

2.2) A) Stress-strain rate relation for a Newt. fluid

B) Viscosity coefficient

C) Vorticity and circulation

White 23-29, 59-69, 89-91

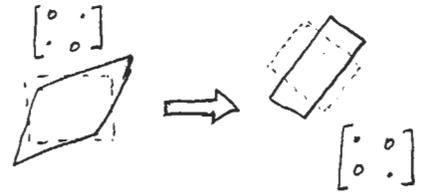
Kreth & Chow 40-50,

Batch - 71-99.

A) Stress-strain rate relation

For any stress tensor σ_{ij} in coordinates x_i , a set of principle axis exists such that

$$\sigma'_{ij} = \begin{bmatrix} \sigma'_{11} & 0 & 0 \\ 0 & \sigma'_{22} & 0 \\ 0 & 0 & \sigma'_{33} \end{bmatrix}$$



σ'_{11} , σ'_{22} , σ'_{33} are eigenvalues of σ_{ij} (σ'_{ij}) invariant under coord. transformation

Physical significance is the avg. principal stress

$$\frac{1}{3}(\sigma'_{11} + \sigma'_{22} + \sigma'_{33}) \equiv \frac{1}{3}\sigma'_{ii} = -p \quad (\text{static pressure})$$

Note: This is the only stress in a fluid at rest ($\sigma_{ij} = -p\delta_{ij}$) (and generally in an inviscid fluid)

This suggest that

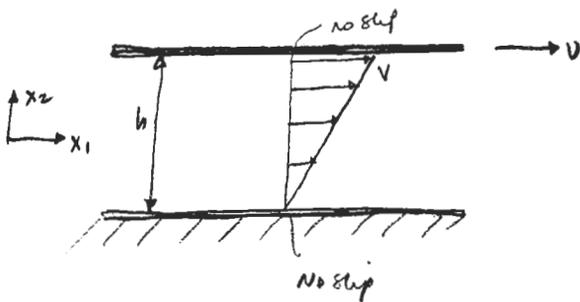
$$\sigma_{ij} = \underbrace{d_{ij}}_{\substack{\text{deviatoric} \\ \text{stresses} \\ \text{(non-isotropic)}}} - p \underbrace{\delta_{ij}}_{\substack{\text{spherical stresses} \\ \text{(isotropic)}}} = (\sigma_{ij} + p\delta_{ij}) + (-p\delta_{ij})$$

such that $d_{ij} = 0$ for a fluid at rest

By definition of a fluid, d_{ij} must depend on the velocity field, more precisely, on strain rate tensor.

$$d_{ij} = f(e_{ij})$$

For a Newtonian fluid this relationship is linear.
Consider two plates in motion



$$e_{12} = \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right) = \frac{1}{2} \frac{du_1}{dx_2}$$

$$\sigma_{12} \sim e_{12} \quad \sigma_{12} = \mu \frac{V}{h} = \mu \frac{du_1}{dx_2} = 2\mu e_{12}$$

μ is the coefficient of viscosity

In general,

$$d_{ij} = 2\mu e_{ij} + \lambda e_{kk} \delta_{ij} \quad ; \quad e_{kk} = e_{11} + e_{22} + e_{33} = \nabla \cdot \vec{u}$$

λ is the coefficient of bulk viscosity (e_{kk} - normal strains)

$$\therefore \sigma_{ij} = -p \delta_{ij} + 2\mu e_{ij} + \lambda \nabla \cdot \vec{u} \delta_{ij}$$

$$\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Since

$$p = -\frac{1}{3}(\sigma_{11} + \sigma_{22} + \sigma_{33}) \Rightarrow \lambda = -\frac{2}{3}\mu \quad \text{— Stokes's Hypothesis}$$

7 Viscosity

Finally we can write a single deformation law for a Newtonian (linear) viscous fluid as:

$$\sigma_{ij} = -p \delta_{ij} + 2\mu(e_{ij} - \frac{1}{3} \nabla \cdot \vec{u} \delta_{ij})$$

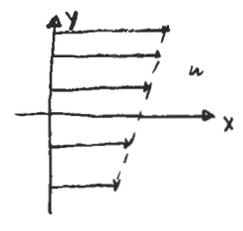
$$\rho \frac{D u_i}{D t} = \rho f_i - \frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right]$$

If $\rho = \text{const}$, $\mu = \text{const} \rightarrow \rho \frac{D \vec{u}}{D t} = \vec{f} - \nabla p / \rho + \nu \left[\nabla^2 \vec{u} + \nabla (\nabla \cdot \vec{u}) \right]$ $\nu = \mu / \rho$

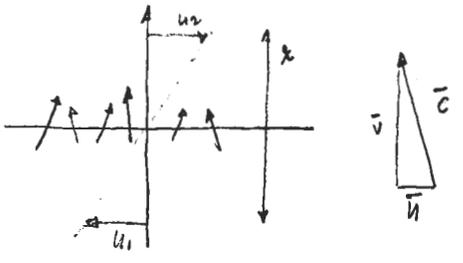
B) Molecular Basis for viscosity and pressure.

Consider mean shear flow

$$u(y) = u_0 + \frac{du}{dy} \cdot y$$



Mass and momentum transport across $y=0$



upward moving molecules

$\lambda = \text{mean free path}$
 $\bar{c} = \text{mean molecular speed}$

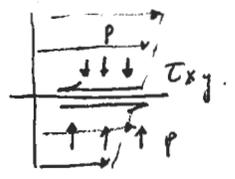
- 1) Mass flux = $\dot{m} = \rho \bar{v} \approx \rho \bar{c}$; $\rho = \text{molecular mass density}$
- 2) x-momentum flux = $\dot{m} \bar{u} \approx -\rho \bar{c} \frac{\lambda}{2} \frac{du}{dy}$; $\bar{u} \approx u_1 = -\frac{du}{dy} \cdot \frac{\lambda}{2}$
- 3) y-momentum flux = $\dot{m} \bar{v} = \rho \bar{c}^2$

suggest $\mu = \frac{1}{2} \rho \bar{c} \lambda$

At length scales $\gg \lambda$

x-mom. flux = tang stress = $-\mu \frac{du}{dy} = \tau_{xy}$.

y-mom flux = normal stress = p



c) Vorticity and Circulation

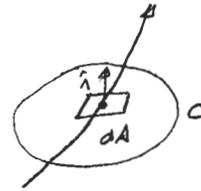
Vorticity = $\vec{\omega} = \nabla \times \vec{u}$ curl of velocity field

Stokes Theorem

$$\nabla \times \vec{u} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ u & v & w \end{vmatrix}$$

$$\iint_A (\nabla \times \vec{u}) \cdot \hat{n} dA = \oint_C \vec{u} \cdot d\vec{l}$$

$$\iint_A \vec{\omega} \cdot \hat{n} dA = \oint_C \vec{u} \cdot d\vec{l}$$



Example: rotating cylinder of fluid



$$\omega A = 2\pi r v_{\text{tang}}$$

$$\omega \pi r^2 = 2\pi r \Omega r$$

$$\omega = 2\Omega \quad - \quad \text{Vorticity is } 2 \times \text{angular velocity}$$

To understand vorticity changes in a flow

$$\frac{D\vec{u}}{Dt} = \vec{f}_{\text{body}} - \frac{\nabla p}{\rho} + \nu \nabla^2 \vec{u} \quad (\text{in comp, } \mu = \text{const})$$

$\nu = \mu/\rho$

$$\vec{f}_{\text{body}} = \nabla \Omega \quad - \quad \text{conservative body force}$$

Vector identity:

$$\vec{u} \cdot \nabla \vec{u} = \nabla(u^2/2) - \vec{u} \times \vec{\omega}$$

rotation of flow

and,

$$\nabla \times \nabla(\quad) = 0, \quad \nabla \cdot (\nabla \times (\quad)) = 0$$

$$\nabla \times \nabla \phi = 0$$

$$\nabla \times \left[\frac{\partial \vec{u}}{\partial t} + \nabla(u^2/2) - \vec{u} \times \vec{\omega} \right] = \nabla \Omega - \frac{1}{\rho} \nabla p + \nu \nabla^2 \vec{u}$$

$$\Rightarrow \frac{\partial \vec{\omega}}{\partial t} + \nabla \times \left(\frac{\vec{u} \times \vec{\omega}}{\rho} \right) - \nabla \times (\vec{u} \times \vec{\omega}) = \nabla \times \left(\frac{\vec{\omega}}{\rho} \right) - \frac{1}{\rho} \nabla \times \left(\frac{\vec{\omega}}{\rho} \right) + \nu \nabla \times \nabla^2 \vec{u}$$

$$\nabla \times (\vec{u} \times \vec{\omega}) = \vec{u} (\nabla \cdot \vec{\omega}) + \vec{\omega} \cdot \nabla \vec{u} - \vec{\omega} \nabla \cdot \vec{u} - \vec{u} \cdot \nabla \vec{\omega}$$

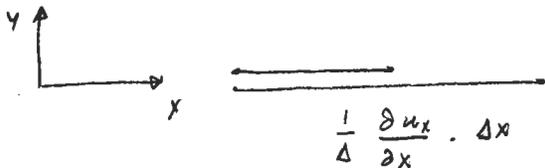
$$\nabla \times (\vec{a} \times \vec{b}) = \vec{a} (\nabla \cdot \vec{b}) + \vec{b} \cdot \nabla \vec{a} - \vec{b} (\nabla \cdot \vec{a}) - \vec{a} \cdot \nabla \vec{b}$$

$$\Rightarrow \frac{D\vec{\omega}}{Dt} = \underbrace{\vec{\omega} \cdot \nabla \vec{u}}_{\text{vorticity stretching + tilting term}} + \nu \nabla^2 \vec{\omega} \quad \downarrow \text{vorticity diffusion}$$

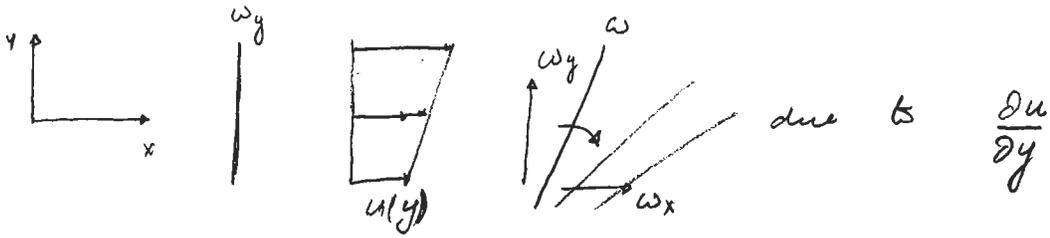
Evolution of vorticity is unaffected by the pressure field. Purely kinematic quantity, just motion.

Consider x component of vorticity equation

$$\frac{D\omega_x}{Dt} = \underbrace{\omega_x \frac{\partial u}{\partial x}}_{\text{stretching term}} + \underbrace{\omega_y \frac{\partial u}{\partial y} + \omega_z \frac{\partial u}{\partial z}}_{\text{tilting or tilting term}}$$



$$\frac{1}{\omega_x} \frac{D\omega_x}{Dt} = \frac{\partial u}{\partial x} \quad \leftarrow \text{vortex stretching}$$



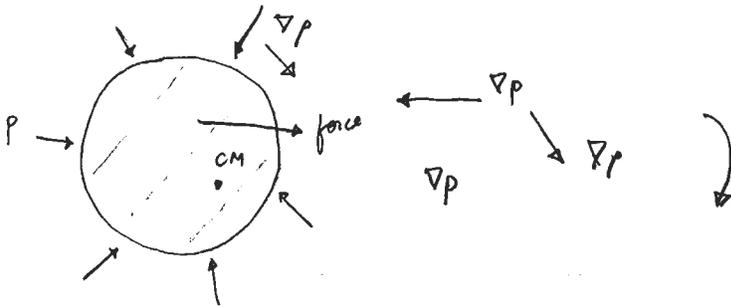
$\vec{\omega}$ gets tipped / tilted in x direction - rate of creation of x vorticity. // by for z component

In a 2-D flow $\vec{\omega} = (0, 0, \omega_z)$

$$\Rightarrow \frac{D\omega_z}{Dt} = \frac{D\omega}{Dt} = 0$$

Compressible, ^{inviscid} form

$$\frac{D}{Dt} \left(\frac{\vec{\omega}}{\rho} \right) = \left(\frac{\vec{\omega}}{\rho} \right) \cdot \nabla \vec{u} + \frac{\nabla P}{\rho} \times \nabla \left(\frac{1}{\rho} \right)$$



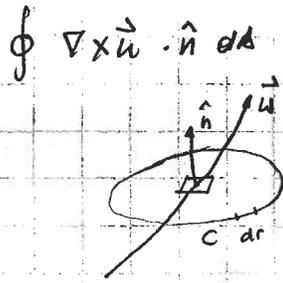
Eraser Board

Circulation

$$\Gamma_c = \oint_C \vec{u} \cdot d\vec{r}$$

$$= \iint_S (\vec{\omega} \cdot \hat{n}) dA$$

↑
vorticity



$$\frac{D\Gamma_c}{Dt} = \frac{D}{Dt} \oint_C \vec{u} \cdot d\vec{l}$$

If we consider a contour with same fluid particles

$$\frac{D\Gamma_c}{Dt} = \oint_C \frac{D}{Dt} (\vec{u} \cdot d\vec{l})$$

$$= \oint_C \frac{D\vec{u}}{Dt} \cdot d\vec{l} + \oint_C \vec{u} \cdot \frac{Dd\vec{l}}{Dt}$$

Rate of change of $d\vec{l}$ is $\frac{\delta(d\vec{l})}{\delta t}$ or $d\vec{u}$

so $\frac{Dd\vec{l}}{Dt} = d\vec{u}$

Hence $\oint_C \vec{u} \cdot \frac{Dd\vec{l}}{Dt} = \oint_C \vec{u} \cdot d\vec{u} = \oint_C d \left(\frac{\vec{u} \cdot \vec{u}}{2} \right) = 0$

↑ exact differential

$$\therefore \frac{D\Gamma_c}{Dt} = \oint_C \frac{D\vec{u}}{Dt} \cdot d\vec{l}$$

$$= \oint_C \left[-\frac{\nabla p}{\rho} + \vec{f}_{\text{body}} + \nabla \cdot \vec{\sigma} \right] \cdot d\vec{l} \quad (\text{Kelvin's Theorem})$$

Uniform density, inviscid, conservative body

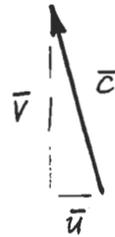
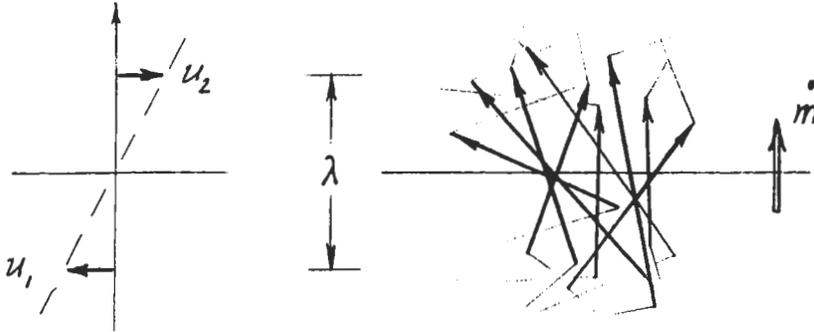
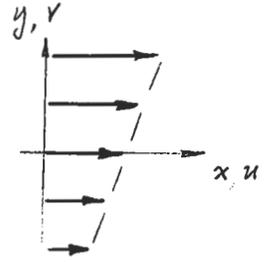
$$\Rightarrow \frac{D\Gamma_c}{Dt} = 0$$

If $\Gamma_c = 0$ for a fluid contour, it always has $\Gamma_c = 0$

MOLECULAR BASIS FOR VISCOSITY AND PRESSURE

Consider mean shear flow: $u(y) = u_0 + \frac{du}{dy} y$

Examine mass and momentum transport across $y=0$ plane in frame moving at $u = u_0$



upward-moving molecules
crossing $y=0$ plane

velocity of average
upward-moving molecules

λ = mean free path
 \bar{c} = mean molecular speed

$$\bar{u} \approx u_1 = -\frac{du}{dy} \frac{\lambda}{2}$$

$$\bar{v} \approx \bar{c}$$

Effects of upward moving molecules on space above $y=0$ plane:

→ Mass flux = $\dot{m} = \rho \bar{v} \approx \rho \bar{c}$; ρ = molecular mass density

→ x-Momentum flux = $\dot{m} \bar{u} \approx -\rho \bar{c} \frac{\lambda}{2} \left(\frac{du}{dy}\right)$

→ y-Momentum flux = $\dot{m} \bar{v} \approx \rho \bar{c}^2$

suggests $\mu \approx \frac{1}{2} \rho \bar{c} \lambda$
actually, $\mu = 0.499 \rho \bar{c} \lambda$

In length scales $\gg \lambda$:

x-mom. flux = tangential stress on $y=0$ plane = $-\mu \left(\frac{du}{dy}\right) = \tau_{xy}$

y-mom. flux = normal " " " " = p

By considering downward-moving molecules,
we get mass and momentum flux
into space below $y=0$ plane

