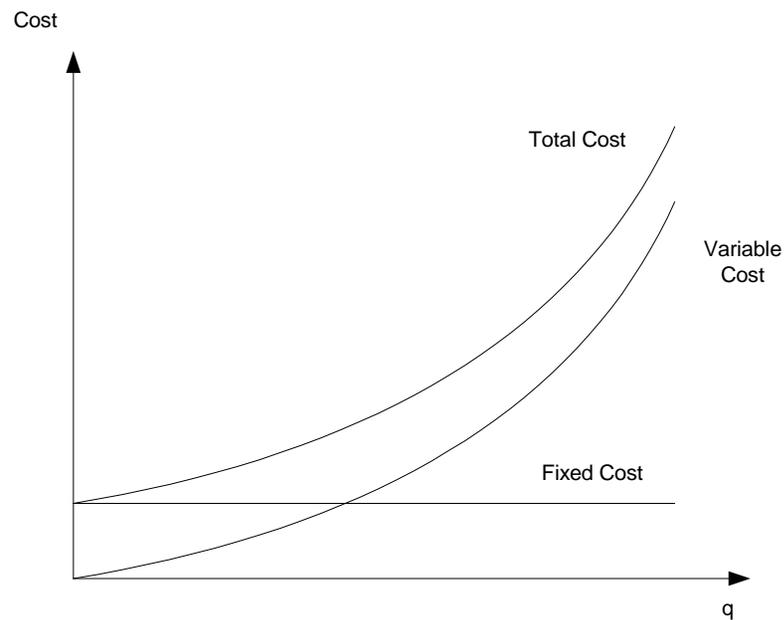
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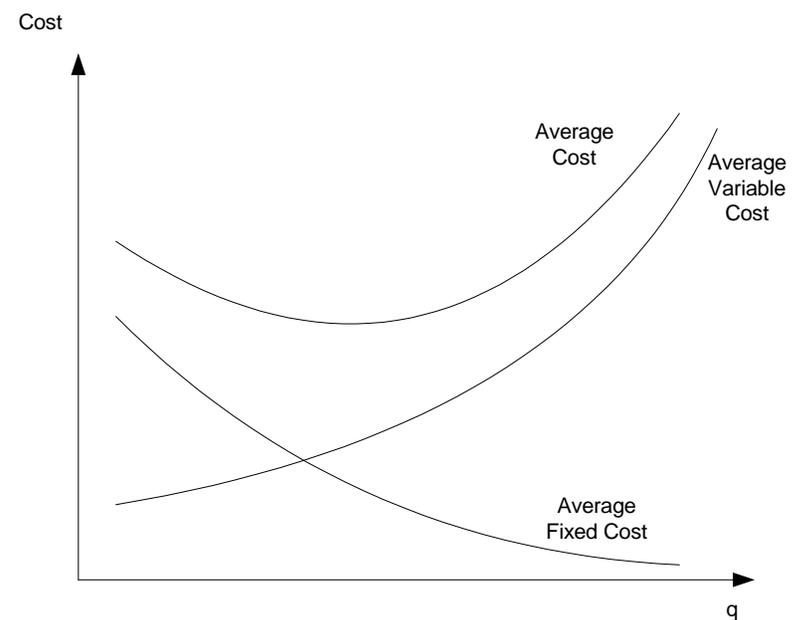
Average and Marginal Costs

- Total cost: $C(q) = WX(W, q)$
- Average cost: $AC(q) = \frac{C(q)}{q}$
- Marginal cost: $MC(q) = \frac{\partial C(q)}{\partial q}$

Geometry of Cost Functions



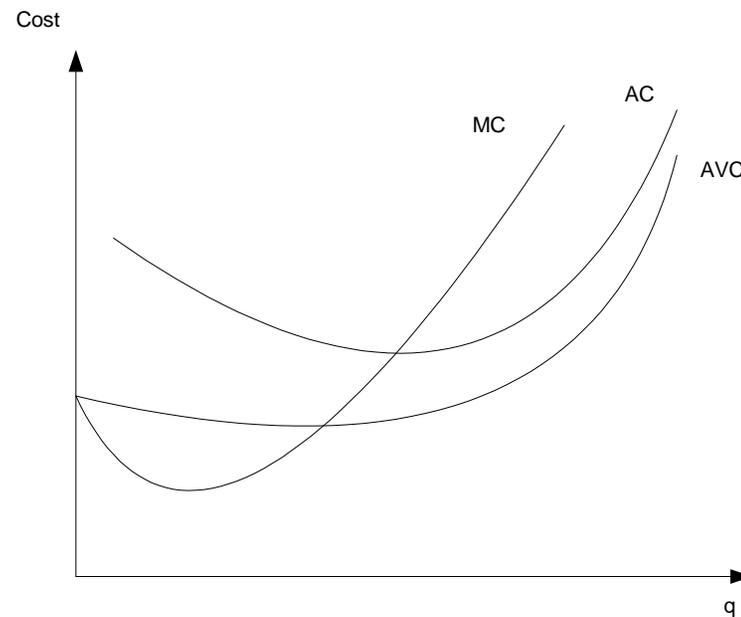
Total Cost



Average Cost

Geometry of Cost Functions

- $AC = MC$ at min AC point
- $AVC = MC$ at min AVC point



Examples of Marginal Costs

- One additional passenger on a plane with empty seats
 - One extra meal
 - Extra terminal processing time
 - Potential delays to other passengers
- 100 additional passengers/day to an air shuttle service
 - The costs above
 - Extra flights
 - Additional ground personnel

Using Average and Marginal Costs

- Profitability/Subsidy Requirements
 - Compare average cost and average revenue
- Profitability of a particular trip
 - Compare marginal cost and marginal revenue
- Economic efficiency
 - Price = MC
- Regulation
 - Declining average cost

Summary

- Basic Concepts
- Production functions
 - Isoquants
 - Rate of technical substitution
- Profit maximization and cost minimization
 - Dual views of the same problem
- Average and marginal costs

Next lecture... Transportation costs



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