

# Lecture 19 - summary

Displacement vector

$$\vec{\xi} = \vec{\xi}^0 + \vec{\xi}^S$$

Strain tensor

$$\underline{\underline{\varepsilon}} = \underline{\underline{\varepsilon}}^0 + \underline{\underline{\varepsilon}}^S$$

Decomposition into beam reference axis and section

From displacement in beam reference axis,  $\vec{\xi}^0(x)$ :

$$\epsilon_{xx}^0 = \frac{\partial \xi_x^0}{\partial x}; \quad \epsilon_{xy}^0 = \frac{1}{2} \frac{\partial \xi_y^0}{\partial x}; \quad \epsilon_{xz}^0 = \frac{1}{2} \frac{\partial \xi_z^0}{\partial x}$$

**Navier-Bernoulli assumption (N-B):**

*An initially plane beam section which is perpendicular to the beam reference axis remains plane throughout the beam deformation and perpendicular to the beam's axis in the deformed configuration.*

1<sup>st</sup> consequence

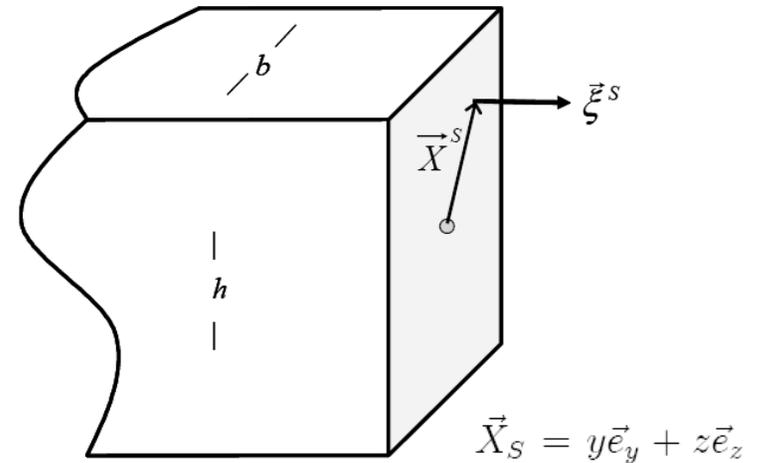
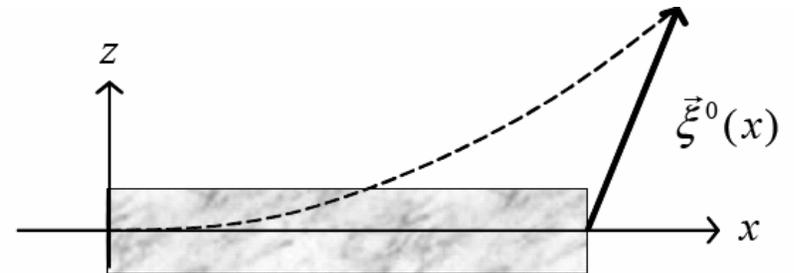
(section remains plane):

$$\vec{\xi}^S = \vec{\omega}(x) \times \vec{X}_S(y, z)$$

2<sup>nd</sup> consequence:

(remains perpendicular)

$$\omega_z = 2\epsilon_{xy}^0 = \frac{\partial \xi_y^0}{\partial x}; \quad -\omega_y = 2\epsilon_{xz}^0 = \frac{\partial \xi_z^0}{\partial x}$$



**Therefore:** From knowledge of  $\vec{\xi}$  can calculate displacements and strain tensor!

**Total displacement and strain tensor coefficients:**

$$\vec{\xi} = \vec{\xi}^0 + \vec{\omega}(x) \times \vec{X}_S(y, z) \quad \epsilon_{xx} = \epsilon_{xx}^0 + \omega'_y z - \omega'_z y \quad \epsilon_{xy} = \epsilon_{xy}^0 - \frac{1}{2} \omega'_z - \frac{1}{2} \omega'_x z \quad \epsilon_{xz} = \epsilon_{xz}^0 + \frac{1}{2} \omega'_y + \frac{1}{2} \omega'_x y$$