

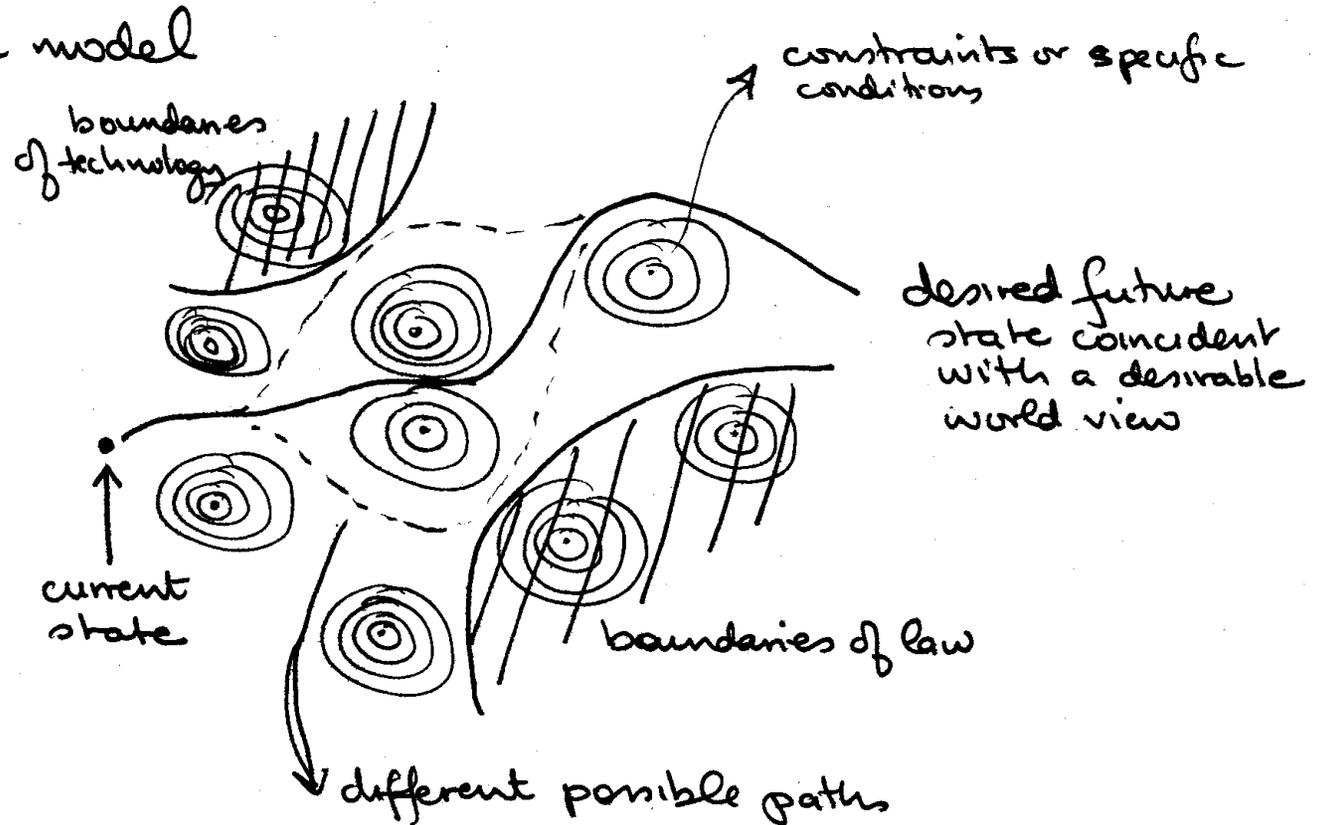
Policy Choices on Space Systems

Definition of Policy

- **Policy**
- “ A definite course or method of action selected from among alternatives and in light of given conditions to guide and determine present and future directions.”
- Thus policy statements can be parsed in the following way
- Policy statements have several features associated with them:
 - definite course(s)
 - selected from alternatives
 - true in light of specific conditions → a model of the world
 - to move one in specific (desired) directions → a model of the world

Definition of Policy

• A simple model



Heuristics

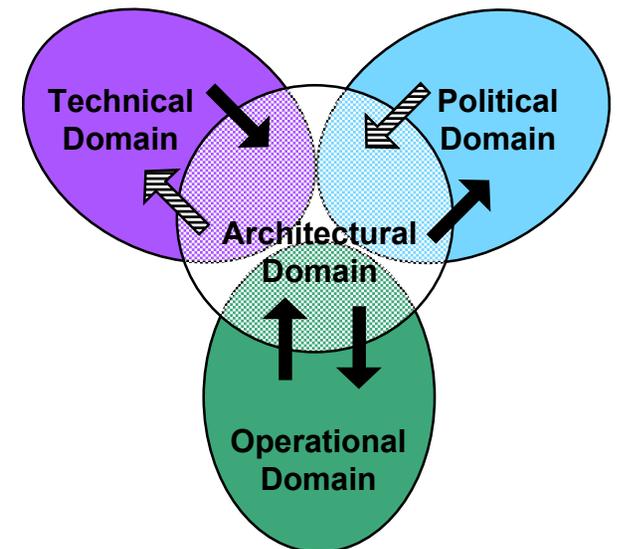
Forman's Heuristic #1: *If the politics don't fly, the system never will.*

Forman's Heuristic #2: *Politics, not technology, sets the limits of what technology is allowed to achieve.*

Forman's Heuristic #3: *A strong, coherent constituency is essential.*

Forman's Heuristic #4: *Technical problems become political problems; there is no such thing as a purely technical problem.*

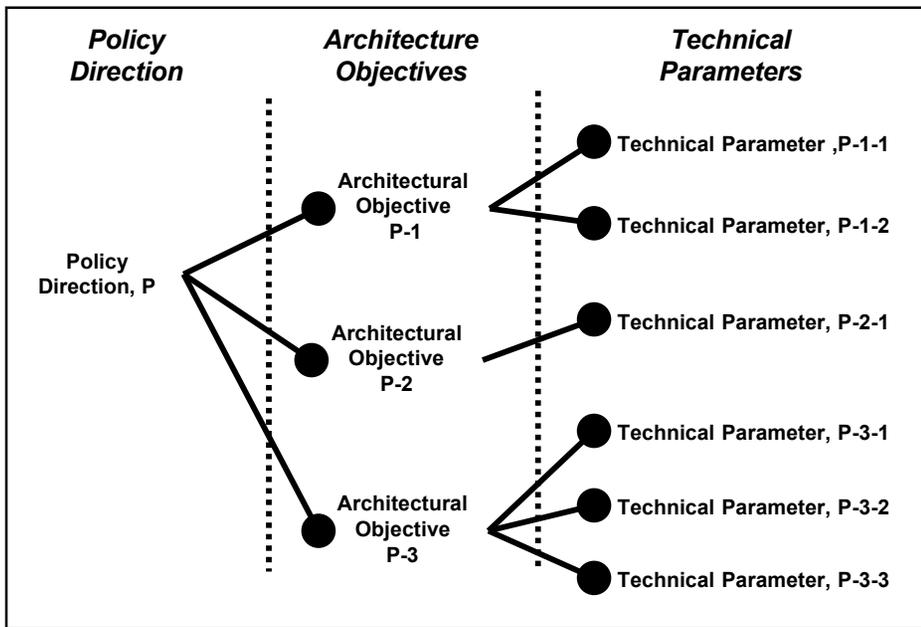
Forman's Heuristic #5: *With few exceptions, schedule delays are accepted grudgingly; cost overruns are not.*



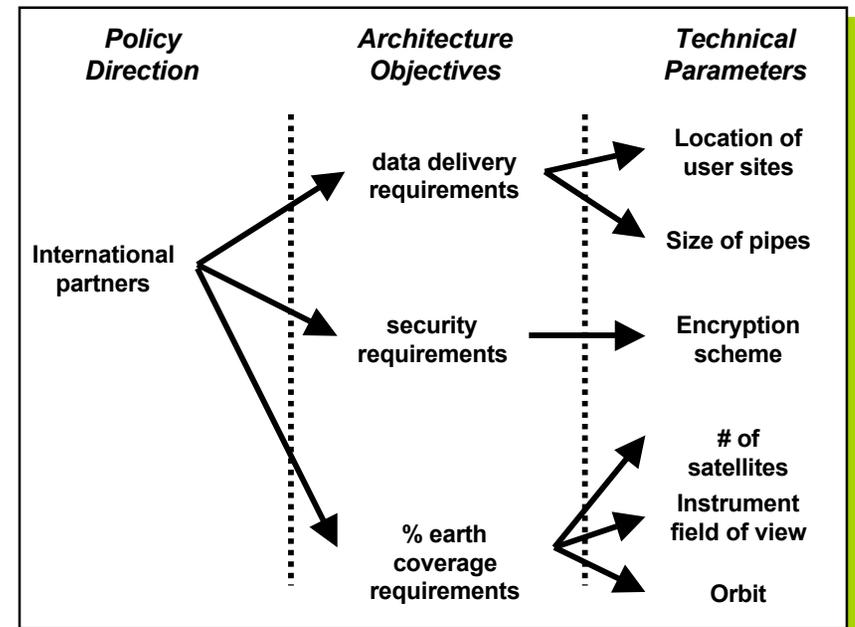
Policy Impact on System Architecture

- Understand policy impacts at early (architecture) stages
- Framework shows flowdown to technical domain

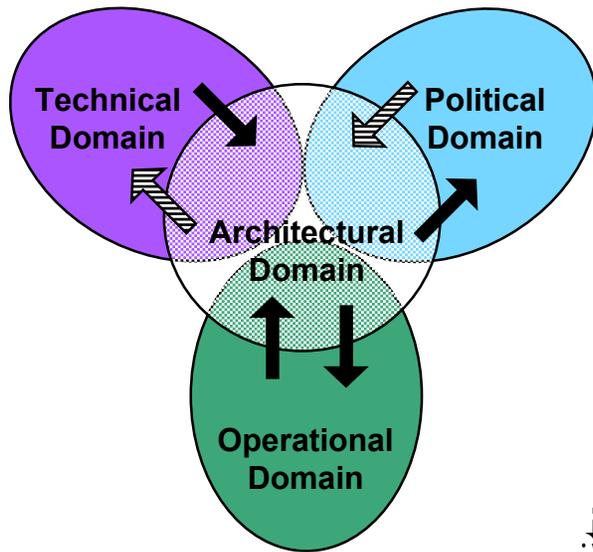
Generic Flow of Policy Impacts into Technical Domain



**Discoverer II Example
(Space-based GMTI mission)**

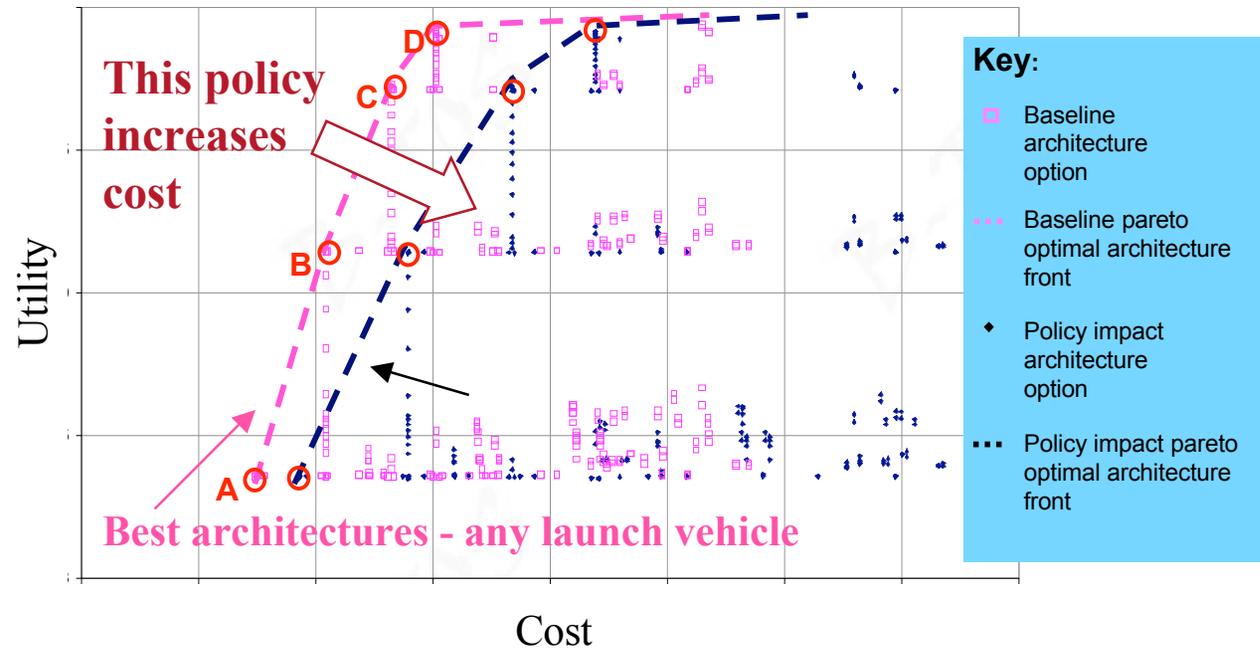


Policy Impact on System Architecture



Space System Architecting “Domain Framework” Schematic

Cost of US Launch Policy: B-TOS Case Study Using Min Cost Rule

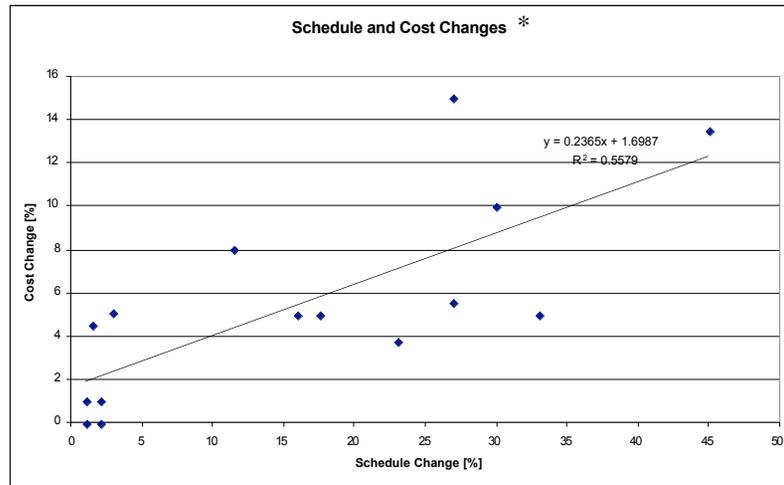


Results from US Launch Policy Impact Modeling

Discussions with senior officials indicate most common policy intervention is budget adjustment

Cost-capping policy intervention

- Cost-capping government program expenditures is **most frequently reported** government policy intervention
 - Annual program budget capped by Congress
 - Capping stretches out program duration and increases total program costs as a result
- Historical examples provide basis for relationship between schedule extension and cost growth



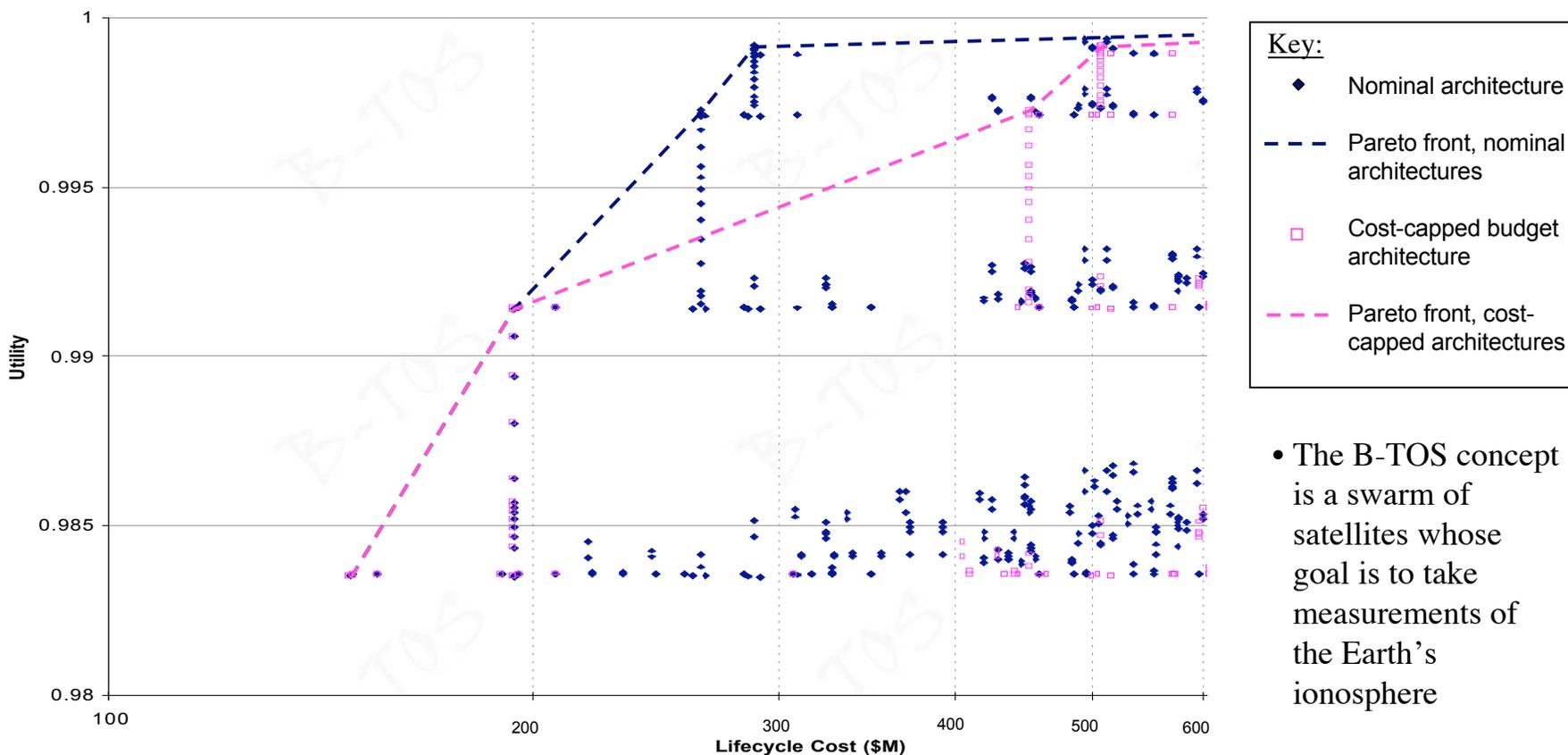
Schedule extension and resulting cost change relationship:

$$c = 0.24s + 1.7$$

where c = % cost change,
and s = % schedule change

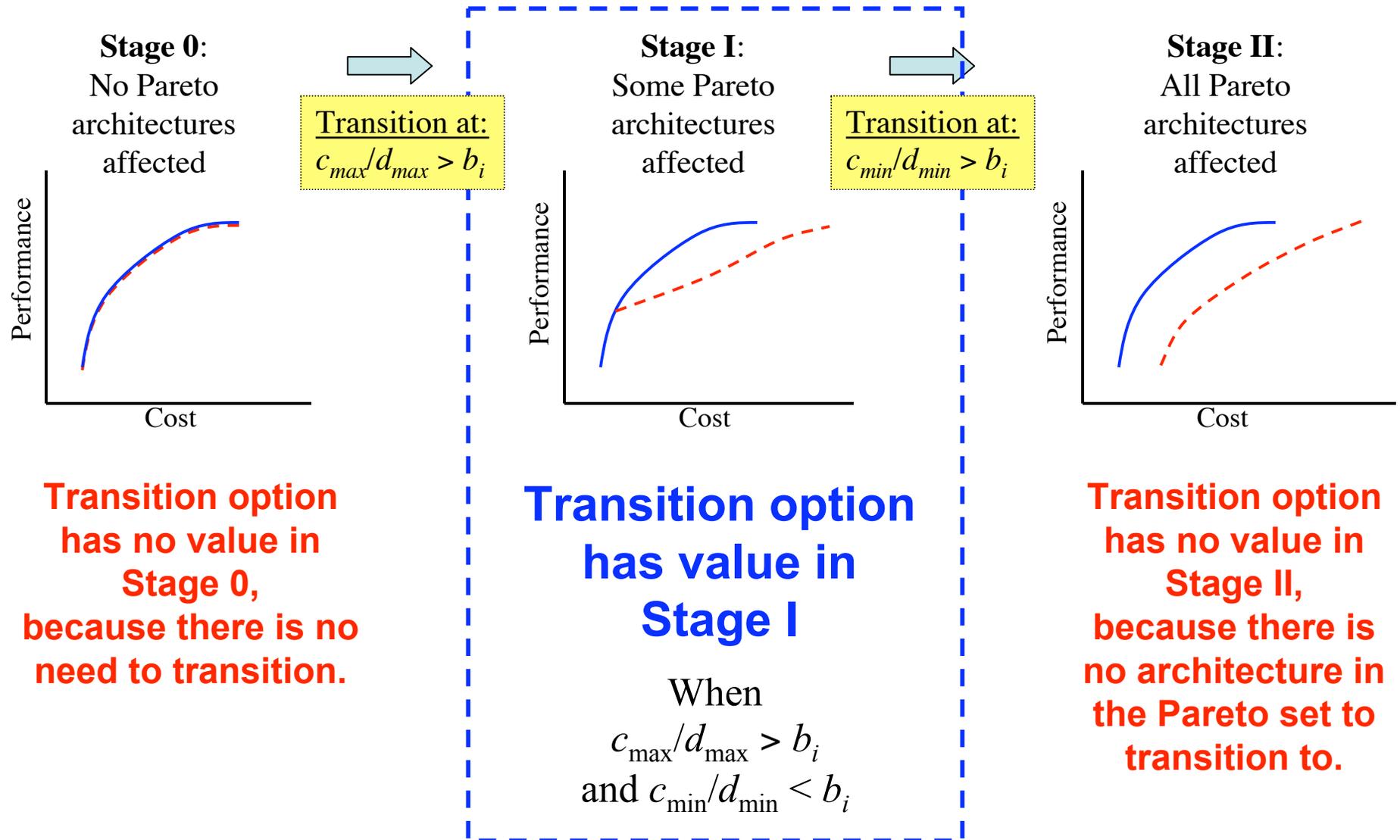
Cost-capping on B-TOS architecture study

Policy Intervention: \$35M annual program budget cap imposed by Congress

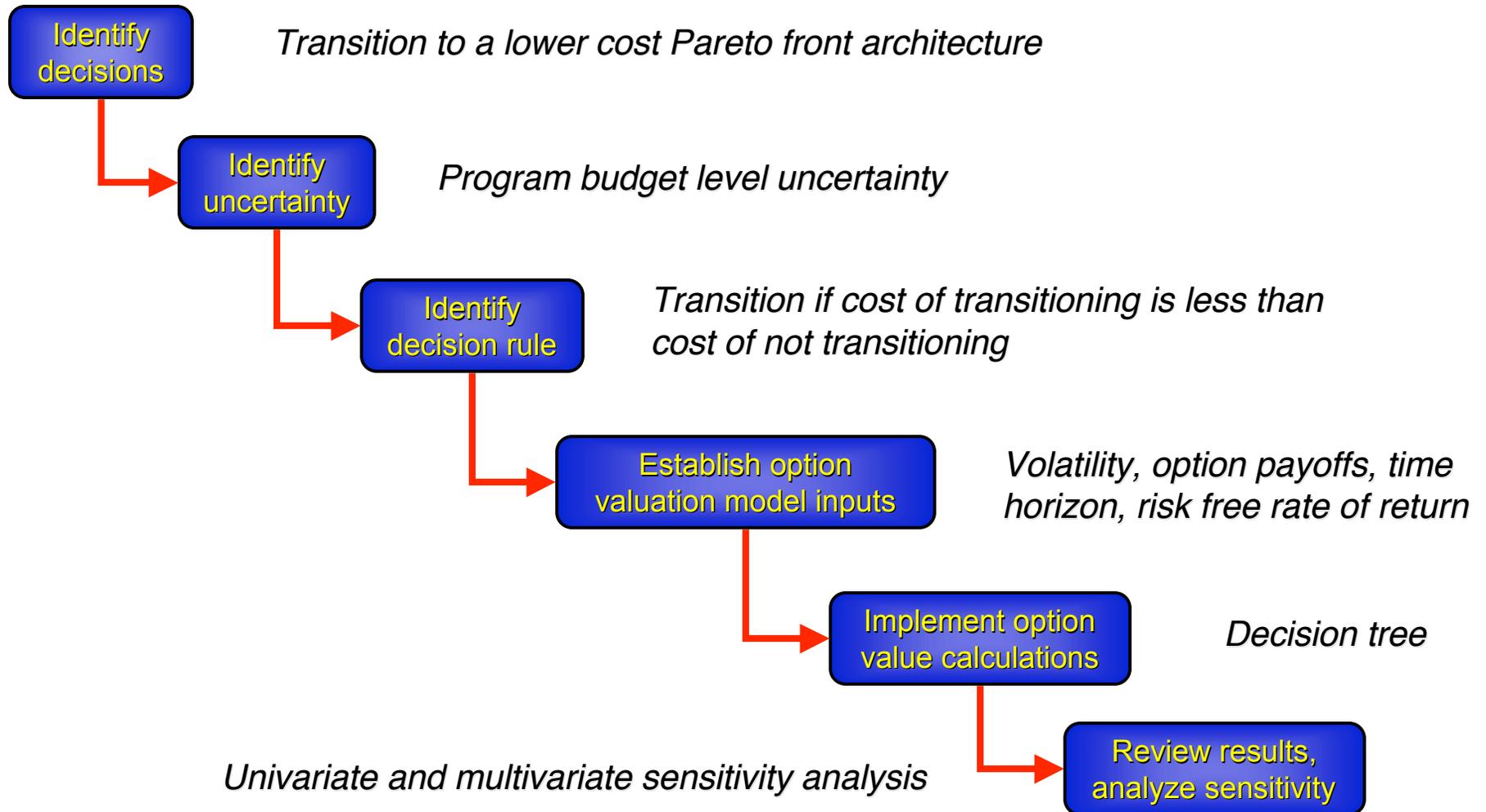


Cost-capping policy pushes architecture tradespace pareto front to the right

Boundary of Option Value



Steps in Real Options Analysis



Designing for Budget Policy

Goal of analysis: Use real options analysis to measure value of designing architecture to accommodate budget policy instability

- Scenario
 - Future budget levels are uncertain
 - Pursue initial architecture choice
 - When budget is cut, program manager may want to transition to a new, lower budget architecture
- What is the **value of a transition architecture option**, which provides insurance against budget policy instability and makes a program more **policy robust**?
- Real options useful for valuing projects under uncertainty

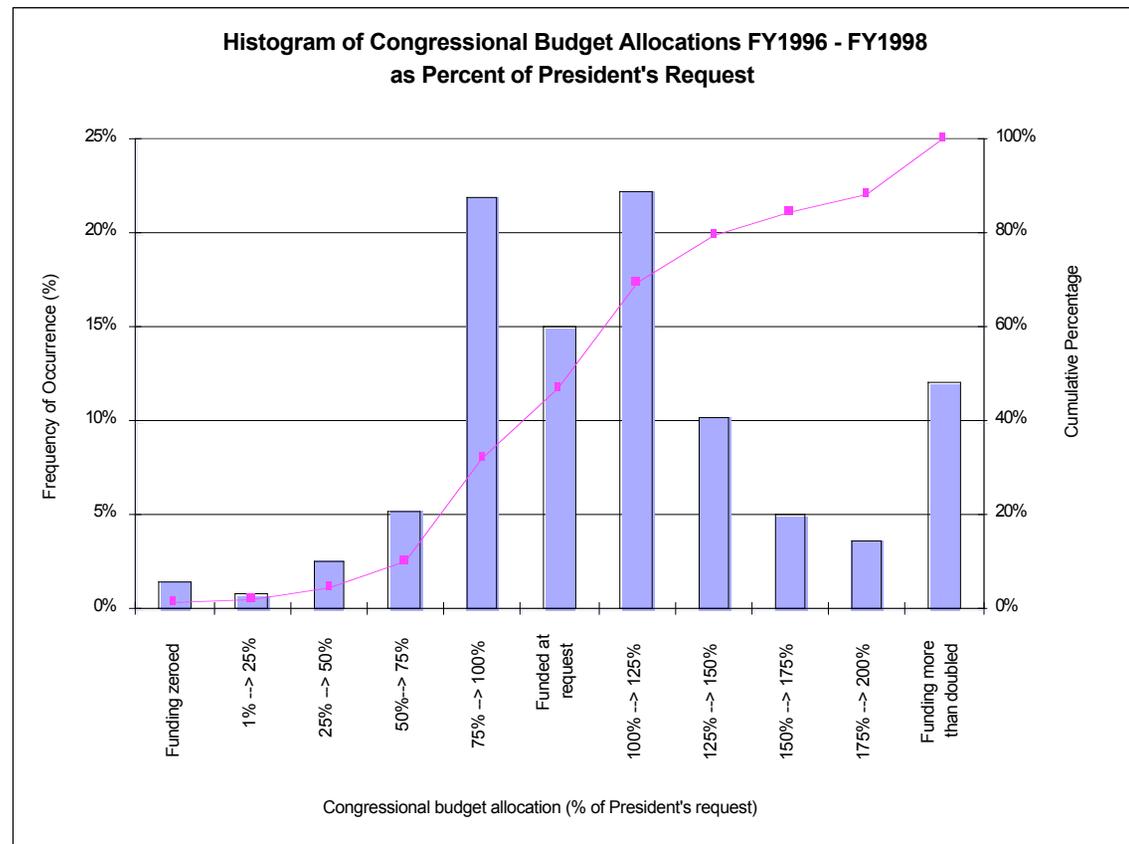
Measuring Volatility

Use **historical** DoD budget reduction data for basis of **volatility** (FY1996-98)

Insights:

- 15% probability get requested budget
- 53% probability get increase
- 32% probability get budget cut

Degree of budget cut follows exponential distribution with $\lambda = 4.65$



B-TOS Transition Option: investing in upfront work on “fallback” system

- Expectation of maximum transition option value calculated with the following assumptions:
 - Five B-TOS Pareto frontier architectures are the architecture set
 - Risk free rate of return, $r = 5\%$ Time to exercise option, $t = 3$ years
 - Volatility of budget cuts follows exponential approximation of historical observed budget cuts with $\lambda = 4.65$, and $1/\lambda = p_c = 0.32$

$$\text{Expectation of maximum transition option value} = p_c * \Delta c_x / e^{-rt}$$
$$\text{where } \Delta c = c_i [0.24(c_i/b_i d_i - 1) + .017]$$

| Expectation of maximum transition option value: | in \$M | As % of spacecraft budget |
|---|--------|---------------------------|
| For Architecture E | 7.4 | 3.1% |
| For Architecture D | 3.9 | 3.1% |
| For Architecture C | 3.4 | 3.1% |
| For Architecture B | 2.6 | 3.1% |
| For Architecture A | 0 | 0% |

By historical averages, a B-TOS transition option will have an expected value of 3% of total spacecraft budget