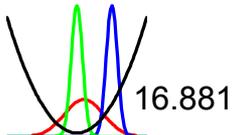


# Control and noise factors

Don Clausing

Red border: emphasized slides



# The engineered system

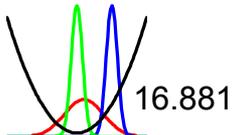
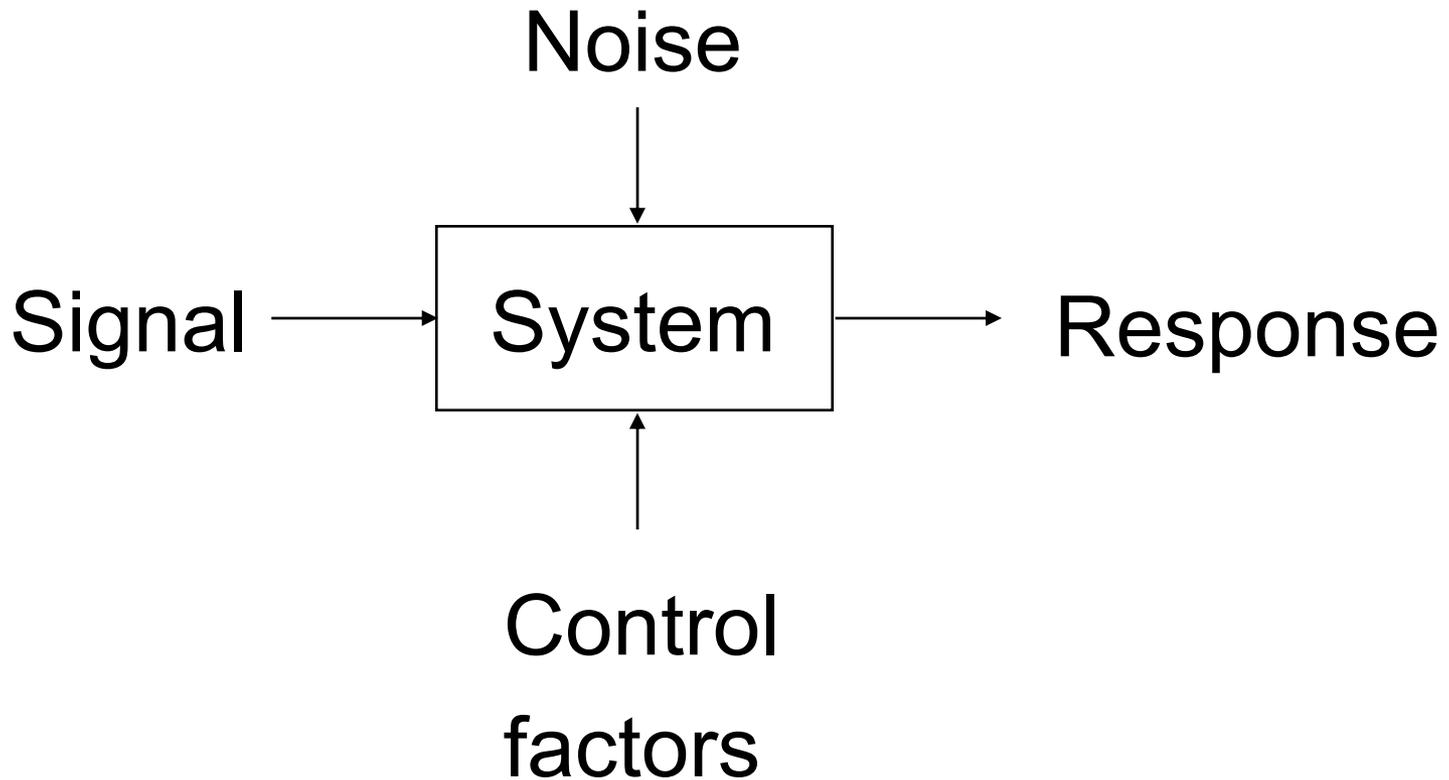


Fig. 2

# Ideal response

- Want Ideal Response to Signal – usually straight-line function
- Actual response is determined by values of control factors and noise factors
- If noise factors are suppressed early, then difficult problems only appear late
- Introduce noises early!

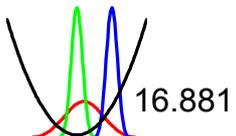


Fig. 3

# Actual response

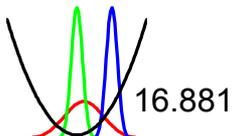
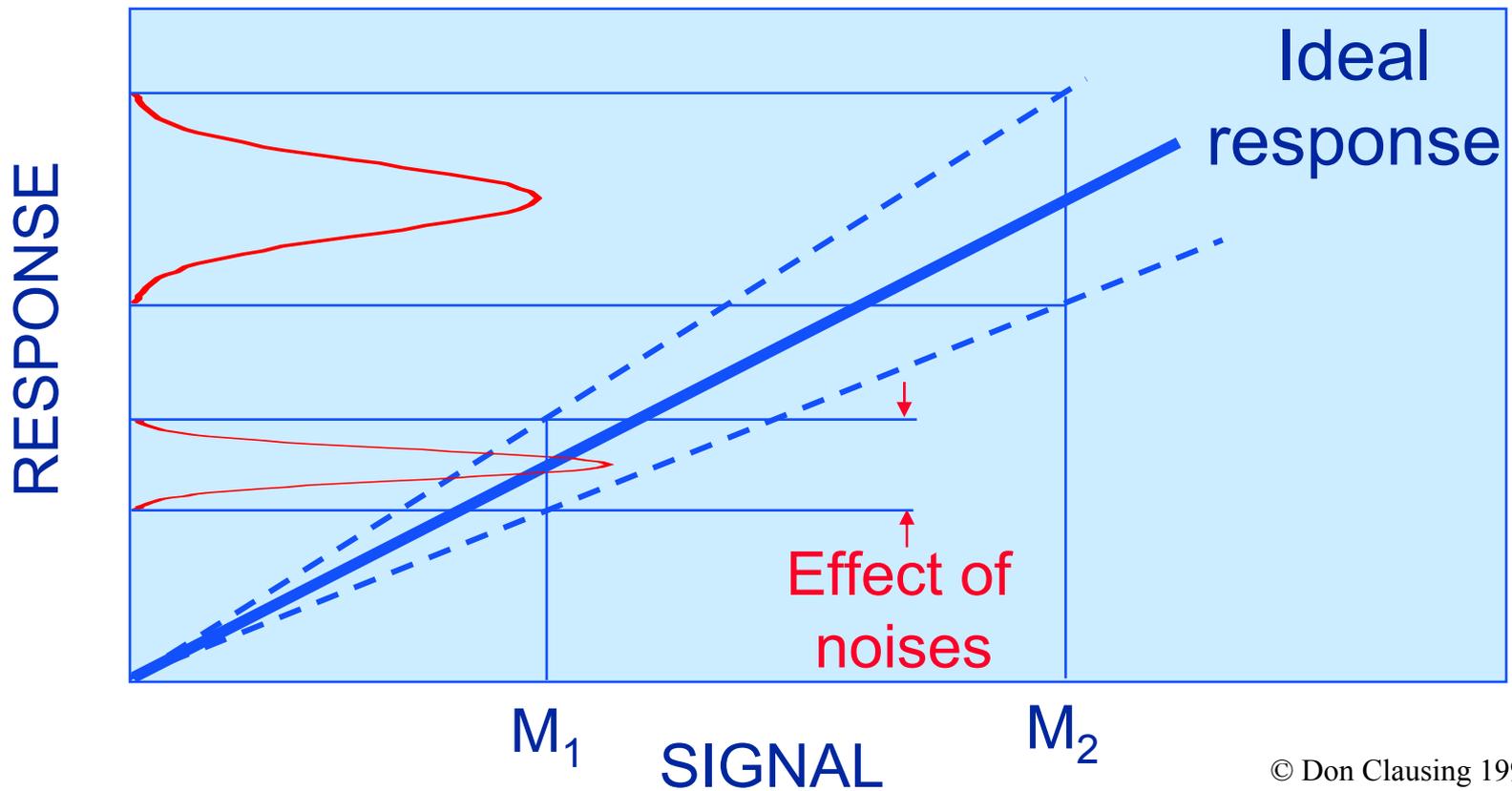


Fig. 4

# Response depends on:

- Value of signal factor
- Values of control factors
  - Engineers can select values
  - Examples: dimensions, electrical characteristics
- Values of noise factors
  - Engineers cannot select values
  - Examples: temperature, part variations

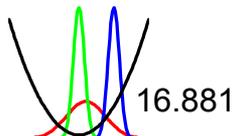


Fig. 5

# Critical control parameters

- Strongly affect performance of the system
- IPDT can control (select) the value
- Complex systems have hundreds of critical control parameters
- Fault trees help IPDT to identify

Note: IPDT is Integrated Product Development Team

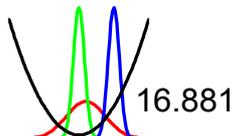
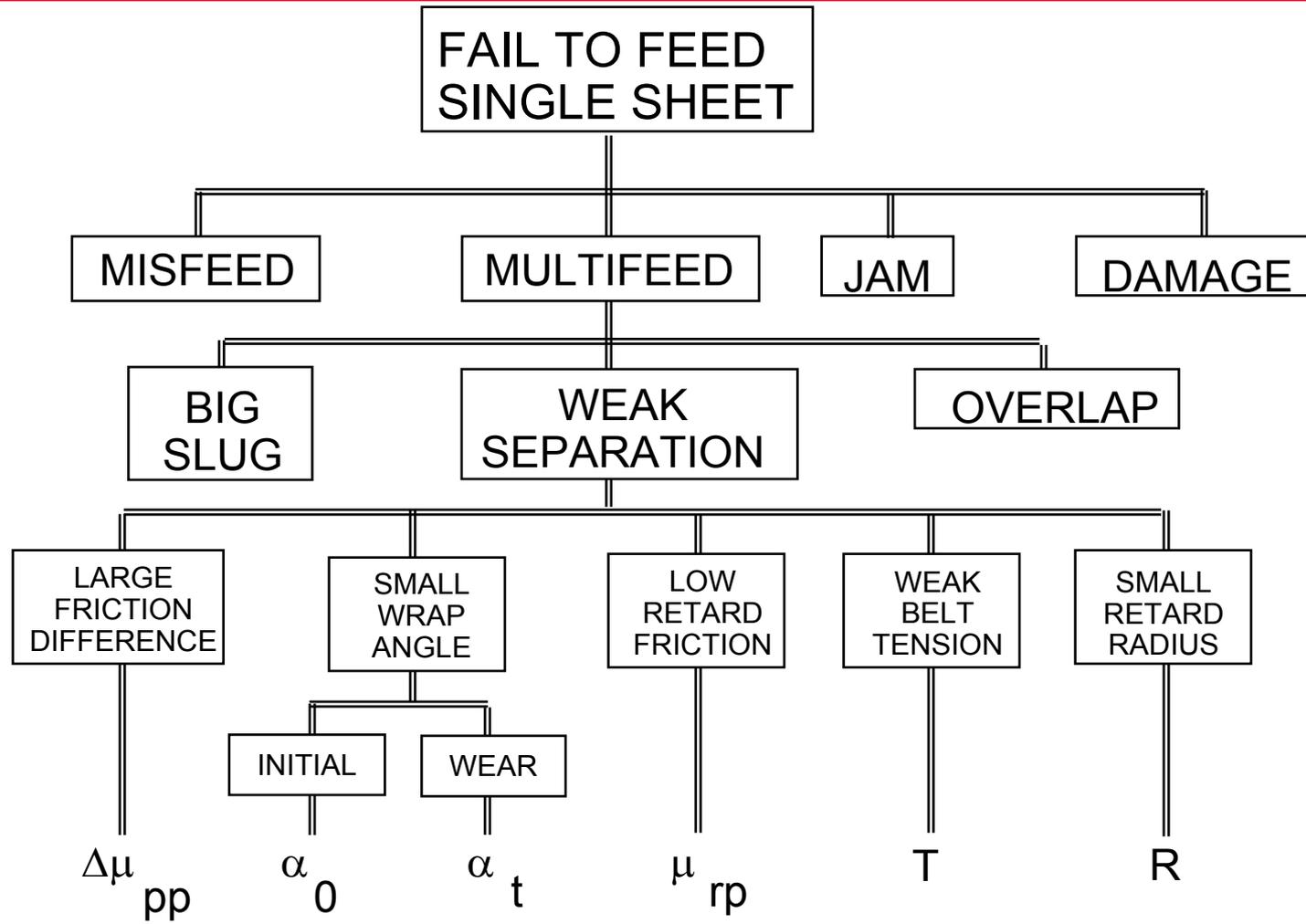


Fig. 6

# Fault tree for paper feeder



Identification of critical parameters – both control and noise

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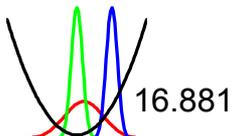
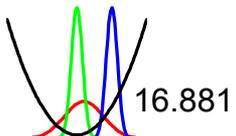


Fig. 7

# Critical parameters at base of tree

- Both control and noise parameters
- Example of control factors:
  - Roll radius
  - Belt tension
- Example of noise factor: paper-to-paper friction,  $\mu_{p-p}$



# Noises

- Affect performance – adversely
- IPDT cannot control – examples:
  - Ambient temperature
  - Power-company voltage
  - Customer-supplied consumables
- IPDT must apply large magnitudes of noise early in the development schedule

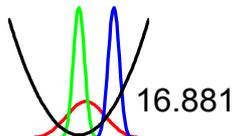
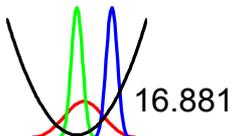


Fig. 9

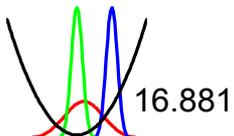
# Role of control factors

- Values of control factors determine response
- Many combinations of control-factors values will give same value for response
- One of these combinations will give the least sensitivity to undesirable variations (noises)
- Improvement is achieved by searching through the combinations of control-factors values to find the one that gives best performance



# Important steps in parameter design

- Define ideal performance
- Select best SN definition
- Identify critical parameters
- Develop sets of noises that will cause performance to deviate from ideal
- Use designed experiments to systematically optimize control parameters



# Three kinds of product noise

- Environment; e.g., ambient temperature
- Manufacturing – no two units of production are exactly alike
- Deterioration – causes further variations in the components of the system

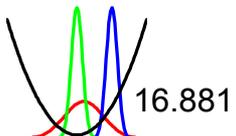
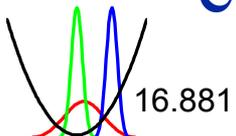


Fig. 12

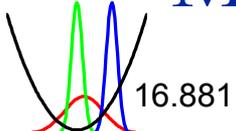
# Searching for robustness

1. Select one combination of control-factors values
2. Test performance when a set of noise values are applied:  $y_1, y_2 \dots y_n$  are performance values for  $n$  combinations of noise
3. Change values of control factors; repeat 2.
4. Search through control-factor space, testing each point with same set of noises



# Introduction of noises

- Natural noises are often small in laboratory environment; therefore slow to learn effect
- Therefore we consciously introduce large magnitudes of noises to obtain quick evaluation of effect of noises
- Example: (1) high temperature, high humidity, (2) low temperature, low humidity
- Measure  $y_1$  and  $y_2$



# Effect of noises, 1 & 2

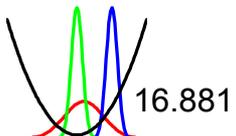
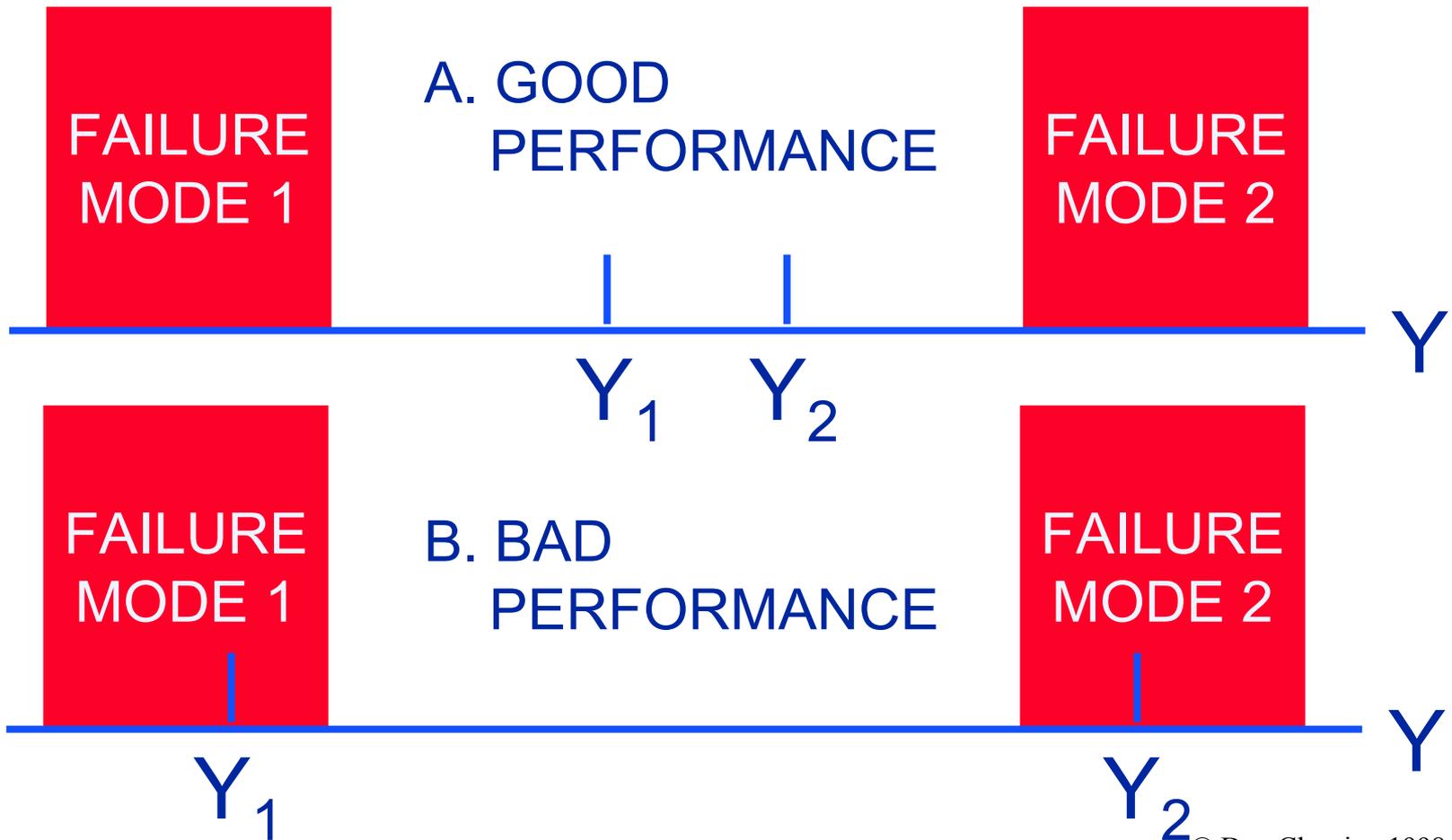


Fig. 15

# Understanding performance

- Case A: Is good performance due to:
  - Good system?
  - Small magnitude of noises?
- Winning approach:
  - Apply large magnitudes of noises 1 & 2 to create Case B
  - Then improve values of control factors;  $B \gg A$
  - Increase noises; repeat improvement,  $B \gg A$

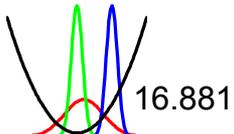
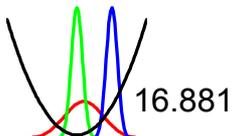


Fig. 16

# Path to success

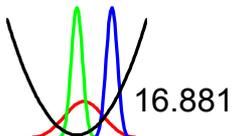
	CONTROL FACTOR SET	NOISE 1	$Y_1$	NOISE 2	$Y_2$	$Y_2 - Y_1$
1	CF SET 1	MODERATE	5	MODERATE	25	20
2	CF SET 2	MODERATE	14	MODERATE	16	2
3	CF SET 2	STRONG	8	STRONG	22	14
4	CF SET 3	STRONG	14	STRONG	16	2

IMPROVEMENT PATH: CF1 ~~↔~~ CF2 ~~↔~~ CF3



# Noises and failure modes

- Apply one noise,  $N_i$ , for each failure mode
- Example: combination of resistances, capacitances, transistor characteristics, and temperature have strong effect on performance
  - Adjust values,  $N_1$ , to cause low voltage out,  $Y_1$
  - Adjust values,  $N_2$ , to cause high voltage out,  $Y_2$
- Then optimize control factors; minimize  $Y_2 - Y_1$



# Fundamental noise situation

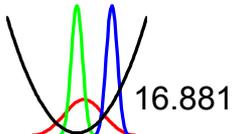
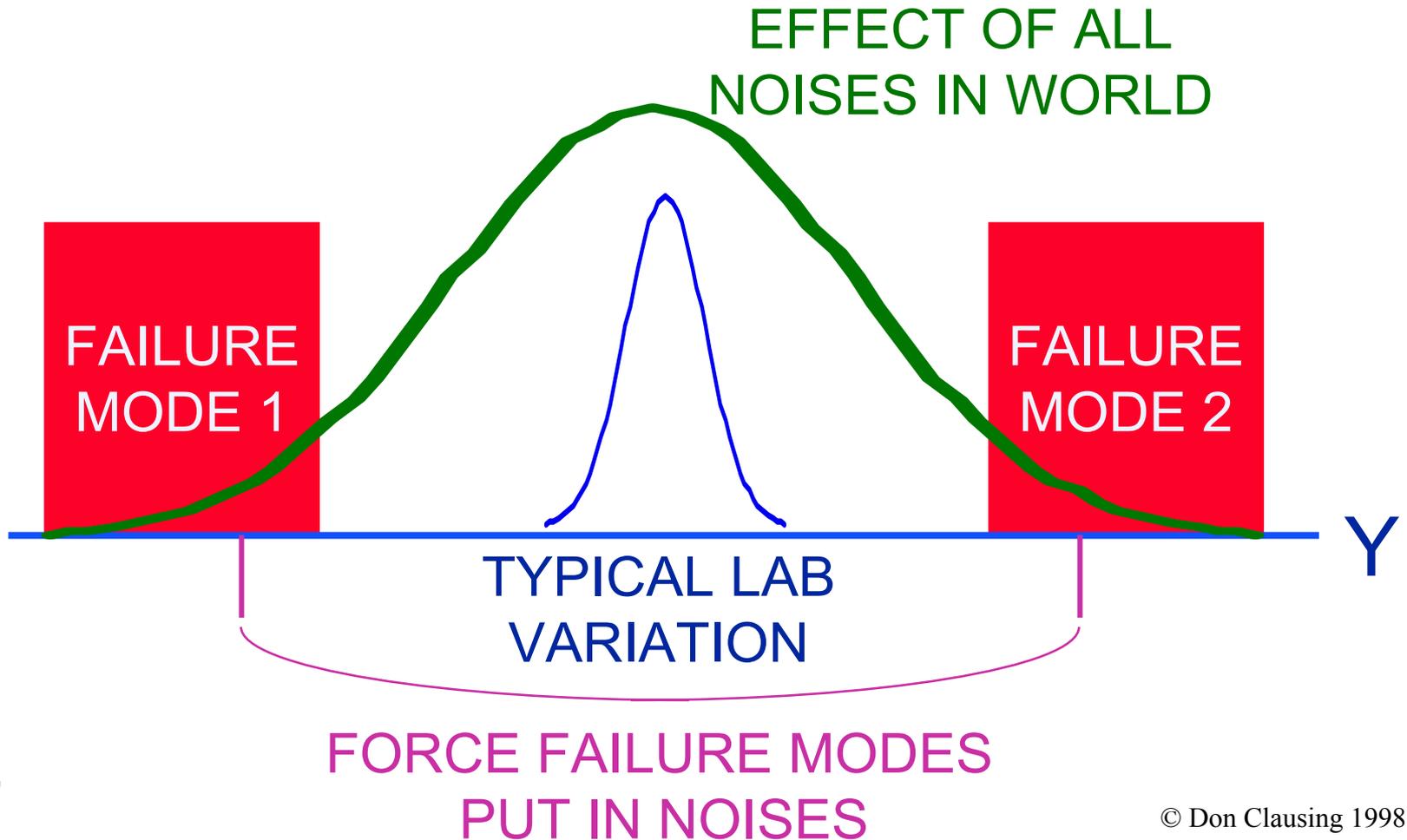
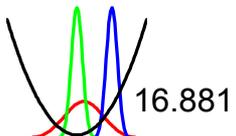
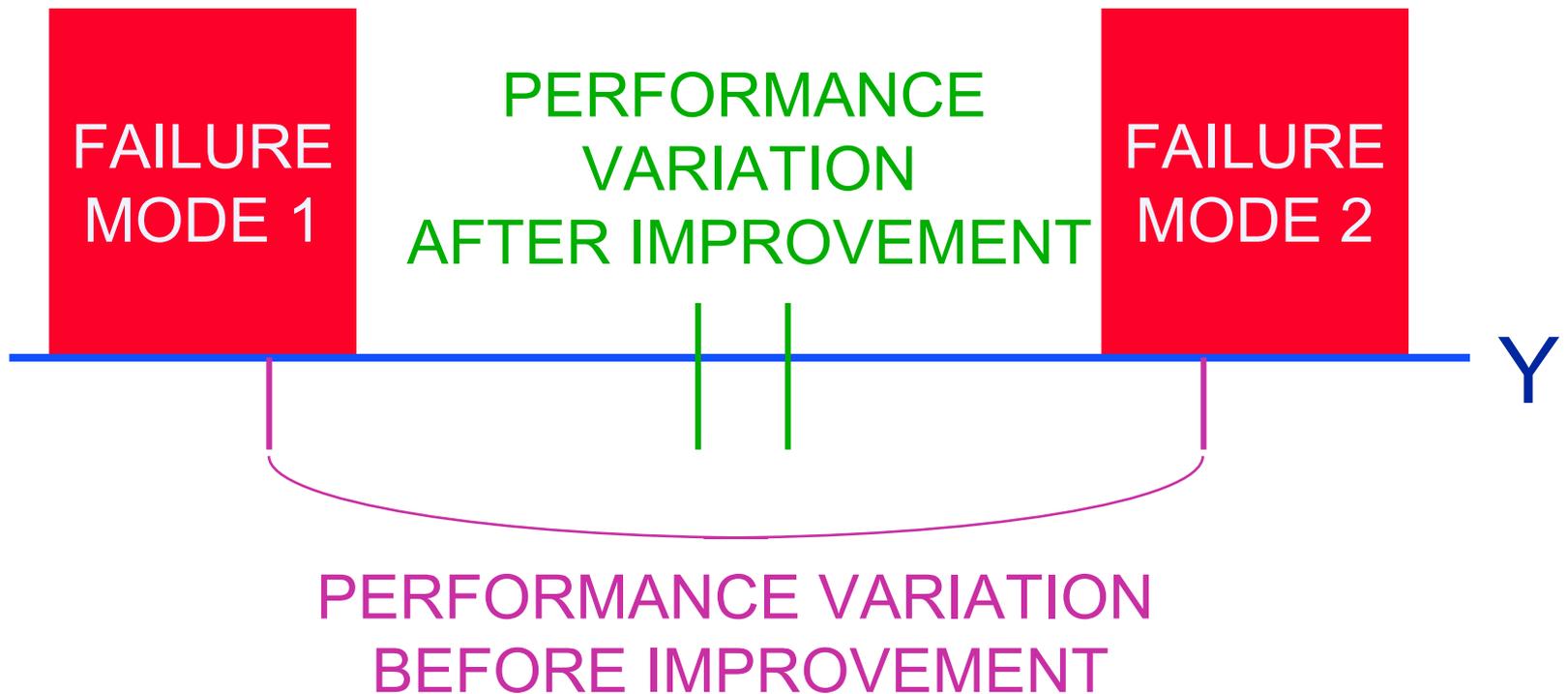


Fig. 19

# Robustness improvement



# Important noise strategy

- Not all sources of noise need to be used
- Identify key noise functional parameter; e.g.
  - Interface friction in paper stack,  $\mu p-p$
  - EM radiation in communications
- Specific source is not important
- Magnitude enables quick optimization
  - Specs on noise are not important
  - Worse noise in field is not important

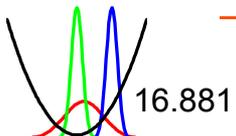
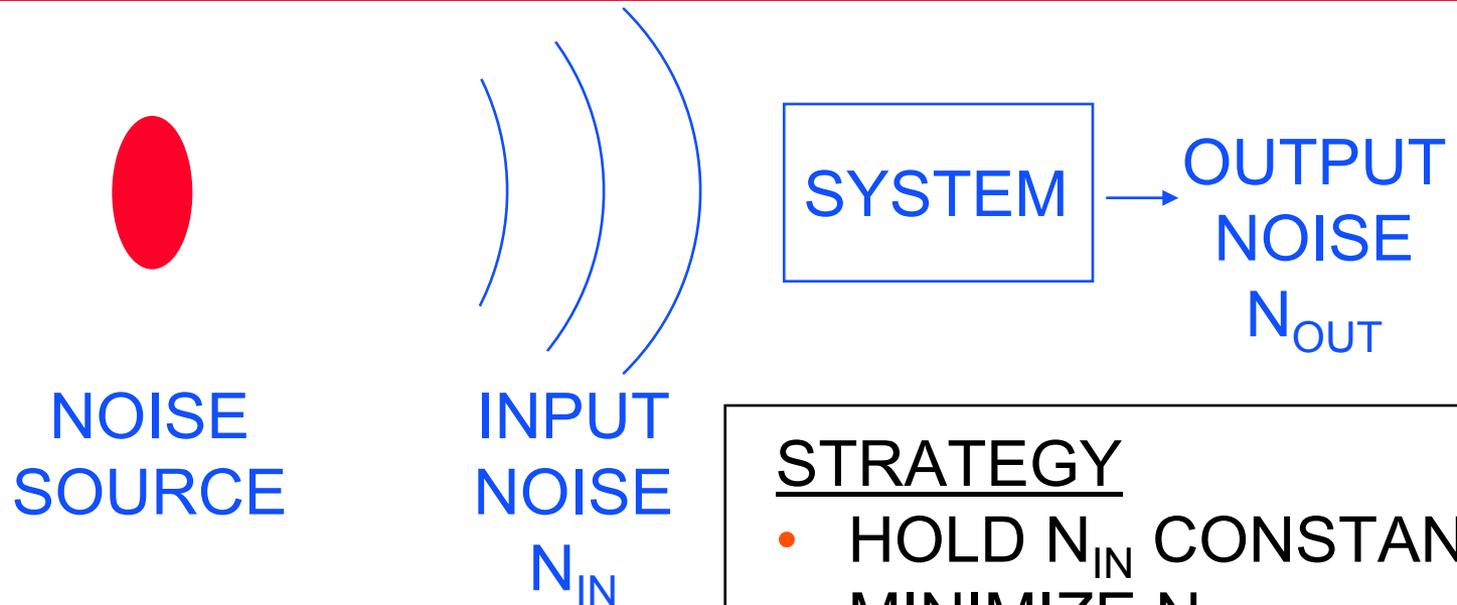


Fig. 21

# Noise strategy



## STRATEGY

- HOLD  $N_{IN}$  CONSTANT
- MINIMIZE  $N_{OUT}$

## NOT IMPORTANT

- SPECIFIC SOURCE
- MAGNITUDE OF  $N_{IN}$

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# Example of noise strategy

- Paper feeder failure modes:
- Sheet 1 arrives too soon: paper jam
- Sheet 1 arrives too late: misfeed
- Sheet 2 arrives too soon: multifeed
  - Caused by large change in paper friction,  $\Delta\mu_{p-p}$
  - Strategy for implementation during improvement?

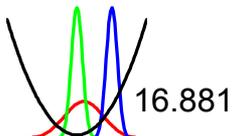
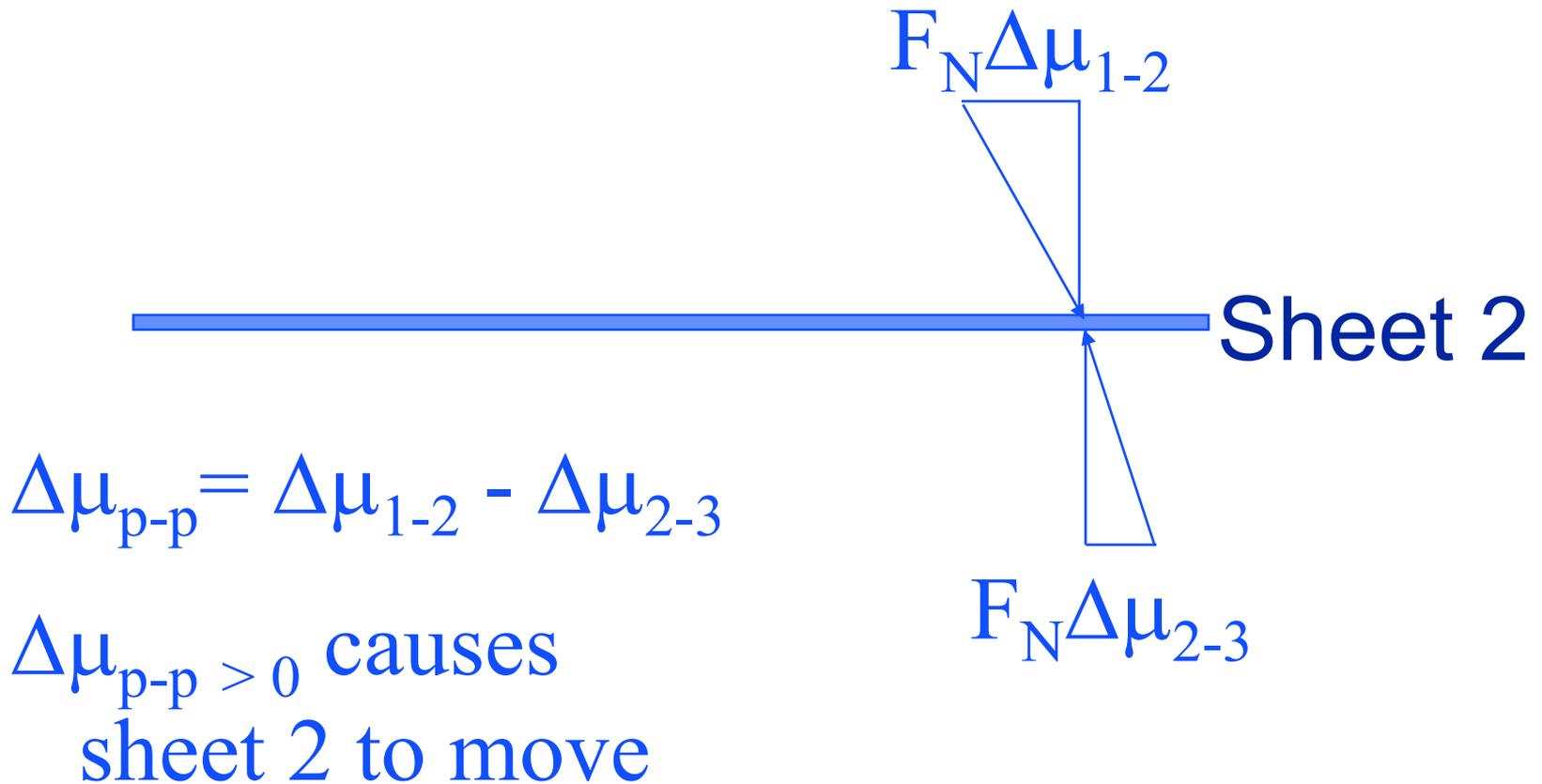


Fig. 23

Introduce large  $\Delta\mu_{p-p}$



# Noises for multifeeds

- Make  $\Delta\mu_{p-p}$  large,  $\approx 0.1$
- Will cause many multifeeds; enable quick improvement
- Ignore
  - Paper brands
  - Customer usage, etc.
- Concentrate on creating paper stack with large  $\Delta\mu_{p-p}$

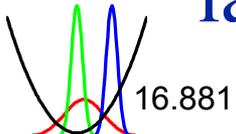
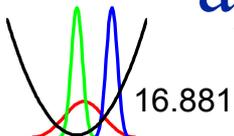


Fig. 25

# Introduce product noises early

- Drive the performance away from ideal
- Do it early. Don't wait for the factory or customers to introduce noises
- IPDT needs to develop the skill of introducing these noises
- Management needs to design this into the PD process and check that it is done to an appropriate degree



# Successful noise strategy

- Enables quick optimization
- Provides best performance inherent in concept
  - Even when future noise sources change
  - Even when future noises are larger
  - Even when spec changes
- Performance is as robust as possible
- Future improvements will require new concept

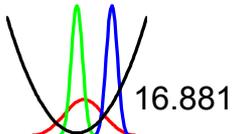
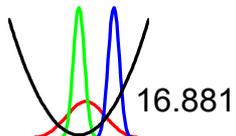


Fig. 27

# Critical control-factor range

- IPDT judges best nominal value
- Then select larger value and smaller value – feasible but significant changes
- Gives 3 values for each of 13 parameters
- $3^{13}=1,594,323$  candidate sets of values
- Must then choose trials to systematically probe 1,594,323 candidates



# Optimization

- Use designed experiments to select 27 out of 1,594,323 control-factor options
- Subject each option to same set of noises
- Select option that gives best SN ratio
- Enter selected values for critical control factors into critical parameter drawing; become requirements for detailed design

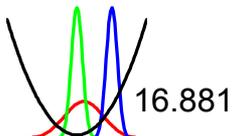
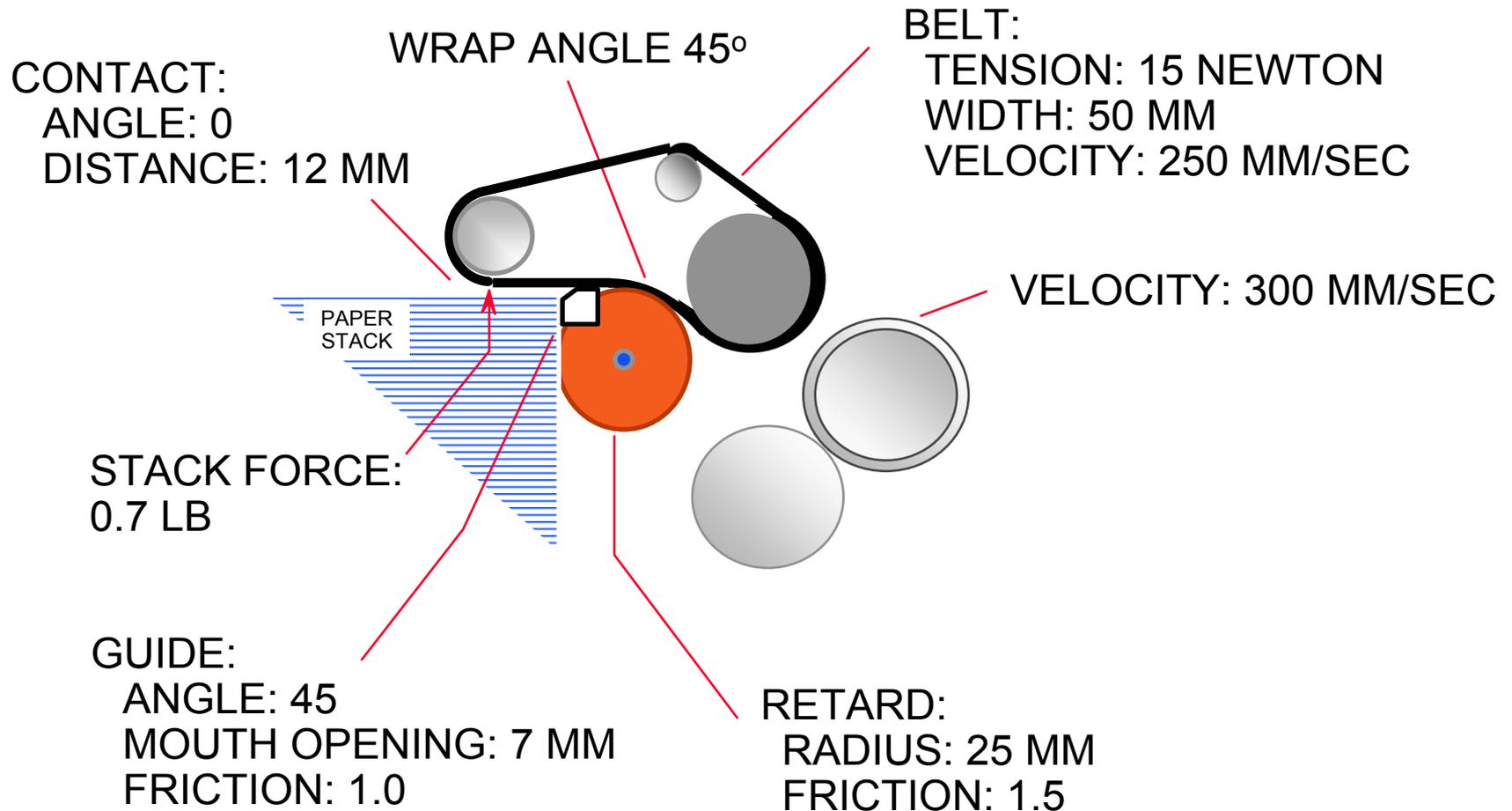
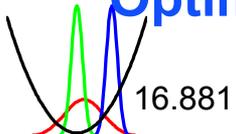


Fig. 29

# Critical parameter drawing for paper feeder



Optimized values of critical parameters guide the detailed design



# Robustness

- Keeps the performance (response) of the system acceptably close to the ideal function
- Optimizes values of control factors to minimize effect of noise factors
- Key to proactive improvement

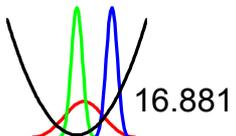


Fig. 31

# Signal/noise ratio

- Measure of deviation from ideal performance (noise here is  $N_{out}$ )
- Based on ratio of deviation from straight line divided by slope of straight line
- Many different types – depends on type of performance characteristic
- Larger values of SN ratio represent more robust performance

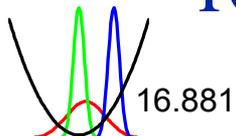


Fig. 32

# Manufacturing

- Machine-to-machine variation is one of three types of noise that affects product
- Machine-to-machine variations can be reduced by making production more robust
- $N_{out}$  for production is one type of  $N_{in}$  for product

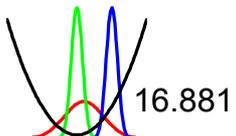


Fig. 33

# Examples of manufacturing noise

- Temperature variations
- Humidity variations
- Cleanliness variations
- Material variations
- Machine-tool variations
- Cutting-tool variations

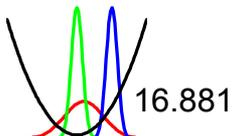


Fig. 34

# Noise strategy for production

- Simply operate in normal manner during optimization of production robustness
- Don't take special care  
Would reduce magnitude of normal noises
- Assure that every trial is done in normal manner – realistic noises are present and the part variation is typical of actual production

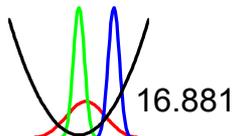


Fig. 35

# Tolerance design

- Select economical precision
- Determines typical variation relative to optimized nominal value
- Primary task is selection of production process (or quality of purchased component) -determines variation of production
- Then put tolerance on drawing

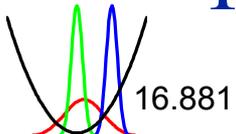


Fig. 36

# Summary; control & noise basics

- Control factors are systematically varied through large ranges seeking best combination
- Noise values are set at large values to enable quick improvement
- Tolerance design selects variation range to be used during production

Clarify these three variations in your mind;  
you will be well on your way to Master<sub>RD</sub>

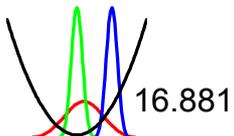


Fig. 37