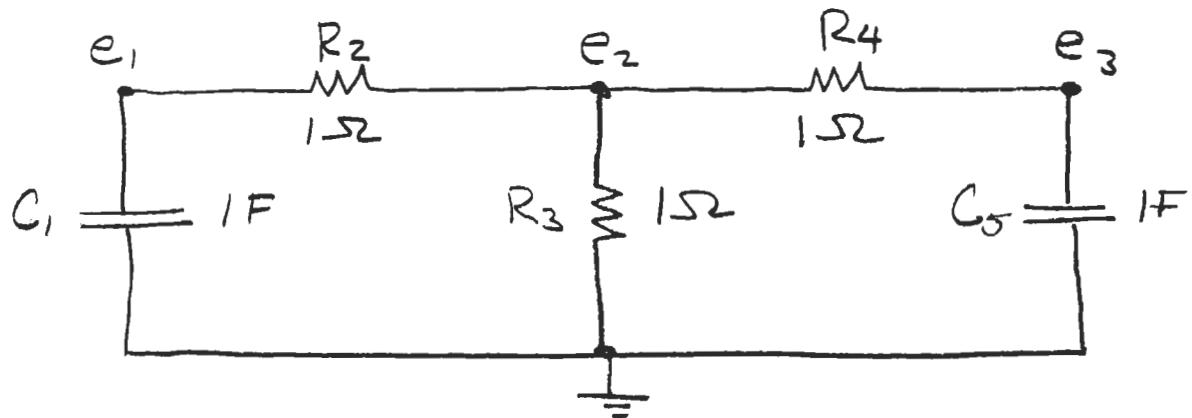


Lecture 8

Time Response of RC Networks

Example:



Given initial conditions $v_1(0)$, $v_3(0)$,
How do we find time histories of
circuit variables (v 's, i 's)?

First, find differential equations using
node method

$$*e_1: C_1 \dot{e}_1 + G_2 e_1 - G_2 e_2 = 0$$

$$**e_2: -G_2 e_1 + (G_2 + G_3 + G_4) e_2 - G_4 e_3 = 0$$

$$*e_3: -G_4 e_2 + C_5 \dot{e}_3 + G_4 e_3 = 0$$

* Dynamic - It's a differential equation
for e_1 or e_3 in terms of e_1, e_2, e_3

** Static - Gives e_2 in terms of e_1, e_3

How do we solve the differential equations? Guess! (But an educated guess.)

Our guess:

$$e_1(t) = E_1 e^{st}$$

$$e_2(t) = E_2 e^{st}$$

$$e_3(t) = E_3 e^{st}$$

E_1, E_2, E_3 are amplitudes.

s is the same number for each exponential, that is, there is not s_1, s_2, s_3 .

Is this a good guess? Try solution and see!

$$e_1: C_1 \dot{e}_1(t) + G_2 e_1(t) - G_2 e_2(t)$$

$$= C_1 \frac{d}{dt} (E_1 e^{st}) + G_2 (E_1 e^{st}) - G_2 (E_2 e^{st})$$

$$= C_1 E_1 s e^{st} + G_2 E_1 e^{st} - G_2 E_2 e^{st} = 0$$

$$\Rightarrow C_1 s E_1 + G_2 E_1 - G_2 E_2 = 0$$

$$\Rightarrow (C_1 s + G_2) E_1 - G_2 E_2 = 0$$

Note that $C_1 s + G_2$ have same units.

G_2 = conductance of resistor R_2

$\Rightarrow C_1 s = \cancel{\text{conductance}}$ of capacitor C_1

↗ experts say "admittance"

$\Rightarrow \frac{1}{C_1 s} = \cancel{\text{resistance}}$ of capacitor C_1

↗ experts say "impedance"

Can do the same for other equations:

$$(C_1 s + G_2) E_1 - G_2 E_2 = 0$$

$$-G_2 E_1 + (G_2 + G_3 + G_4) E_2 - G_4 E_3 = 0$$

$$-G_4 E_2 + (C_5 s + G_4) E_3 = 0$$

In matrix form,

$$\begin{bmatrix} C_1 s + G_2 & -G_2 & 0 \\ -G_2 & G_2 + G_3 + G_4 & -G_4 \\ 0 & -G_4 & C_5 s + G_4 \end{bmatrix} \begin{bmatrix} E_1 \\ E_2 \\ E_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Or, $M(s) \underline{E} = \underline{0}$ vectors

One obvious solution is $E = \Omega$.
But this is a trivial solution —
it doesn't help at all.

There is a non-trivial solution only
if

$$\phi(s) = \det(M(s)) = 0 \text{ "characteristic equation"}$$

At this point, plug in numbers:

$$M(s) = \begin{bmatrix} s+1 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & s+1 \end{bmatrix}$$

(see linear algebra handout to review
how to take determinant)

$$\begin{aligned}\phi(s) &= |M(s)| = 3(s+1)(s+1) - (-1)(-1)(s+1) \\ &\quad - (-1)(-1)(s+1) \\ &= 3s^2 + 4s + 1 \\ &= (3s+1)(s+1) = 0\end{aligned}$$

Solutions are

$$\begin{aligned}s &= -1 \text{ sec}^{-1} \quad \text{or} \quad s = -\frac{1}{3} \text{ sec}^{-1} \\ &= s_1 \qquad \qquad \qquad = s_2\end{aligned}$$

These are the "characteristic values"

Now, solve for E_1, E_2, E_3

$S = S_1 = -1$:

$$M(-1) \underline{E}' = \begin{bmatrix} 0 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 0 \end{bmatrix} \underline{E}' = 0$$

Do row reductions (see linear alg. primer!)

$$\Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \underline{E}' = 0$$

A solution is

$$\underline{E}' = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \quad (\text{or any multiple})$$

"characteristic vector"

So one solution is

$$\left. \begin{array}{l} e_1 = -1 e^{-t} \\ e_2 = 0 \\ e_3 = 1 e^{-t} \end{array} \right\} (\text{or any multiple})$$

$$S = S_2 = -\frac{1}{3} \text{ sec}^{-1} :$$

$$M(-\frac{1}{3}) = \begin{bmatrix} \frac{2}{3} & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & \frac{2}{3} \end{bmatrix}$$

Do row reductions:

$$\begin{bmatrix} 1 & -\frac{3}{2} & 0 \\ 0 & 1 & -\frac{2}{3} \\ 0 & 0 & 0 \end{bmatrix} \underline{E^2} = \underline{0}$$

One solution is

$$\underline{E^2} = \begin{bmatrix} 1 \\ \frac{2}{3} \\ 1 \end{bmatrix}$$

So I have two possible solutions:

$$\underline{e}(t) = \underline{E^1} e^{-t} \text{ or } \underline{e}(t) = \underline{E^2} e^{-\frac{1}{3}t}$$

Because system is linear and homogeneous, any linear combination of these is a solution. Therefore, most general solution is

$$e(t) = a \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} e^{-t} + b \begin{bmatrix} 1 \\ 2/3 \\ 1 \end{bmatrix} e^{-t/3}$$

where a, b are constants chosen to satisfy initial conditions:

$$\left. \begin{array}{l} e_1(0) = -a + b \\ e_3(0) = a + b \end{array} \right\} \Rightarrow \begin{array}{l} a = \frac{e_3(0) - e_1(0)}{2} \\ b = \frac{e_3(0) + e_1(0)}{2} \end{array}$$

So,

$$e_1(t) = \frac{e_1(0) - e_3(0)}{2} e^{-t} + \frac{e_1(0) + e_3(0)}{2} e^{-t/3}$$

$$e_2(t) = \frac{2}{3} \frac{e_1(0) + e_3(0)}{2} e^{-t/3}$$

$$e_3(t) = \frac{e_3(0) - e_1(0)}{2} e^{-t} + \frac{e_3(0) + e_1(0)}{2} e^{-t/3}$$

Whew!!