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16.346 Astrodynamics
Fall 2008

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Lecture 25 The Restricted Problem of Three Bodies #8.2

Jacobi's Equations

If the third mass $m_3 \equiv m$ is infinitesimal, then

$$m \left[\frac{d^2 \mathbf{r}}{dt^2} + 2\boldsymbol{\omega} \times \frac{d\mathbf{r}}{dt} + \frac{d\boldsymbol{\omega}}{dt} \times \mathbf{r} + \boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) \right] = -\frac{Gmm_1}{\rho_1^3} \boldsymbol{\rho}_1 - \frac{Gmm_2}{\rho_2^3} \boldsymbol{\rho}_2$$

where

$$\begin{aligned} \boldsymbol{\rho}_1 &= \mathbf{r} - \mathbf{r}_1 & \boldsymbol{\rho}_2 &= \mathbf{r} - \mathbf{r}_2 & \mathbf{r} &= \mathbf{r}_3 - \frac{m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2}{m_1 + m_2} = \xi \mathbf{i}_\xi + \eta \mathbf{i}_\eta + \zeta \mathbf{i}_\zeta \\ \boldsymbol{\omega} &= \omega \mathbf{i}_\zeta \quad \text{with} \quad \omega^2 = \frac{G(m_1 + m_2 + m)}{r_{12}^3} \approx \frac{G(m_1 + m_2)}{r_{12}^3} \end{aligned}$$

With m_1 and m_2 on ξ -axis, then

$$\begin{aligned} \mathbf{r}_1 &= \xi_1 \mathbf{i}_\xi & \rho_1^2 &= (\xi - \xi_1)^2 + \eta^2 + \zeta^2 \\ \mathbf{r}_2 &= \xi_2 \mathbf{i}_\xi & \rho_2^2 &= (\xi - \xi_2)^2 + \eta^2 + \zeta^2 \end{aligned}$$

Now

$$\boldsymbol{\omega} \times (\boldsymbol{\omega} \times \mathbf{r}) = -\omega^2(\xi \mathbf{i}_\xi + \eta \mathbf{i}_\eta)$$

so that

$$\frac{d^2 \mathbf{r}}{dt^2} + 2\boldsymbol{\omega} \times \frac{d\mathbf{r}}{dt} = \omega^2(\xi \mathbf{i}_\xi + \eta \mathbf{i}_\eta) - \frac{Gm_1}{\rho_1^3} \boldsymbol{\rho}_1 - \frac{Gm_2}{\rho_2^3} \boldsymbol{\rho}_2$$

Define

$$\boxed{\mathcal{J}(\xi, \eta, \zeta) = \frac{\omega^2}{2}(\xi^2 + \eta^2) + \frac{Gm_1}{\rho_1} + \frac{Gm_2}{\rho_2}}$$

Then

$$\begin{aligned} \frac{d^2 \xi}{dt^2} - 2\omega \frac{d\eta}{dt} &= \frac{\partial \mathcal{J}}{\partial \xi} \\ \boxed{\frac{d^2 \mathbf{r}}{dt^2} + 2\boldsymbol{\omega} \times \frac{d\mathbf{r}}{dt} = \left[\frac{\partial \mathcal{J}}{\partial \mathbf{r}} \right]^T} \quad \text{or} \quad \frac{d^2 \eta}{dt^2} + 2\omega \frac{d\xi}{dt} &= \frac{\partial \mathcal{J}}{\partial \eta} \\ \frac{d^2 \zeta}{dt^2} &= \frac{\partial \mathcal{J}}{\partial \zeta} \end{aligned}$$

Jacobi's Integral

Take scalar product with $d\mathbf{r}/dt$

$$\underbrace{\frac{d^2 \mathbf{r}}{dt^2} \cdot \frac{d\mathbf{r}}{dt}}_{\frac{1}{2} \frac{d}{dt} \left(\frac{d\mathbf{r}}{dt} \cdot \frac{d\mathbf{r}}{dt} \right)} + \underbrace{2\boldsymbol{\omega} \times \frac{d\mathbf{r}}{dt} \cdot \frac{d\mathbf{r}}{dt}}_{= 0} = \underbrace{\frac{\partial \mathcal{J}}{\partial \mathbf{r}} \frac{d\mathbf{r}}{dt}}_{\frac{d\mathcal{J}}{dt}}$$

Integrate to obtain

$$\frac{1}{2} \left(\frac{d\mathbf{r}}{dt} \cdot \frac{d\mathbf{r}}{dt} + C \right) = \mathcal{J} \quad \text{or} \quad v_{rel}^2 = 2\mathcal{J}(\xi, \eta, \zeta) - C$$

Hence

$$v_{rel}^2 = \omega^2(\xi^2 + \eta^2) + \frac{2Gm_1}{\rho_1} + \frac{2Gm_2}{\rho_2} - C$$

Surfaces of Zero Relative Velocity

In ξ, η, ζ space, surfaces of zero relative velocity are

$$\omega^2(\xi^2 + \eta^2) + \frac{2Gm_1}{\rho_1} + \frac{2Gm_2}{\rho_2} = \text{constant}$$

In the ξ, η plane (in terms of bipolar coordinates) curves of zero relative velocity are

$$Gm_1 \left(\frac{\rho_1^2}{\rho^3} + \frac{2}{\rho_1} \right) + Gm_2 \left(\frac{\rho_2^2}{\rho^3} + \frac{2}{\rho_2} \right) = \text{constant}$$

Note: In the two-body problem, curves of zero relative velocity are

$$v^2 = \mu \left(\frac{2}{r} - \frac{1}{a} \right) = 0 \quad \text{or} \quad r = 2a$$

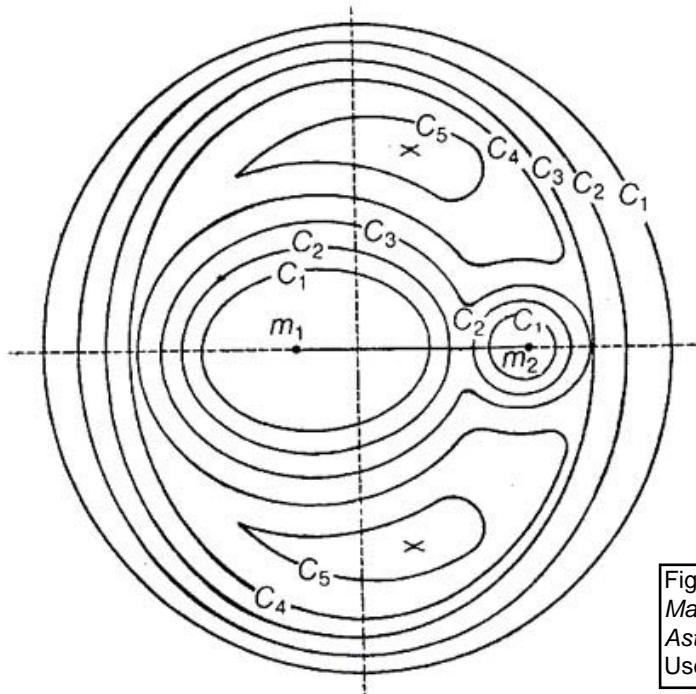


Fig. 8.1 from *An Introduction to the Mathematics and Methods of Astrodynamics*. Courtesy of AIAA. Used with permission.

Jacobi's integral $\left(\frac{d\zeta}{dt}\right)^2 = \frac{4Gm}{\rho} - C$ where $\rho^2 = D^2 + \zeta^2$ and $\omega^2 = \frac{Gm}{4D^3}$

With velocity v_0 when $\zeta = 0$, then $C = \frac{4Gm}{D} - v_0^2$.

Hence $\left(\frac{d\zeta}{dt}\right)^2 = v_0^2 - 16\omega^2 D^2 \left(1 - \frac{D}{\rho}\right)$

Define $\zeta = D \tan \theta$, $\rho = D \sec \theta$ and $B = \frac{v_0^2}{16\omega^2 D^2}$.

Then $\left(\frac{d\theta}{dt}\right)^2 = 16\omega^2 \cos^4 \theta [B - (1 - \cos \theta)]$

Now $\frac{d\theta}{dt} = 0$ if and only if $B \leq 1$. Define $\theta = \theta_m$ when $\frac{d\theta}{dt} = 0$. Then $B = 1 - \cos \theta_m$.

Therefore, $\left(\frac{d\theta}{dt}\right)^2 = 16\omega^2 \cos^4 \theta (\cos \theta - \cos \theta_m)$

Define $x = \cos \theta$ and $x_m = \cos \theta_m$.

Then $\left(\frac{dx}{dt}\right)^2 = 16\omega^2 x^4 (1 - x^2)(x - x_m)$

Let T be the quarter period. Then $4\omega T = \int_{x_m}^1 \frac{dx}{x^2 \sqrt{P(x)}}$ with $P(x) = (1 - x^2)(x - x_m)$

Integrate by parts $4\omega x_m T = \frac{\sqrt{P(x)}}{x} \Big|_{x_m}^1 + \frac{1}{2} \int_{x_m}^1 \frac{x dx}{\sqrt{P(x)}} + \frac{1}{2} \int_{x_m}^1 \frac{dx}{x \sqrt{P(x)}}$

Convert $P(x)$ to fourth degree with the substitution $x = 1 - z^2$

$$4\omega x_m T = \int_0^\alpha \frac{(1 - z^2) dz}{\sqrt{Q(z)}} + \int_0^\alpha \frac{dz}{(1 - z^2) \sqrt{Q(z)}}$$

$$Q(z) = 2\alpha^2 \left(1 - \frac{z^2}{2}\right) \left(1 - \frac{z^2}{\alpha^2}\right) \equiv R(y) = (1 - y^2)(1 - k^2 y^2)$$

where we have defined $\alpha = \sqrt{1 - x_m}$, $z = \alpha y$ and $k^2 = \frac{1}{2} \alpha^2$ and obtain

$$4\sqrt{2} \omega x_m T = \int_0^1 \frac{(1 - 2k^2 y^2) dy}{\sqrt{R(y)}} + \int_0^1 \frac{dy}{(1 - 2k^2 y^2) \sqrt{R(y)}}$$

After some algebra, convert to Legendre form with $y = \sin \phi$ to obtain

$$4\sqrt{2} \omega x_m T = 2E(k) - K(k) + \Pi(2k^2, k, \frac{1}{2}\pi)$$