

Human Vision

PERCEPTION

SPATIAL ORIENTATION IN FLIGHT

Limitations of the Senses

2

Visual Sense

Nonvisual Senses

SPATIAL ORIENTATION IN FLIGHT

Limitations of the Senses

3

Visual Sense

Nonvisual Senses



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SPATIAL ORIENTATION IN FLIGHT

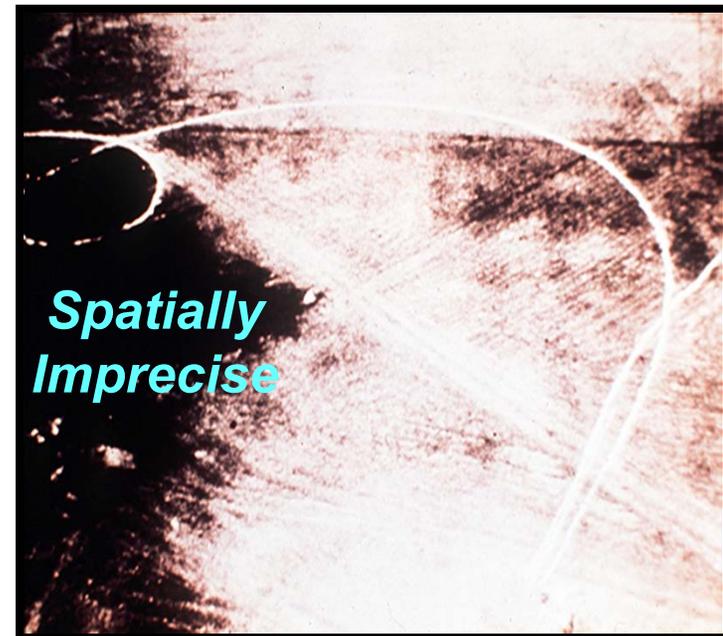
Limitations of the Senses

4

Visual Sense



Nonvisual Senses



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VISUAL ORIENTATION

3-D Neurobehavioral Model

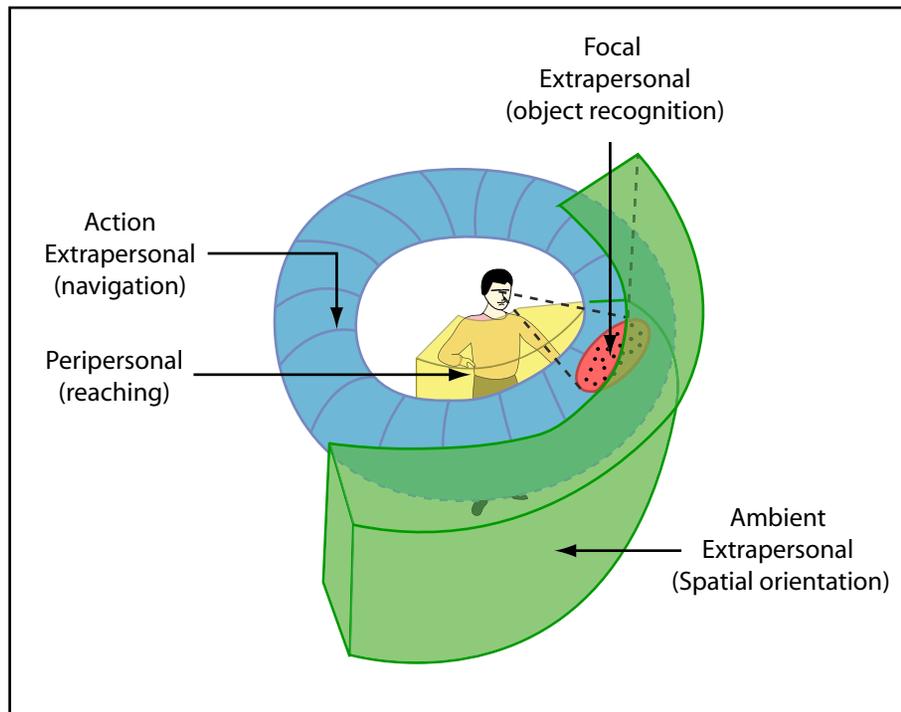


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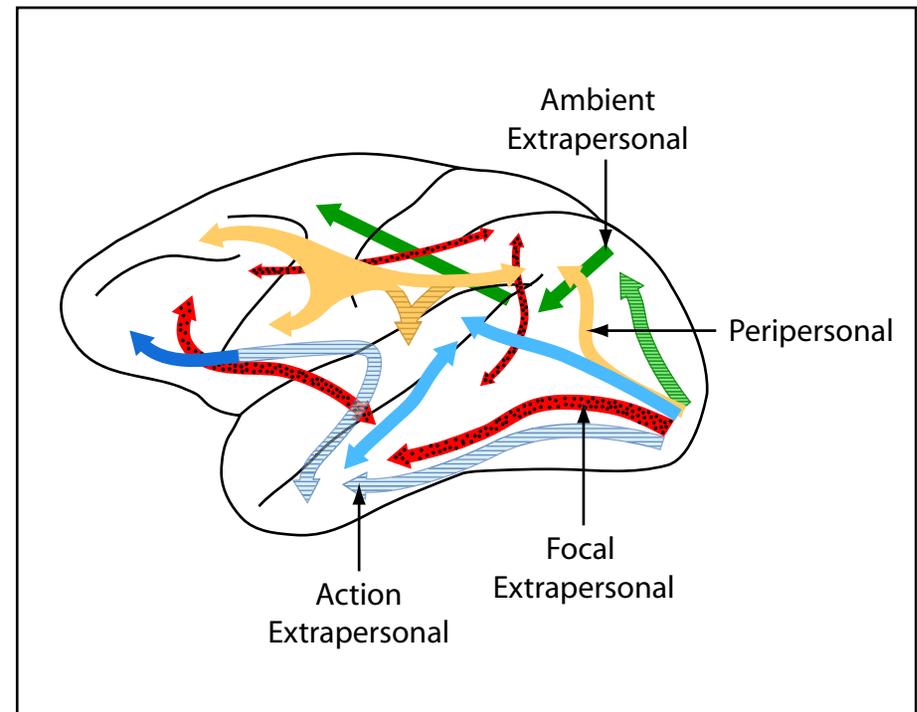


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VISUAL ORIENTATION

The Two Visual System Hypothesis

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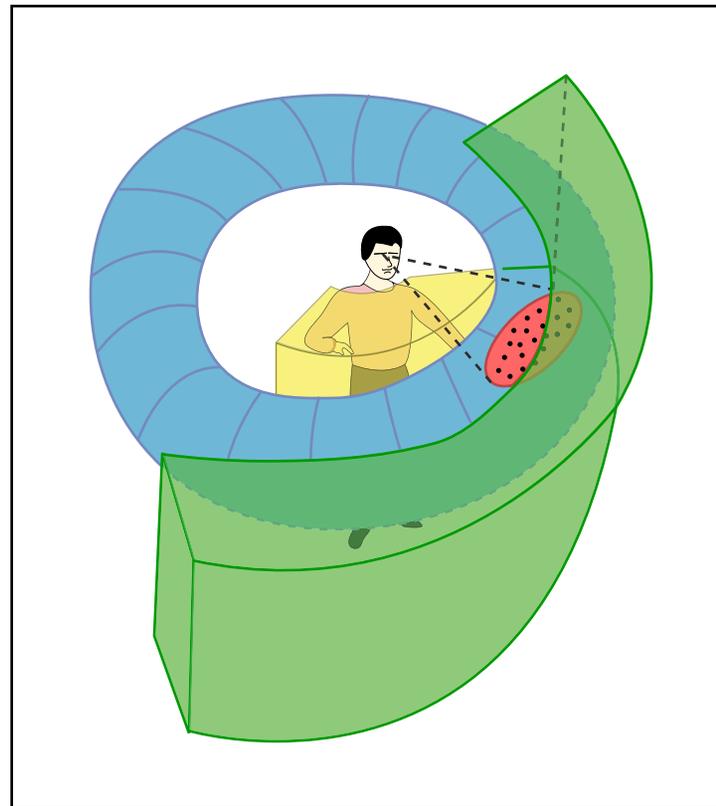


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Human Vision - Perception

VISUAL ORIENTATION

The Two Visual System Hypothesis

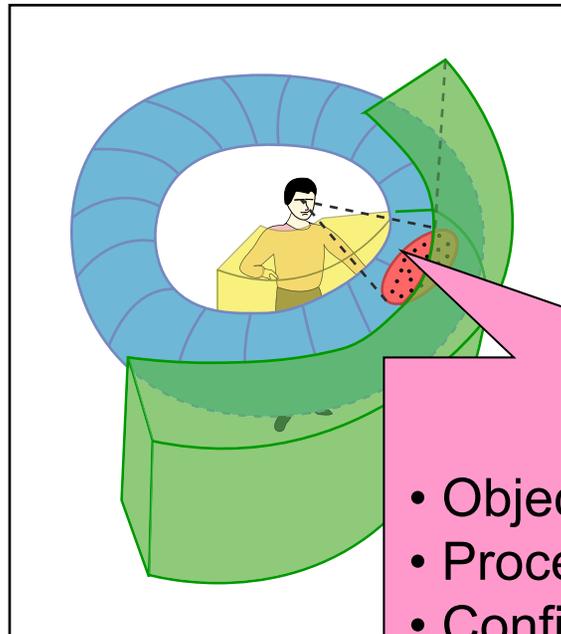


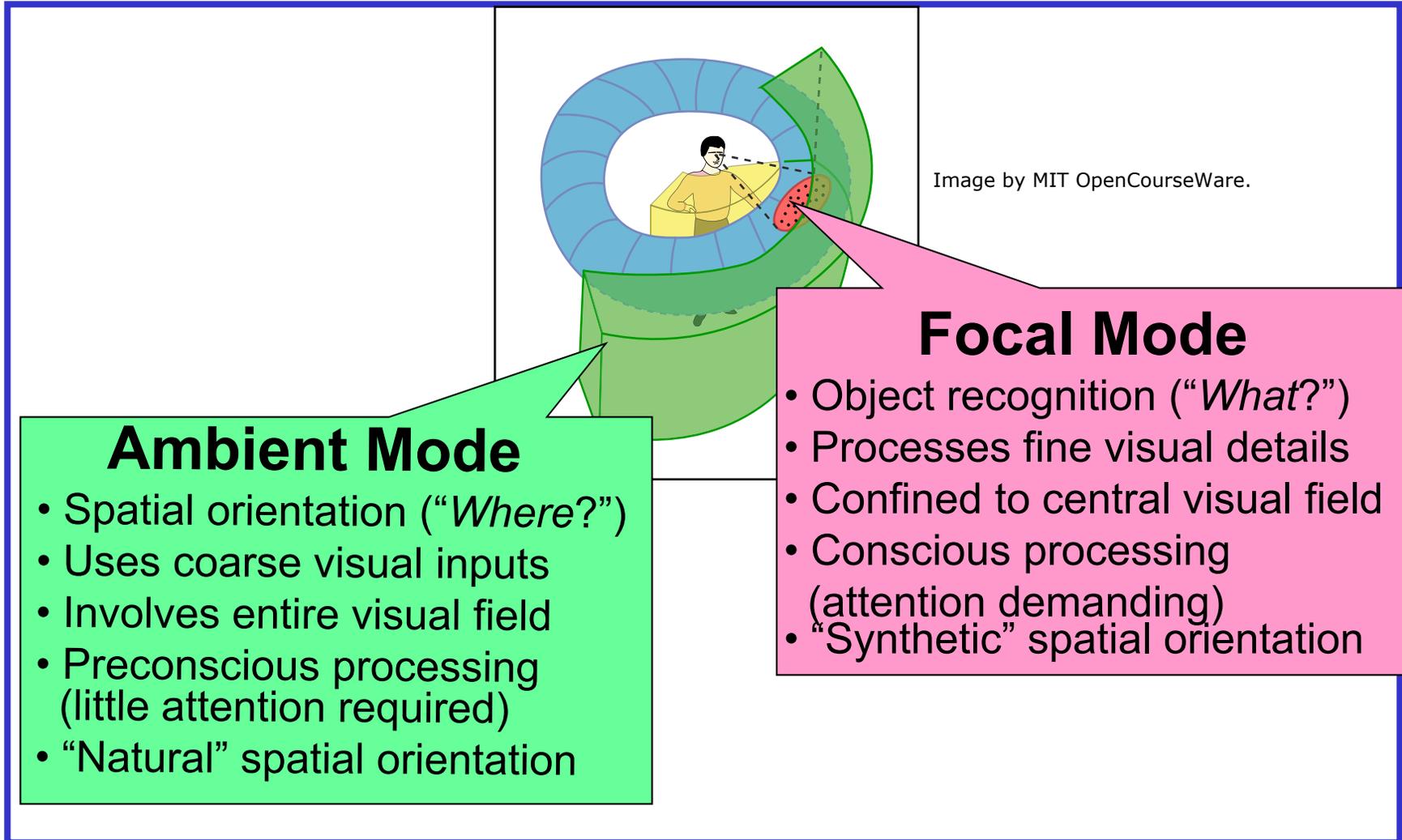
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Focal Mode

- Object recognition (“*What?*”)
- Processes fine visual details
- Confined to central visual field
- Conscious processing (attention demanding)
- “Synthetic” spatial orientation

VISUAL ORIENTATION

The Two Visual System Hypothesis

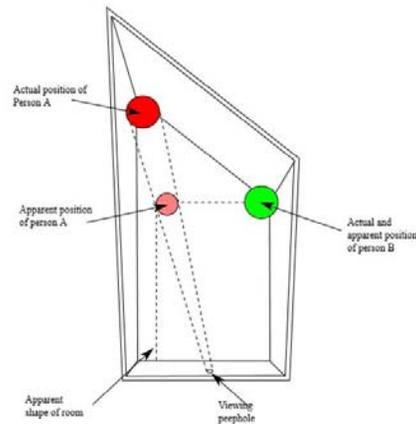


VISUAL ORIENTATION

Alterations of The Ambient Visual Frame

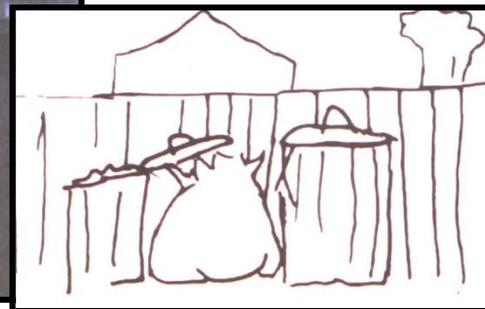
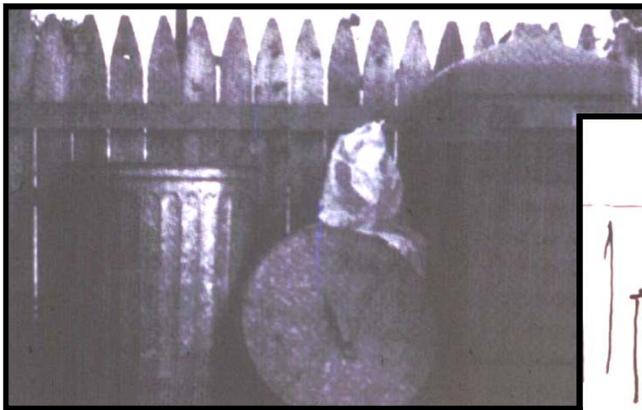
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Distortion -- *The Ames Room*



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Distortion -- *Memory*



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Absence -- *The "Black Hole" Approach*

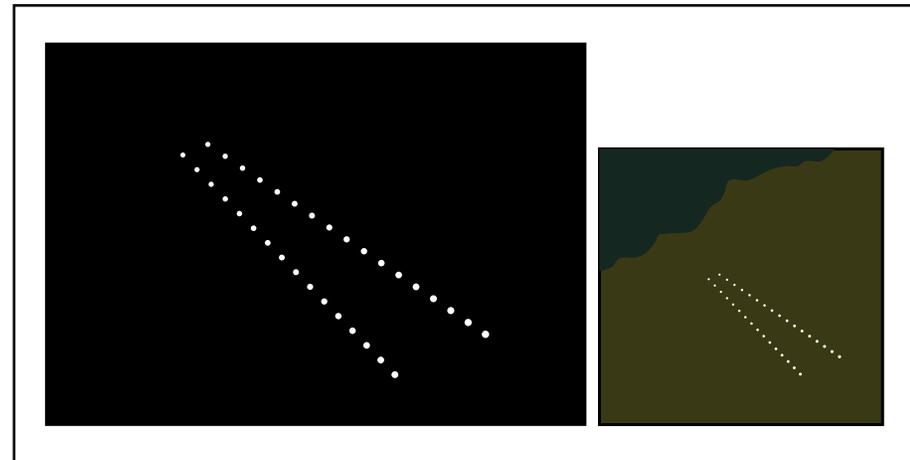


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VISUAL ORIENTATION

Ambient Visual Effects (Self-Motion)

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Characteristics of Vection

- Requires large retinal area (including periphery)
- More dependent on background visual field
- Relies on moving textures (sluggish response, low frequency)
- Can occur with optically degraded stimuli

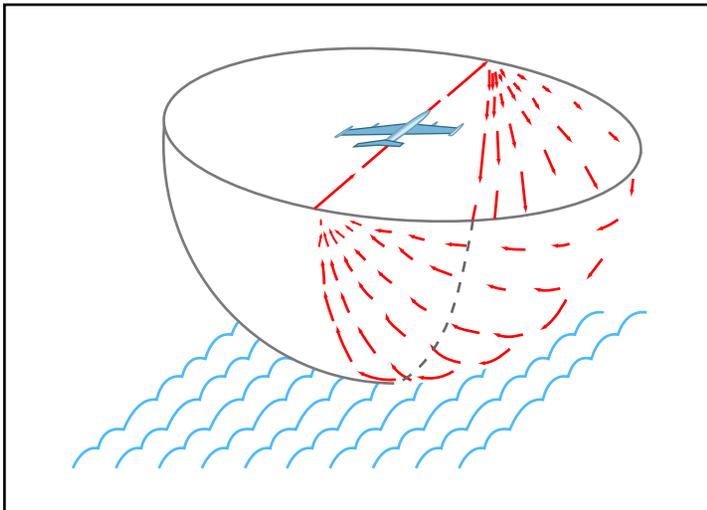


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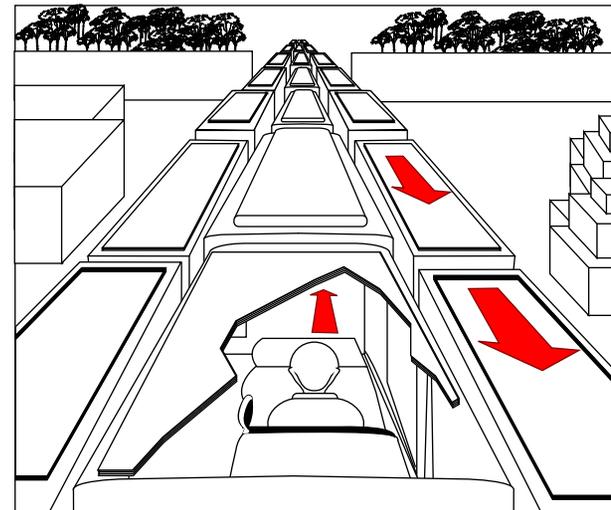


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VISUAL ORIENTATION

Ambient Visual Effects (Self-Position)

Characteristics of Field-Dependence

- **Similar visual requirements asvection (e.g., reliance on background field, can tolerate optical degradation)**
- **Tilted scenes produces changes in perceived visual vertical, gravitational vertical and posture**
- **Other position effects (luminance gradients, depth)**



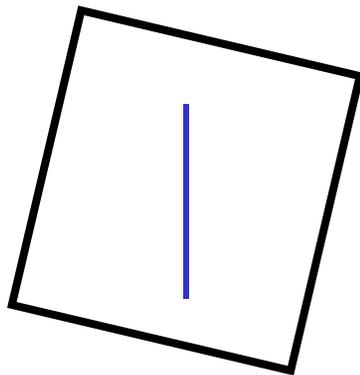
Rod-and-frame

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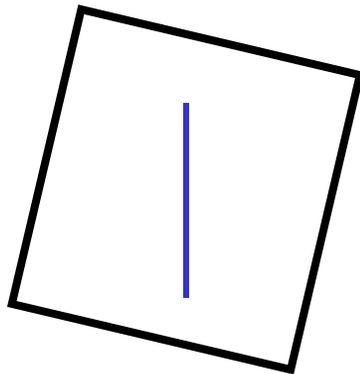
Rod-and-frame

VISUAL ORIENTATION

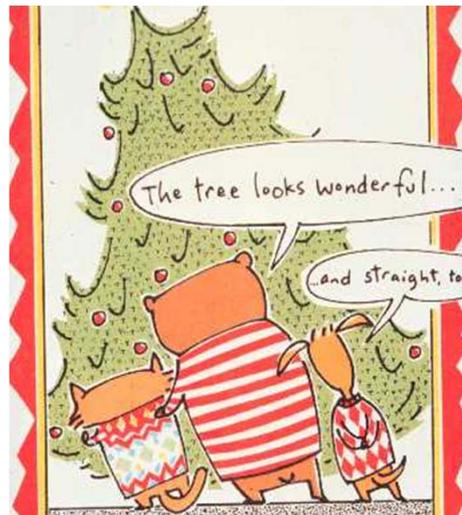
Ambient Visual Effects (Self-Position)

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Rod-and-frame



Postural Effects

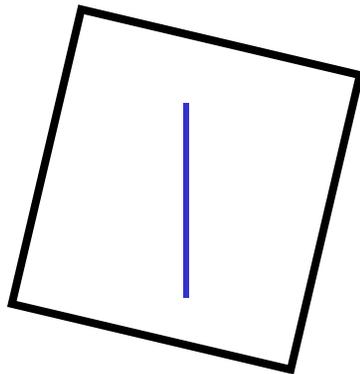
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VISUAL ORIENTATION

Ambient Visual Effects (Self-Position)

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Rod-and-frame



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Postural Effects



Optokinetic-Cervical Reflex

VISUAL ORIENTATION

Ambient Luminance Gradients

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Luminance Gradients

- Light-to-Dark Gradient Important in Judging Visual Vertical
- Gradient Inversions Caused by
 - Low Sun Angles
 - Clouds
 - Terrain Shadowing
 - Lunar Reflections
- Can Result in Inversion Illusions



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VISUAL ORIENTATION

Ambient Luminance Gradients

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Luminance Gradients

- Light-to-Dark Gradient Important in Judging Visual Vertical
- Gradient Inversions Caused by
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- Can Result in Inversion Illusions



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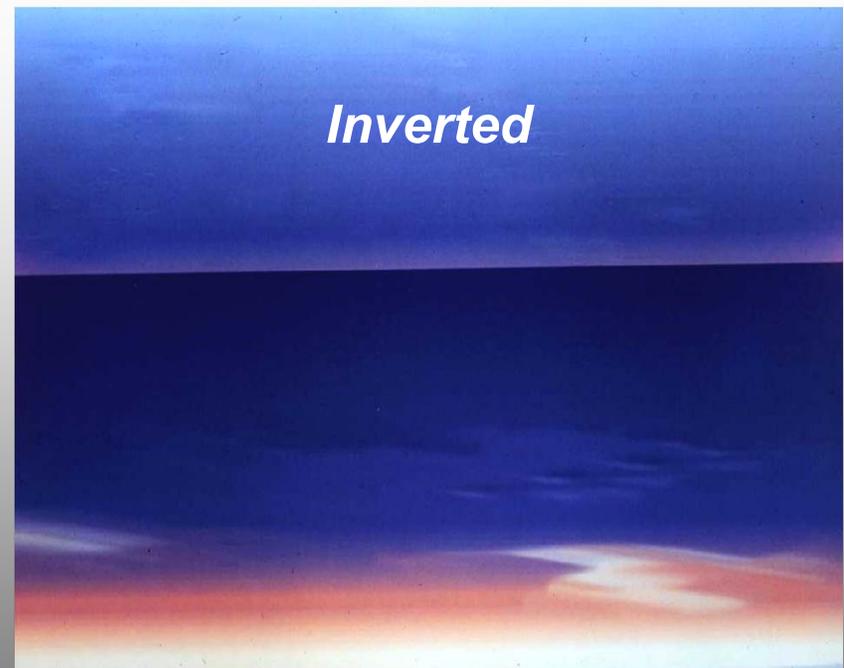
VISUAL ORIENTATION

Ambient Luminance Gradients

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Luminance Gradients

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VISUAL ORIENTATION

Ambient Luminance Gradients

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Luminance Gradients

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VISUAL ORIENTATION

Ambient Visual Cues to Depth

Ambient Depth Cues

- Linear perspective/foreshortening
- Gradient of texture
- Motion parallax
- Illumination
- Aerial perspective



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Linear perspective

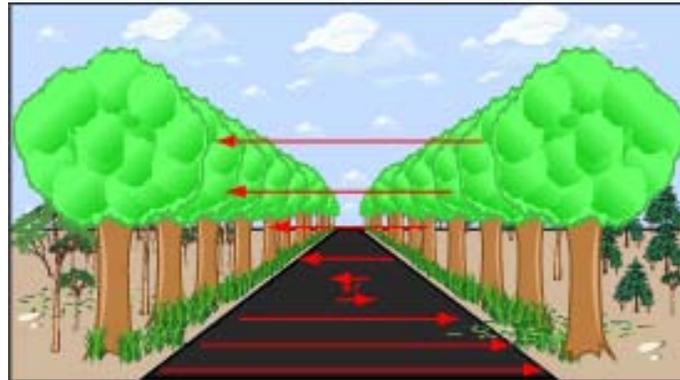


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Motion parallax

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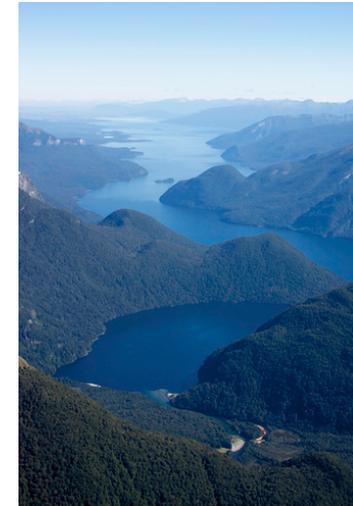


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Aerial perspective

VISUAL ORIENTATION

Ambient Visual Cues to Depth

20

Linear Perspective & Gradient of Texture

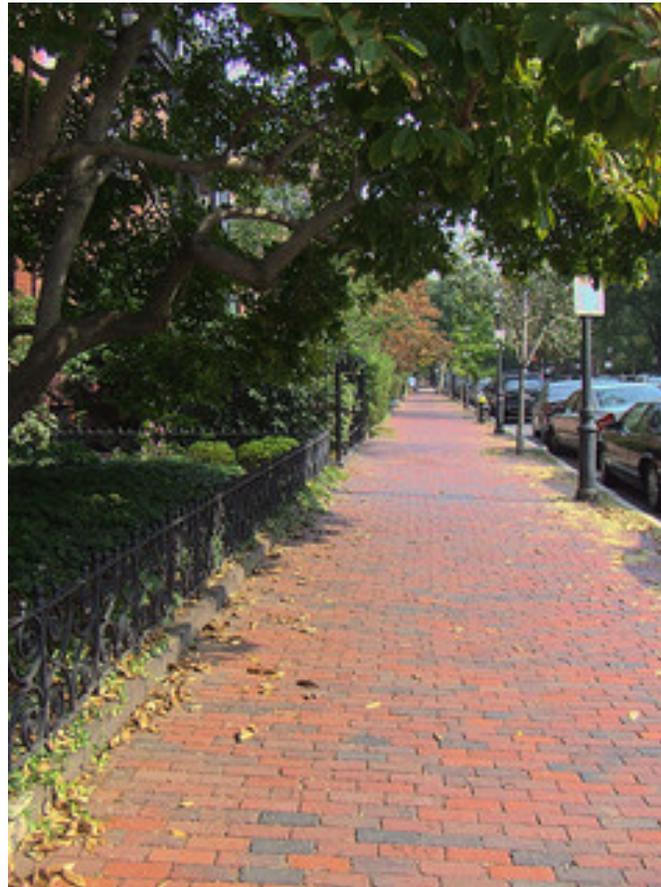


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Human Vision - Perception

VISUAL ORIENTATION

Ambient Visual Cues to Depth

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Ambient Depth Cues

- Linear perspective/foreshortening
- Gradient of texture
- **Motion parallax**
- Illumination
- Aerial perspective



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Linear perspective

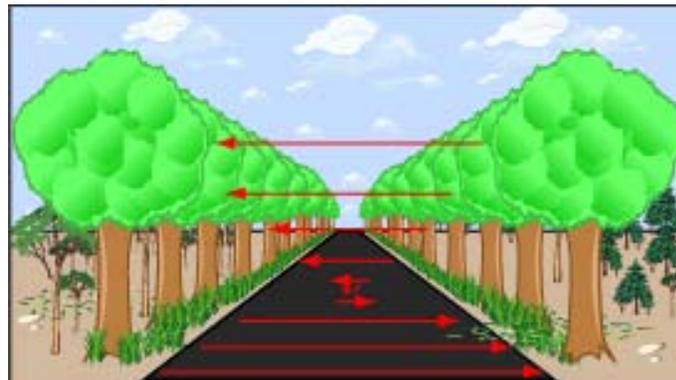


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Motion parallax
Human Vision - Perception



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Aerial perspective

VISUAL ORIENTATION

Ambient Visual Cues to Depth

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Motion Parallax

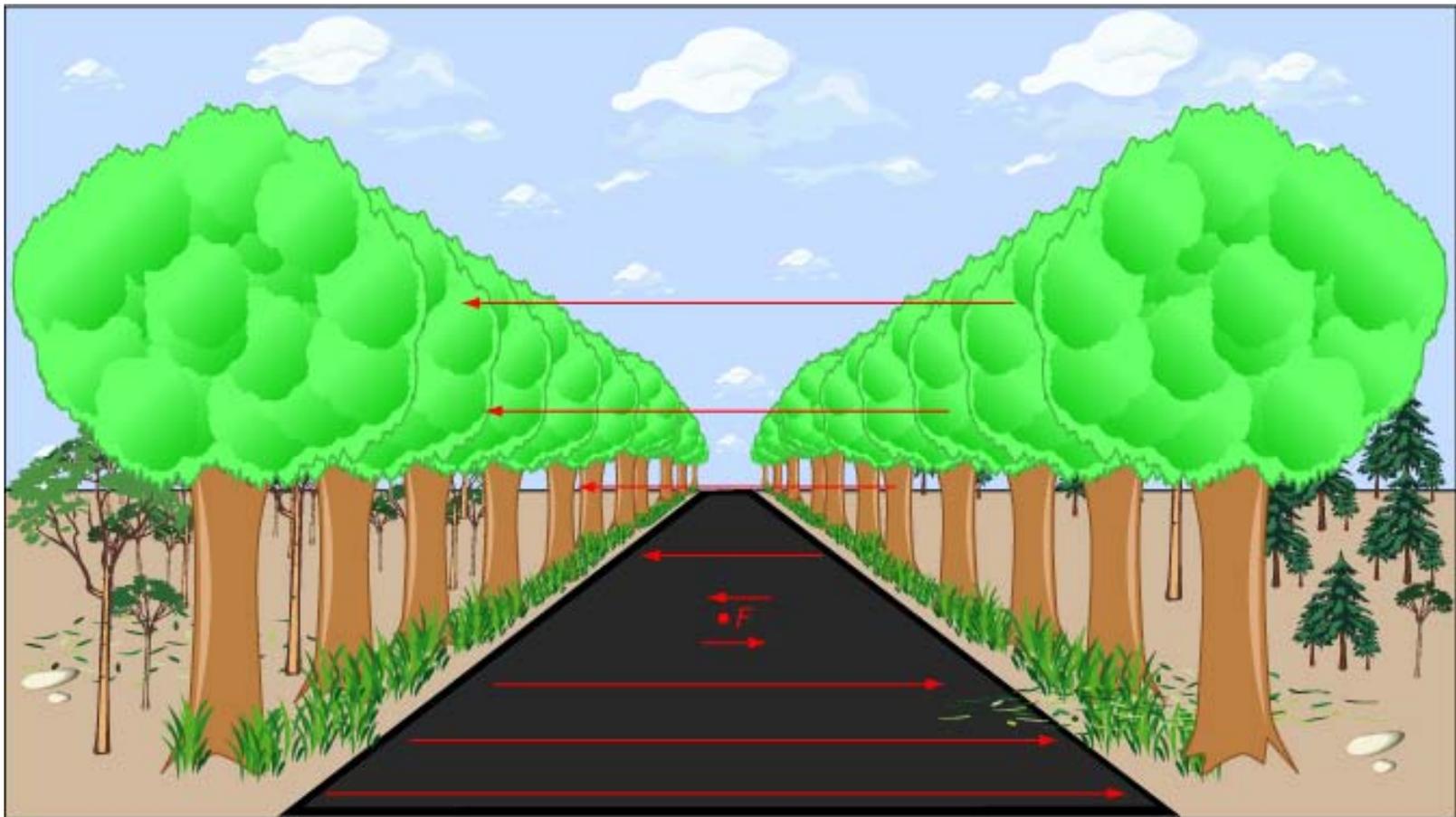


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Human Vision - Perception

VISUAL ORIENTATION

Ambient Visual Cues to Depth

23

Ambient Depth Cues

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- Gradient of texture
- Motion parallax
- Illumination
- Aerial perspective



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Linear perspective

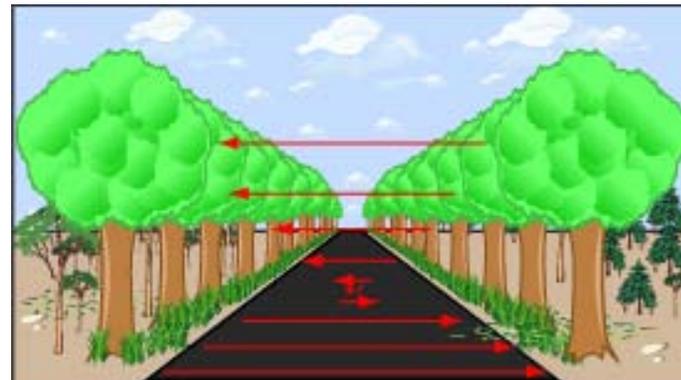


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Motion parallax
Human Vision - Perception



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Aerial perspective

VISUAL ORIENTATION

Ambient Visual Cues to Depth

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Aerial Perspective

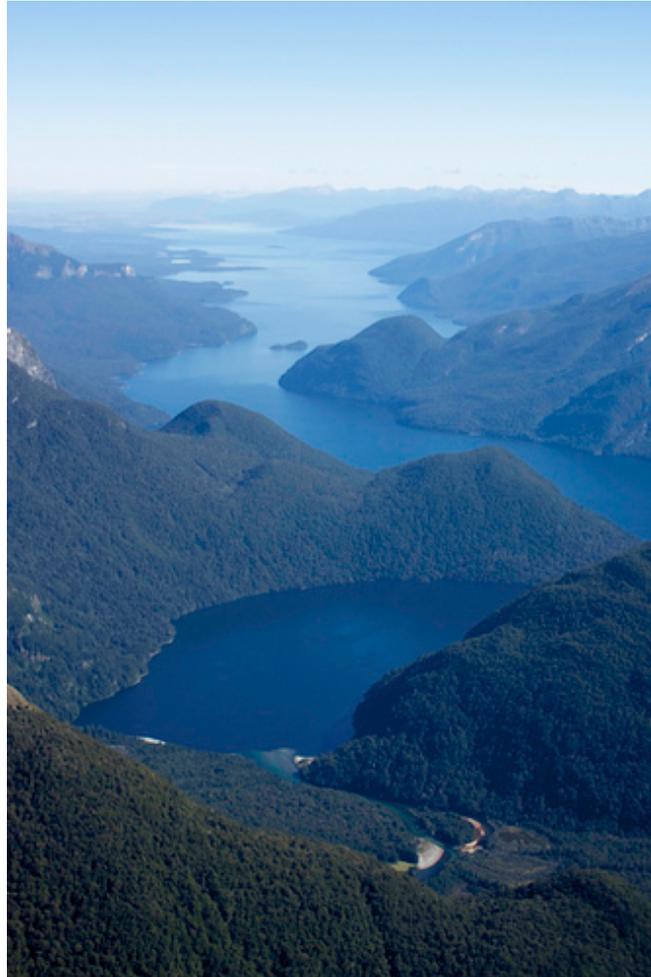


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Human Vision - Perception

VISUAL ORIENTATION

Focal Visual Effects

Size and Shape Constancies

Rigidity is considered to be a fundamental property of objects; therefore, deviations in the size and shape of ground objects are perceived as changes in our orientation relative to the ground



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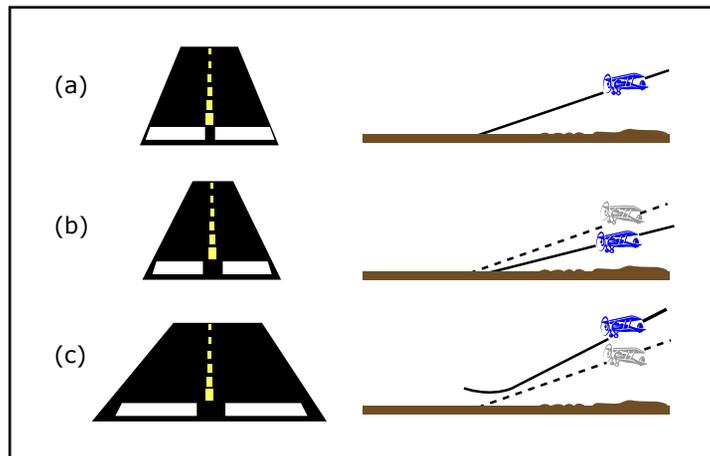


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Size Constancy

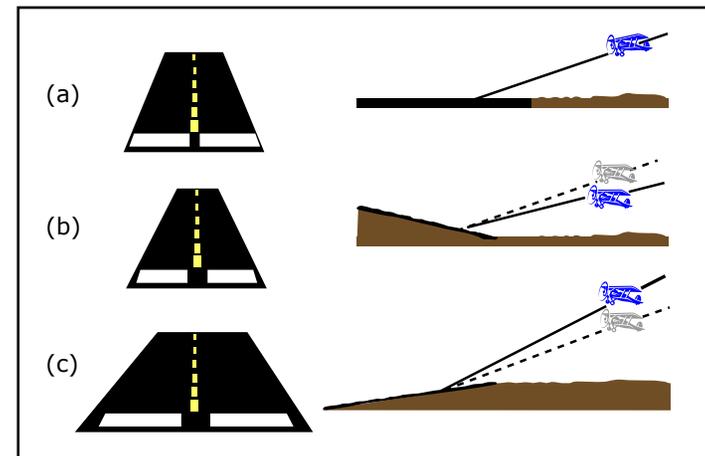


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Shape Constancy

VISUAL ORIENTATION

Focal Visual Effects

Size and Shape Constancies

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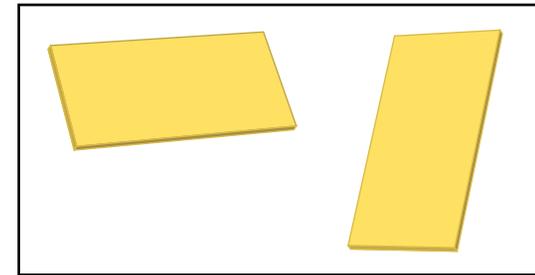


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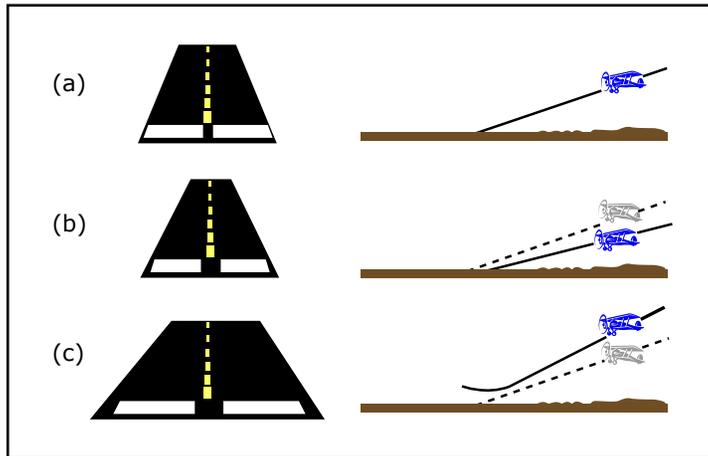


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Size Constancy

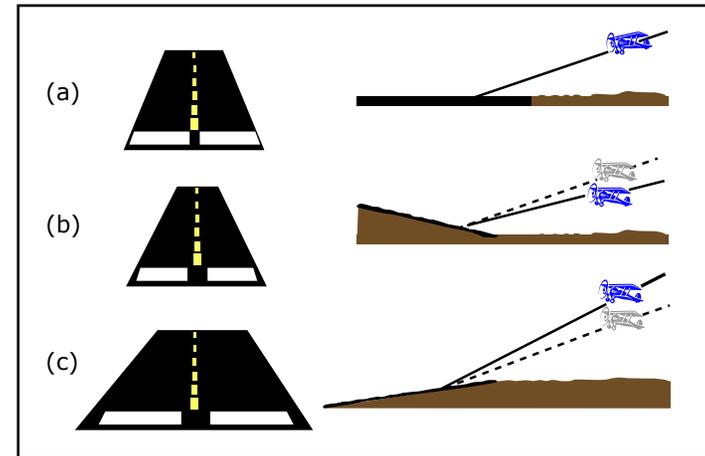


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Shape Constancy

VISUAL ORIENTATION

Focal Visual Effects

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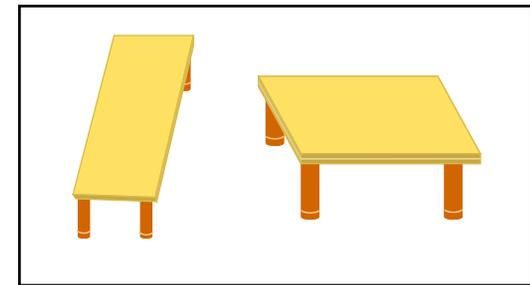


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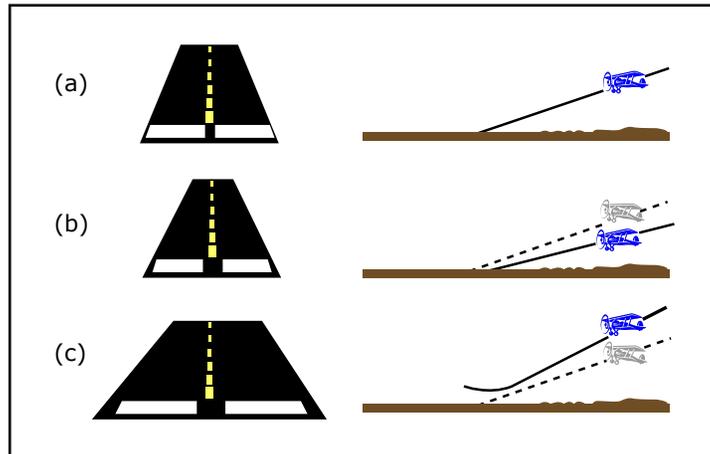


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Size Constancy

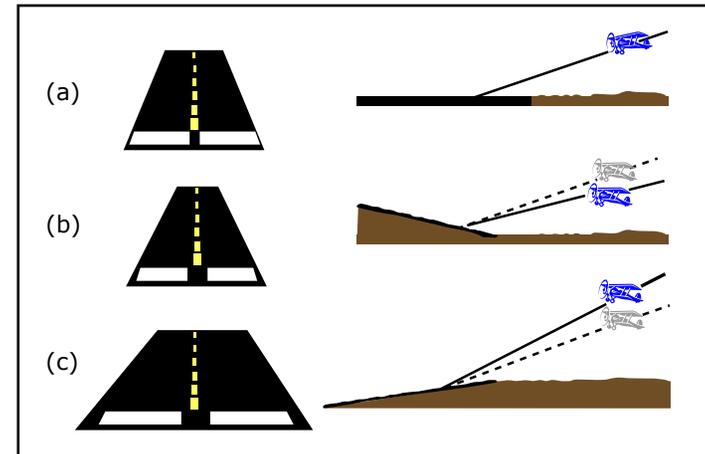


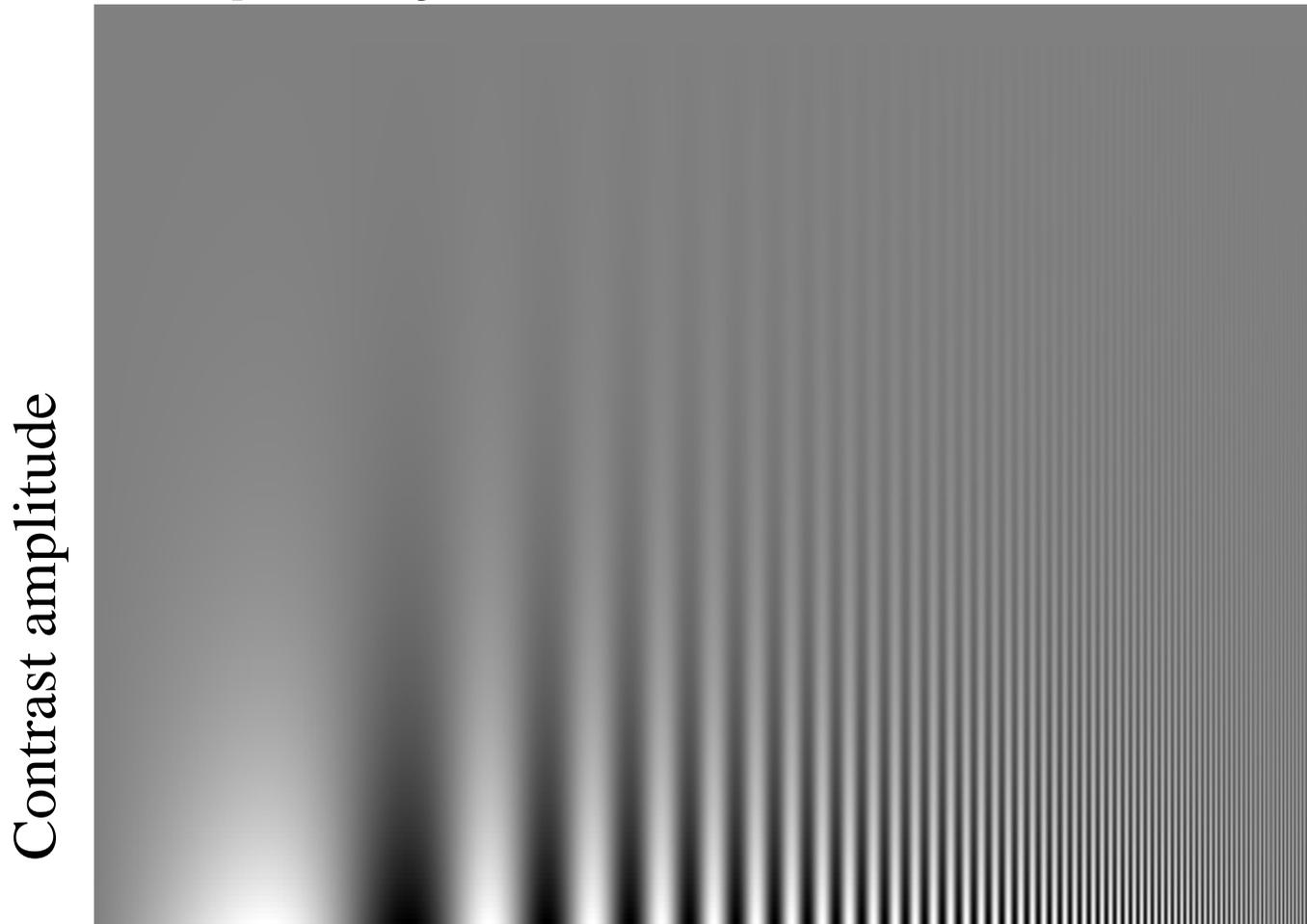
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Shape Constancy

Contents

- Introduction
- Contrast & Frequency
- Visual Pathway, Visual Image
- Receptive Fields, Gestalt
- Color, Color deficits, after images
- Size of objects

Spatial Frequency and Contrast



Spatial frequency of grid

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http://visiome.neuroinf.jp/modules/xoonips/detail.php?item_id=3181.

Optic nerve - from eye to brain

30

- Left visual field
-> right brain side
- Right visual field
-> left brain side
- Retina 11cm^2
- Optic nerve diameter 2mm
- **convergence**
receptors -> ganglion
- **divergence**
optic nerv -> visual cortex

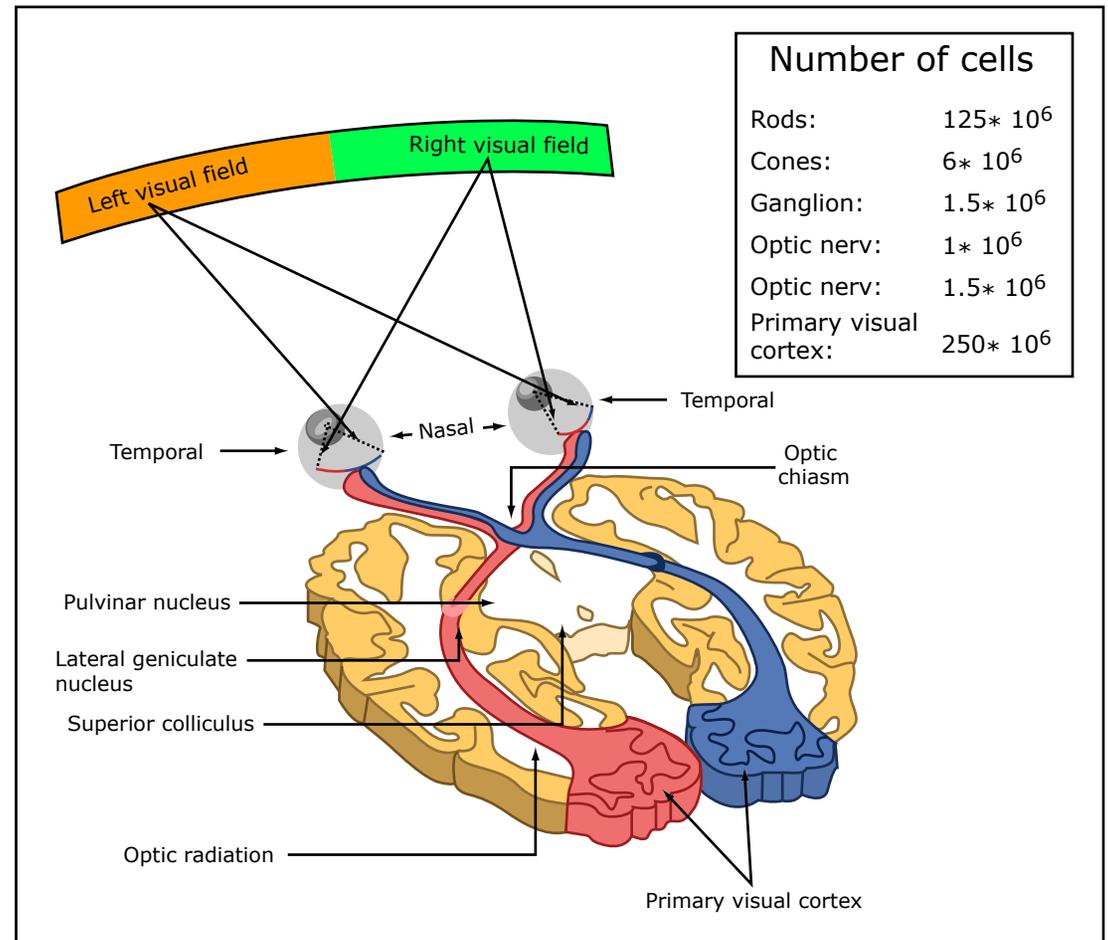


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Rod and cone density

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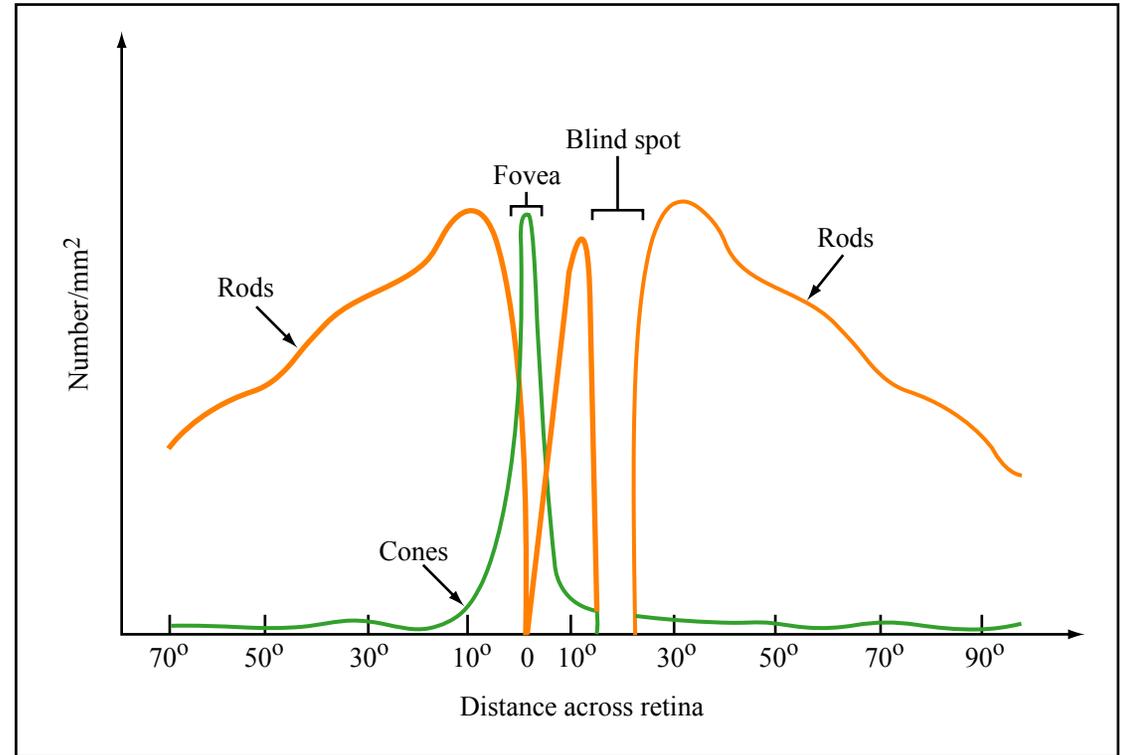


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- On average 120 rods converge on 1 ganglion cell
- On average 6 cones converge on 1 ganglion cell

Questions

- How come that we perceive such a nice and homogenous image of our surrounding?
- What happened to the blind-spot hole?
- Why do we perceive color in the periphery?

Receptive Fields

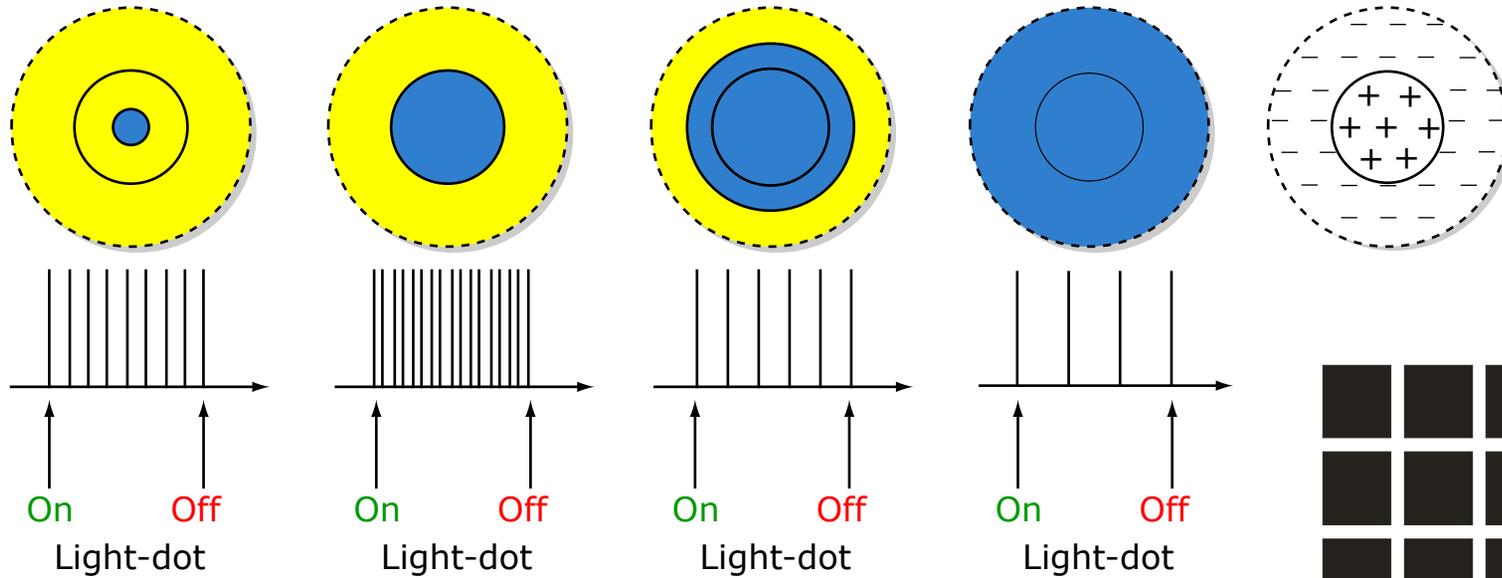


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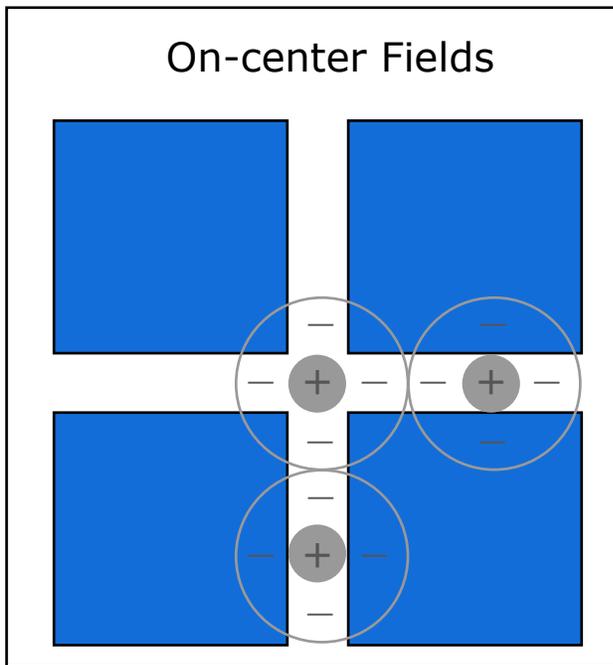
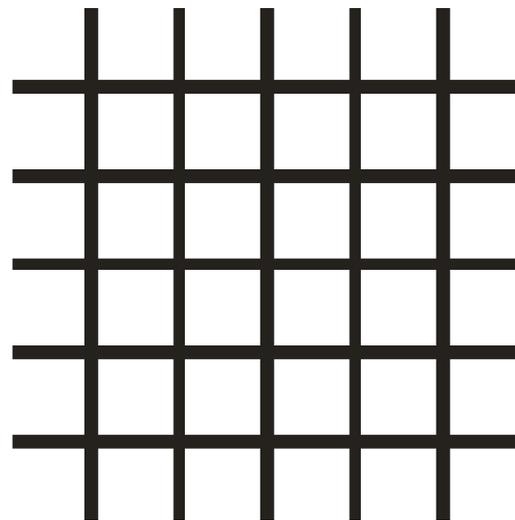
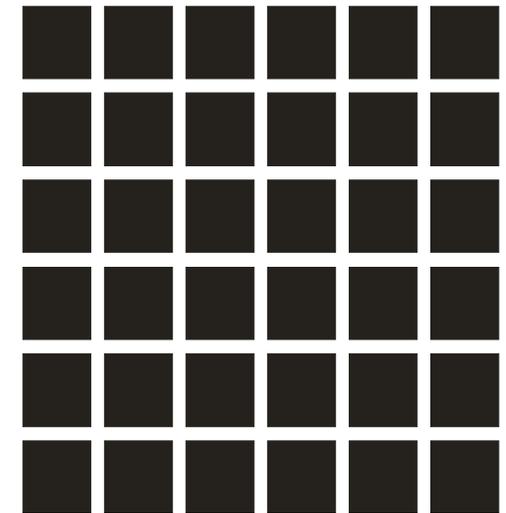
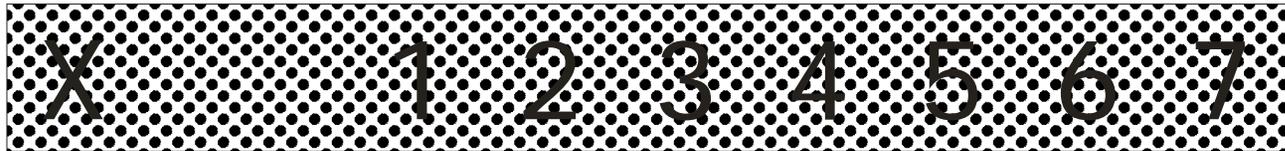


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Filling the blind spot

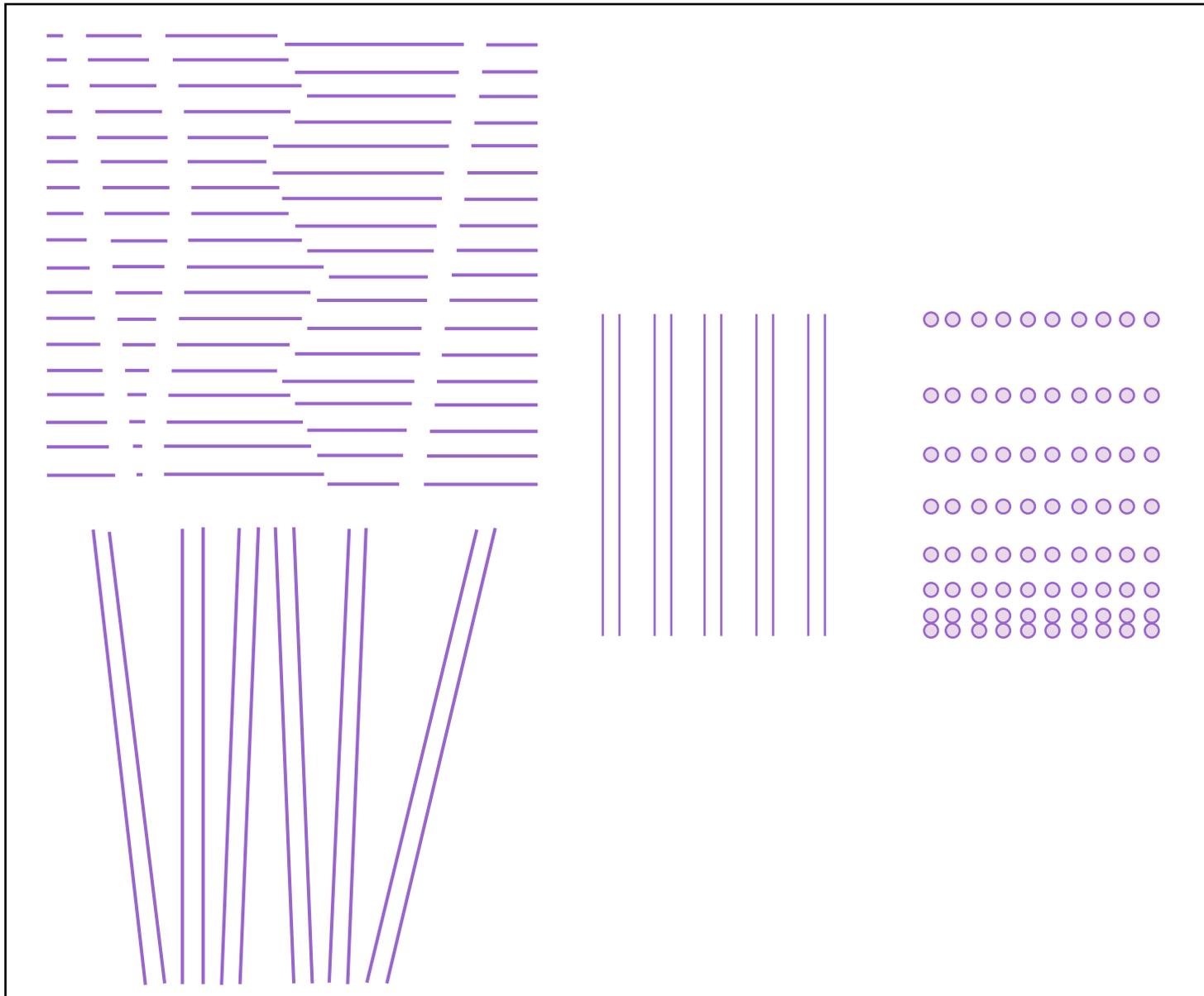


- Close your left eye and fixated with the right eye the X.
Which number is missing? What is the color pattern at the psotion of the missing number?
- The blind spot is filled with the surrounding pattern.

Figure and background

- The total visual input is organized into figures and background.
- The Gestalt-laws describe principles how figure and ground are separated.
- **Figures** are in front, have a border, connected, “things”.
- The **background** is behind the figure, without border, uninterrupted, homogenous.

Gestalt-laws



Human Vision - Perception

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Perceptual categories

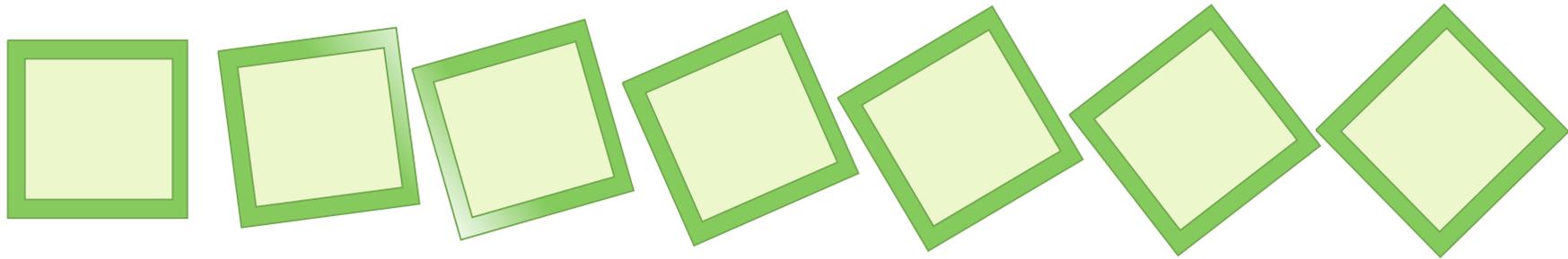


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Square.....Diamond

- The shapes in-between are neither square nor diamond.
- Our perception is organized in categories, even if the stimuli are continuous.

Perceptual categories: Reproducing shapes

- Figure in B is the drawing when the shape of the Figure A is given as a tactile stimulus (without vision).

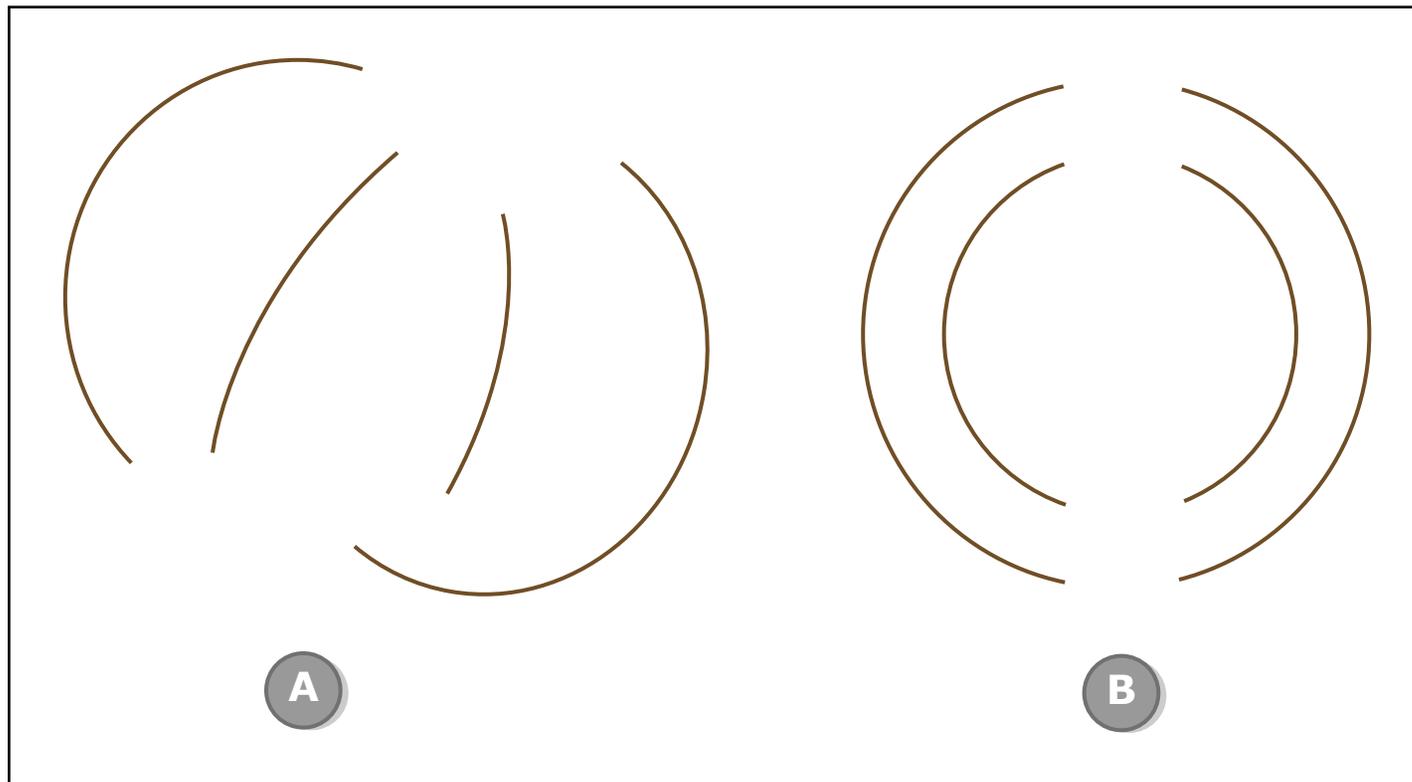
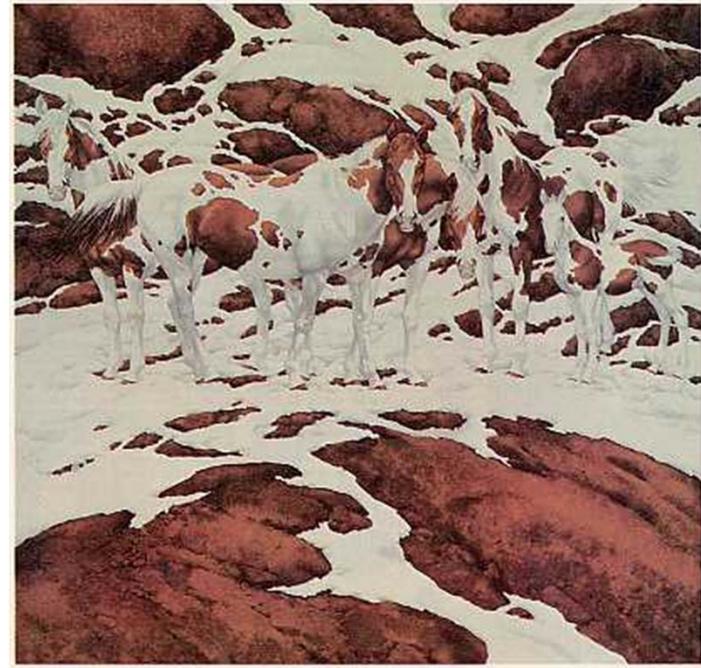


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Emergence

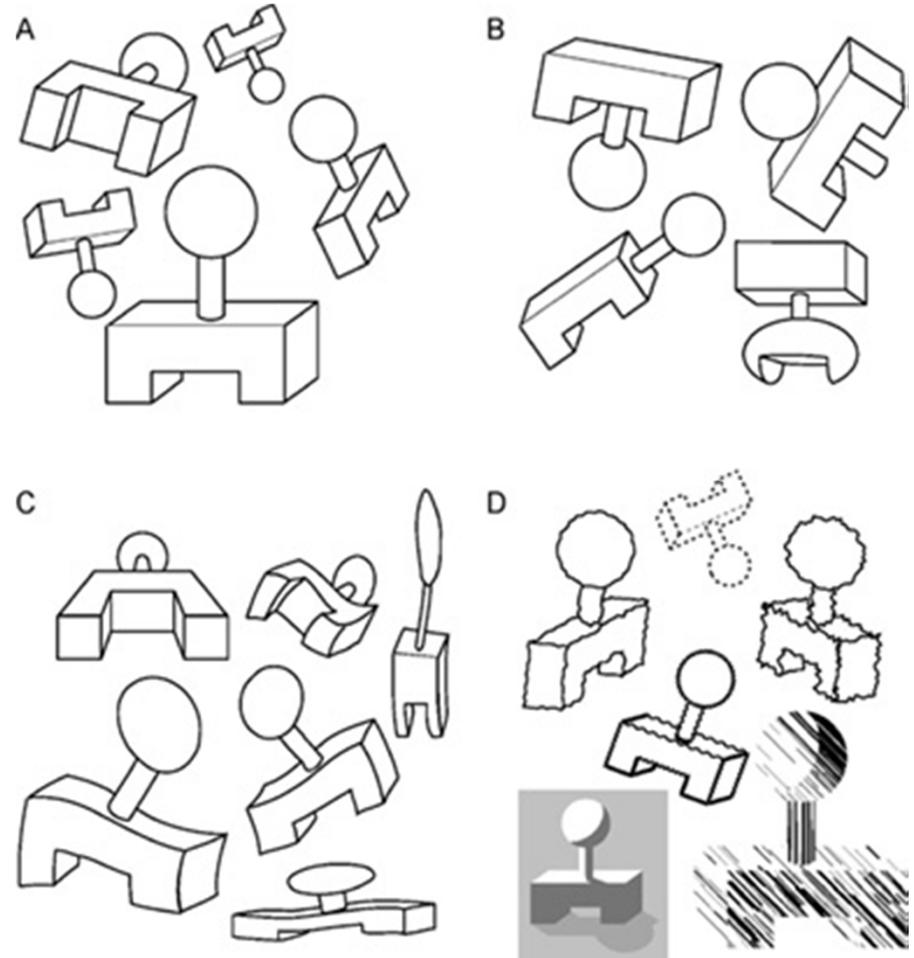


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- The dog is perceived as a whole, all at once.
- We do not construct the “dog” by first identifying its parts, e.g. combining feet, ears, nose, tail, etc.

Invariance

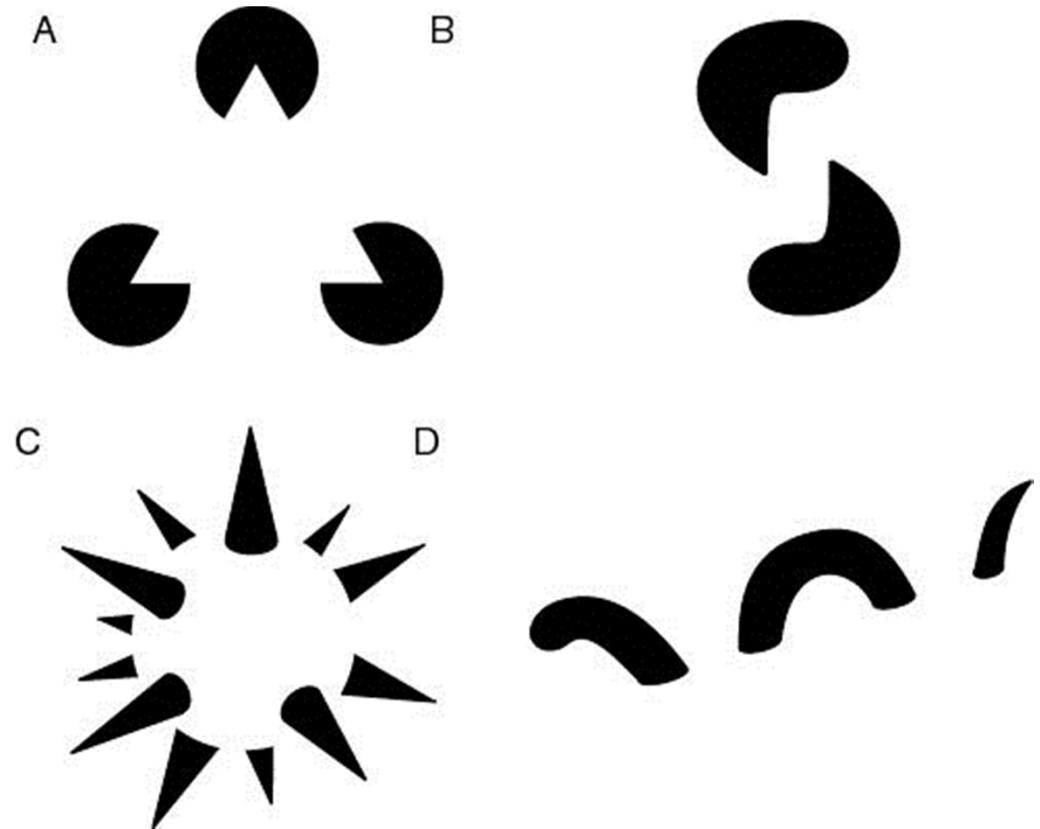
- simple geometrical objects are recognized independent of rotation, translation, and scale, (and other deformations)
- Objects in A are immediately recognized as the same shape,
- are different from those in B,
- are the same as in C despite perspective and elastic deformations,
- and can be depicted using different graphic elements as in D.



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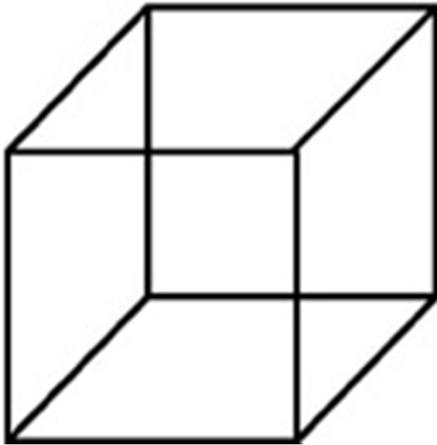
Reification

- The perceived object can contain more information as given by the sensory input. (e.g. ball in C)
- Mostly for spatial information.



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Multistable perception



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Necker cube



Rubin's Figure / Vase

- Ambiguous perceptual experiences (2 figures share a common border) lead to multistable perception. The experiences pop back and forth between two or more alternative interpretations.

What are the components?

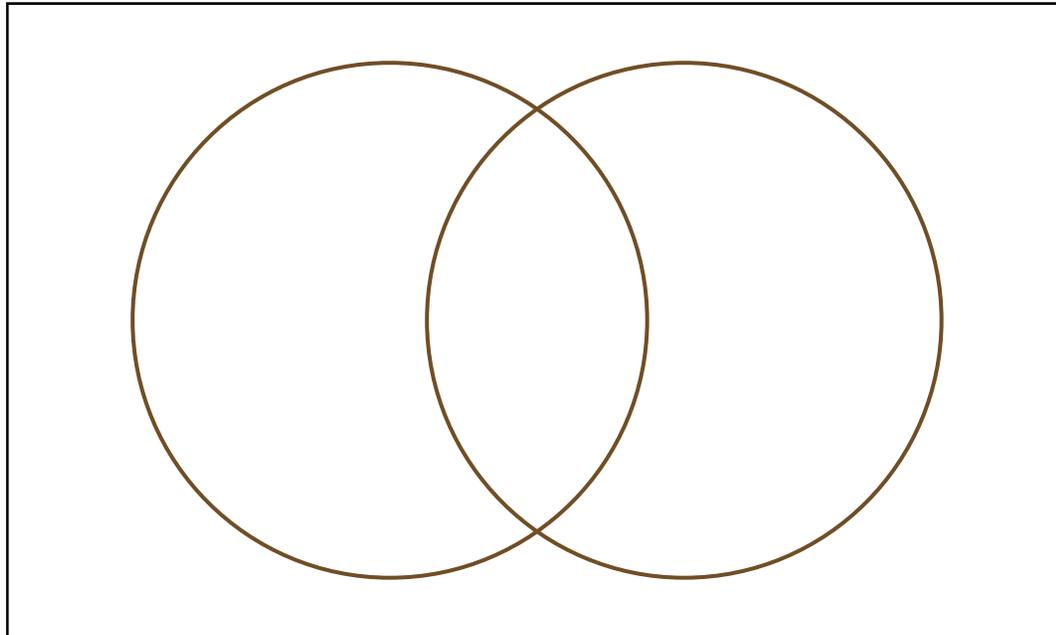


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Some of the combinations

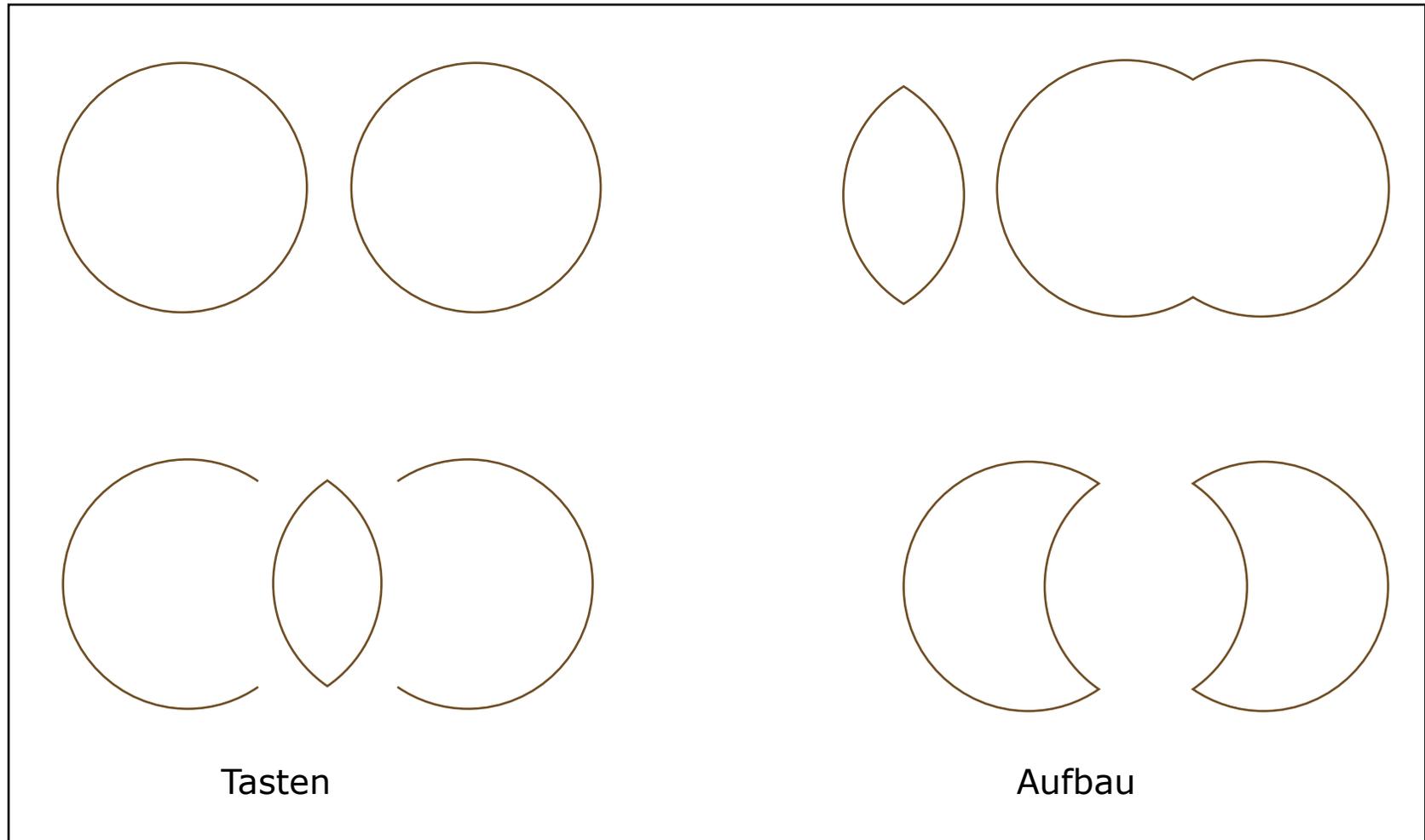


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Color

- Wavelength - physics
- Color - perception

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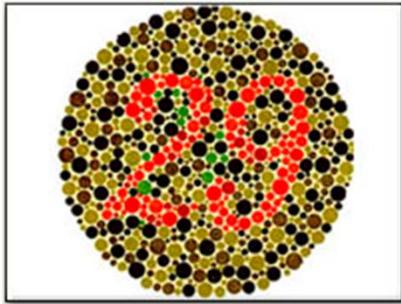
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Color blindness

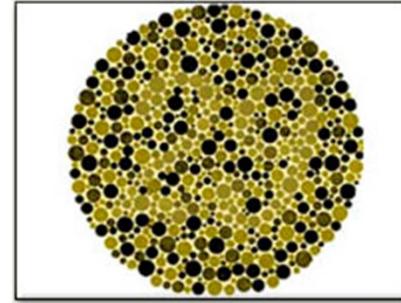
- Normal color vision is **trichomat**, 3 cone types are used.
- Dichromacy, most common Red-Green color blindness lacking or reduced long-wavelength or medium-wavelength cones (4-8% of the male population!)
includes: Protanopia (rare), Deuteranopia (1% m), Protanomaly (1% m), Deuteranomaly (6% m)
- Monochromacy, complete inability to distinguish any colors
cone monochromacy (only 1 cone type)
rod monochromacy (only rods)
- Human Factors
Color codes
(Maps, Signals, etc)

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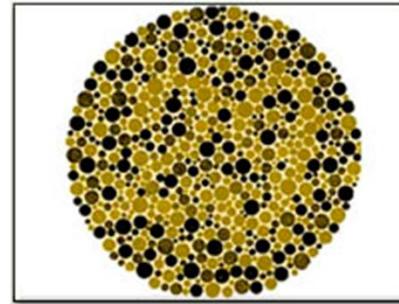
Color blindness - samples



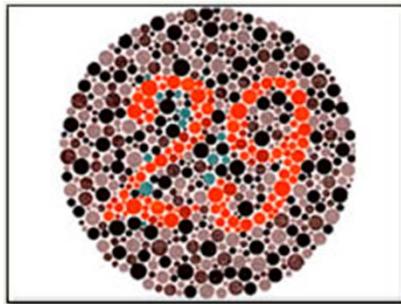
Trichomat
(all cones)



Protanopia
(L-cone)



Deutanopia
(M-cone)

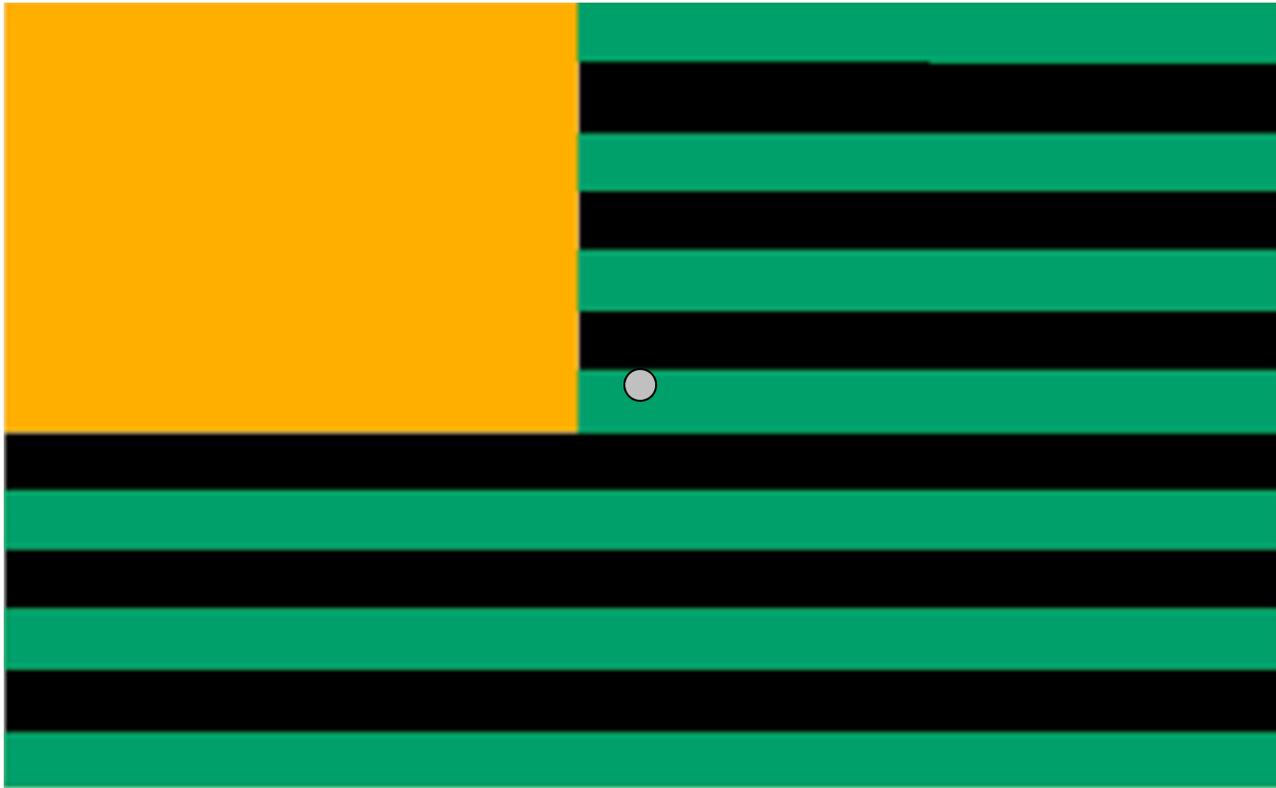


Tritanopia
(S-cone)



Color vision - after images 1

- Fixate center dot on flag for 1 minute, then look at a white surface



Color vision - after images 2



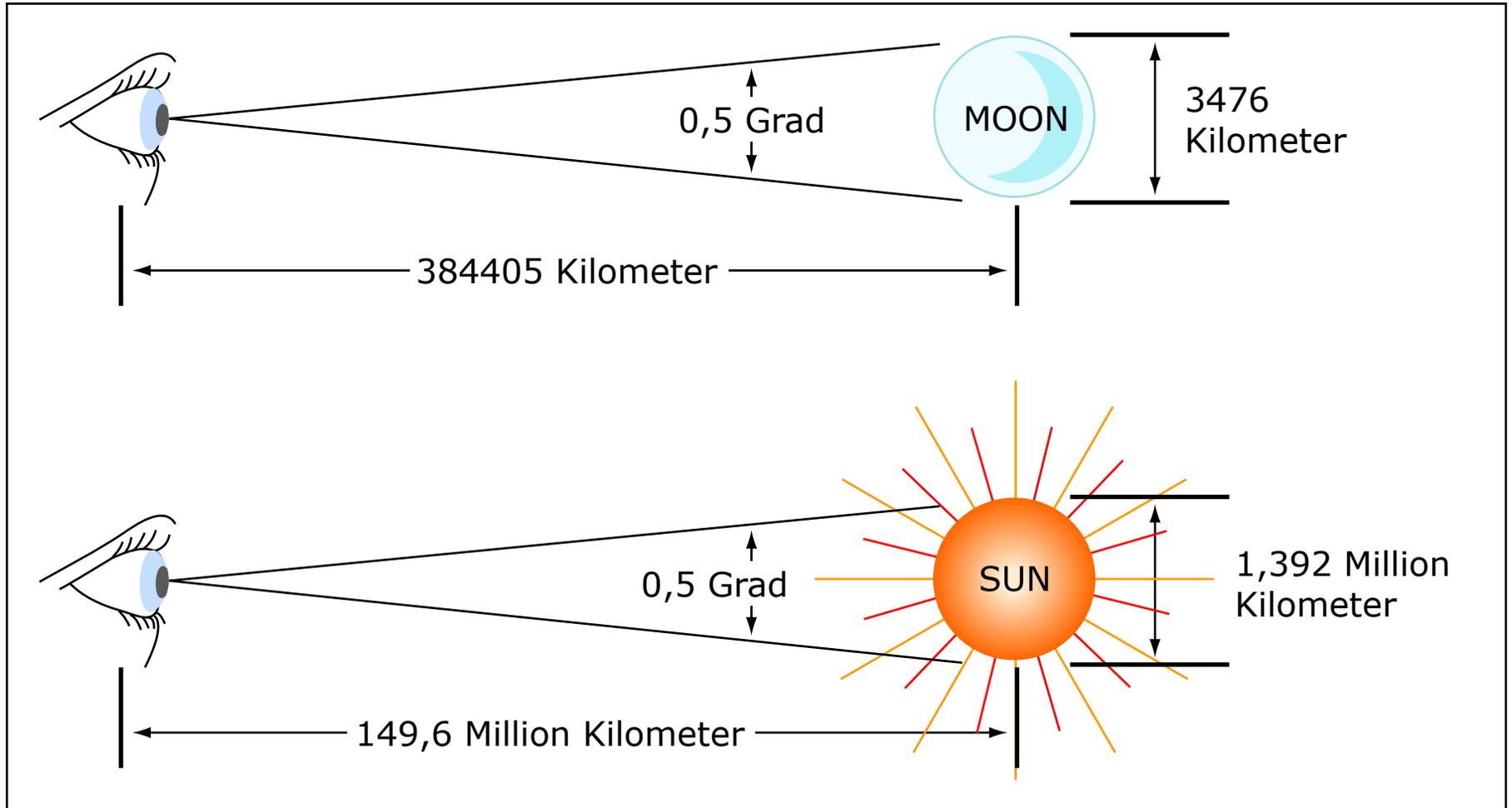


Image by MIT OpenCourseWare.

Perceived size

- How to estimate the distance of person?

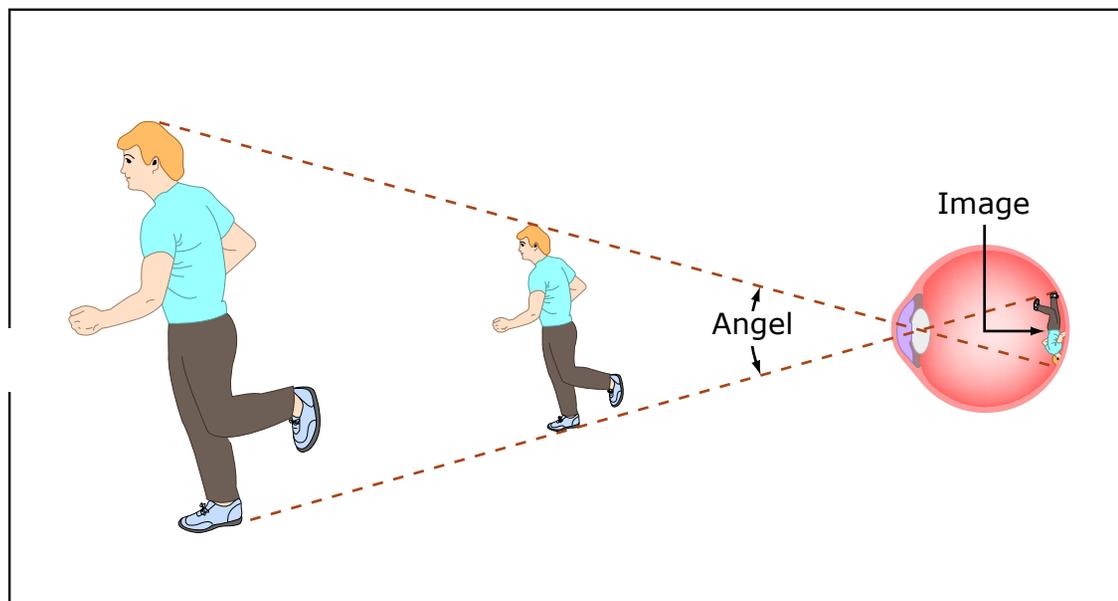
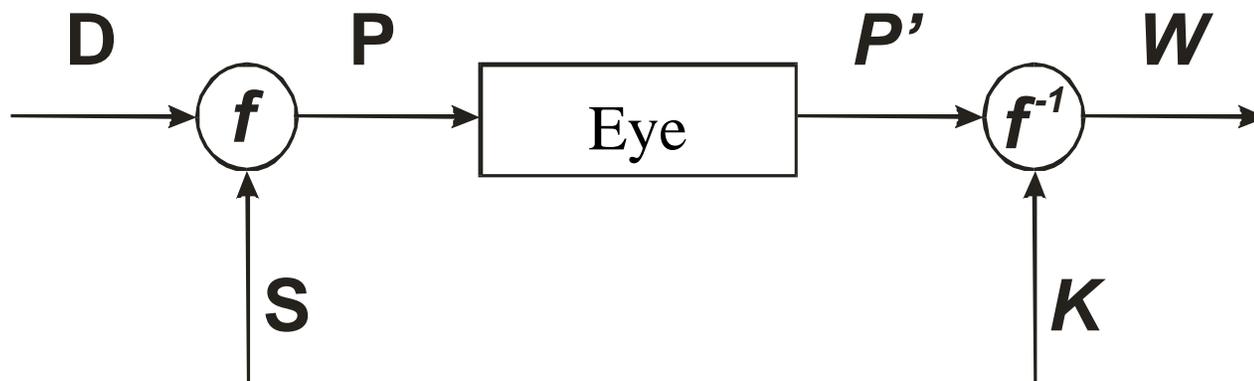


Image by MIT OpenCourseWare.

$$P = D/S$$

$$W = P' * K$$



Additional Slides

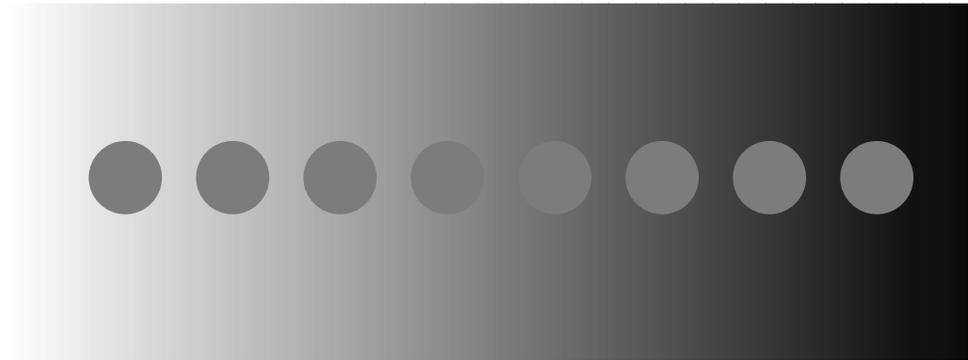
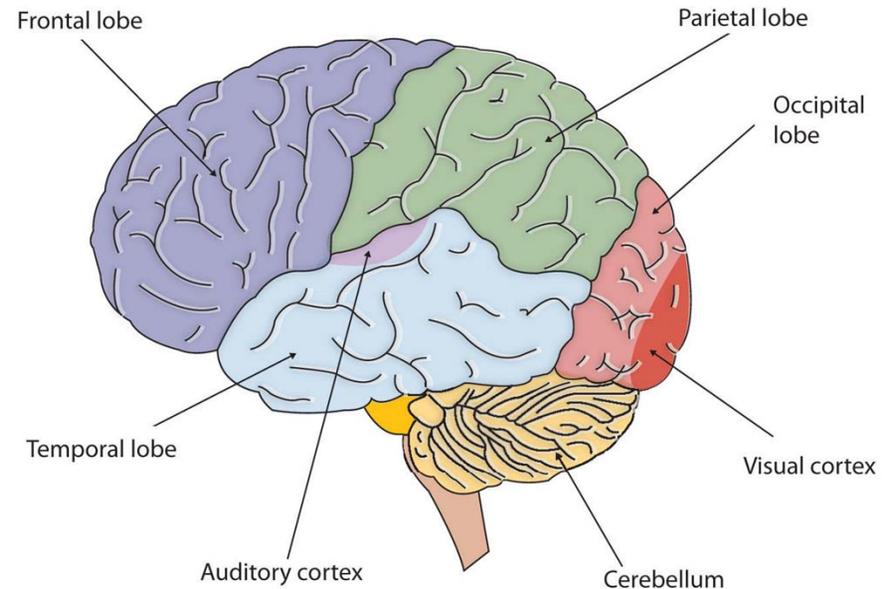


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Major parts

- **Occipital lobe:** visual perception system
- E.g., visuospatial processing, discrimination of movement and colour discrimination



Adapted from Stangor, C. *Introduction to Psychology*. Flatworld Knowledge, 2010. Courtesy of Flatworld Knowledge.

Sensory Maps - Homunculus

Image of Homunculus removed due to copyright restrictions.

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