

## Lecture S15

### The Transfer Function

Often, we want to find response of system to sinusoidal or exponential inputs. Why?

- Exponential inputs produce exponential outputs
- Sine waves are also exponentials

$$\cos \omega t = \frac{e^{j\omega t} + e^{-j\omega t}}{2}$$
$$= \text{Real}[e^{j\omega t}]$$

- Any <sup>input</sup> signal (almost) can be built up out of sines and cosines, or exponentials. By superposition, can find output signal, if we can find response to exponentials.
- Sines and cosines are easily produced in the lab, and are frequently used to test systems.

So, what is response to an exponential input?

Assume our system is in state-space form, with

$$\begin{aligned}\dot{x}(t) &= Ax(t) + Bu(t) \\ y(t) &= Cx(t) + Du(t)\end{aligned}$$

Suppose our input is

$$u(t) = U e^{st}$$

The solution will be

$$x(t) = \text{homogeneous solution} + \text{particular solution}$$

For now, we don't care about the homogeneous solution. What does particular solution look like? Guess that

$$x(t) = X e^{st}$$

Plug into differential equation and solve:

$$\begin{aligned}\dot{x}(t) &= \frac{d}{dt} \underline{\mathbf{X}} e^{st} \\ &= \underline{\mathbf{X}} s e^{st} = A \underline{\mathbf{X}} e^{st} + B \mathbf{U} e^{st}\end{aligned}$$

$$\Rightarrow s \underline{\mathbf{X}} = A \underline{\mathbf{X}} + B \mathbf{U}$$

$$\Rightarrow (sI - A) \underline{\mathbf{X}} = B \mathbf{U}$$

$$\Rightarrow \underline{\mathbf{X}} = (sI - A)^{-1} B \mathbf{U}$$

Given  $x(t)$ ,  $y(t)$  is

$$\begin{aligned}y(t) &= Cx(t) + Du(t) \\ &= CXe^{st} + DUe^{st} \\ &= C(sI - A)^{-1} B \mathbf{U} e^{st} + DUe^{st}\end{aligned}$$

So

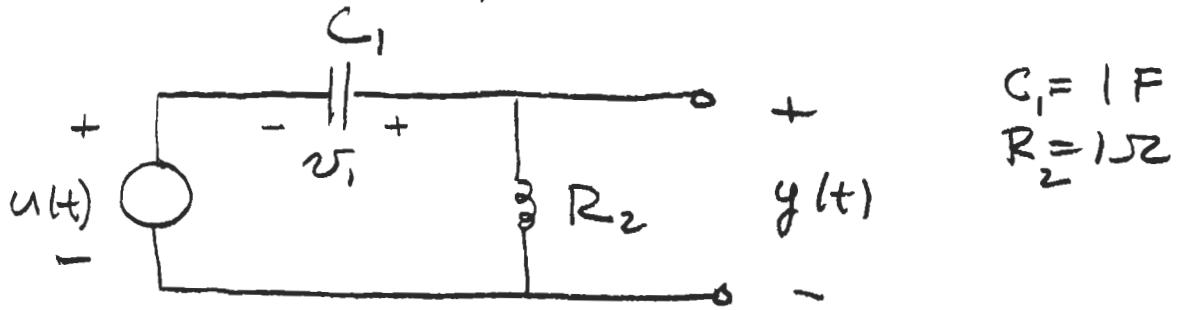
$$y(t) = Y e^{st}$$

where

$$Y = \underbrace{[C(sI - A)^{-1} B + D]}_{\text{G}(s)} \mathbf{U}$$

$G(s)$  = "transfer function"

Example - "high-pass filter"



Differential equation is

$$\ddot{v}_1 = -\frac{1}{R_2 C_1} v_1 - \frac{1}{R_2 C_1} u$$

$$y = v_1 + u$$

$$A = -\frac{1}{R_2 C_1} = -1 \quad B = \frac{-1}{R_2 C_1} = -1$$

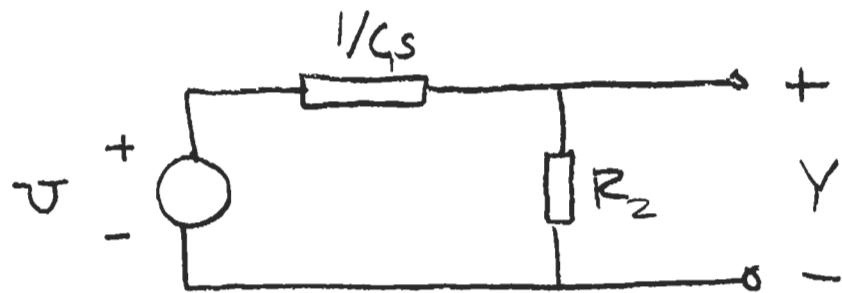
$$C = 1 \quad D = 1$$

$$G(s) = C(sI - A)^{-1}B + D \quad \left[ = \frac{R_2 C_1 s}{R_2 C_1 s + 1} \right]$$

$$= 1 \cdot (s+1)^{-1} \cdot (-1) + 1$$

$$= 1 - \frac{1}{s+1} = \frac{s}{s+1}$$

Note! Can also find  $G(s)$  using impedances:



This is a voltage divider. So

$$Y = \frac{R_2 U}{R_2 + 1/C_s} = \underbrace{\frac{R_2 C_s s}{R_2 C_s s + 1}}_{G(s)} U$$

as before.

$G(s)$

What is response of high pass filter to sinusoidal input?

$$u(t) = \cos \omega t = \operatorname{Real} \left[ 1 \cdot e^{j\omega t} \right]$$

So take  $V=1$ . Then

$$Y = G(j\omega) V$$

$$= \frac{j\omega}{j\omega+1} \cdot 1 = \frac{j\omega}{j\omega+1} \cdot \frac{-j\omega+1}{-j\omega+1}$$

$$= \frac{\omega^2 + j\omega}{\omega^2 + 1}$$

$$\Rightarrow y(t) = \operatorname{Real} \left[ \left( \frac{\omega^2}{\omega^2+1} + j \frac{\omega}{\omega^2+1} \right) e^{j\omega t} \right]$$

$$y(t) = \frac{\omega^2}{\omega^2+1} \cos \omega t - \frac{\omega}{\omega^2+1} \sin \omega t$$

For large  $\omega$ ,  $y(t) \approx \cos \omega t$

For small  $\omega$ ,  $y(t) \approx -\frac{1}{\omega} \sin \omega t$ .

I.e., the filter "passes" high frequency sine waves, and attenuates low frequencies.